

SPL13-001

Digital pressure sensor

Restricted

1. Security warning

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2. Publication history

Version	Date	Description	Author	Approved
6.0	2018.03.04	Correct the error in Page 7 (absolute accuracy temperature @0-65°C)	Don	Devin
7.0	2018.05.03	 a. Update the description of water resistance degree b. Add the limit value of performance parameter in Table 3 c. Update the quantity per reel and update Figure 7 (packing box) 	Don	Devin
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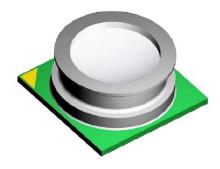


1. Introduction

The SPL13-001 is a miniaturized Digital Barometric Air Pressure Sensor with a high accuracy and a low current consumption. The SPL13-001 is both a pressure and a temperature sensor. The pressure sensor element is based on a capacitive sensing principle which guarantees a high precision during temperature changes. The small package makes the SPL13-001 ideal for mobile applications and wearable devices.

The SPL13-001's internal signal processor converts the output from the pressure and temperature sensor elements to 24-bit results. Each pressure sensor has been calibrated individually and contains calibration coefficients. The coefficients are used in the application to convert the measurement results to true pressure and temperature values.

The SPL13-001 has a FIFO that can store the latest 32 measurements. By using the FIFO, the host processor can remain in a sleep mode for a longer period of time between readouts. This can reduce the overall system power consumption. Sensor measurements and calibration coefficients are available through the serial I2C interface.



Key features

- Water resistance degree: water resistance rating of 50 meters
- Pressure range: 300 ... 1100hPa (+9000m ... -500m relating to sea level)
- Temperature Range: -40...+85°C
- Supply voltage: 1.7 ... 3.6V (VDD), 1.2 ... 3.6V (VDDIO)
- Relative accuracy: ±0.06hPa, equiv. to ±0.5 m
- Absolute accuracy: typ. ±1hPa (300 ... 1100hPa)
- Temperature accuracy: ± 0.5°C
- Pressure temperature sensitivity: < 0.5Pa/K
- Measurement time: Typical: 27.6 ms
 Minimum: 3.6 ms
- Average current consumption: High precision: 40 μA, Low power: 3 μA, Standby: <1 μA
- I2C interface, Embedded 24-bit ADC
- FIFO: Stores latest 32 pressure or temperature measurements
- Pb-free, halogen-free and RoHS compliant

Typical applications

- Wearable devices
- Altimeter and barometer for portable devices
- Enhancement of GPS navigation (dead-reckoning, slope detection, etc.)
- In- and out-door navigation
- Weather station equipment
- Vertical velocity indication (rise/sink speed)

Specific notes

Particles can influence the performance of the pressure sensor, we strongly recommend you to introduce special measures to avoid deposition of particles on the coating gel or screen particles after assembly as the assembly process is considered to be the main root cause for particle generation.

2. Test condition

Table 1: Test condition

Standard Conditions	Temperature	Humidity	Air pressure
Environment conditions	-40°C+85°C	25%RH75%RH	300hPa1100hPa
Basic test conditions	+25°C	60%RH70%RH	300hPa1100hPa

3. Absolute maximum ratings

Table 2: Absolute maximum ratings

Parameter	Condition	Min	Max	Units
Storage temperature		-40	+125	°C
Supply Voltage	All pins		+3.6	V
Voltage at all IO Pins	All pins		+3.6	V
ESD rating	JESD22-A114	-2	+2	kV
Overpressure			10000	hPa

4. Electrical characteristics

VDD = 1.8V, VDDIO=1.8V, $T=25^{\circ}$ C, unless otherwise noted. If not stated otherwise, the given values are ± 3 -Sigma values over temperature/voltage range in the given operation mode.



Table 3: Operating conditions, output signal and mechanical characteristics

Parameter	Symbol	(Condition	Min	Typ. ⁽¹⁾	Max	Units
Operating temperature	TA	0	perational	-40	25	85	Ŝ
Operating temperature	IA	Fu	II accuracy	0	25	65	Ŝ
Operating Pressure	Р			300		1100	hPa
Supply voltage	VDD			1.7		3.6	V
Interface supply	VDDIO			1.2		3.6	V
voltage	VDDIO			1.2		5.0	V
Supply current (with 1			Low Power		3	5	
measurement per	ldd	1 Hz	Hz Standard		11	15	uA
second.)			High precision		40	50	

Note: The current consumption depends on both pressure measurement precision and rate. Please refer to the Pressure Configuration (PRS_CFG) register description for an overview of the current consumption in different combinations of measurement precision and rate.

