

# Programmatic Truthmaker Semantics

ADVANCES IN TRUTHMAKER SEMANTICS: II

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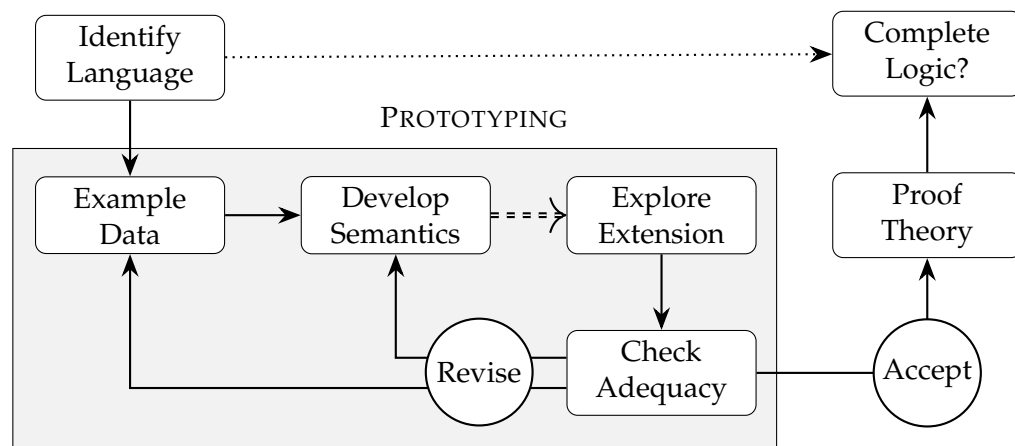
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## Broad Ambitions

Extend the standard methodology in semantics to:

- Rapidly prototype semantic theories by reducing cognitive load
- Facilitate collaboration and increase accessibility
- Support the maturity of the discipline

## “Standard Methodology”



## Difficulties

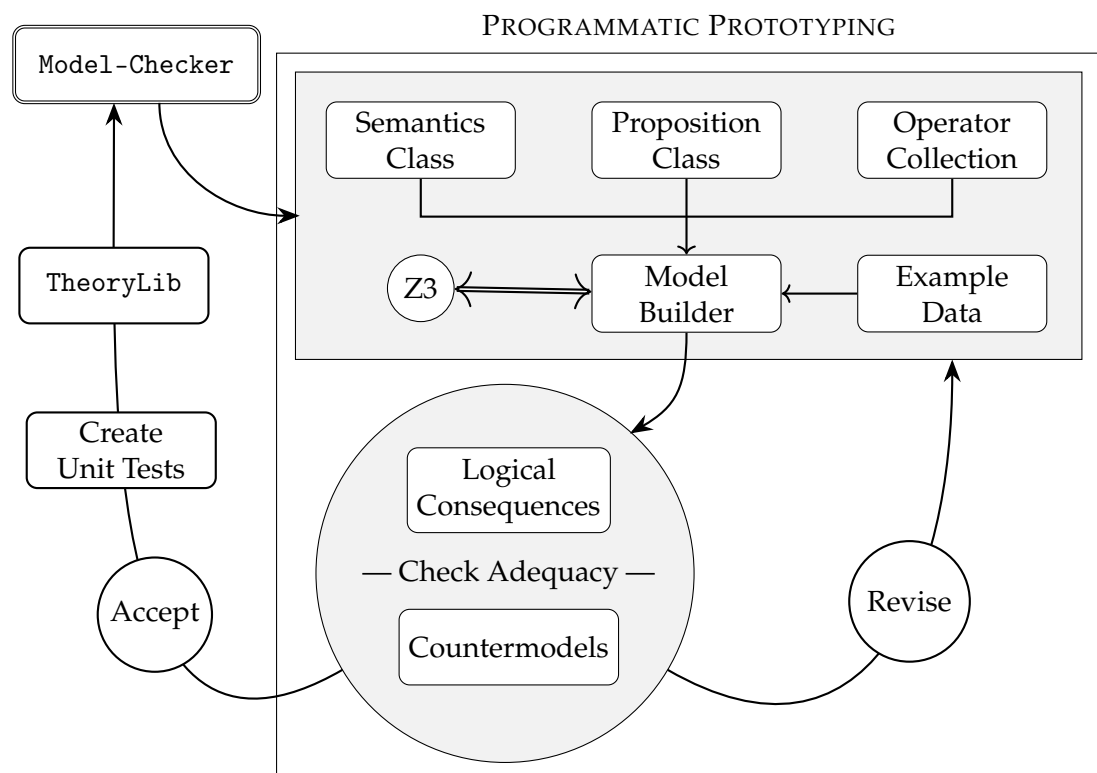
The standard methodology has the following drawbacks:

- Computationally grueling to prototype semantic theories
- Problems of accuracy, redundancy, and memory
- Limits the development of complex semantic theories
- Restricts which language fragments can be studied/combined

## An Extended Methodology

Humans should not be carrying the computational load.

