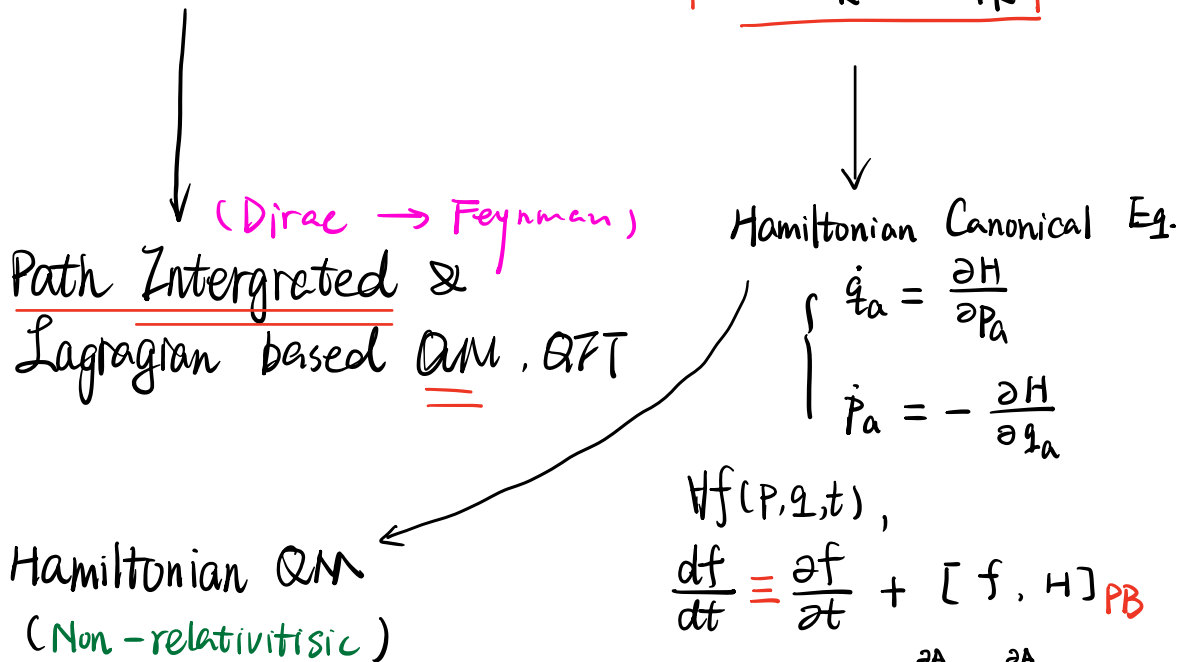
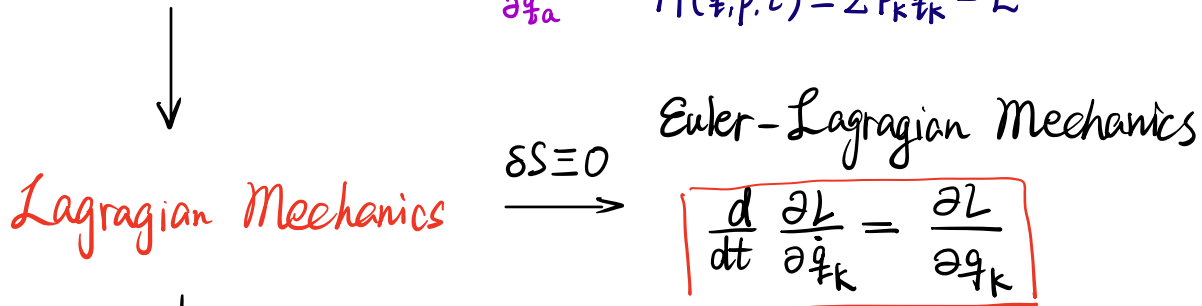
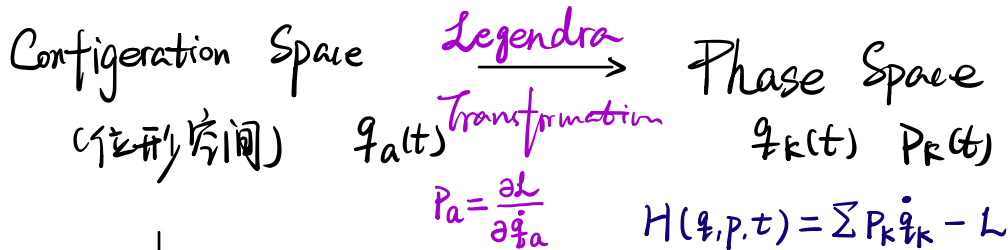