Peak current	Ipeak	During conversion		400	500	uA	
Standby current	Iddsbm				1	uA	
Relative accuracy	P_R	9501050hPa +25+40°C		±6		Pa	
pressure		+25+40 C		±0.5		m	
Absolute accuracy pressure	P_A	3001100hPa 0+65°C	-3.0	±1.0	3.0	hPa	
Resolution of output		Pressure		0.06		Pa	
data		Temperature		0.01		°C	
		Low Power mode		5			
Noise in pressure	P_Noise	Standard mode		1.2		PaRMS	
		High precision mode		0.6			

Note: Pressure noise is measured as the average standard deviation. Please refer to the Pressure Configuration (PRS_CFG) register description for all precision mode options.

Offset temperature	TCO	1000hPa		±0.5		Pa/K		
coefficient	100	+25+40°C		±4.2		cm/K		
Absolute accuracy		@+25°C		±0.5		°C		
temperature		0+65°C	-3	±1	3	°C		
Pressure/Temperature	f		1		128	Hz		
measurement rate	1				120	1 12		
D		Low Power mode		5	8			
Pressure measurement time	t	Standard mode		28	35	ms		
unio		High precision mode		105	115			

Note: The pressure measurement time (and thus the maximum rate) depends on the pressure measurement precision. Please refer to the Pressure Configuration (PRS_CFG) register description for an overview of the



possible combinations of measurement precision and rate.									
		Measured with 217Hz square							
Power supply rejection	Ap_psr	wave and broad band noise,			0.063	PaRMS			
		100mVpp							
Supply voltage ramp-up	tyddun	Time for supply voltage to	0.001		5	ms			
time	tvddup	reach 90% of final value							
Serial data clock	f _{I2C}	For I2C			3.4	MHz			
Long term stability		12 months	-1		1	hPa			
		The SENSOR_RDY bit in							
Time to concer ready		the Measurement			10	ma			
Time to sensor ready	TSensor_rdy	Configuration register will be	iguration register will be		12	ms			
		set when the sensor is ready							
		The COEF_RDY bit in the							
Time to coefficients are	TCoof rdv	Measurement Configuration			40	ma			
available	TCoef_rdy	register will be set when the			40	ms			
		coefficients can be read out							

Note: (1) Typical specifications are not guaranteed.

5. Operation

5.1 Operating Modes

The SPL13-001 supports 3 different modes of operation: Standby, Command, and Background mode.

- · Standby Mode
 - Default mode after power on or reset. No measurements are performed.
 - All registers and compensation coefficients are accessible.
- · Command Mode
 - One temperature or pressure measurement is performed according to the selected precision.
 - The sensor will return to Standby Mode when the measurement is finished, and the measurement result will be available in the data registers.
- · Background Mode
 - Pressure and/or temperature measurements are performed continuously according to the selected measurement precision and rate. The temperature measurement is performed immediately after the pressure measurement.
 - The FIFO can be used to store 32 measurement results and minimize the number of times the sensor must be accessed to read out the results.

Note: Operation mode and measurement type are set in the Sensor Operating Mode and Status (MEAS_CFG) register.

5.2Measurement Precision and Rate

Different applications require different measurement precision and measurement rates. Some applications, like weather stations, require lower precision and measurement rates than for instance indoor navigation and sports applications.

The SPL13-001's measurement precision and rate (in background mode) can be configured to match the requirements of the application in which it is being used. This reduces current consumption of the sensor and the system.

In order to achieve a higher precision, the SPL13-001 will read the sensor multiple times (oversampling), and combine the readings into one result. This increases the current consumption and the measurement time, which again reduces the maximum measurement rate.

The measurement precision, rate and time is set in the *Pressure Configuration (PRS_CFG)* and *Temperature Configuration (TMP_CFG)* registers. The register descriptions contain information about the current consumption and the possible combinations of measurement precision, time, and rate.

Please note that the pressure sensor is temperature dependent. Temperature measurements must be made together with the pressure measurements in order to compensate for the temperature dependency. This reduces the maximum pressure measurement rate, *since:* Ratetemperature*Timetemperature + Ratepressure*Timepressure< 1 second. Measurement Settings and Use Case Examples contains a table with examples of combinations of pressure and temperature precision and rates for different use cases.

5.3 Sensor Interface

The SPL13-001 can be accessed as a slave device through I2C serial interface.

I2C interface

- The sensor's default interface.
- The sensor's address is 0x77.

I2C write

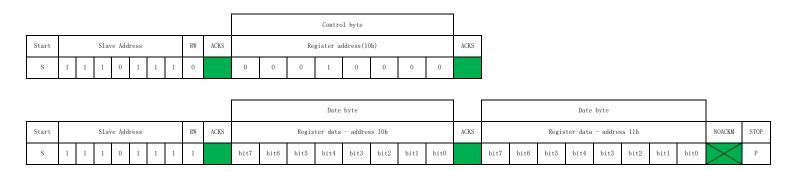
Writing is done by sending the slave address in write mode (RW='0'), resulting in slave address 11101110. Then the master sends pairs of register addresses and register data. The transaction is ended by a stop condition.



