

Using numerical models to design the future of the Arctic observing system

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A comprehensive framework for verification, validation, and uncertainty quantification in scientific computing

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uncertainty are discussed: aleatory and epistemic uncertainty. Then the key sources of uncertainty in scientific computing are identified: model inputs, numerical approximations, and model form uncertainty. A comprehensive framework for treating all sources of uncertainty in scientific computing is then described. The framework includes the identification of all sources of uncertainty, characterization of input uncertainties, elimination of uncertainties in the system response quantities, propagation of model form uncertainty, and estimation of model form uncertainty due to extrapolation to application conditions of interest. This paper concludes with a discussion of the paradigm shift from deterministic to nondeterministic simulations and the impact of this shift on the decision-making process.

II. Types of Uncertainty

While there are many different ways to classify uncertainty, we will use the taxonomy prevalent in the risk assessment community which categorizes uncertainties according to their fundamental essence [2-5]. Thus, uncertainty is classified as either a) *aleatory* - the inherent variation in a quantity that, given sufficient samples of the stochastic process, can be characterized via a probability distribution, or b) *epistemic* - where there is insufficient information concerning the quantity of interest to specify either a fixed value or a precisely known probability distribution. In scientific computing, there are many sources of uncertainty including the model inputs, the form of the model, and poorly-characterized numerical approximation errors. All of these sources of uncertainty can be classified as either purely aleatory, purely epistemic, or a mixture of aleatory and epistemic uncertainty.

A. Aleatory Uncertainty

Aleatory uncertainty (also called irreducible uncertainty, stochastic uncertainty, or variability) is uncertainty due to inherent variation or randomness and can occur among members of a population or due to spatial or temporal variations. Aleatory uncertainty is generally characterized by a probability density at any value over the range of the probability density function (PDF) - which quantifies the probability that a random variable will be less than or equal to a certain value (see Figure 1). Here we will find it more convenient to describe variable uncertainties with CDFs. An example of an aleatory uncertainty is a manufacturing process which produces parts that are nominally 0.5 meters long. Measurement of these parts will reveal that the actual length for any given part will be different than 0.5 meters. With sufficiently large number of samples, both the form of the CDF and the parameters describing the distribution of the population can be determined. The aleatory uncertainty in the manufactured part can only be changed by modifying the fabrication or quality control processes; however, for a set of processes, the uncertainty due to manufacturing is considered irreducible.

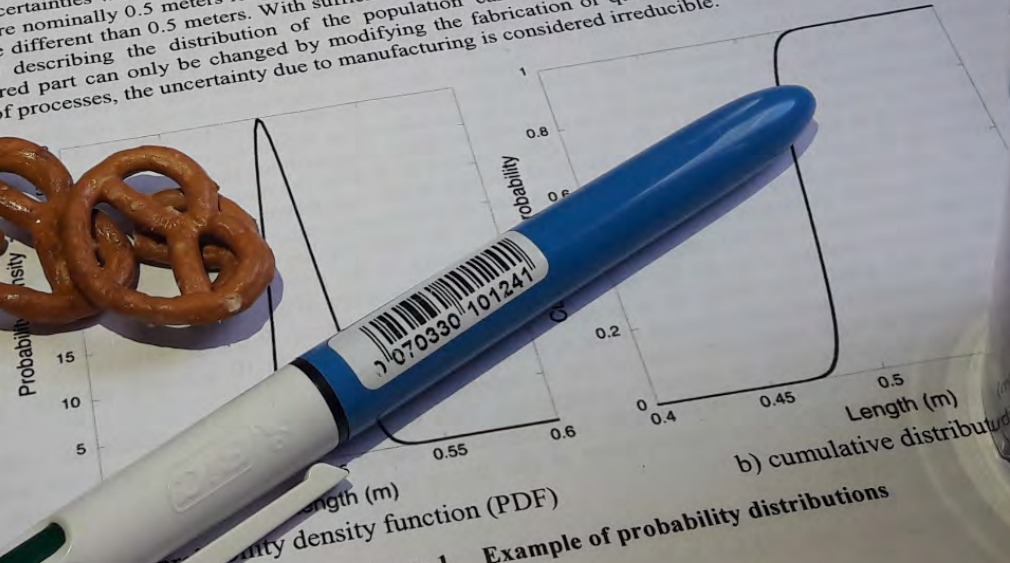
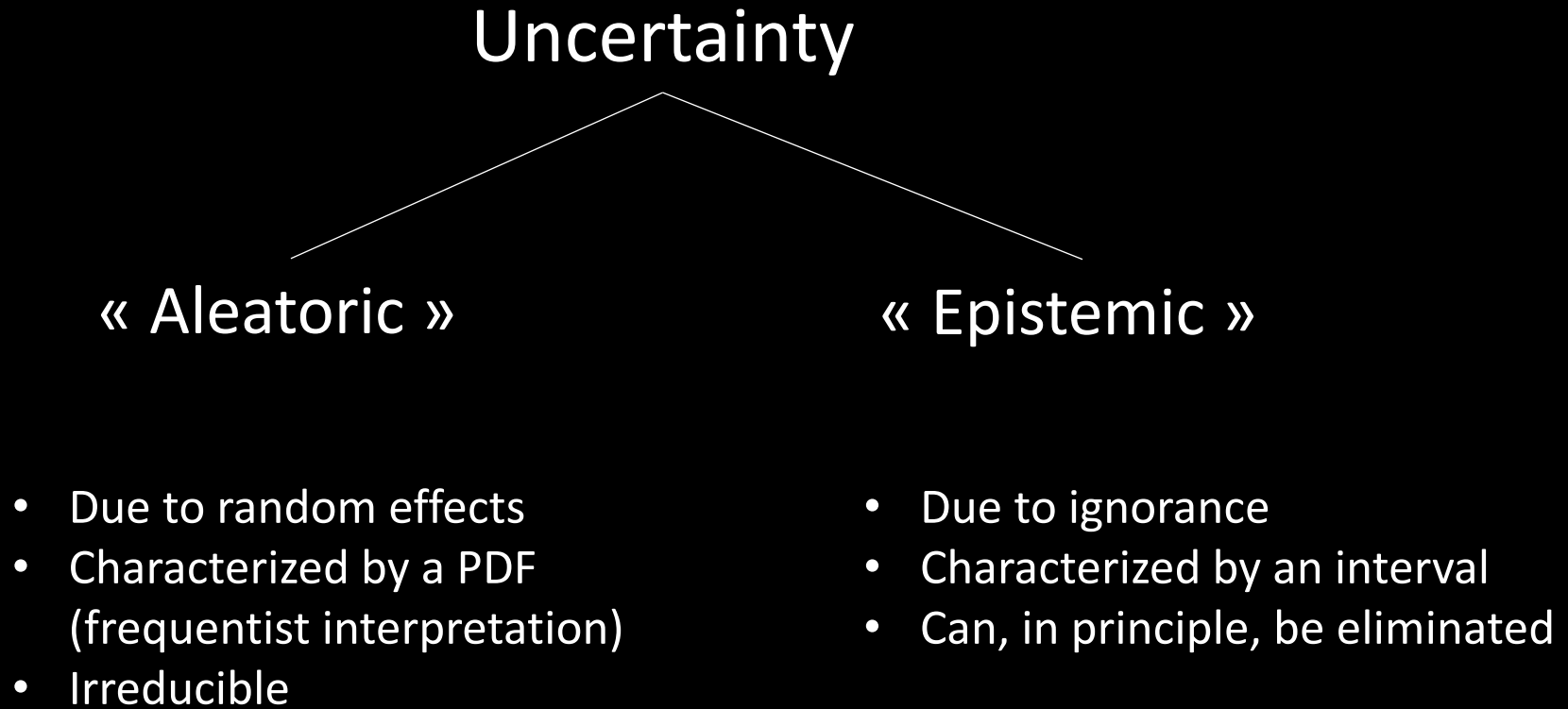


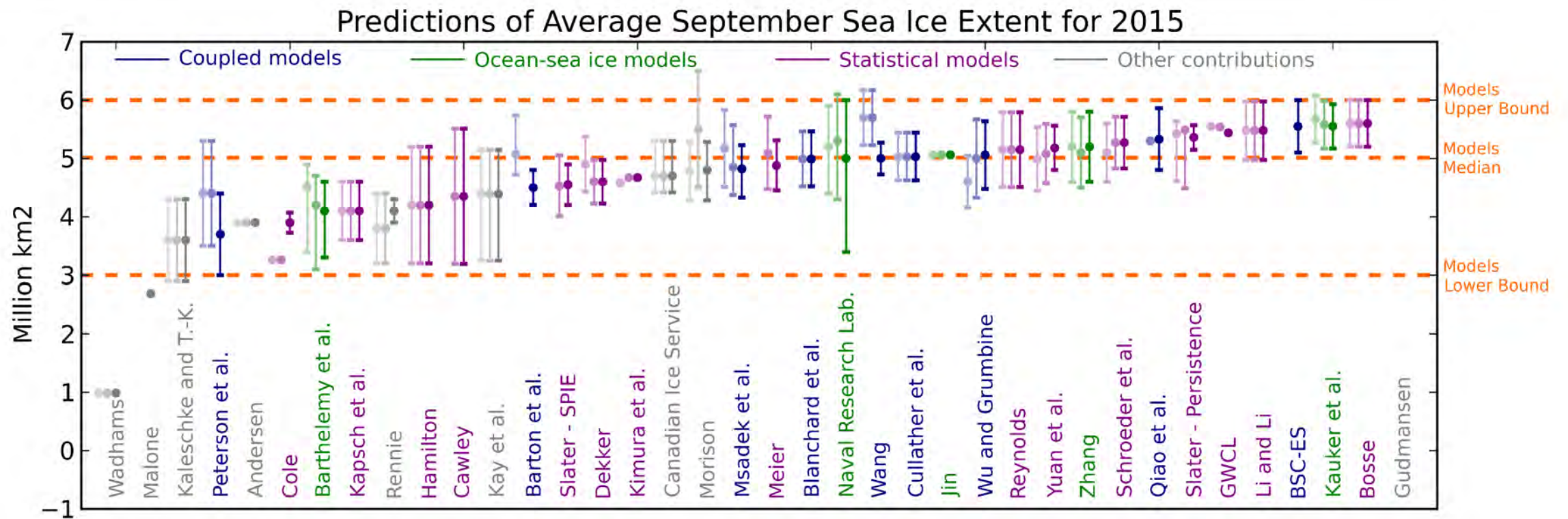
Figure 1. Example of probability distributions