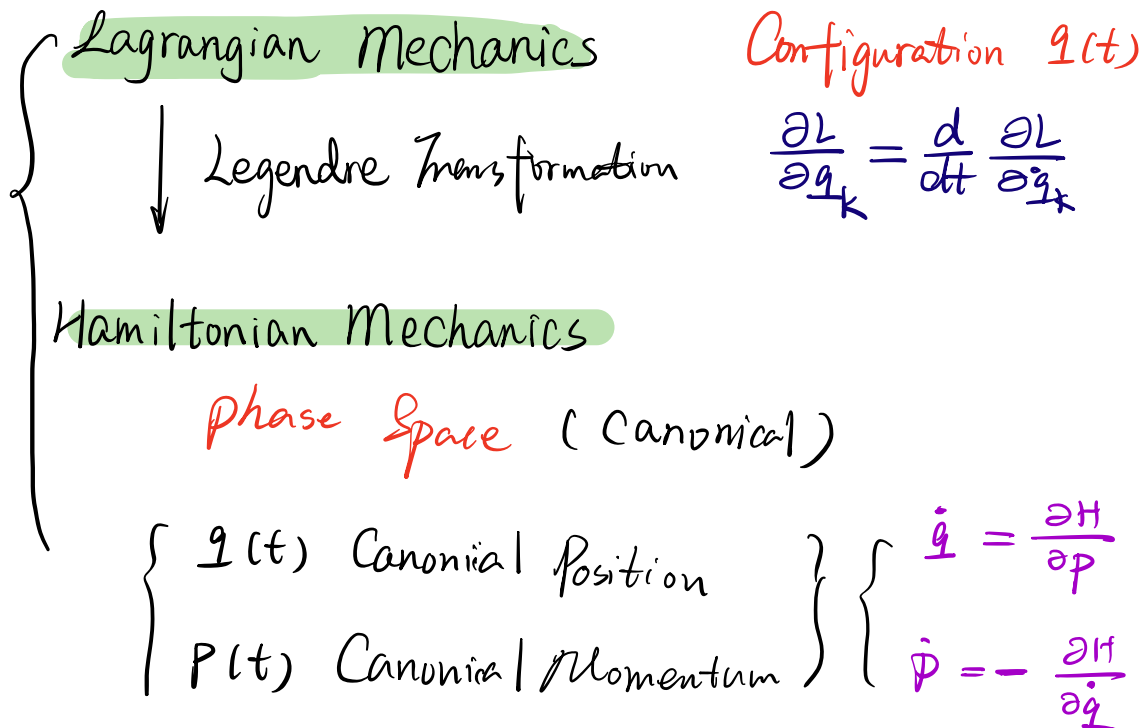
Newtonian Mechanics

Physics - Space

$$\vec{F} = m \frac{d^2 \vec{x}}{dt^2} \quad \frac{d\vec{p}}{dt} = \vec{F}$$



For holonomic Constraint (定常约束: 约束与速度无关)



For Non-holonomic Constraints (like CED)

- d'Alembert Principle

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}_i} \right) - \frac{\partial T}{\partial q_i} = Q_i$$

T : Kinetic Energy Q_i : Generalize Force

Generalized Coordinate

$$q_k(t) \quad k=1, 2, \dots, D$$

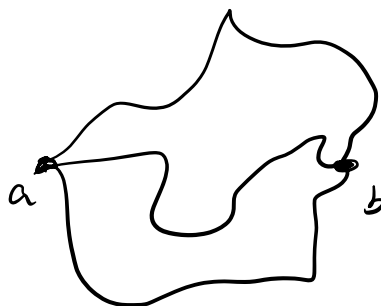
$$L[q] = L(q(t), \dot{q}(t); t) \quad \text{Lagrangian}$$

$$S = \int_{t_1}^{t_2} L(q(t), \dot{q}(t); t) dt \quad \text{Action}$$

Principle of Least Action :

$$\delta S = 0$$

Euler-Lagrange Eq.