Control byte										Date	e byte					_												
Start			Sla	ve Addı	ress			RW	ACKS		Register address(06h)				ACKS		Register data - address 06h						ACKS					
S	1	1	1	0	1	1	1	0		0	0	0	0	0	1	1	0		bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0		
													Contr	ol byte								Date	e byte					
										Register address(07h)			ACKS			Re	gister data	a - address (07h			ACKS	STOP					
										0	0 0 0 0 0 1 1 1					bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0		Р			

I2C read

To be able to read registers, first the register address must be sent in write mode (slave address 11101110). Then either a stop or a repeated start condition must be generated. After this the slave is addressed in read mode (RW='1') at address 11101111, after which the salve sends out data from auto-incremented register addresses until a NOACKM and stop condition occurs.



5.4 FIFO Operation

The SPL13-001 FIFO can store the last 32 measurements of pressure or temperature. This reduces the overall system power consumption when the host processor does not need to continuously pull data from the sensor but can go into standby mode for longer periods of time.

The FIFO will store any combination of temperature and pressure measurements since the measurement rate of temperature and pressure can be set up independently in Background Mode. The pressure rate can for instance be set 4 times higher than the temperature rate and thus only every fifth result will be a temperature result. The measurement type can be seen in the result data. The sensor will set the least significant bit to:

- '1' if the result is a pressure measurement.
- '0' if it is a temperature measurement.
- The sensor uses 24 bits to store the measurement result. Because this is more bits than is needed to cover the full dynamic range of the pressure sensor, using the least significant bit to label the measurement type will not affect the precision of the result.

The data from the FIFO is read out from the *Pressure Data (PRS_Bn) registers* regardless of the next result in the FIFO is a temperature or a pressure measurement.



When a measurement has been read out, the FIFO will auto increment and place the next result in the data register. A flag will be set in the *FIFO Status (FIFO_STS) register* when the FIFO is empty and all following reads will return 0x800000.

If the FIFO runs full a flag will be set in the FIFO Status (FIFO_STS) register

5.5 Calibration and Measurement Compensation

The SPL13-001 is a calibrated sensor and contains calibration coefficients. These are used in the application (for instance by the host processor) to compensate the measurement results for sensor non-linearity's.

The sections that follow, describe how to calculate the compensated results and convert them into Pa and °C values.

5.6.1 How to Calculate Compensated Pressure Values

1. Read the calibration coefficients (c00, c10, c20, c30, c01, c11, and c21) from the Calibration Coefficient register.

Note: The coefficients read from the coefficient register are 16 bit 2's complement numbers.

- 2. Choose scaling factors kT (for temperature) and kP (for pressure) based on the chosen precision rate. The scaling factors are listed in Table 4.
- 3. Read the pressure and temperature result from the registers or FIFO.

Note: The measurements read from the result registers (or FIFO) are 24 bit 2's complement numbers.

Depending on the chosen measurement rates, the temperature may not have been measured since the last pressure measurement.

4. Calculate scaled measurement results.

5. Calculate compensated measurement results.

$$P_{comp}(Pa) = c00 + P_{raw_sc}*(c10 + P_{raw_sc}*(c20 + P_{raw_sc}*c30)) + T_{raw_sc}*c01 + T_{raw_sc}*(c11 + P_{raw_sc}*c21)$$



5.6.2 How to Calculate Compensated Temperature Values

1. Read the calibration coefficients (c0 and c1) from the Calibration Coefficients (COEF) register.

Note: The coefficients read from the coefficient register are 12 bit 2's complement numbers.

- 2. Choose scaling factor kT (for temperature) based on the chosen precision rate. The scaling factors are listed in Table 4.
- 3. Read the temperature result from the temperature register or FIFO.

Note: The temperature measurements read from the temperature result register (or FIFO) are 24 bit 2's complement numbers.

Calculate scaled measurement results.

Traw sc = Traw/kT

5. Calculate compensated measurement results

Tcomp (°C) = $c0*0.5 + c1*Traw_sc$

5.6.3 Compensation Scale Factors

Table 4 Compensation Scale Factors

Oversampling Rate	Scale Factor (kP or kT)				
1 (single)	524288				
2 times (Low Power)	1572864				
4 times	3670016				
8 times	7864320				
16 times (Standard)	253952				
32 times	516096				
64 times (High Precision)	1040384				



6. Applications

6.1 Measurement Settings and Use Case Examples

Table 5 Measurement Settings and Use Case Examples (TBD)

Use Case	Performance	Pressure Register Configuration Address: 0x06	Temperature Register Configuration Address: 0x07	Other
Weather Station (Low power, Background mode)	5 Pa precision. 1 pr sec. 6 uA	0x01	0x80	Start background measurements (addr 0x08)
Indoor navigation (Standard precision, Background mode)	10 cm precision. 2 pr sec. 30 uA	0x14	0x80	Enable P shift (addr 0x09) Start background measurements (addr 0x08)
Sports (High precision, high rate, background mode)	5 cm precision 4 pr sec. 200 uA	0x26	0xA0	Enable P shift (addr 0x09) Start background measurements (addr 0x08)



6.2 Application Circuit Example

The example application circuit example uses the I2C serial interface.