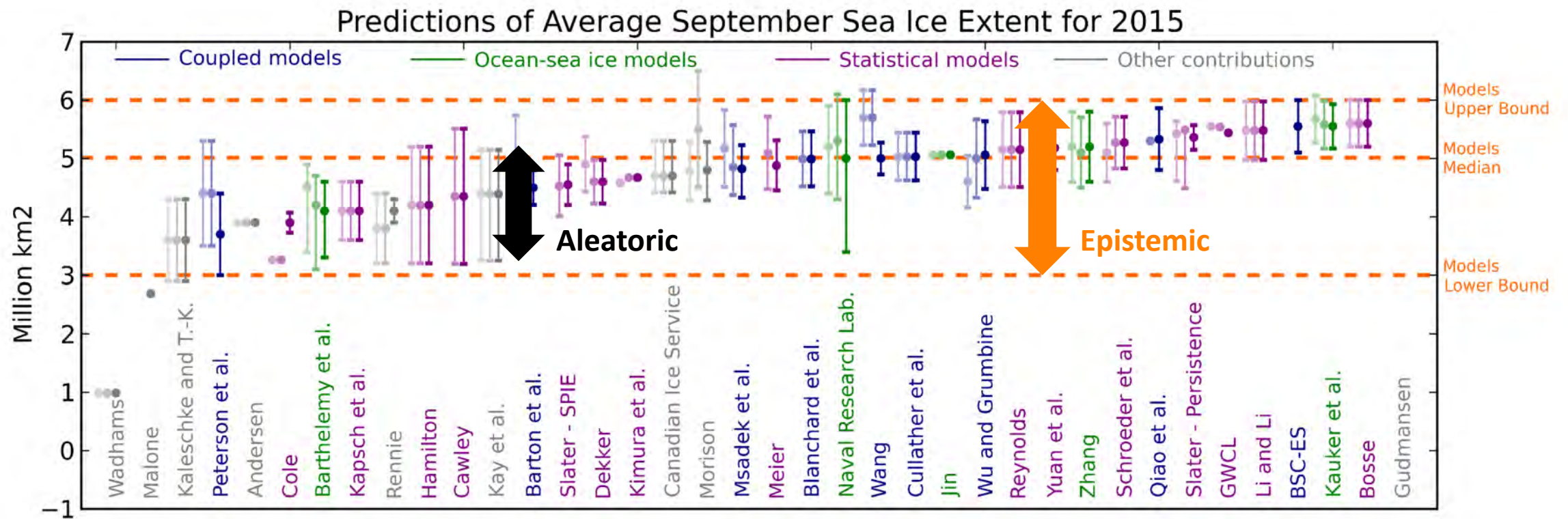
Classification of uncertainty



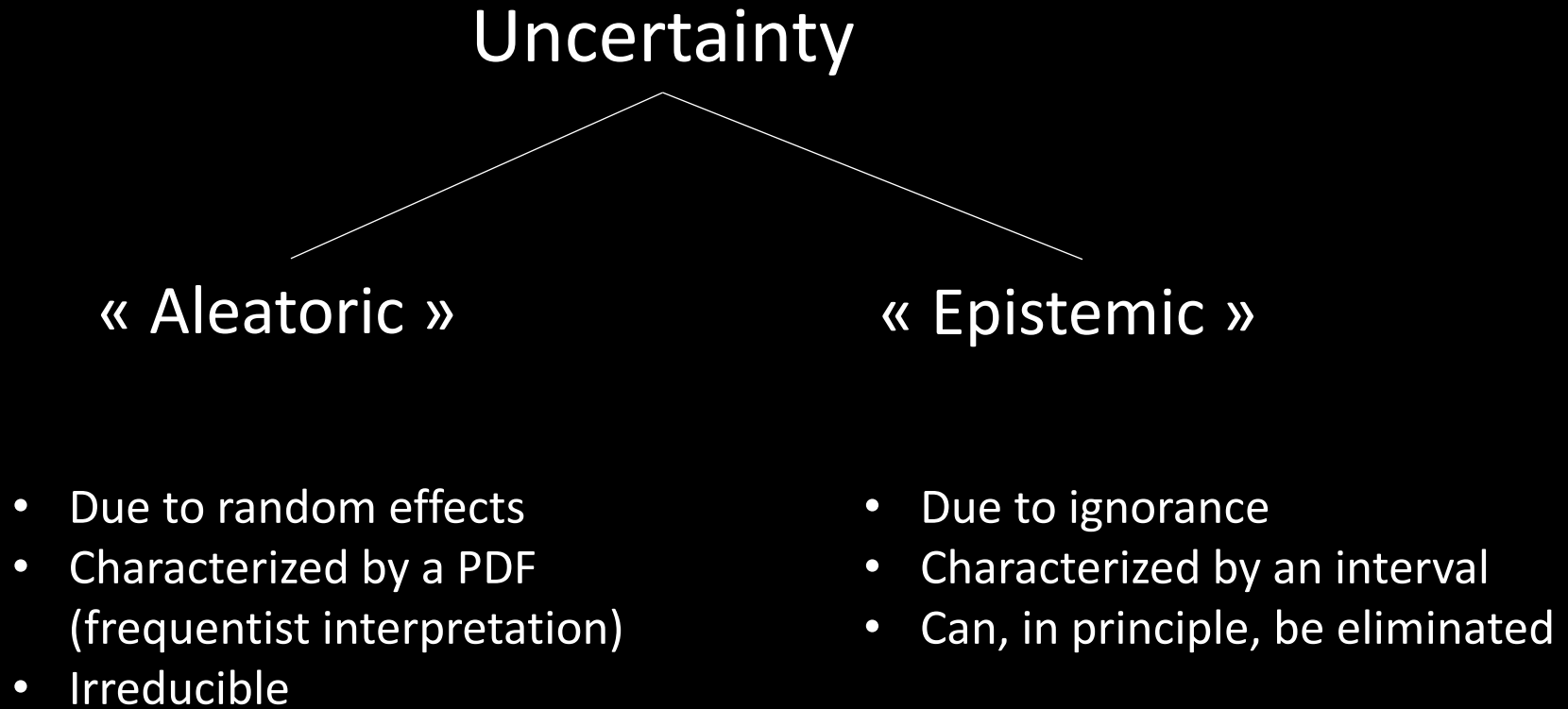
Aleatoric vs epistemic uncertainty in the Sea Ice Outlooks



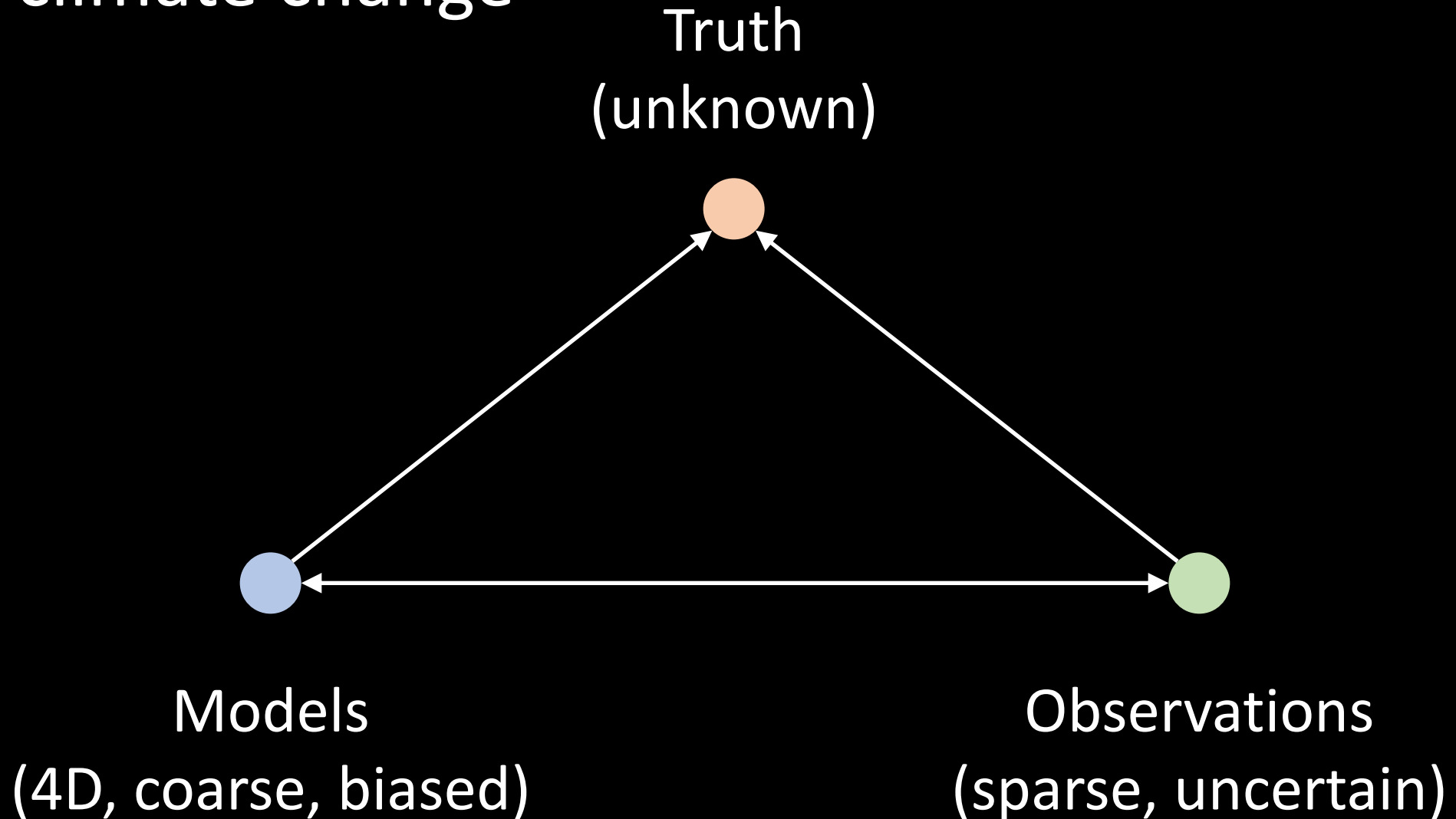
Aleatoric vs epistemic uncertainty in the Sea Ice Outlooks



Classification of uncertainty



The Trinity of understanding polar climate change



A sea ice climate change perspective on the running questions of the workshop

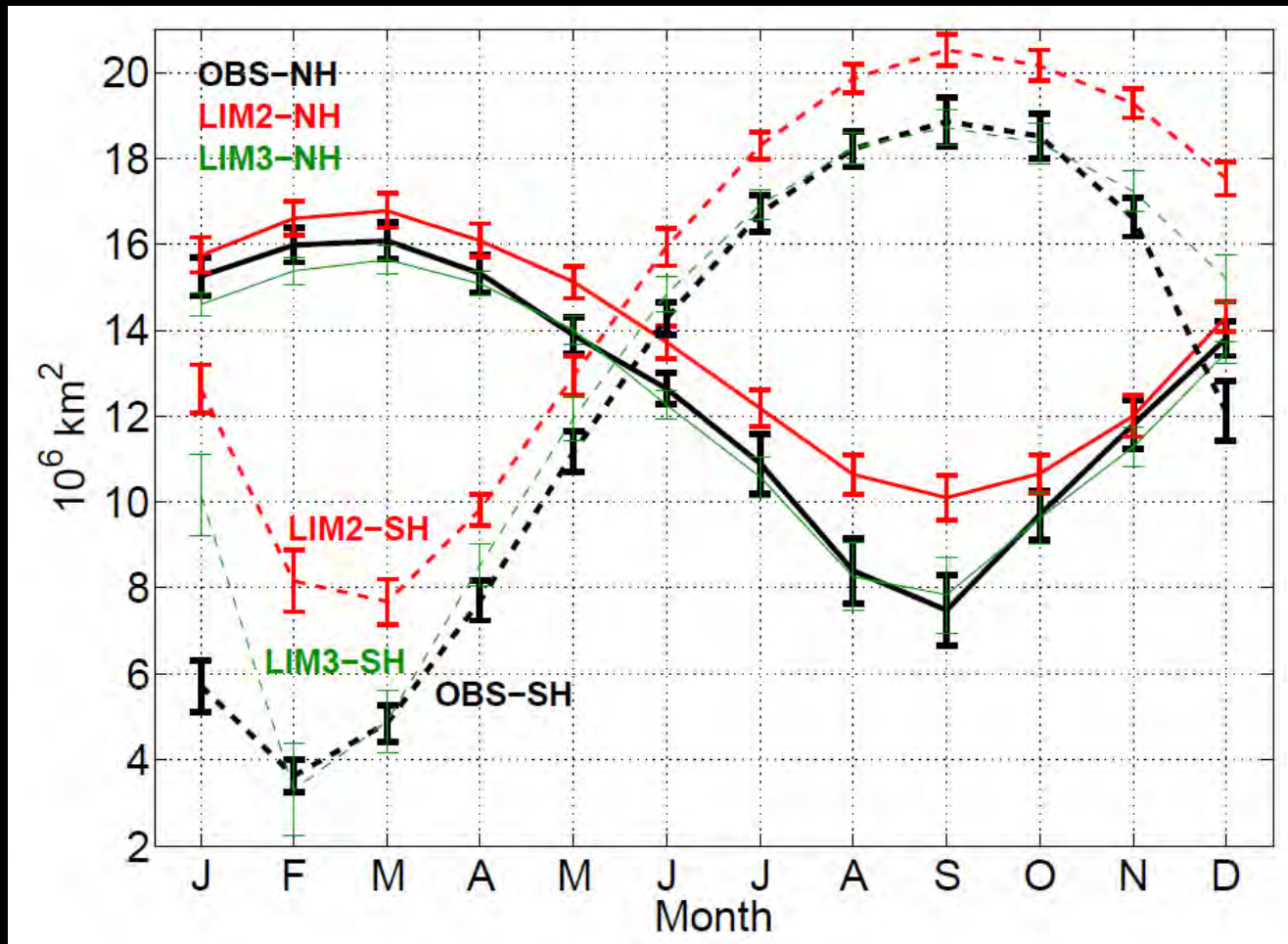
1. How should we design a climate model to obtain better predictions of polar climates on timescales of decades?
2. How can we integrate observations better with models?
3. What additional observations would help improving models?