$$\left[\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_k} \right) = \frac{\partial L}{\partial q_k} \right] \quad k=1, 2, \dots, D$$

$$\begin{aligned} \text{[Proof]} \quad \delta S &= \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q_k} \delta q_k + \frac{\partial L}{\partial \dot{q}_k} \delta \dot{q}_k \right) dt \\ &= \int_{t_1}^{t_2} \left\{ \frac{\partial L}{\partial q_k} \delta q_k + \frac{d}{dt} \left[\frac{\partial L}{\partial \dot{q}_k} \delta q_k \right] - \left[\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_k} \right) \right] \delta q_k \right\} dt \\ &= \cancel{\frac{\partial L}{\partial \dot{q}_k} \delta q_k} \Big|_{t_1}^{t_2} + \int_{t_1}^{t_2} \left[\frac{\partial L}{\partial q_k} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_k} \right) \right] \delta q_k dt \\ &\equiv 0 \end{aligned}$$

$$\Leftrightarrow \frac{\partial L}{\partial q_k} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_k} \right) \equiv 0$$

Hamiltonian

$$H = \sum p_i \dot{q}_i - L$$

$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

$$dH = \frac{\partial H}{\partial t} dt + \sum_i \left(\frac{\partial H}{\partial q_i} dq_i + \frac{\partial H}{\partial p_i} dp_i \right) \quad \begin{matrix} p_i dq_i \\ // \\ p_i d\dot{q}_i \end{matrix}$$

$$\begin{aligned} dH &= \sum_i \left((dp_i) \dot{q}_i + (dq_i) p_i \right) - \sum_i \left(\frac{\partial L}{\partial p_i} dp_i + \frac{\partial L}{\partial \dot{q}_i} d\dot{q}_i \right) - \frac{\partial L}{\partial t} dt \\ &= \sum_i \left(\dot{q}_i dp_i - \dot{p}_i dq_i \right) - \frac{\partial L}{\partial t} dt \end{aligned}$$

$$\Rightarrow \begin{cases} \frac{\partial H}{\partial t} = - \frac{\partial L}{\partial t} \\ \frac{\partial H}{\partial q_i} = - \dot{p}_i \\ \frac{\partial H}{\partial p_i} = \dot{q}_i \end{cases}$$

$$f(p, q, t)$$

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \sum \left(\frac{\partial f}{\partial q} \dot{q} + \frac{\partial f}{\partial p} \dot{p} \right)$$

$$= \frac{\partial f}{\partial t} + \sum \left(\frac{\partial f}{\partial q} \cdot \frac{\partial H}{\partial p} - \frac{\partial f}{\partial p} \frac{\partial H}{\partial q} \right)$$

$$= \frac{\partial f}{\partial t} + [f, H]_{PB}$$

CCC

Classical Canonical Commutator

While for any observable:

$$\frac{d\hat{A}}{dt} = \frac{\partial \hat{A}}{\partial t} + \frac{1}{i\hbar} [A, H] \quad \text{QCC}$$

Fundamental CCC

$$\begin{cases} [q_i, p_j]_{PB} = \delta_{ij} \\ [q_i, q_j]_{PB} = [p_i, p_j]_{PB} = 0 \end{cases}$$

Angular Momentum:

$$\vec{L} = \vec{x} \times \vec{p}$$

$$L_i = (\vec{x} \times \vec{p})_i = \epsilon_{ijk} x_j p_k$$

$$\begin{cases} [L_i, L_j]_{PB} = \epsilon_{ijk} L_k \\ \Downarrow \\ [L_i, L^2]_{PB} = 0 \end{cases}$$