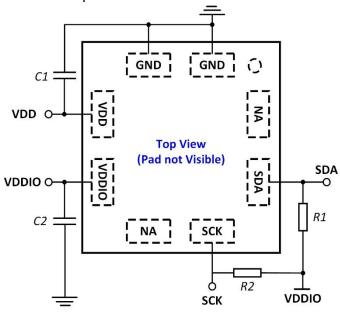


Figure 1: Typical application circuit

Table 6 Component Values

0	0	Values		L lade	Nata / Tast Ossalition		
Component	Symbol	Min.	Тур.	Max.	Unit	Note / Test Condition	
Pull-up/down Resistor	R1, R2			10	ΚΩ		
Supply Blocking Capacitor	C1, C2	100	100		nF	The blocking capacitors should be placed as close to the package pins as possible.	

6.3 Calculating absolute altitude and calculating pressure at sea level

With the measured pressure P and the pressure at sea level P_0 =1013.25hPa, the altitude in meters can be calculated with the international barometric formula:

Altitude=44330×
$$\left[1-\left(\frac{P}{P_0}\right)^{\frac{1}{5.255}}\right]$$

Thus, a pressure change of ΔP = 1hPa corresponds to 8.43m at sea level.



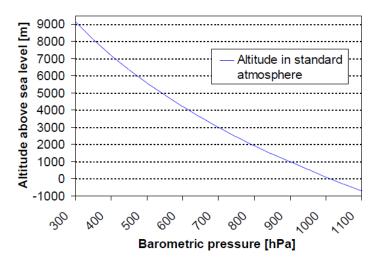


Figure 2: Transfer function: Altitude over sea level – Barometric pressure

With the measured pressure *P* and the absolute altitude the pressure at sea level can be calculated:

$$P_0 = \frac{P}{\left(1 - \frac{altitude}{44330}\right)^{5.255}}$$

Thus, a difference in altitude of Δ altitude = 10m corresponds to 1.2hPa pressure change at sea level.



7. Register Map

Table 7 Register Map

	egister				I					1		
Register Name	Addr.	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Reset State		
PSR_B2	0x00	PSR[23:16]	PSR[23:16] (r)									
PSR_B1	0x01	PSR[15:8](r										
PSR_B0	0x02	PSR[7:0](r)								00h		
TMP_B2	0x03	TMP[23:16]	(r)							00h		
TMP_B1	0x04	TMP[15:8] ((r)							00h		
TMP_B0	0x05	TMP[7:0] (r))							00h		
PRS_CFG	0x06	-	PM_RATE [2:0] (rw)		PM_PRC [3:0] (rw)			00h		
TMP_CFG	0x07	TMP_ EXT (rw)	EXT TMP_RATE [2:0] (rw) - TM_PRC [2:0] (rw)							00h		
MEAS_CFG	0x08	COEF_ RDY (r)	RDY					00h				
CFG_REG	0x09	-	-	-	-	TMP_ SHIFT_ EN (rw)	PRS_ SHIFT_ EN (rw)	FIFO_ EN (rw)	-	00h		
FIFO_STS	0x0B	-	-	-	-	-	-	FIFO_ FULL (r)	FIFO_ EMPTY (r)	00h		
RESET	0x0C	FIFO_ FLUSH (w)	FLUSH SOFT_RST [3:0] (w)							00h		
ID	0x0D	PROD_ID	[3:0] (r)			REV_ID [3	:0] (r)			00h		
COEF	0x10- 0x21	< see regis	ster description	ı >						XXh		
Reserved	0x22- 0x27	Reserved								XXh		



8. Register Description

8.1Pressure Data (PRS_Bn)

The Pressure Data registers contains the 24 bit (3 bytes) 2's complement pressure measurement value. If the FIFO is enabled, the register will contain the FIFO pressure and/or temperature results (please see *FIFO Operation*). Otherwise, the register contains the pressure measurement results and will not be cleared after read.

8.1.1 PRS_B2

The highest byte of the three bytes measured pressure value.

PRS_B2				Address			00H
Pressure (M	/ISB data)		Reset value: 00H				
7	6	5	4	3	2	1	0
PRS23	PRS22	PRS21	PRS20	PRS19	PRS18	PRS17	PRS16
			r	•			

Field	Bits	Туре	Description
PRS[23:16]	7:0	r	MSB of 24 bit 2's complement pressure data.

8.1.2 PRS_B1

The middle byte of the three bytes measured pressure value.

