

Name: Alfath Adia Yahya

NIM: 2307004

Class: D4 SIKC 3A

Autonomous Public Transportation

Thesis:

Autonomous public transportation should be implemented in modern cities because it improves traffic efficiency, enhances safety, and supports environmental sustainability.

Argument 1: Increased Efficiency

Firstly, autonomous public transportation increases transportation efficiency. Traditional public transport often faces delays caused by human factors such as fatigue or inconsistent driving behavior. In contrast, autonomous vehicles use real-time sensors and AI-based navigation systems that allow them to follow optimized routes and maintain consistent travel times. This results in smoother operations, reduced traffic congestion, and faster commuting for city residents.

Argument 2: Improved Safety

Another reason autonomous public transportation should be adopted is that it can significantly improve safety. Many traffic accidents are caused by human error, including distraction and misjudgment. Autonomous vehicles reduce these risks by using advanced detection systems that identify obstacles and react immediately. By minimizing human mistakes, cities can lower accident rates and create a safer environment for passengers and pedestrians.

Argument 3: Environmentally Friendly

Finally, autonomous public transportation supports environmental sustainability. Many autonomous buses and shuttles are electric, producing fewer emissions than conventional gasoline-powered vehicles. Additionally, AI systems can optimize energy usage by controlling speed, acceleration, and braking more efficiently. As a result, cities can reduce air pollution and move toward cleaner, greener transportation systems.

Conclusion:

Therefore, autonomous public transportation should be implemented because it increases efficiency, improves public safety, and reduces environmental impact. Cities that invest in this technology will be better prepared to support sustainable and intelligent urban mobility in the future.