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In [6]: import cv2
import numpy as np

In [ ]: # all cv2 color functions
flags = [i for i in dir(cv2) if i.startswith('COLOR_')]
print(flags)

In [7]: green = np.uint8([[[0, 255, 0]]])

In [8]: hsv_green = cv2.cvtColor(green, cv2.COLOR_BGR2HSV)

In [9]: hsv_green
Out[9]: array([[[ 60, 255, 255]]], dtype=uint8)

In [13]: lower_red = np.array([150, 150, 0])
upper_red = np.array([180, 255, 255])

In [ ]: cap = cv2.VideoCapture(0) # 0 internal camera

while(1):
    _,frame = cap.read()
    hsv = cv2.cvtColor(frame, cv2.COLOR_BGR2HSV)
    mask = cv2.inRange(hsv, lower_red, upper_red)
    result = cv2.bitwise_and(frame, frame, mask = mask)

    cv2.imshow('HSV', hsv)
    cv2.imshow('frame', frame)
    cv2.imshow('mask', mask)
    cv2.imshow('result', result)

    k = cv2.waitKey(5) & 0xFF

    if k == 27: # if user pressed escape button on keyboard
        break

cap.release()
cv2.waitKey(1)
cv2.destroyAllWindows()
cv2.waitKey(1)

[ WARN:0] global ../modules/videoio/src/cap_gstreamer.cpp (616) isPipelinePlaying OpenCV | GStreamer warning: GStreamer: pipeline have not been created

In [ ]:
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