PRS_B1	_B1 Address									
Pressure (L	Pressure (LSB data) Reset value:									
7	6	5	4	3	2	1	0			
PRS15	PRS14	PRS13	PRS12	PRS11	PRS10	PRS9	PRS8-			
			r							

Field	Bits	Туре	Description
PRS[15:8]	7:0	r	LSB of 24 bit 2's complement pressure data.



8.1.3 PRS_B0

The lowest byte of the three bytes measured pressure value.

PRS_B0			Address 0.						
Pressure (X	LSB da	ata)		Re	eset value:			00H	
7	6		5 4 3 2 1				0		
PRS7	PR	S6	PRS5	PRS4	PRS3	PRS2	PRS1	PRS0	
				r					
Field		Bits	Type	Description	on				
PRS[7:0]		7:0	co r XLSB of 24 bit 2's complement pressure data				a.		

8.2Temperature Data (TMP_Tn)

The Temperature Data registers contain the 24 bit (3 bytes) 2's complement temperature measurement value (unless the FIFO is enabled, please see *FIFO Operation*) and will not be cleared after the read.

8.2.1 TMP_B2

The highest byte of the three bytes measured temperature value.

TMP_B2 Temperatur	e (MSB data	a)	Re	Address eset value:			03H 00H
7	6	5	4	3	2	1	0
TMP23	TMP22	TMP21	TMP20	TMP19	TMP18	TMP17	TMP16
			r				

Field	Bits	Type	Description
TMP[23:16]	7:0	r	MSB of 24 bit 2's complement temperature data.



8.2.2 TMP_B1

The middle byte of the three bytes measured temperature value.

TMP_B1 Address 04H

Temperature (LSB data) Reset value: 00H

7 6 5 4 3 2 1 0

TMP15 TMP14 TMP13 TMP12 TMP11 TMP10 TMP9 TMP8

r

Field	Bits	Туре	Description
TMP[15:8]	7:0	r	LSB of 24 bit 2's complement temperature data.

8.2.3 TMP_B0

The lowest part of the three bytes measured temperature value.

TMP_B0 Address 05H

Temperature (XLSB data) Reset value: 00H

7 6 5 4 3 2 1 0

TMP7TMP6TMP5TMP4TMP3TMP2TMP1TMP0

r

Field	Bits	Туре	Description
TMP[7:0]	7:0	r	XLSB of 24 bit 2's complement temperature data.

8.3Pressure Configuration (PRS_CFG)

Configuration of pressure measurement rate (PM_RATE) and resolution (PM_PRC).

PRS_CFG Address: 06H

Pressure measurement configuration Reset value: 00H

7 6 5 4 3 2 1 0 - PM_RATE[2:0] PM_PRC[3:0]

- rw rw



Field	Bits	Type	Description
_	7	-	Reserved.
PM_RATE[2:0]	6:4	rw	Pressure measurement rate:
			000 - 1 measurements pr. sec.
			001 - 2 measurements pr. sec.
			010 - 4 measurements pr. sec.
			011 - 8 measurements pr. sec.
			100 - 16 measurements pr. sec.
			101 - 32 measurements pr. sec.
			110 - 64 measurements pr. sec.
			111 - 128 measurements pr. sec.
			Applicable for measurements in Background mode only
PM_PRC[3:0]	3:0	rw	Pressure oversampling rate:
			0000 - Single.
			0001 - 2 times (Low Power).
			0010 - 4 times.
			0011 - 8 times.
			0100 *)- 16 times (Standard).
			0101 *) - 32 times.
			0110 *) - 64 times (High Precision).

^{*)} Note: Use in combination with a bit shift. See FIFO configuration (CFG_REG) register

Table 8 Pressure measurement time (ms) and precision (PaRMS)

Oversampling (PRC[3:0])	Single (0000)	2 times (0001)	4 times (0010)	8 times (0011)	16 times (0100)	32 times (0101)	64 times (0110)
Measurement time (ms)	3.6	5.2	8.4	14.8	27.6	53.2	104.4
Precision (PaRMS)	5		2.5		1.2	0.9	0.5



Table 9 Estimated current consumption (uA)

Oversampling (PRC[3:0]) Measurements pr sec.(PM_RATE([2:0])	Single (0000)	2 times (0001)	4 times (0010)	8 times (0011)	16 times (0100)	32 times (0101)	64 times (0110)
1 (000)	2.1	2.7	3.8	6.1	11	20	38
2 (001)							
4 (010)							
8 (011)			nt consul te * Curre	•			
16 (100)							n.a.
32 (101)						n.a.	n.a.
64 (110)					n.a.	n.a.	n.a.
128 (111)			n.a.	n.a.	n.a.	n.a.	n.a.

Note: The table shows the possible combinations of Pressure Measurement Rate and oversampling when no temperature measurements are performed. When temperature measurements are performed the possible combinations are limited to Ratetemperature x Measurement Timetemperature + Ratepressure x Measurement Timepressure < 1 second.