A sea ice climate change perspective on the running questions of the workshop

- 1. How should we design a climate model to obtain better predictions of polar climates on timescales of decades?**
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Adding complexity to a sea ice model leads to improved Arctic mean sea ice state (and variability)

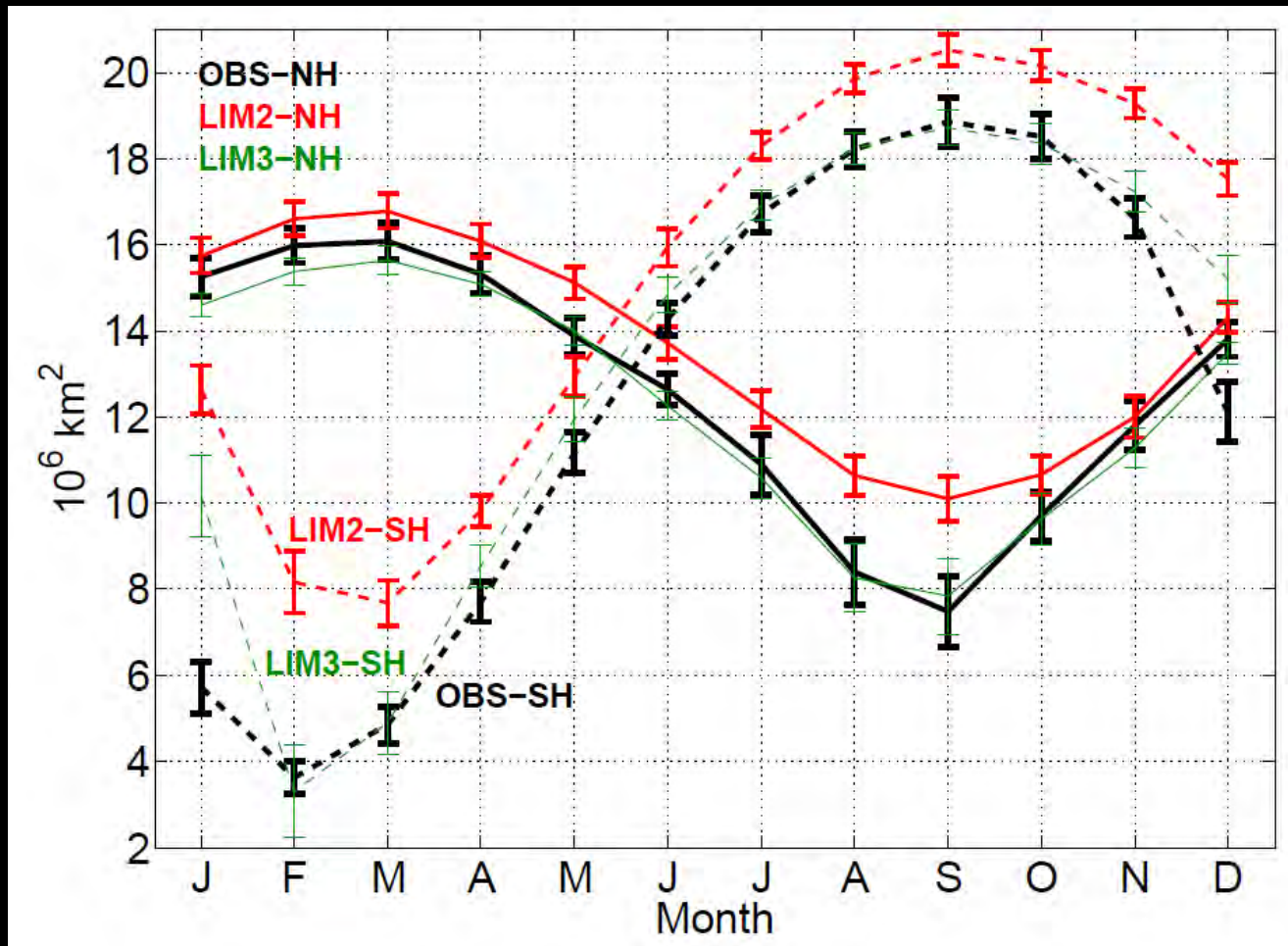
Seasonal cycles of sea ice extent (1983-2007)



tion, extent and thickness. We suggested that the inclusion of a detailed ice thickness distribution (ITD) in one of the model enhanced the interannual variability of sea ice extent, and significantly improved and reduced the simulated ice thickness in the Arctic. We also emphasized that the ex-

Adding complexity to a sea ice model leads to improved Arctic mean sea ice state (and variability)

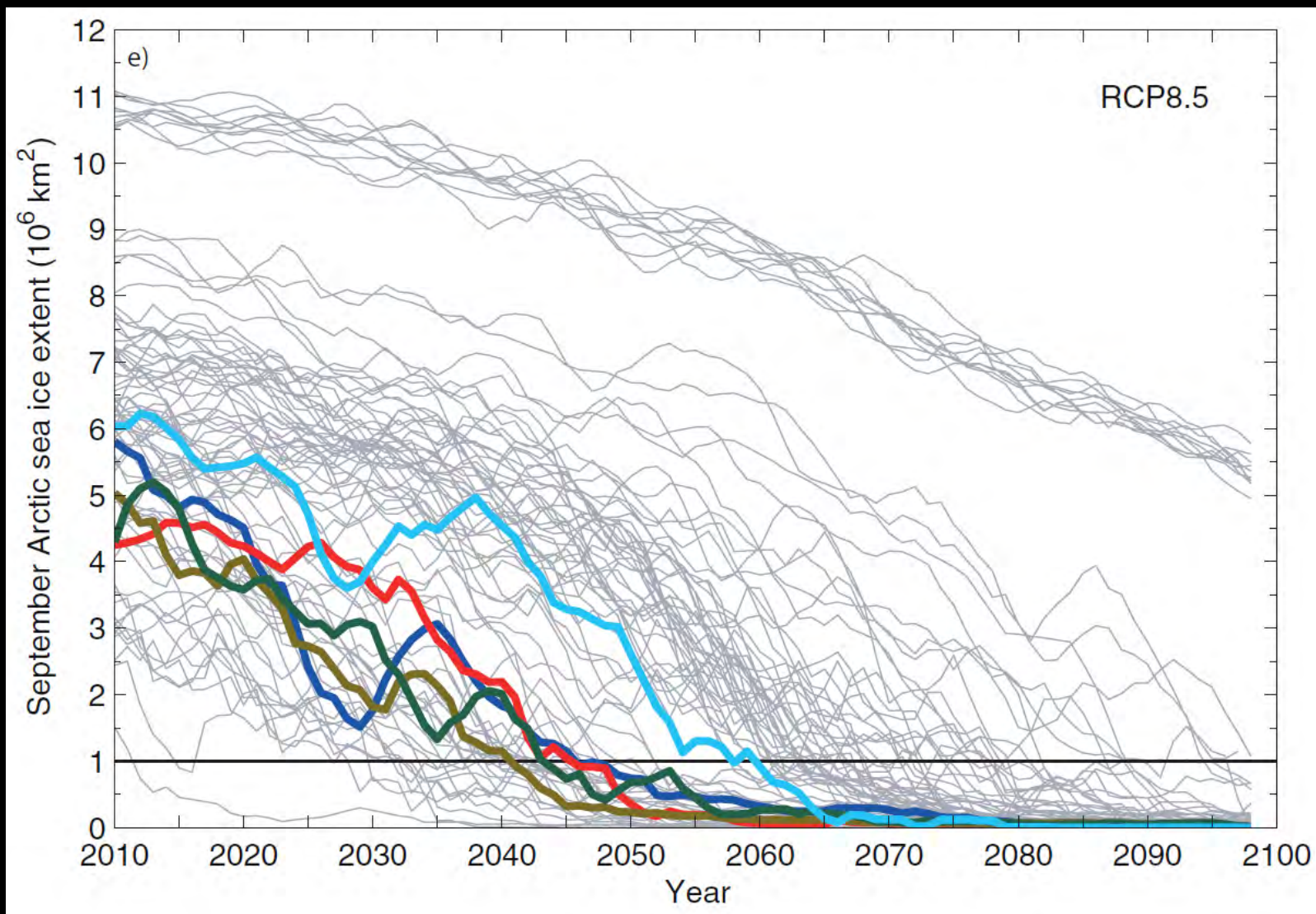
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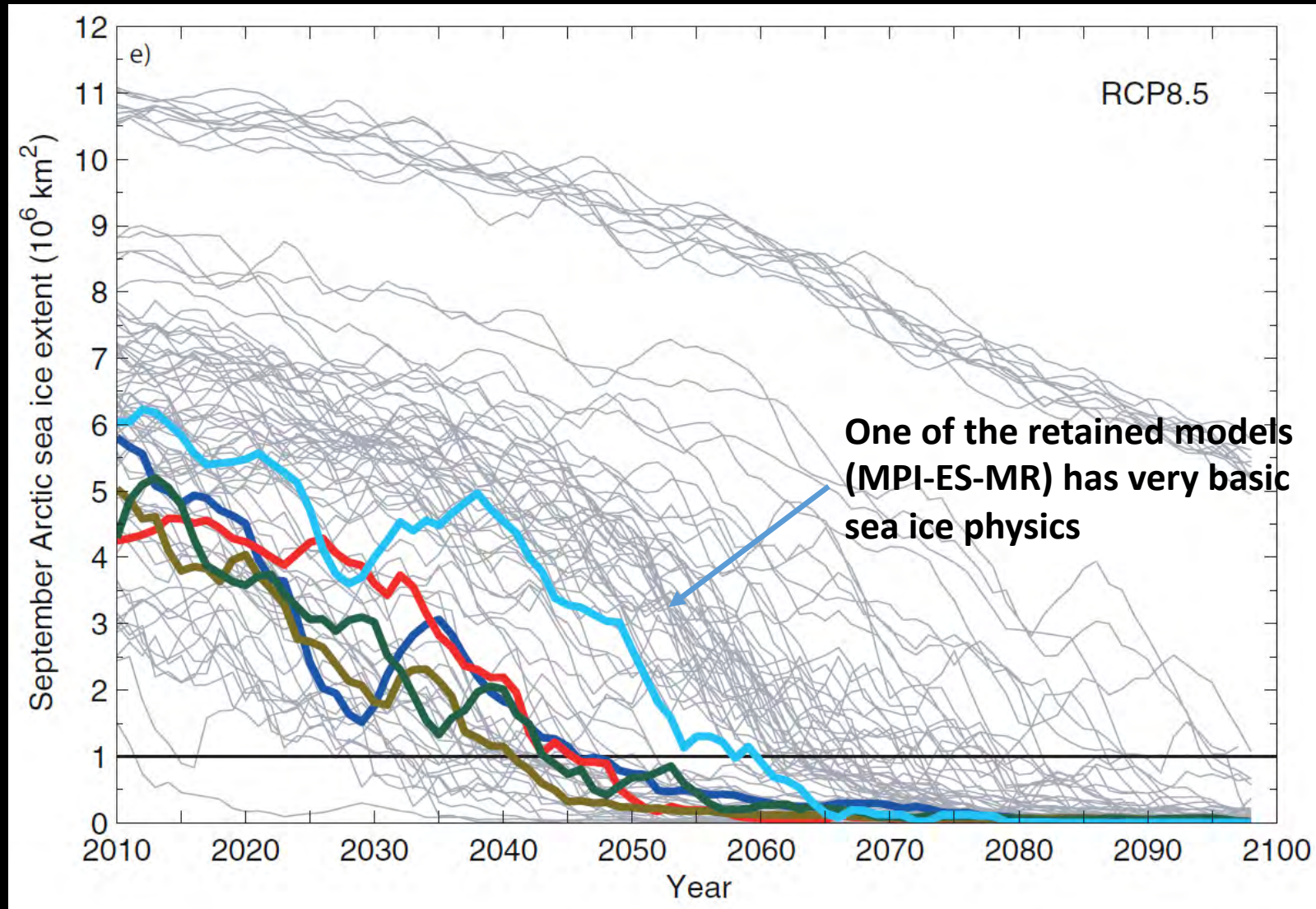
tion, extent and thickness. We suggested that the inclusion of a detailed ice thickness distribution (ITD) in one of the model enhanced the interannual variability of sea ice extent, and significantly improved and reduced the simulated ice thickness in the Arctic. We also emphasized that the ex-

