# A Complete Comparison of Multi-Point Target Tracking Algorithms over Simulation and NuScenes Data

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\*Authors contribute equally to the work.

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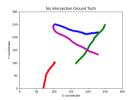
### Project Overview

# Project Objective: Compare 3 Categories of Trackers over simulated scenarios and real measured NuScenes data

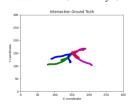
- Random Vector Bayesian Filter based Trackers (PDA, JPDA + Track Management)
- Random Finite Set Filter based Trackers (PHD, CPHD, PMBM)
- Neural Network based Trackers (LSTM, Transformer)

#### Simulation Data: 6 Different Scenarios

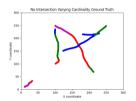
No Intersection No Cardinality Change



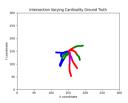
Intersection No Cardinality Change



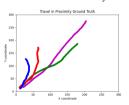
No Intersection with Cardinality Change



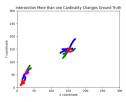
Intersection with Cardinality Change



Travel in Proximity



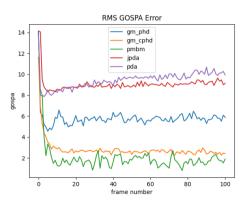
Intersection, Multi-Cardinality Changes

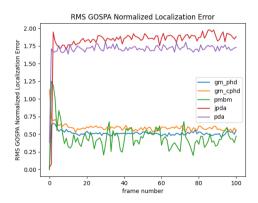


### Scenario 1: No Intersection, No Cardinality Change

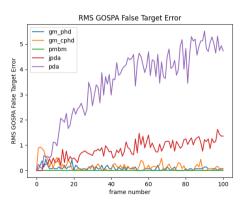
- In this scenario, four targets are initiated and there would be no intersection whatsoever when the track progresses, also there will be no Cardinality change.
- The objective of this scenario is to act as a baseline.
- All trackers should perform relatively well for this scenario.

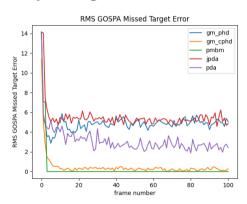
#### Scenario 1: No Intersection, No Cardinality Change





#### Scenario 1: No Intersection, No Cardinality Change

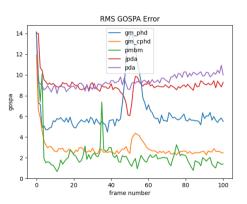


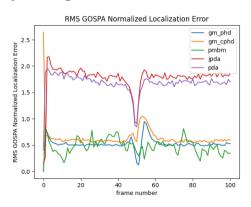


#### Scenario 2: Intersection, No Cardinality Change

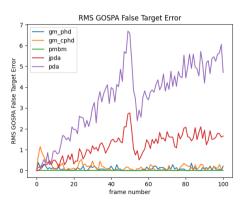
- The four tracks will meet at n\_scan/2 steps, and the Cardinality will remain the same through out the simulation.
- The objective of this scenario is the compare how the 5 trackers fare against the intersection point.

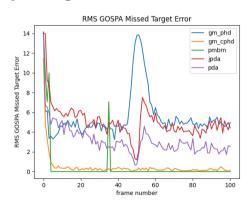
#### Scenario 2: Intersection, No Cardinality Change





#### Scenario 2: Intersection, No Cardinality Change

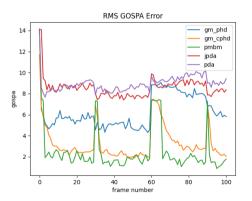


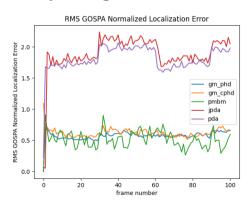


#### Scenario 3: No Intersection, with Cardinality Change

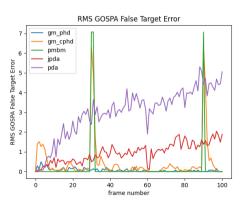
- In this scenario, four targets are initiated and there would be no intersection whatsoever when the track progresses. However, there will be Cardinality changes every 30 scans, in dicated by the color changes in the following graph.
- The objective of this scenario is to see how the trackers fare against Cardinality variation.