8.4Temperature Configuration (TMP_CFG)

Configuration of temperature measurement rate (TMP_RATE) and resolution (TMP_PRC).

TMP_CFG				Address:			07H
Temperature	measureme	ent configur	ation R	eset value:			00H
7	6	5	4	3	2	1	0
TMP_EXT	Т	MP_RATE[[2:0]	-		TMP_PRC[2	::0]
rw		rw		-		rw	
Field	Bits	Туре	Descript	ion			
TMP_EXT	7	rw	Tempera	ature measu	rement		
			0 - Interr	nal sensor (ii	n ASIC)		
			1 - Exter	rnal sensor (in pressure	sensor MEM	IS element)
			Note: Th	nis bit must l	pe set to '1'.		



TMP_RATE[2:0]	6:4	rw	Temperature measurement rate:
			000 - 1 measurement pr. sec.
			001 - 2 measurements pr. sec.
			010 - 4 measurements pr. sec.
			011 - 8 measurements pr. sec.
			100 - 16 measurements pr. sec.
			101 - 32 measurements pr. sec.
			110 - 64 measurements pr. sec.
			111 - 128 measurements pr. sec.
			Applicable for measurements in Background mode only
-	3	-	Reserved.
TMP_PRC[2:0]	2:0	rw	Temperature oversampling (precision):
			000 - single. (Default) - Measurement time 3.6 ms.
			Note: Following are optional, and may not be relevant:
			001 - 2 times.
			010 - 4 times.
			011 - 8 times.
			100 - 16 times.
			101 - 32 times.
			110 - 64 times.

8.5Sensor Operating Mode and Status (MEAS_CFG)

Setup measurement mode.

MEAS_CFG Measurement configuration						Re	Address eset value:			08H 00H
7	6			5	4		3	2	1	0
COEF_RDY	SENSOR	R_RDY	ΤM	IP_RDY	PRS_F	RDY	-	MEAS_CTRL		
r	r			r	r		-		rw	
Field		Bits		Туре	Des	cripti	ion			
COEF_RD	Y	7	r		afte	Coefficients will be read to the Coefficients Register after start- up: 0 - Coefficients are not available yet. 1 - Coefficients are available.				



SENSOR_RDY	6	r	The pressure sensor is running through self-initialization after start-up.
			0 - Sensor initialization not complete
			1 - Sensor initialization complete
			It is not recommended to start measurements until the sensor has completed the self-initialization.
TMP_RDY	5	r	Temperature measurement ready
			1 - New temperature measurement is ready.Cleared when temperature measurement is read.
PRS_RDY	4	r	Pressure measurement ready
			 New pressure measurement is ready. Cleared when procurement measurement is read.
_	3	-	Reserved.
MEAS_CTRL	2:0	rw	Set measurement mode and type:
			Standby Mode
			000 - Idle / Stop background measurement
			Command Mode
			001 - Pressure measurement
			010 - Temperature measurement
			011 - na.
			100 - na.
			Background Mode
			101 - Continuous pressure measurement
			110 - Continuous temperature measurement
			111 - Continuous pressure and temperature
			measurement

8.6FIFO configuration (CFG_REG)

Configuration of measurement data shift, and FIFO enable.

CFG_REG			Address			09H	
Configuration	on register		Re	eset value:			00H
7	6	5	4	3	2	1	0
-	-	-	-	T_SHIFT	P_SHIFT	FIFO_EN	-
-	-	-	-	rw	rw	rw	-



Field	Bits	Type	Description
-	7:4	-	-
T_SHIFT	3	rw	Temperature result bit-shift
			0 - no shift.
			1 - shift result right in data register.
			Note: Must be set to '1' when the oversampling rate is >8 times.
P_SHIFT	2	rw	Pressure result bit-shift
			0 - no shift.
			1 - shift result right in data register.
			Note: Must be set to '1' when the oversampling rate is >8 times.
FIFO_EN	1	rw	Enable the FIFO:
			0 - Disable.
			1 - Enable.
-	0	-	-

8.7FIFO Status (FIFO_STS)

FIFO status register

FIFO_STS	Address	0BH
FIFO status register	Reset value:	00H

7	6	5	4	3	2	1	0
			-			FIFO_FUL	FIFO_EMPT
						L	Υ

		_	l l
Field	Bits	Type	Description
-	7:2	-	Reserved.
FIFO_FULL	1	r	0 - The FIFO is not full
			1 - The FIFO is full
FIFO_EMPTY	0	r	0 - The FIFO is not empty
			1 - The FIFO is empty



8.8Soft Reset and FIFO flush (RESET)

RESET			dress:				0CH
FIFO flush and soft reset		Reset value:					00H
7	6	4	3	2	1	0	
FIFO_FLUSH	-			-			
W	-					W	
Field	Bits	Type Description		า			
FIFO_FLUSH	7	w	FIFO flush				

Field	Bits	Type	Description			
FIFO_FLUSH	7	w	FIFO flush			
			1 - Empty FIFO			
			After reading out all data from the FIFO, write '1' to clear			
			all old data.			
-	6:4	-	Reserved.			
SOFT_RST	3:0	W	Write '1001' to generate a soft reset. A soft reset will run through the same sequences as in power-on reset.			