This study was conducted all other things being equal (only epistemic uncertainty was estimated)

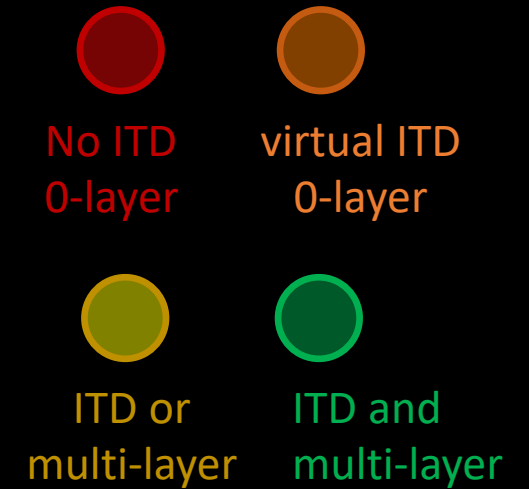
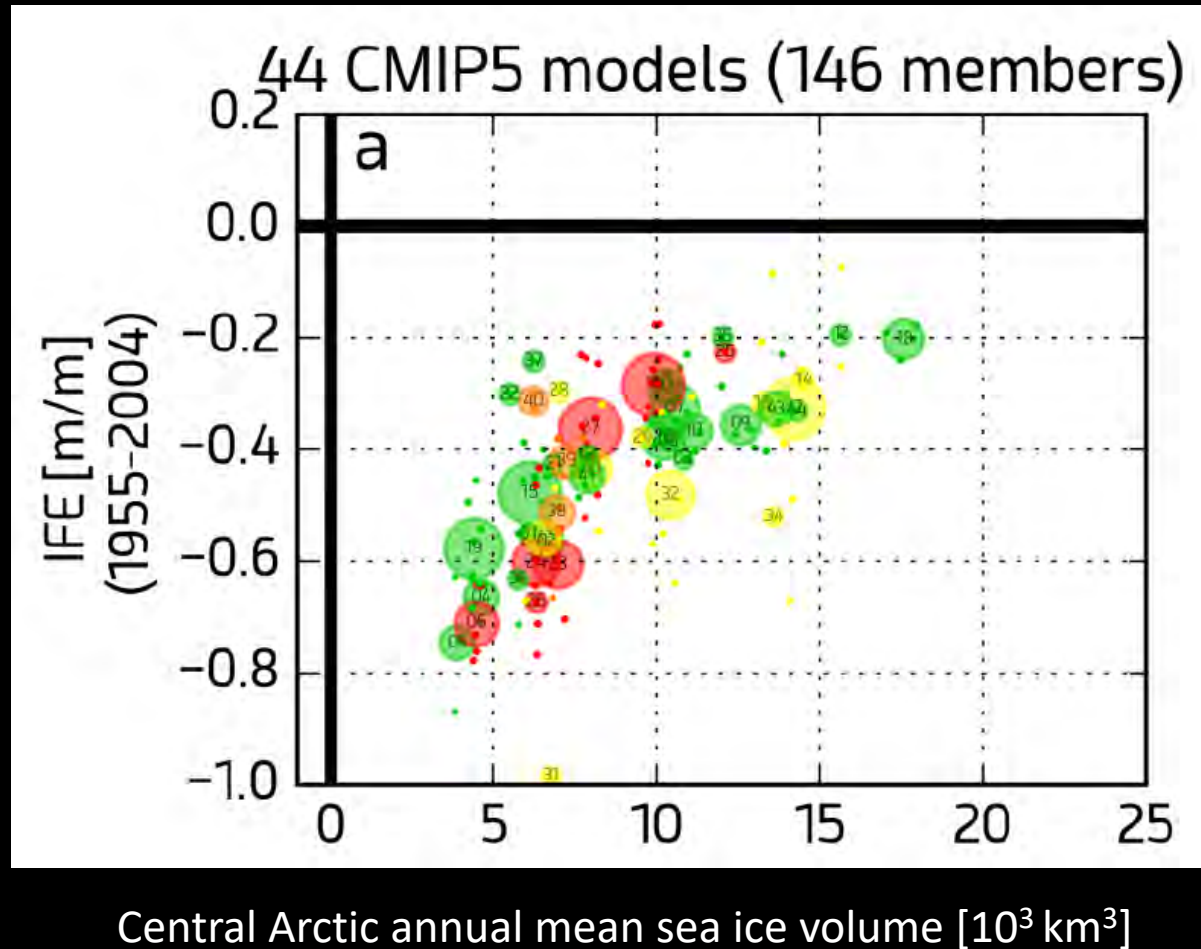
CMIP5 projections of September Arctic sea ice extent



CMIP5 projections of September Arctic sea ice extent



In CMIP5 models, sea ice model physics is not a good predictor for the sea ice mean state and feedbacks



Do we need more complex sea ice models for climate change studies?

In principle, yes:

- Adding knowledge reduces epistemic uncertainty
- Model development is essential for process understanding

In practice, not until:

- internal variability is properly quantified
- parameter tuning is documented
- the source of biases is identified

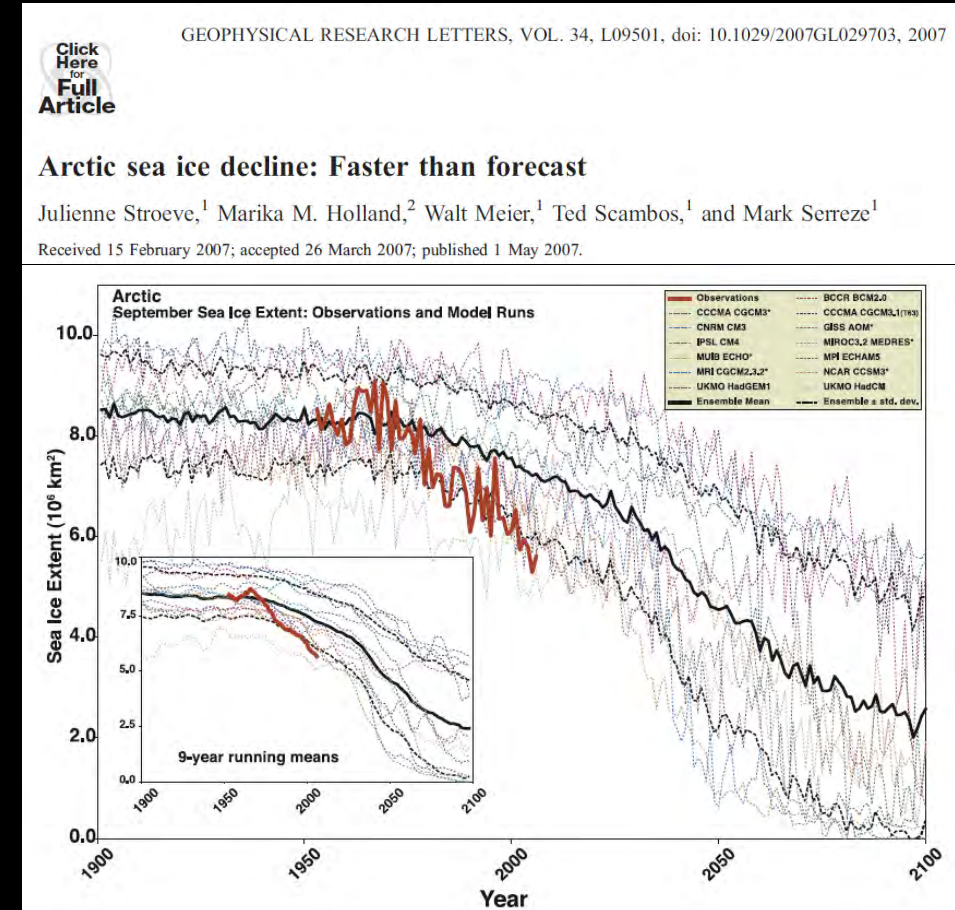
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Do we need more complex sea ice models for climate change studies?

15 DECEMBER 2016

ROSENBLUM AND EISENMAN

9179

Faster Arctic Sea Ice Retreat in CMIP5 than in CMIP3 due to Volcanoes

ERICA ROSENBLUM AND IAN EISENMAN

Scripps Institution of Oceanography, University of California, San Diego, La Jolla, California

(Manuscript received 24 May 2016, in final form 4 October 2016)

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Sea Ice Trends in Climate Models Only Accurate in Runs with Biased Global W...

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Sea Ice Trends in Climate Models Only Accurate in Runs with Biased Global Warming

Erica Rosenblum and Ian Eisenman

Scripps Institution of Oceanography, University of California, San Diego, La Jolla, California

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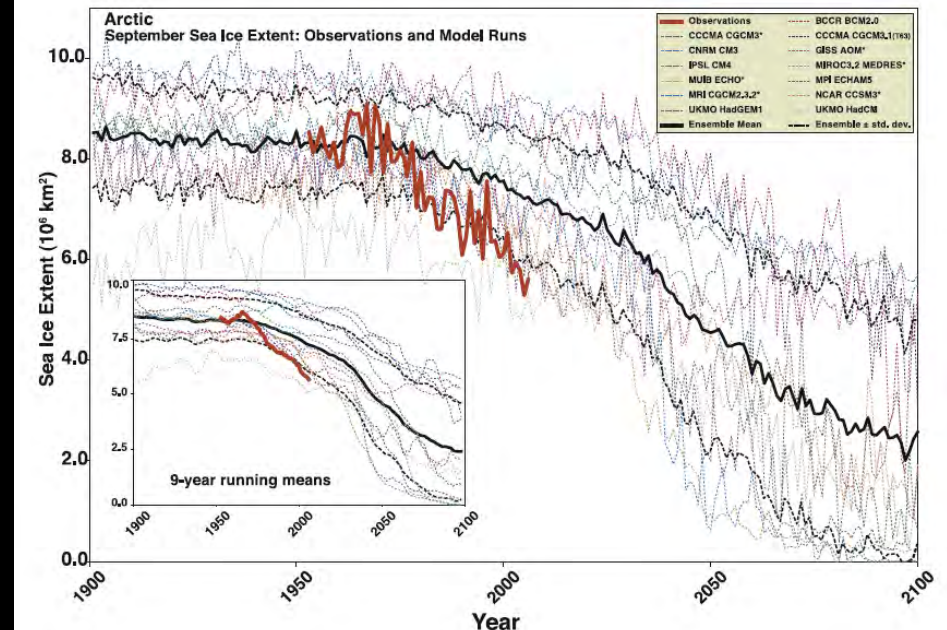
GEOPHYSICAL RESEARCH LETTERS, VOL. 34, L09501, doi: 10.1029/2007GL029703, 2007

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Arctic sea ice decline: Faster than forecast

Julienne Stroeve,¹ Marika M. Holland,² Walt Meier,¹ Ted Scambos,¹ and Mark Serreze¹

Received 15 February 2007; accepted 26 March 2007; published 1 May 2007.