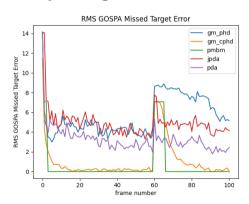
#### Scenario 3: No Intersection, with Cardinality Change





#### Scenario 3: No Intersection, with Cardinality Change

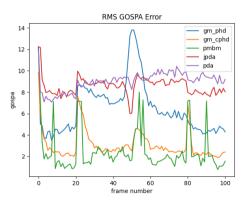


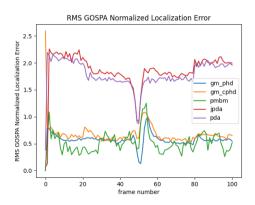


### Scenario 4: Intersection, with Cardinality Change

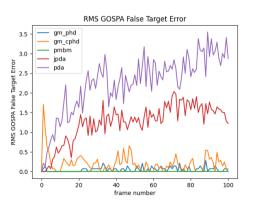
- The tracks will meet at n\_scan/2 steps, and the Cardinality will change every 30 scans.
- The objective of this scenario is the compare how the 5 trackers fare against the intersection point and Cardinality variation.

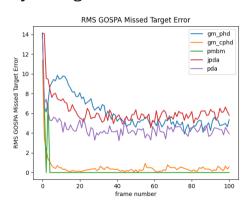
#### Scenario 4: Intersection, with Cardinality Change





#### Scenario 4: Intersection, with Cardinality Change

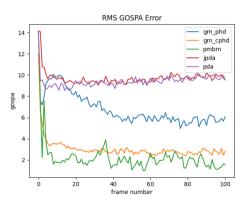


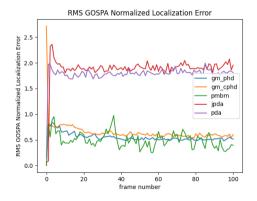


#### Scenario 5: Travel in Proximity

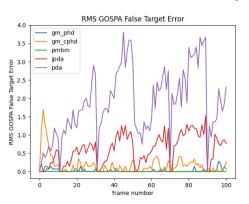
- This scenario has 4 targets travel in proximity, without any Cardinality changes.
- This scenario is designed to mimic the road traffic where cars are moving in parallel with each other closely.

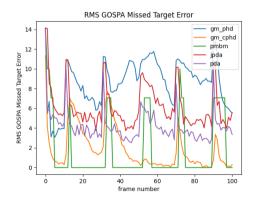
#### Scenario 5: Travel in Proximity





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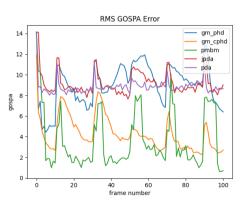


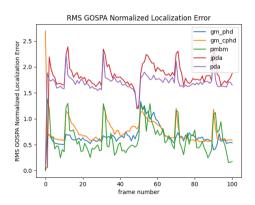


#### Scenario 6: Intersection, with Multiple Cardinality Change

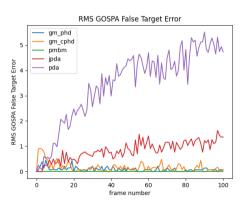
This scenario is designed to be the highest difficulty. At n\_scan/2 step, there
would be intersection. There would also be multiple varying Cardinalities,
such as disappearing of more than one object and appearing of more than one
object simultaneously.

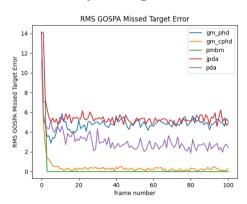
#### Scenario 6: Intersection, with Multiple Cardinality Change





#### Scenario 6: Intersection, with Multiple Cardinality Change





### Project Overview

NuScenes Data: N Different Scenarios