## Shuanghao Bai

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Homepage | \$\mathbf{9}\$ Google Scholar | \$\mathbf{G}\$ Github

Xi'an, Shannxi - China

## **EDUCATION**

Xi'an Jiaotong University

Sept. 2022 - Jun. 2027

Ph.D. candidate. of Control Science and Technology

Xi'an, China

Advisor: Badong Chen

• Research Interests: Generalization of Machine Learning, Robot Learning.

Westlake University

Sept. 2024 - Feb. 2025

Hangzhou, China

Visiting Student in MiLAB

◦ Advisor: Donglin Wang

· Research Interests: Robot Learning.

Chongqing University

Sept. 2018 - Feb. 2022

Chongqing, China

Bachelor of Automation

Advisor: Min Zhao
GPA: 3.68/4.00

**PROJECTS** 

• Cloud-Edge-Device Robot Platform

Sept. 2022 - Dec. 2025

Basic theories and key technologies of cloud-edge-device integrated service robot cloud-brain platform

- Mainly focuses on generalization tasks in computer vision, addressing the challenges posed by limited data availability and significant distribution shifts between training and test data.
- $\circ$  Extend the utility of multilayer perceptron to cross-domain few-shot classification. [ $\bigcirc$ ]
- Implement prompt tuning vision-language model CLIP to unsupervised domain adaptation. [ ]
- Applied prompt tuning vision-language model CLIP to domain generalization. [0]

• Robotic Arm Platform Jan. 2024 - Dec. 2025

Robotic arm platform technology and application based on visual language action model

• Developed a vision language action model that enables robot manipulation.

Multi-agent Collaboration

Jun. 2023 - Dec. 2023

Research on natural human-machine interaction technology for heterogeneous unmanned swarms

- The system primarily enables robots (drones and little car fleets) to understand human language and make decisions based on environmental perception.
- Language comprehension involves task decomposition and code generation using a large language model. Environmental perception relies on drones capturing RGB images. A vision-language model analyzes these images to generate heatmaps, which guide the cars' actions.

## HONORS AND AWARDS

• National Scholarship Dec. 2021, Dec. 2019

 National Third Prize in the Phoenix Intelligent Technology Innovation and Application Competition

Jun. 2021

Grade A Comprehensive Scholarship in Chongqing University

Dec. 2020

• Outstanding Individual Youth Volunteer of Chongqing University

May. 2020

• Outstanding Student of Chongqing University

Dec. 2019

**SKILLS** 

- Programming Languages: Python, Pytorch, C++
- Languages: Chinese, English

- [C.1] Shuanghao Bai, Yuedi Zhang, Wanqi Zhou, Zhirong Luan, Badong Chen. Soft Prompt Generation for Domain Generalization. In European Conference on Computer Vision (ECCV). 2024. [Paper]
- [C.2] Shuanghao Bai, Min Zhang, Wanqi Zhou, Siteng Huang, Zhirong Luan, Donglin Wang, Badong Chen. Prompt-based Distribution Alignment for Unsupervised Domain Adaptation. In Proceedings of the AAAI Conference on Artificial Intelligence (AAAI). 2024. [Paper]
- [C.3] Shuanghao Bai, Wanqi Zhou, Zhirong Luan, Donglin Wang, Badong Chen. Improving Cross-domain Few-shot Classification with Multilayer Perceptron. In IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP). 2024. [Paper]
- [C.4] Wanqi Zhou, Shuanghao Bai, Shujian Yu, Qibin Zhao, Badong Chen. Jacobian Regularizer-based Neural Granger Causality. In International Conference on Machine Learning (ICML). 2024. [Paper]
- [J.1] Zhirong Luan, Yijun Lai, Rundong Huang, **Shuanghao Bai**, Yuedi Zhang, Haoran Zhang, Qian Wang. Enhancing Robot Task Planning and Execution through Multi-Layer Large Language Models. In Sensors. 2024. [Paper]
- [S.1] Wanqi Zhou, Shuanghao Bai, Qibin Zhao, Badong Chen. Revisiting the Adversarial Robustness of Vision Language Models: a Multimodal Perspective. ArXiv preprint arXiv:2404.19287. [Paper]
- [S.2] Wanqi Zhou, Shuanghao Bai, Yicong He, Badong Chen. An Information-Theoretic Approach for Heterogeneous Differentiable Causal Discovery. ssrn:4837242. [Paper]

## ABOUT ME

As a third-year Ph.D. candidate at Xi'an Jiaotong University, I'm deeply fascinated by computer vision, with a particular focus on generalization in visual perception and its applications in robotics. The more I learn, the more I realize how much there is to explore in these fields!

I am actively seeking academic exchange opportunities for Fall 2025, particularly through the CSC program or other joint Ph.D. programs. My hope is to find a research team where I can roll up my sleeves, dive into some cutting-edge projects, and both contribute my skills and learn new ones. I'm eager to experience a different academic environment and see how it shapes my perspective on research.