Rosenblum and Eisenman, *J. Climate*, 2016, 2017; Stroeve et al., *Geophys. Res. Lett.*, 2007

1. How should we design a climate model to obtain better predictions of polar climates on timescales of decades?

- The problem is that we have too many too similar sea ice models around for IPCC-like assessments
- For climate change studies, sea ice model complexity is perhaps less important than thought: mean state matters a lot for projected mass balance
- Keep developing models, but make them modular
- The NEMO4 will have a unified yet modular sea ice model

1. How should we design a climate model to obtain better predictions of polar climates on timescales of decades?

2. How can we integrate observations better with models?

3. What additional observations would help improving models?



Model evaluation

Data assimilation

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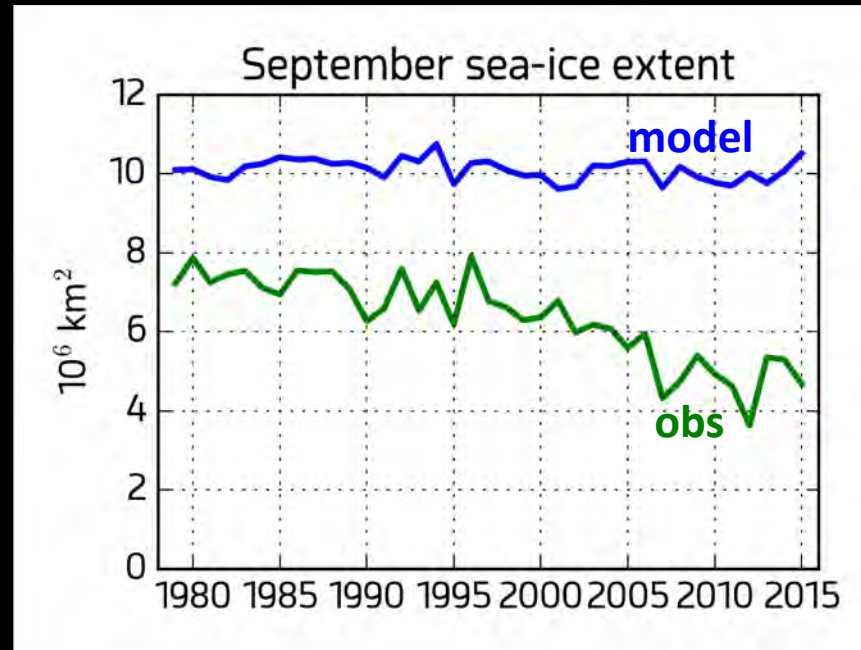
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Model evaluation

Data assimilation

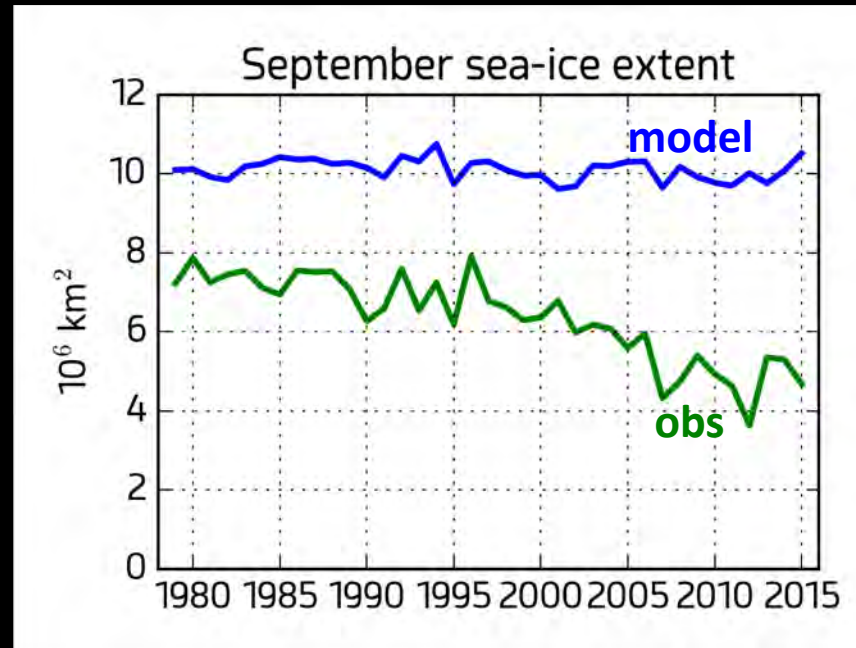
Why don't models and observations match each other?



Why don't models and observations match each other?

It's the modellers fault

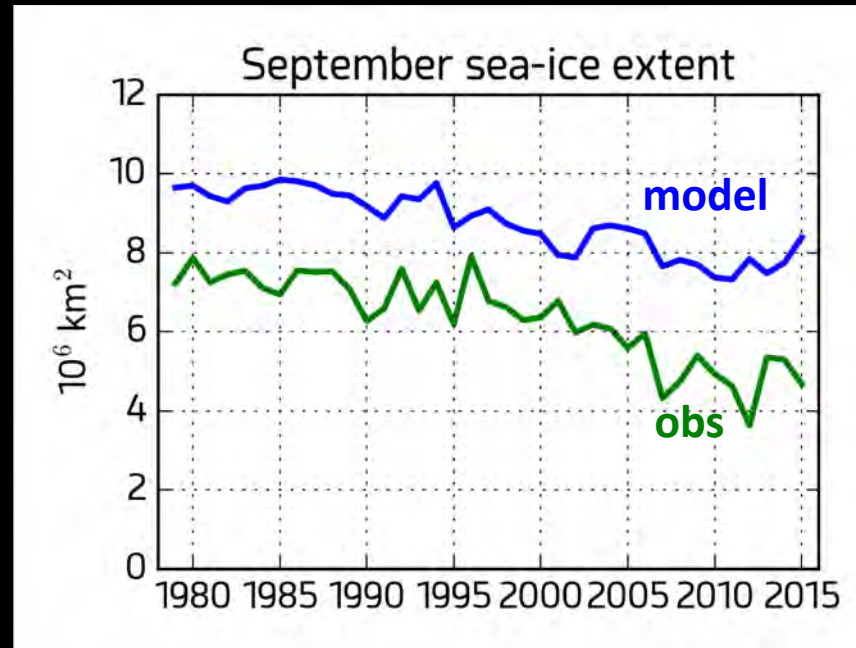
- Physical equations are wrong
- Equations are discretized
- Forcing is not correct
- Initial conditions are not correct
- Parameterizations
- HPC error



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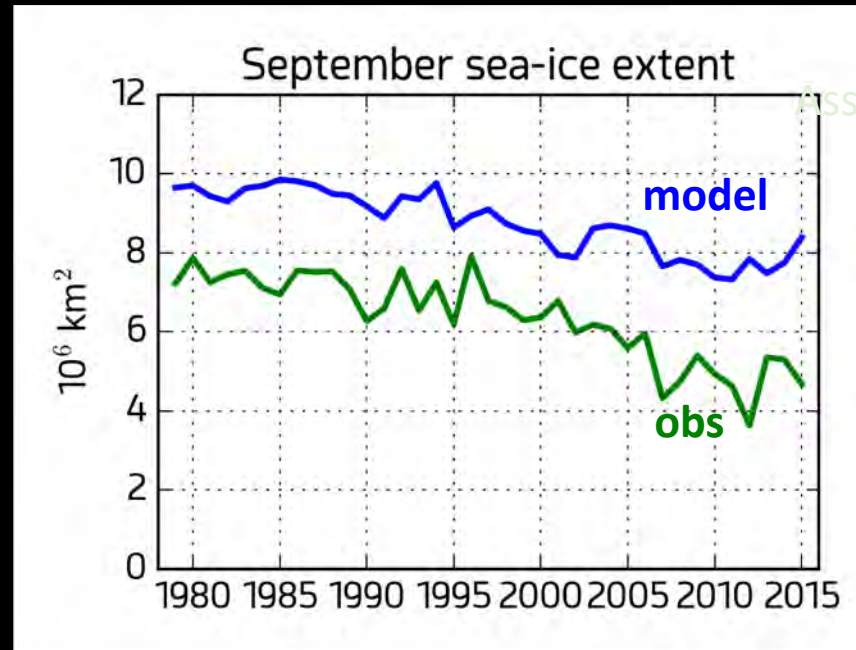
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It's the observers fault



Instrumental error

Algorithm error

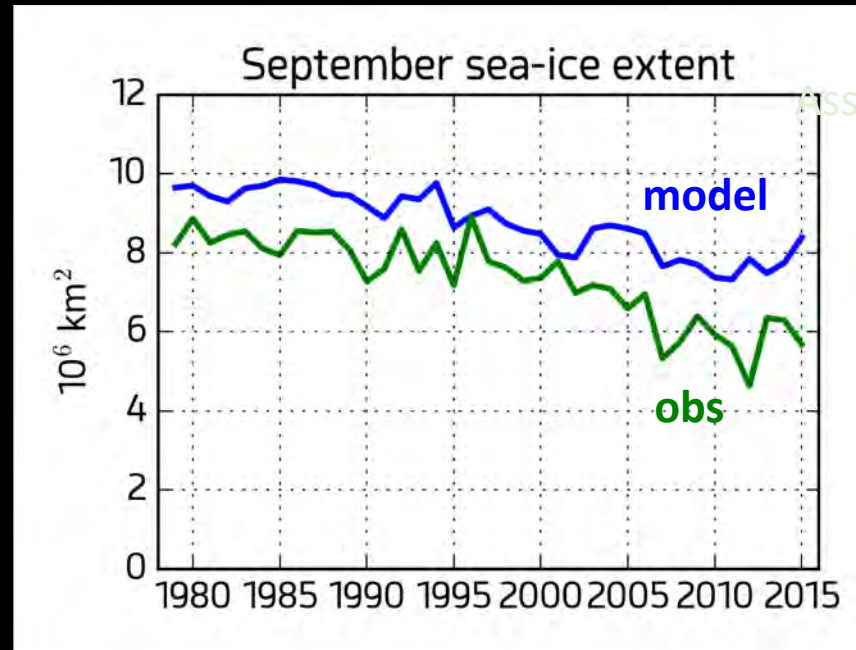
Assumptions (e.g. hydrostatic)

Sampling error

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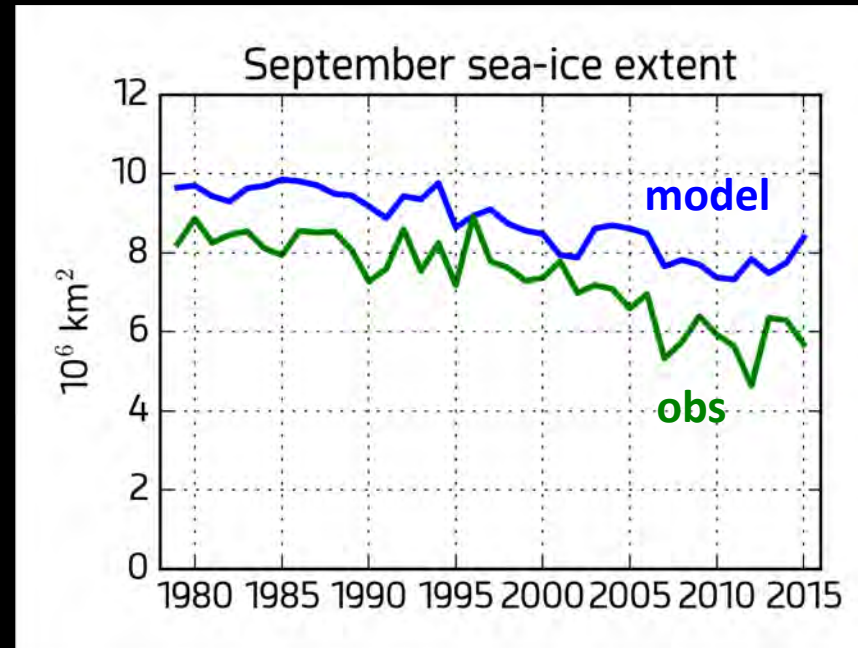
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Why don't models and observations match each other?