- SAT solvers, SMT solvers, Z3
- Examples: inequalities, bitvectors as states
- Z3 constraints as truth-conditions



## Conceptual Engineering

This methodology has the following advantages:

- Efficiently prototype new semantic theories
- Modular semantics, theory of propositions, operators
- Evaluate unified languages with many operators
- Compare rival theories over large data sets

Give it a try at: <https://pypi.org/project/model-checker/>

## Bilateral Propositions

Following ???, a *modalized state space* is any  $\mathcal{S}^\diamond = \langle S, P, \sqsubseteq \rangle$  where  $\langle S, \sqsubseteq \rangle$  is a complete lattice of *states*,  $P \subseteq S$  is a nonempty subset of *possible states*, and  $\sqsubseteq$  is the *parthood relation* satisfying the following constraints:

NONEMPTY:  $P \neq \emptyset$ .

POSSIBILITY: If  $s \in P$  and  $t \sqsubseteq s$ , then  $t \in P$ .

The world states may then be defined, and a further constraint imposed:

*Compatible*:  $s \circ t := s.t \in P$ .

*World States*:  $W := \{w \in P \mid \forall s \circ w (s \sqsubseteq w)\}$ .

WORLD SPACE: If  $s \in P$ , then  $s \sqsubseteq w$  for some  $w \in W$ .

A *bilateral proposition* is any ordered tuple  $\langle V, F \rangle \in \mathbb{P}$  where

*Closure*:  $V, F \subseteq S$  are each closed under nonempty fusion.

*Exclusive*: The states in  $V$  are incompatible with the states in  $F$ .

*Exhaustive*: Every possible state in  $P$  is compatible with a state in  $V$  or  $F$ .

A *model*  $\mathcal{M} = \langle S, P, \sqsubseteq, |\cdot| \rangle$  of  $\mathcal{L}$  assigns each  $|p_i| = \langle |p_i|^+, |p_i|^- \rangle \in \mathbb{P}$ .

- $|\neg A| = \langle |A|^-, |A|^+ \rangle$ .
- $|A \wedge B| = \langle |A|^+ \otimes |B|^+, |A|^- \oplus |B|^- \rangle$  where  $X \otimes Y := \{s.t \mid s \in X, t \in Y\}$ .
- $|A \vee B| = \langle |A|^+ \oplus |B|^+, |A|^- \otimes |B|^- \rangle$  where  $X \oplus Y := X \cup Y \cup (X \otimes Y)$ .

## Minimal Countermodels

? originally introduced a primitive *imposition relation*  $t \rightarrow_w u$  which indicates that “ $u$  is a possible outcome of imposing the change  $t$  on the world [state]  $w$ ”, and is subject to the following frame constraints on imposition:

INCLUSION: If  $t \rightarrow_w u$ , then  $t \sqsubseteq u$ .

ACTUALITY: If  $t \sqsubseteq w$ , then  $t \rightarrow_w u$  for some  $u \sqsubseteq w$ .

INCORPORATION: If  $t \rightarrow_w u$  and  $v \sqsubseteq u$ , then  $t.v \rightarrow_w u$ .

COMPLETENESS: If  $t \rightarrow_w u$ , then  $u$  is a world-state.

An abridged semantics for  $\mathcal{L} = \langle \mathbb{L}, \neg, \wedge, \vee, \Box \rangle$  may then be stated as:

- $\mathcal{M}, w \models p_i$  iff  $s \in |p_i|^+$  for some  $s \sqsubseteq w$ .
- $\mathcal{M}, w \models A \Box \rightarrow C$  iff  $\mathcal{M}, u \models C$  whenever  $t \in |A|^+$  and  $t \rightarrow_w u$ .

## Defining Imposition

*Definition:* The frame constraints admit exceptions to  $\Box A := \top \Box \rightarrow A$ .

*State Space:*  $P = \{\Box, a, b, c, b.c\}$ ,  $W = \{a, b.c\}$ ,  $S/P = \{a.b, a.c, a.b.c\}$

*Imposition:*  $\rightarrow = \{ \langle a, a, a \rangle, \langle b, b.c, b.c \rangle, \langle c, b.c, b.c \rangle, \langle \Box, a, a \rangle, \langle \Box, b.c, b.c \rangle, \langle \Box, b.c, b.c \rangle \}$

*Interpretation:*  $|A| = \langle \{a\}, \{b.c\} \rangle$

*Premise:*  $\mathcal{M}, a \models \top \Box \rightarrow A$  since the set of  $\top$ -alternatives to  $a = \{a\}$ .

*Conclusion:*  $\mathcal{M}, a \not\models \Box A$  since  $\mathcal{M}, b.c \not\models A$ .