8.9Product and Revision ID (ID)

Product and Revision ID.

IDAddress0DHProduct and revision IDReset value:0x10H

	7	6	5	4	3	2	1	0
		PROI	D_ID			REV_	ID	
,	r					r	•	

Field	Bits	Type	Description
PROD_ID	7:4	r	Product ID
REV_ID	3:0	r	Revision ID



8.10 Calibration Coefficients (COEF)

The Calibration Coefficients register contains the 2's complement coefficients that are used to calculate the compensated pressure and temperature values.

Table 10 Calibration Coefficients

Coefficient	Addr.	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
с0	0x10	c0 [11:4	c0 [11:4]						
c0/c1	0x11	c0 [3:0]	c0 [3:0] c1 [11:8]						
c1	0x12	c1[7:0]	c1[7:0]						
c00	0x13	c00 [19):12]						
c00	0x14	c00 [11	c00 [11:4]						
c00/c10	0x15	c00 [3:0	c00 [3:0] c10 [19:16]						
c10	0x16	c10 [15	c10 [15:8]						
c10	0x17	c10 [7:	c10 [7:0]						
c01	0x18	c01 [15	c01 [15:8]						
c01	0x19	c01 [7:0]							
c11	0x1A	c11 [15	c11 [15:8]						
c11	0x1B	c11 [7:0	c11 [7:0]						
c20	0x1C	c20 [15	c20 [15:8]						
c20	0x1D	c20 [7:0]							
c21	0x1E	c21 [15:8]							
c21	0x1F	c21 [7:0]							
c30	0x20	c30 [15:8]							
c30	0x21	c30 [7:0]							



9. Mechanical characteristics

9.1Pin configuration

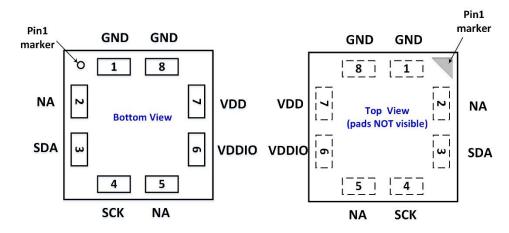


Figure 3: Layout pin configuration SPL13-001 (bottom view and top view)

Table 11: Pin configuration of SPL13-001

Pin	Name	I2C
1	GND	Ground
2	NA	Not available
3	SDA	Serial data in/out
4	SCK	Serial Clock
5	NA	Not available
6	VDDIO	Digital supply voltage for digital blocks and I/O interface
7	VDD	Supply voltage for analog blocks
8	GND	Ground



9.2 Outline dimensions

The sensor is an 8-pin metal housing LGA $3.65 \times 3.65 \times 1.45$ mm³ package. Its dimensions are depicted in Figure 4.

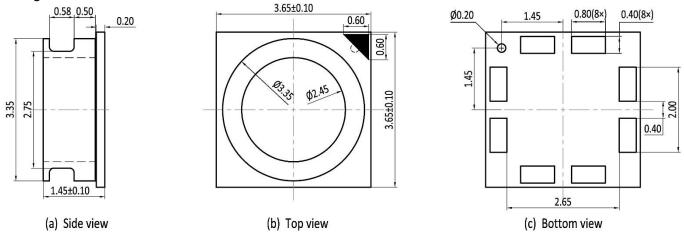


Figure 4: SPL13-001 outline and mechanical data

Note: General tolerances are ±0.05mm.

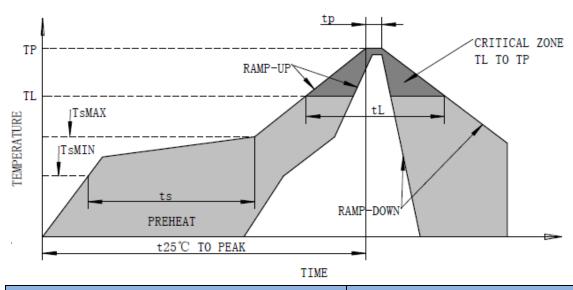
10. Storage and transportation

- Keep in warehouse with less than 75% humidity and without sudden temperature change, acid air, any other harmful air or strong magnetic field.
- The MEMS pressure sensor with normal pack can be transported by ordinary conveyances. Please protect products against moist, shock, sunburn and pressure during transportation.
- Storage Temperature Range: -40°C∼+125°C
- Operating Temperature Range: -40°C∼+85°C