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It's my fault

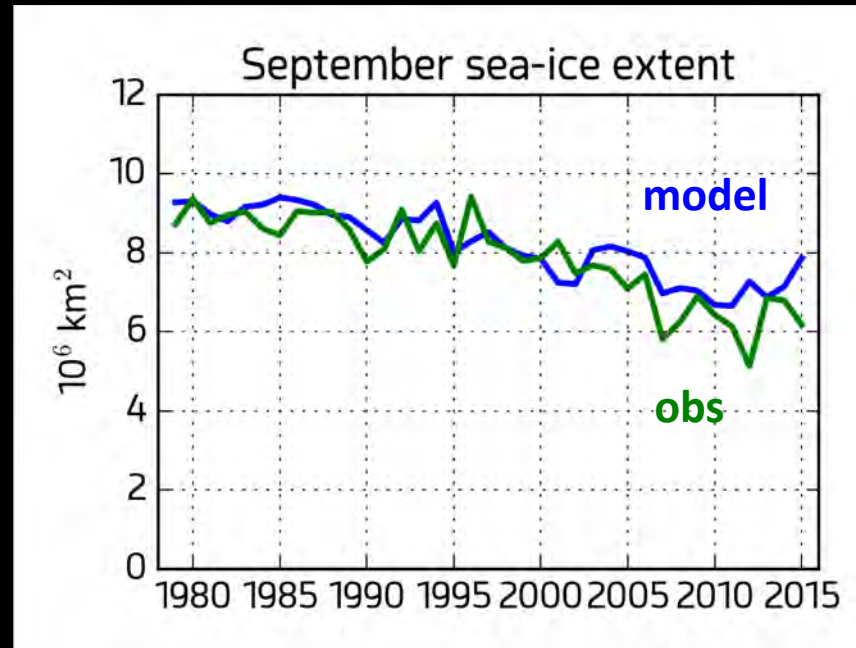
No scale-awareness

No definition-awareness

Why don't models and observations match each other?

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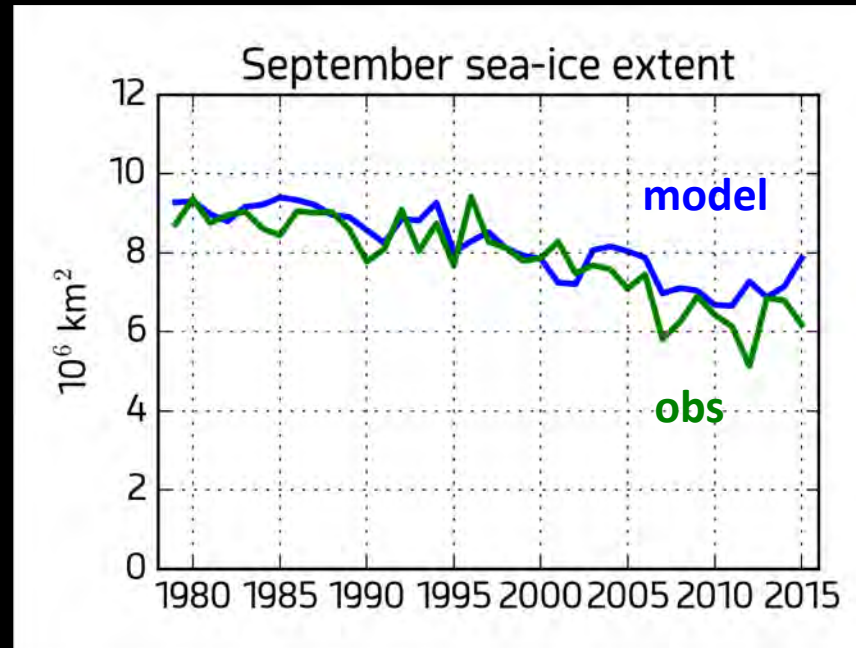
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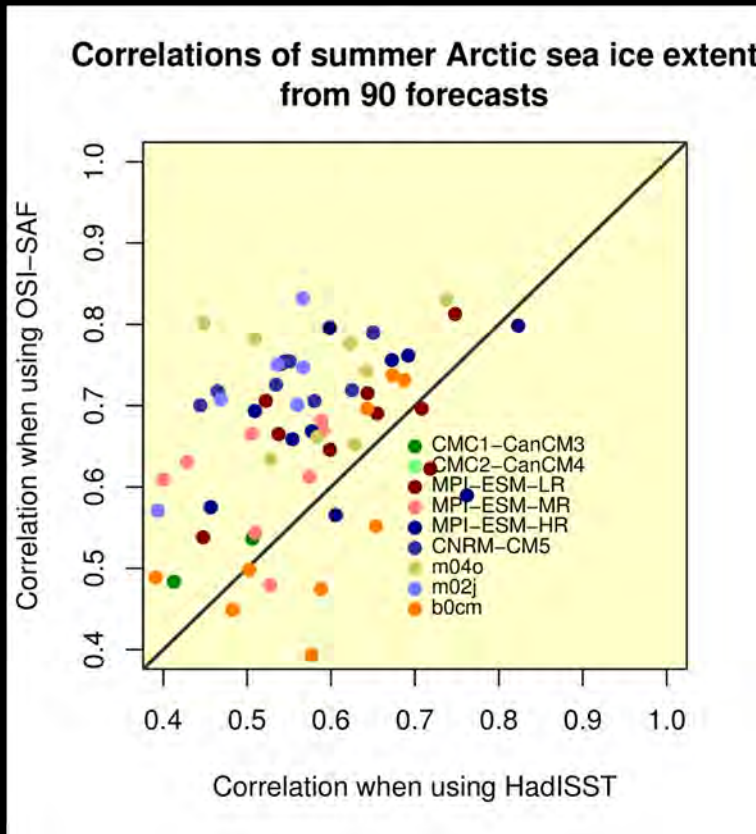
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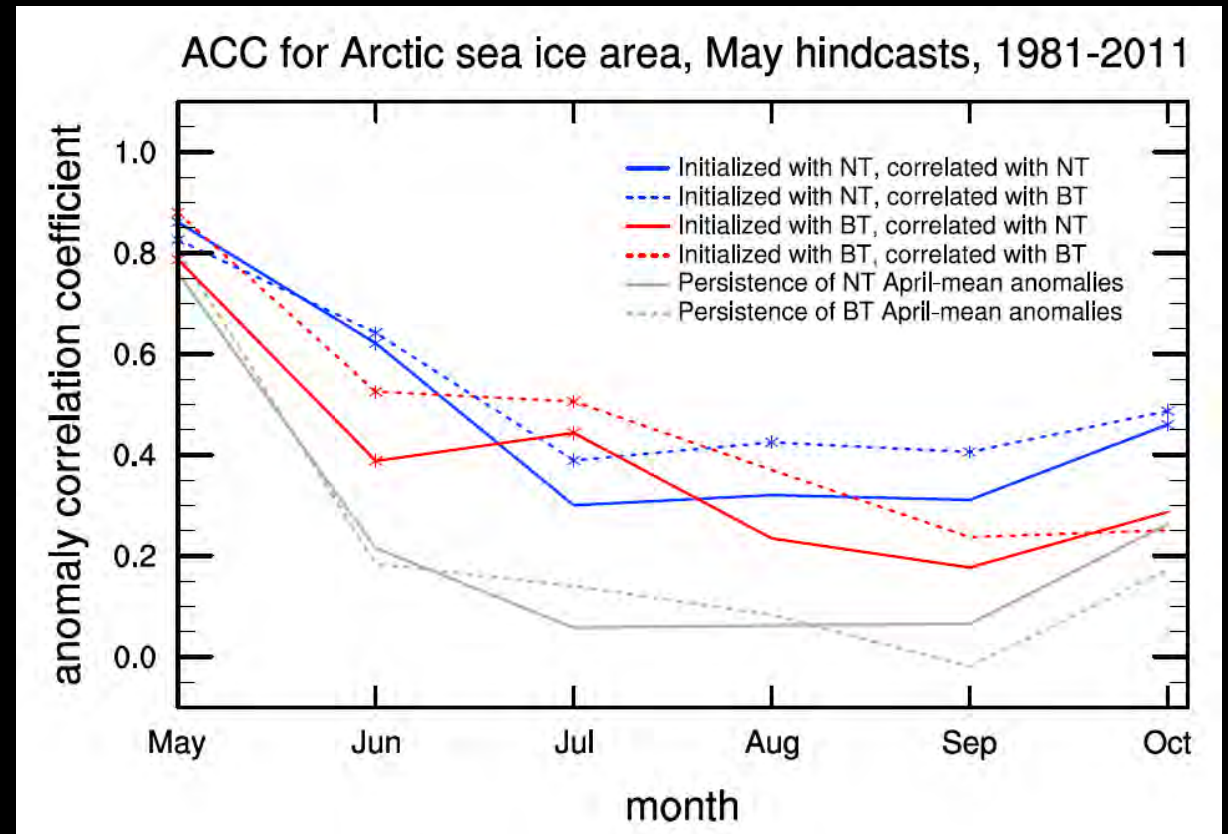
It's no one's fault

Internal variability

Seasonal sea ice prediction skill is significantly affected by the choice of the verification product



Massonnet et al., *Science*, 2016



Bunzel et al., *Geophys. Res. Lett.*, 2016

Any statement on model quality cannot be formulated
before of uncertainty in verification observational data
is properly quantified