The definition  $\Box A := \top \Box \rightarrow A$  is preserved by the following definition of  $\rightarrow$ , where ' $s \sqsubseteq_t w$ ' reads ' $s$  is a  $t$ -compatible part of  $w$ ':

*Compatible Part:*  $s \sqsubseteq_t w := s \sqsubseteq w \wedge s \circ t$ .

*Maximal Compatible Parts:*  $w_t := \{s \sqsubseteq_t w \mid \forall r \sqsubseteq_t w (s \sqsubseteq r \rightarrow r = s)\}$ .

*Imposition:*  $t \rightarrow_w u := u \in W \wedge \exists s \in w_t (s.t \sqsubseteq u)$ .

We may then derive rather than posit the frame constraints on imposition, making the logic for  $\Box \rightarrow$  both stronger and more computable.

## Computational Complexity as a Theoretical Virtue

1. Z3 saves its 'Function' objects as a mix of array-like and lambda-like objects.
2. This means Z3 saves every value (that it is forced to for a given countermodel) for every input combination, meaning that the (worst-case) space complexity of functions is proportional to the input space.
3. Defining computational complexity: an algorithm takes  $O(n)$  runtime or space if it scales linearly with some quantity  $n$  as  $n$  grows indefinitely large.
4. With inputs in  $A \times B$ ,  $A$  being the space of atomic sentences and  $B$  the space of bitvectors, 'verify' has a worst-case complexity of  $O(|A||B|) = O(|A|2^N)$ ,  $N$  the size of the bitvectors.
5. With inputs in  $B^3$ , 'imposition' has a complexity of  $O(2^{3N})$ .
6. In practice, this means much slower runtimes for the imposition semantics: imposition semantics takes about 10 times as long as logos to run for  $N = 4$ .

7. Since the complexity of ‘imposition’ is exponential with  $N$ , this is only more marked for larger values of  $N$ , which can be useful for finding easily interpretable models.
8. As a result, we now have methodological reason to favor theories that keep the arity of primitives low.
9. This reasoning is not too different from familiar questions of theoretical simplicity: this is just a notion of simplicity with regards to the computer

## Proofs

**P1 (INCLUSION)** *If  $t \rightarrow_w u$ , then  $t \sqsubseteq u$ .*

*Proof.* Assuming  $t \rightarrow_w u$ , it follows that  $u \in W$  where  $s.t \sqsubseteq u$  for some  $s \in w_t$ . Since  $t \sqsubseteq s.t$ , it follows that  $t \sqsubseteq u$  as desired.  $\square$

**P2 (ACTUALITY)** *If  $t \sqsubseteq w$  and  $w \in W$ , then  $t \rightarrow_w u$  for some  $u \sqsubseteq w$ .*

*Proof.* Assume  $t \sqsubseteq w$  for  $w \in W$ . Thus  $w \in P$  where  $w.t = w$ , and so  $w \circ t$ . Since  $w \sqsubseteq w$ , we know  $w \sqsubseteq_t w$ . Let  $r \sqsubseteq_t w$  where  $w \sqsubseteq r$ , and so  $r \sqsubseteq w$ , and so  $w \in w_t$ . Since  $w.t \sqsubseteq w$ , we know  $t \rightarrow_w w$ , and so  $t \rightarrow_w u$  for some  $u \sqsubseteq w$ .  $\square$

**P3 (INCORPORATION)** *If  $t \rightarrow_w u$  and  $v \sqsubseteq u$ , then  $t.v \rightarrow_w u$ .*

*Proof.* Assuming  $t \rightarrow_w u$  and  $v \sqsubseteq u$ , we know  $u \in W$  where  $s.t \sqsubseteq u$  for some  $s \in w_t$ . Thus  $s.t.v \sqsubseteq u$  and  $s \sqsubseteq_t w$  where (1):  $r \sqsubseteq s$  whenever  $r \sqsubseteq_t w$  and  $s \sqsubseteq r$ . So  $s \sqsubseteq w$ . Since  $u \in P$ , we also know that  $s \circ t.v$ , and so  $s \sqsubseteq_{t.v} w$ .

Let  $q \sqsubseteq_{t.v} w$  where  $s \sqsubseteq q$ , and so  $q \sqsubseteq w$  where  $q \circ t.v$ , and so  $q.t.v \in P$ . Thus  $q.t \in P$ , and so  $q \circ t$ . It follows that  $q \sqsubseteq_t w$ , and so  $q \sqsubseteq s$  follows from (1). Generalizing on  $q$ , we know (2):  $q \sqsubseteq s$  whenever  $q \sqsubseteq_{t.v} w$  and  $s \sqsubseteq q$ .

Having already shown that  $s \sqsubseteq_{t.v} w$ , it follows from (2) that  $s \in w_{t.v}$ . Since  $s.t.v \sqsubseteq u$  for  $u \in W$ , we may conclude that  $t.v \rightarrow_w u$  as desired.  $\square$