Leibniz:

$$[A, BC]_{PB} = [A, B]_{PB} C + B [A, C]_{PB}$$

$$[AB, C]_{PB} = [A, C]_{PB} B + A [B, C]_{PB}$$

Jacobi $[]$ mean PB

$$[A, [B, C]] + [B, [C, A]] + [C, [A, B]] \equiv 0$$

Differentiate

$$[A, B^n]_{PB} = n [A, B]_{PB} B^{n-1} \quad \text{if } [B, [A, B]] = 0$$

d'Alembert Principle (Non-holonomic) 非定常约束

If $U = f(q, \dot{q}, t)$ \rightarrow 约束与广义速度有关

$$L = T - U \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = \frac{\partial L}{\partial q}$$

$$Q_i = \begin{cases} \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}} \right) - \frac{\partial T}{\partial q} \\ \frac{d}{dt} \left(\frac{\partial U}{\partial \dot{q}} \right) - \frac{\partial U}{\partial q} \end{cases}$$

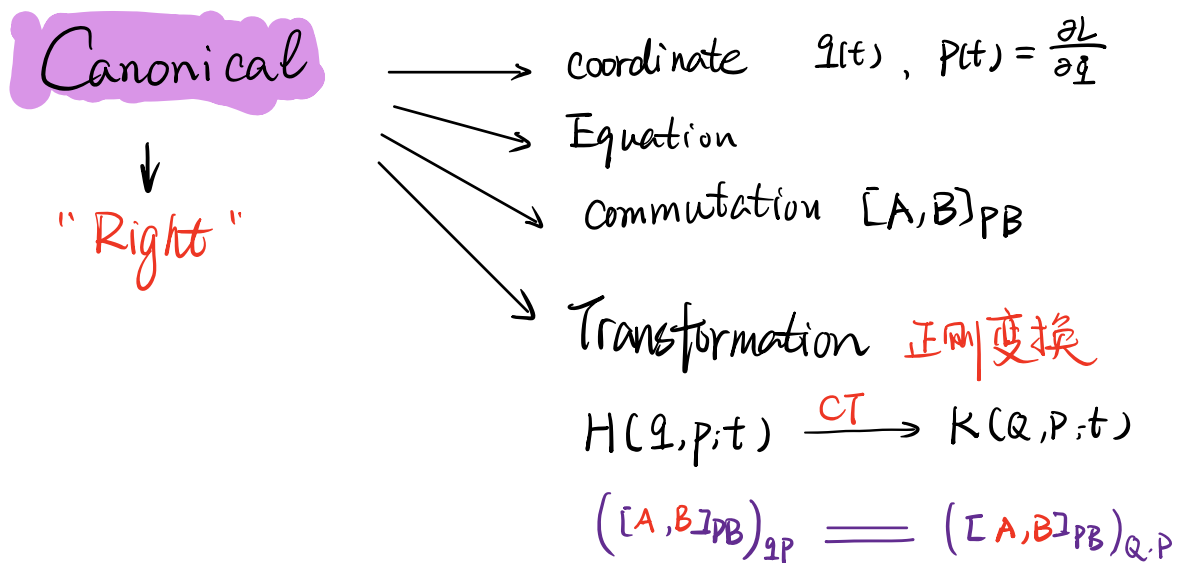
(广义力)

$$\vec{F} = q \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$$

Legendra transformation

$$f(x) \xrightarrow{p=f'(x)} g(p) = f(x) - x f'(x)$$

$$\text{If } \left| \frac{\partial^2 L}{\partial \dot{q}_i \partial \dot{q}_j} \right| \neq 0 \Rightarrow \begin{aligned} L &= T - V \\ H &= T + V \end{aligned}$$



Canonical transformation

$$\begin{aligned} \delta \int L(q, \dot{q}; t) dt &= \delta \int \sum_a p_a \dot{q}_a - H(p, q; t) dt \\ &= \delta \int \sum_a p_a \dot{Q}_a - K(p, Q; t) dt + dG \end{aligned}$$

$$\Rightarrow dG = \left(\sum_a p_a d\dot{q}_a - H(p, q; t) dt \right) - \left(\sum_a p_a d\dot{Q}_a - K(p, Q; t) dt \right)$$