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Model evaluation

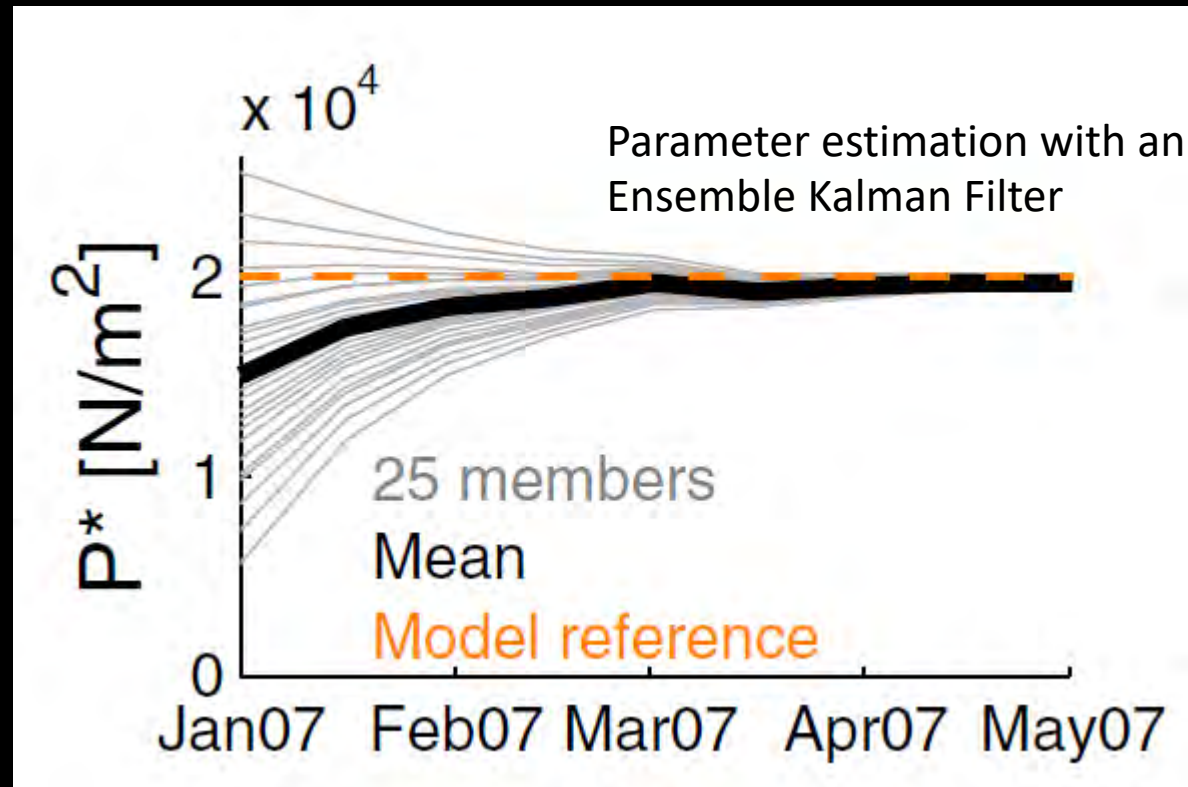
Data assimilation

Which data assimilation approach for sea ice models?

	Nudging	Variational (3D/4D Var)	Sequential methods (EnKF)	Particle filtering
<i>Ease of implementation</i>	Fair	Hard (coding adjoint)	Medium-Hard	Medium
<i>CPU consumption</i>	Low	Low-Medium	High (~20-50 members)	Very high (~100 members to avoid degenerate solution)
<i>Needs changes in model code?</i>	Yes (restoring term added to tendencies)	Yes (adjoint)	No	No
<i>Physical consistency</i>	Little (univariate)	Up to linear approximation	Up to linear approximation	Full consistency
<i>Estimation of prior uncertainty</i>	None	Static	Dynamic	Dynamic
<i>Assumptions to reach optimality</i>	Not defined as an optimization problem	Gaussian centered errors	Gaussian centered errors	None
<i>Produces ensembles?</i>	No	No	Yes (hence available as IC)	Yes (hence available as IC)

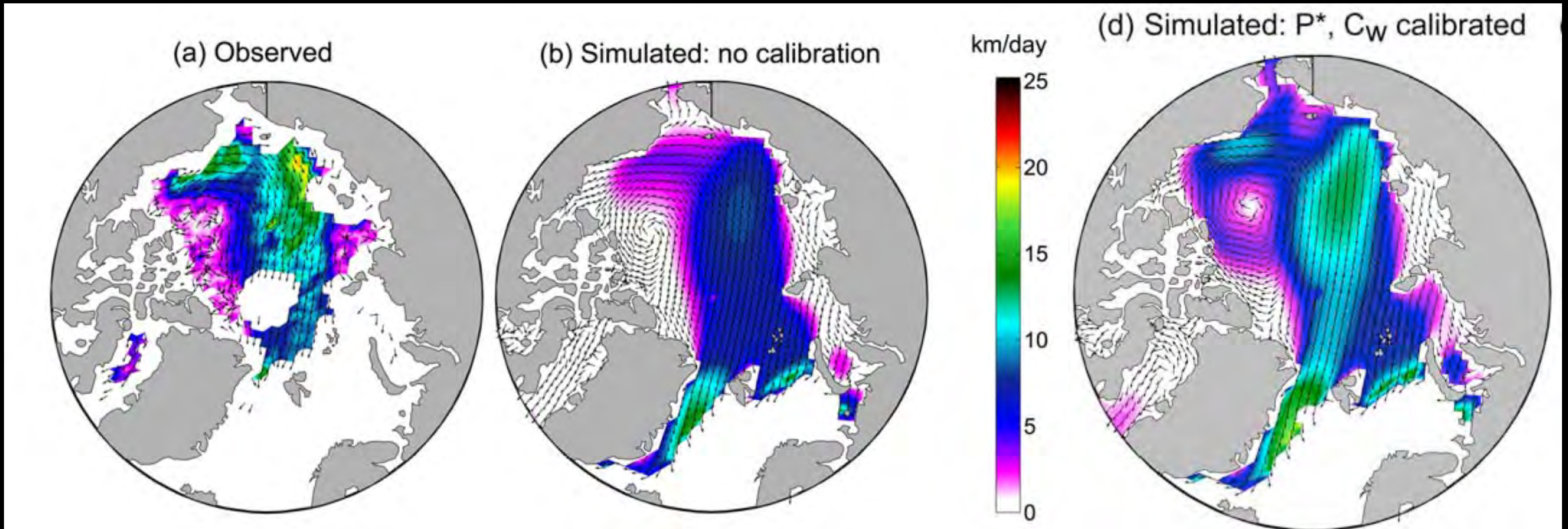
Data assimilation as an elegant way for tuning large-scale sea ice models

Perfect model tuning exercise: retrieving the reference value



Data assimilation as an elegant way for tuning large-scale sea ice models

Snapshot of 12-14 april 2012 sea ice drift



2. How can we integrate observations better with models?

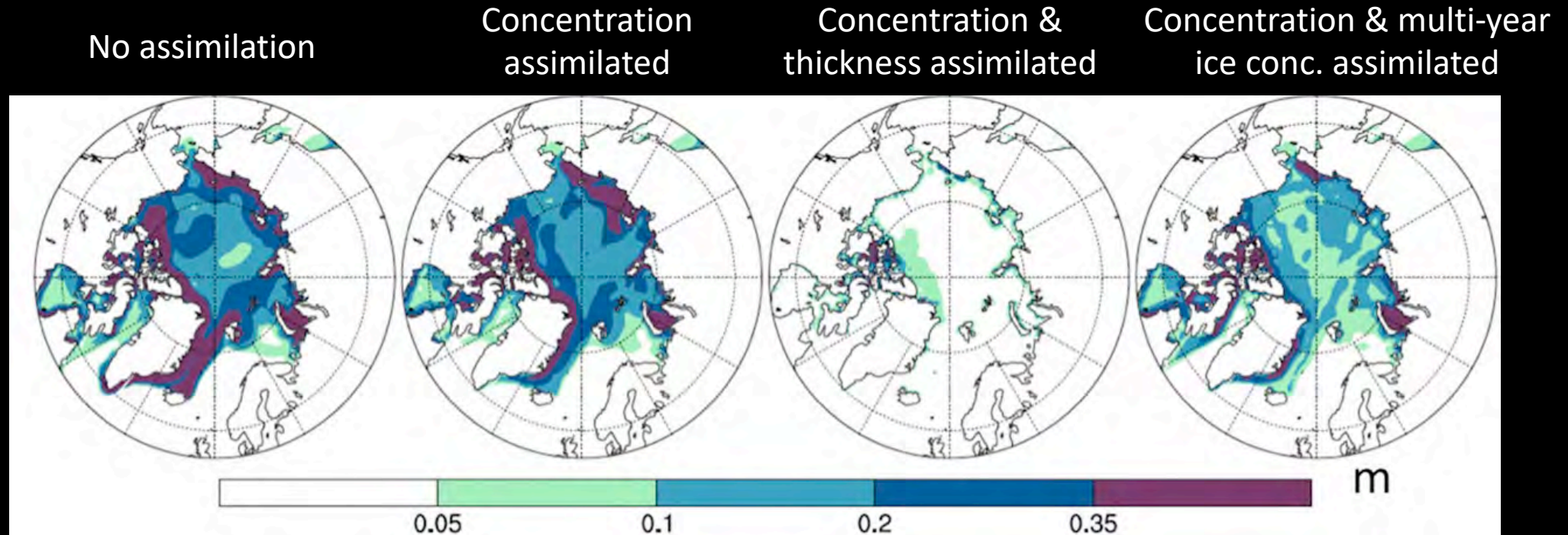
- Account for (epistemic) observational uncertainty by using multiple products
- Work on quantifying aleatoric observational uncertainty is making its way
- « Ensembles » of observations (e.g., HadISST2)
- Data assimilation offers a mathematically robust framework for integrating observations in models for many purposes (state estimation, initialization, parameter calibration)

1. How should we design a climate model to obtain better predictions of polar climates on timescales of decades?
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Observing System Experiments inform on what observations make the most impact

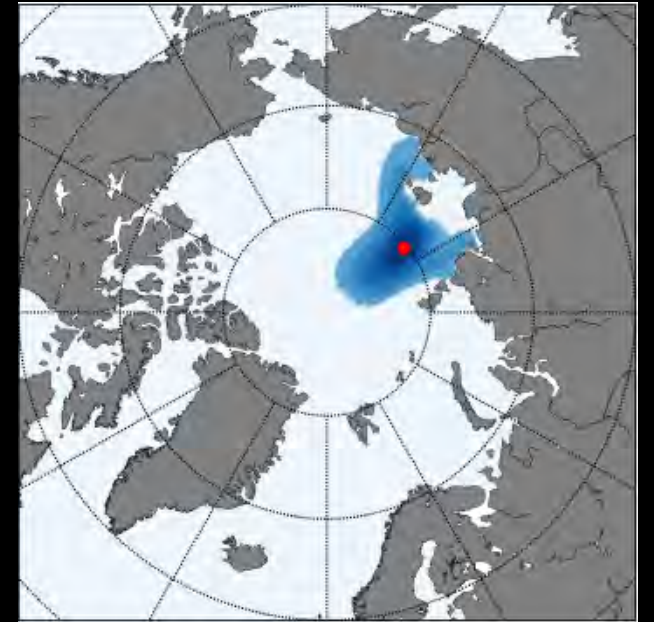
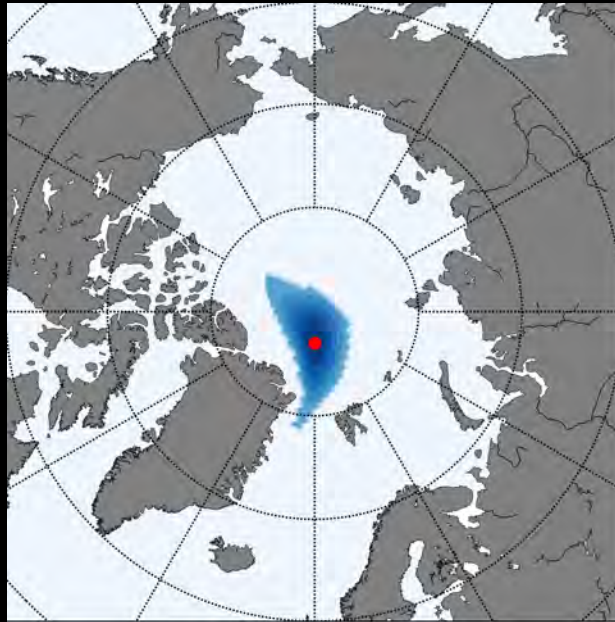
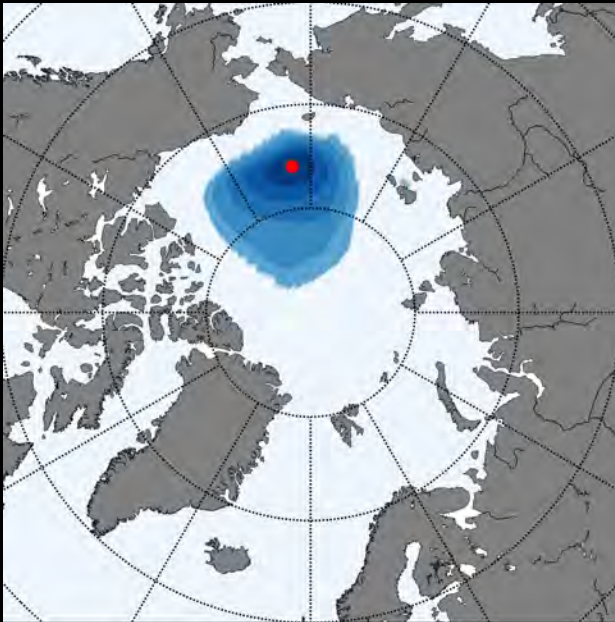
Root mean square error of 2001-2003 sea ice thickness
(CICE5 sea ice model + slab ocean + atmospheric forcing)

Reference: one model realization.