11. Soldering recommendation

Recommended solder reflow for flex board:



Profile Feature	Pb-Free Assembly
Average ramp-up rate(TsMAX to TP)	2°C /seconds max
Preheat	
-Temperature Min.(TsMIN)	130°C
-Temperature Max.(TsMAX)	200°C
-Time(TsMIN to TsMAX)(Ts)	$90{\sim}110$ seconds
Time maintained above:	
-Temperature(TL)	217°C
-Time(tL)	50∼60 seconds
Ramp time of Ts to TL	15-25 seconds
Time 25°C to peak temperature	300 seconds max
Peak temperature(TP)	235-240 °C
Ramp-down rate (peak to 217°C)	2~4°C /seconds



12. Package specifications

Carrier Tape Information [Unit: mm] Quantity per reel: 4.0 kpcs.

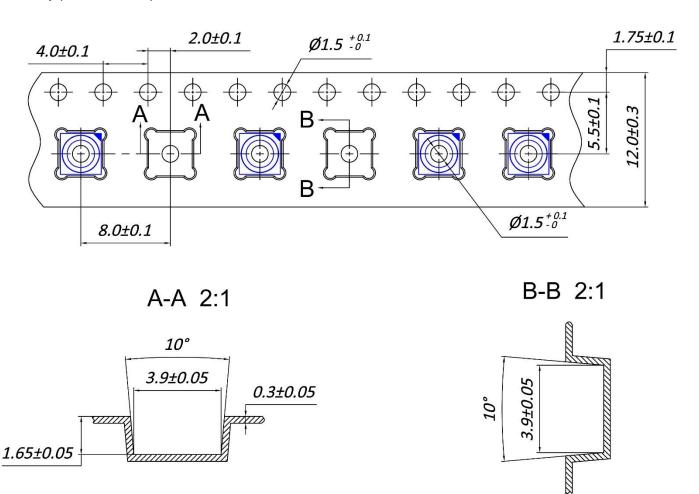


Figure 5: Carrier Tape (1)



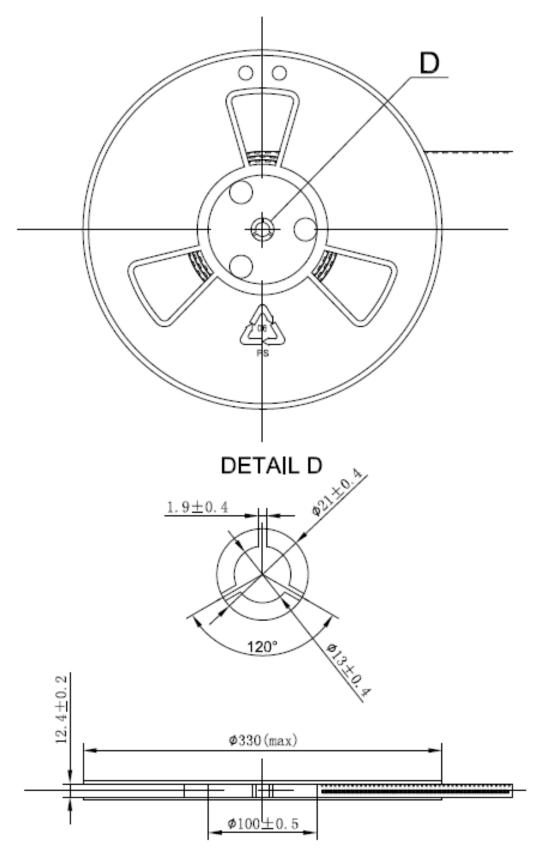


Figure 6: Carrier Tape (2)



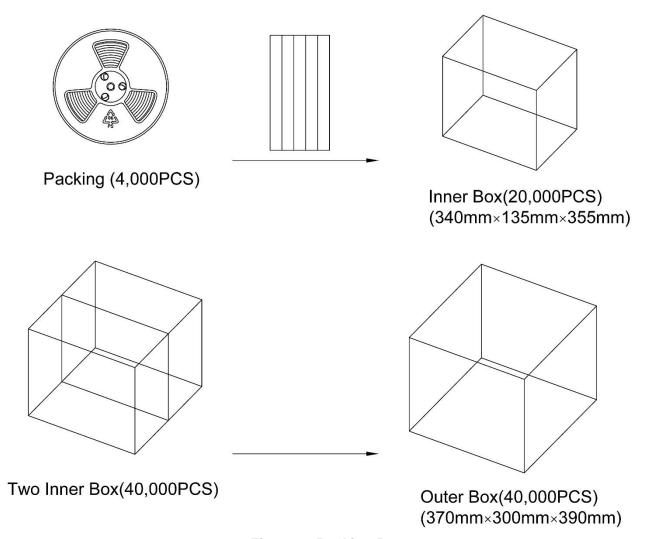


Figure 7: Packing Box