↓
Generator function $G(\underline{q}, \underline{p}; \underline{Q}, \underline{P})$ 4个中2个是独立的

$$= \frac{\partial G}{\partial t} dt + \sum_a \left(\frac{\partial G}{\partial q_a} dq_a + \frac{\partial G}{\partial Q_a} dQ_a \right)$$

dt-term: $K = H + \frac{\partial G}{\partial t}$

dq_a -term: $p_a = \frac{\partial G}{\partial q_a}$ dQ_a -term: $P_a = -\frac{\partial G}{\partial Q_a}$

$$\Rightarrow \frac{\partial P_a}{\partial Q_b} = \frac{\partial^2 G}{\partial Q_b \partial q_a} \quad \frac{\partial P_a}{\partial q_b} = - \frac{\partial^2 G}{\partial q_b \partial Q_a}$$

$$\Rightarrow \left[\frac{\partial P_a}{\partial Q_b} + \frac{\partial P_b}{\partial q_a} = 0 \right] \quad \text{If } G_{,q_b Q_a} = G_{Q_a q_b}$$

\Downarrow

$$\left[([A, B]_{PB})_{P, q} = ([A, B])_{IP, Q} \right]$$

Let $K \equiv 0$, $Q = q_0$

Dynamics on Phase Space

$\rho(q, p; t)$ Density Distribution

$$\int \rho(q, p; t) d^D q d^D p = 1$$

① Liouville's Theorem: $\frac{d\rho}{dt} \equiv 0 \Rightarrow \frac{\partial \rho}{\partial t} = [\hat{H}, \rho]_{PB}$

↓ Liouville's Eq.

$$\left| \frac{\partial \hat{\rho}}{\partial t} = \frac{1}{i\hbar} [\hat{H}, \hat{\rho}] \right|$$

Valid for closed system

and Both pure and mixed State

If $\hat{\rho} = |\psi\rangle\langle\psi|$ (Pure State)

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle\langle\psi| = \hat{H}|\psi\rangle\langle\psi| - |\psi\rangle\langle\psi|\hat{H}$$

$$(i\hbar \frac{\partial}{\partial t} |\psi\rangle)\langle\psi| + |\psi\rangle i\hbar \frac{\partial}{\partial t} \langle\psi| = \hat{H}|\psi\rangle\langle\psi| - |\psi\rangle\langle\psi|\hat{H}$$

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle + |\psi\rangle (i\hbar \frac{\partial}{\partial t} \langle\psi|) |\psi\rangle = \hat{H}|\psi\rangle - |\psi\rangle\langle\psi|\hat{H}|\psi\rangle$$

$$\langle\psi| (i\hbar \frac{\partial}{\partial t} |\psi\rangle - \hat{H}|\psi\rangle) = (-i\hbar \frac{\partial}{\partial t} \langle\psi| + \langle\psi|\hat{H}) |\psi\rangle = 0$$

↪ Schrodinger !!

② Continue Eq. $\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} \equiv 0 \Rightarrow \text{Liouville}$

In phase space, $\vec{j} = (\rho \dot{q}, \rho \dot{p})$

$$\nabla \cdot \vec{j} = \sum_a \frac{\partial}{\partial q_a} (\rho \dot{q}_a) + \frac{\partial}{\partial p_a} (\rho \dot{p}_a)$$

$$= \sum_a \left[\frac{\partial \rho}{\partial q_a} \dot{q}_a + \cancel{\rho \frac{\partial \dot{q}_a}{\partial q_a}} + \frac{\partial \rho}{\partial p_a} \dot{p}_a + \cancel{\rho \frac{\partial \dot{p}_a}{\partial p_a}} \right]$$

$$= \sum_a \frac{\partial \rho}{\partial q_a} \frac{\partial H}{\partial p_a} - \frac{\partial \rho}{\partial p_a} \frac{\partial H}{\partial q_a} = [\rho, H]_{PB}$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = \frac{\partial \rho}{\partial t} + [\rho, H]_{PB} \Rightarrow \text{Liouville}$$