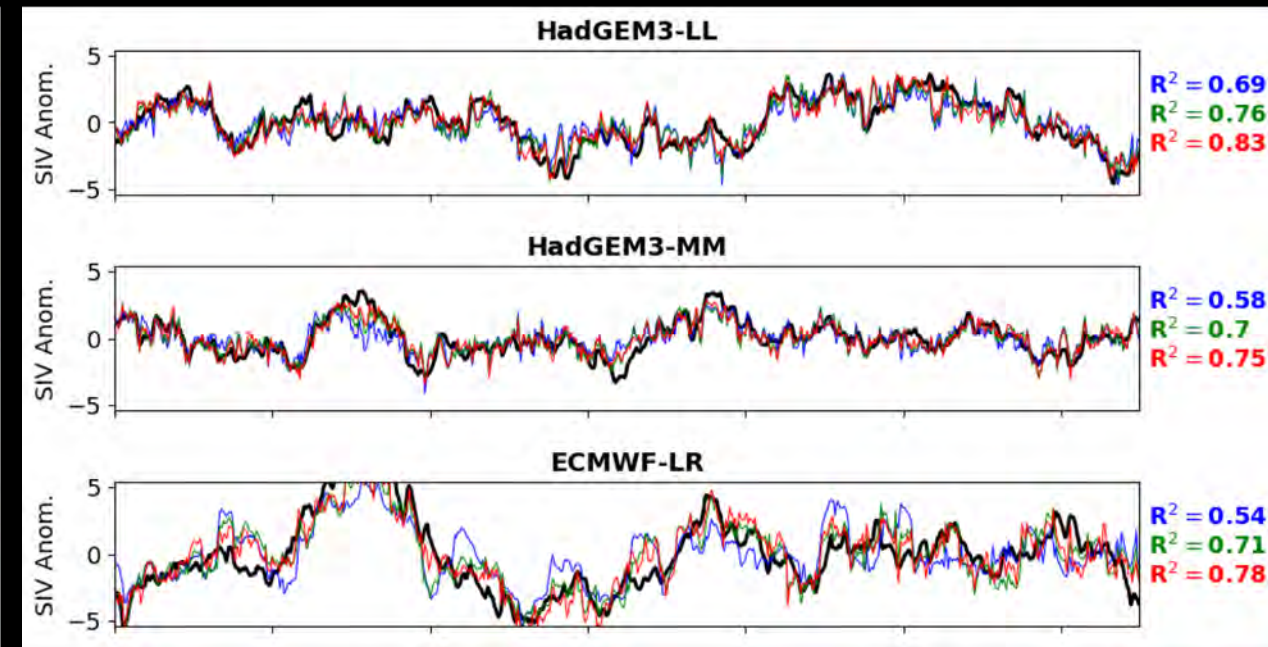
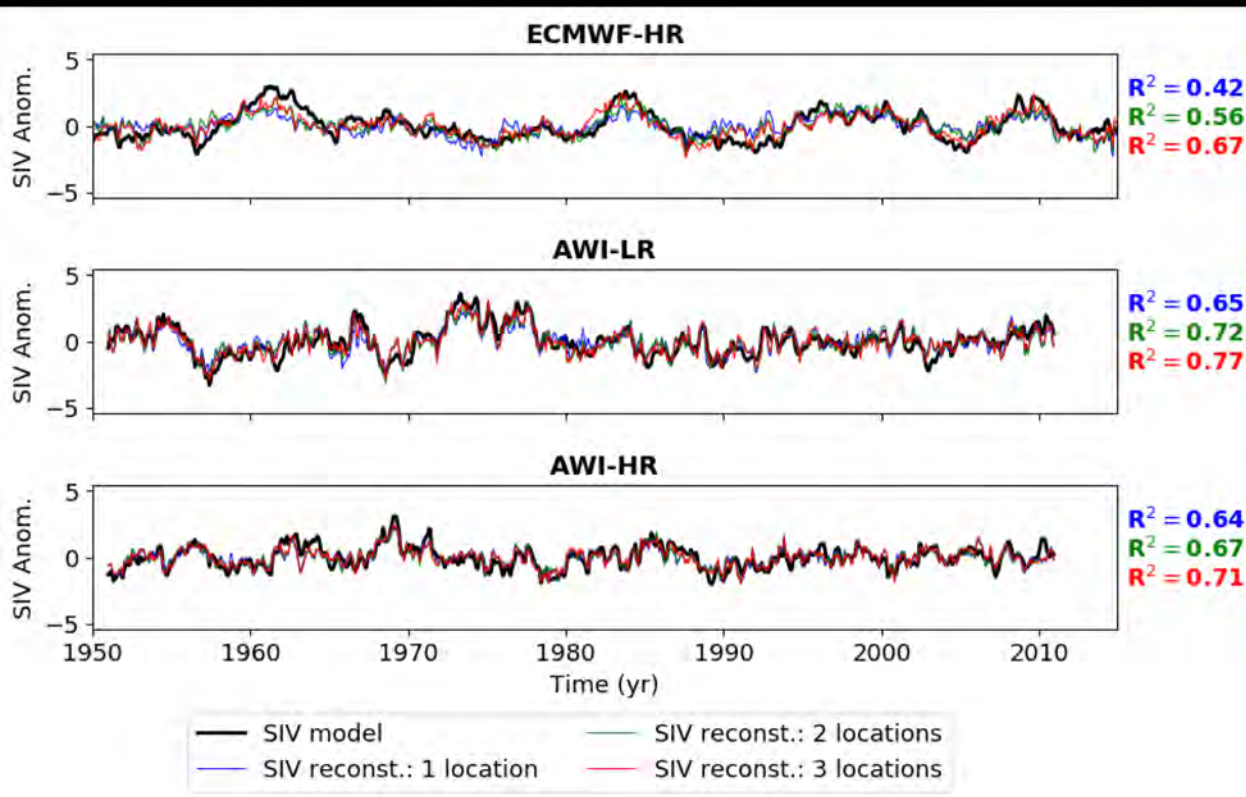


Optimal design of a sea ice thickness monitoring system

Area of influence of three given points for sea ice thickness (CESM-LE output)



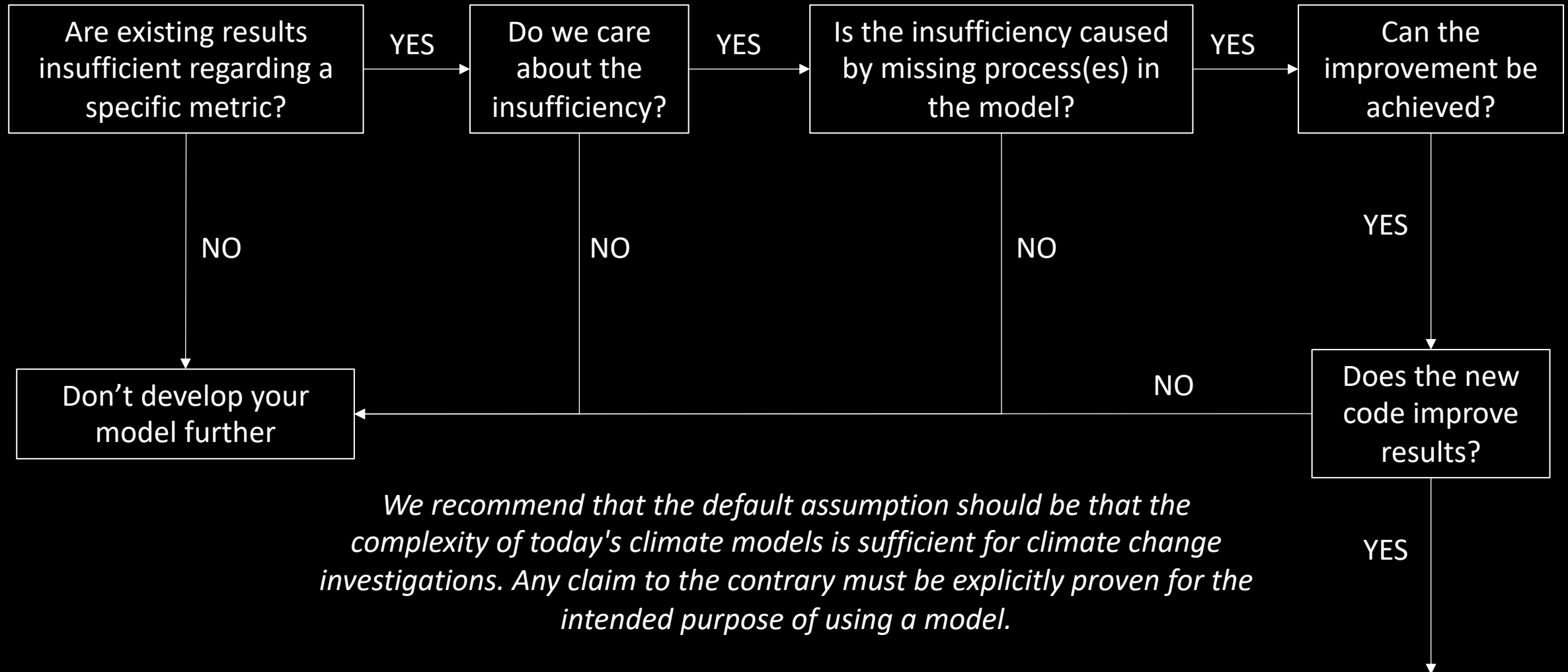
Retrieving Arctic sea ice volume from a selected set of thickness measurements



Conclusions

- We climate scientists all attempt to reduce epistemic (structural) uncertainty in the presence of aleatoric (irreducible) uncertainty
- Model development has value, but in a finite world with limited resources, priorities must be set depending on the underlying scientific question
- Model shortcomings are (by far) not the sole reason for model-observation mismatch
- Models can be used to find out which observation(s) are most valuable for prediction or climate change studies

A decision tree to guide model development (and to consider the need thereof)



Why do models score better for the two most advanced and recent products?

Models simulate directly sea ice concentration and output it as a physical variable; observations don't. Models can be really good references in that case!

Observations have deficiencies that models don't have e.g. concentration of thin ice

According to the toy model results, ESA-CCI and OSI-SAF should have lower errors (but only these two provide errors)

Note: remarkably, the models are also the most independent w.r.t. OSI-SAF and ESA-CCI

