# System of Linear Equations

**Example** A manufacturer produces two kinds of toys: wooden cars and wooden trains. The amounts of two raw materials needed to product 1 piece of toys are given in the table.

	car	train
wood	2	3
paint	5	4

Determine the number of cars and trains produced on a given day, when we know that for the production there were used 540 units of wood and 1070 units of paint.

# Systems of linear equations (SLE)

#### **Definition**

The system of equations

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

where the numbers  $a_{ij} (i \in \{1, ..., m\}, j \in \{1, ..., n\})$  and  $b_k (k \in \{1, ..., m\})$  are known, the variables  $x_1, ..., x_n$  are unknown, is called a system of linear equations.

- $a_{ij}$ : the coefficients of the system of linear equations
- $b_k$ : the constant terms

The coefficient matrix and the augmented matrix:

$$A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & \dots & a_{2n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \quad \text{and} \quad A|b = \begin{pmatrix} a_{11} & \dots & a_{1n} & b_1 \\ a_{21} & \dots & a_{2n} & b_2 \\ \vdots & & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} & b_m \end{pmatrix}.$$

The right-hand side vector and the solution vector

$$b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \quad \text{and} \quad x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

The corresponding matrix-vector equation: Ax = b.

# Solvability of systems of linear equations

#### Definition

The system of linear equations is

- solvable if there exists at least one solution, that is, an x such that Ax = b holds; determined if there is exactly 1 solution; undetermined if there are more than 1 solutions;
- inconsistent if it doesn't have a solution.

#### Remark

The SLE can be solved if and only if the vector b can be expressed as a linear combination of the column vectors of A. This means, that b is in the subspace spanned by the column vectors of A.

If b can be expressed uniquely (i.e. the columns vectors of A are linearly independent), then there exists a unique solution.

If the column vectors of A are linearly dependent, and b is in the subspace spanned by the column vectors of A, then there are infinitely many solutions.

#### Definition

The rank of a matrix is the rank of the system of column vectors of the matrix. Notation: rank(A).

## Condition on solvability

- A system of lin. eq.s is solvable if, and only if  $rank(A) = rank(A \mid b)$ .
- If it is solvable and rank(A) = n (where n is the number of unknown parameters), then the system is determined, if rank(A) < n, then undetermined.

# Solutions of a system of linear equations

#### Definition

A system of linear equations is homogeneous if b = 0, thus then the matrix equation has the form Ax = 0. Otherwise it's called nonhomogeneous.

**Remark:** 0 is a solution of any homogenous system of linear equations (it is the trivial solution).

#### Theorem

A homogeneous system of linear equations has a nontrivial solution if and only if the column vectors of A are linearly dependent.

### Solutions of a homogeneous system of linear equations

The solutions of a real homogeneous system of linear equations form a vector subspace of  $\mathbb{R}^n$  with dimension n - rank(A).

### Solutions of a nonhomogeneous system of linear equations

The solutions of a (solvable) nonhomogeneous system of linear equations Ax = b are of the form  $x^* + y$ , where

- $x^*$  is a particular solution of the system of linear equations;
- y is an arbitrary solution of the corresponding homogeneous system of linear equation, that is Ax = 0.

### Solving a system of linear equations with Gaussian elimination

The set of solutions of a system of linear equations does not change, if we

- multiply an equation by a nonzero constant;
- add a scalar multiple of an equation to another equation;
- interchange two equations:
- discard an equation which is a scalar multiple of another equation.

We eliminate the numbers under the main diagonal with the modifications above. The resulting system is easier to solve.

- If during the process we obtain a row like  $(0...0 \neq 0)$ , then the system of linear equations has no solution.
- If at the end of the process there are n number of not identically 0 rows, then the system is determined (there is a unique solution), if fewer number of rows remains, then undetermined (infinitely many solutions). (Here n is the number of the unknown parameters.)

#### Example

Solve the system Ax = b using Gaussian elimination. .

$$A = \begin{pmatrix} 2 & 2 & 3 \\ -4 & -1 & -5 \\ -2 & 4 & 0 \end{pmatrix}, \quad b = \begin{pmatrix} -4 \\ 12 \\ 10 \end{pmatrix}$$

Solution:

$$\begin{pmatrix} 2 & 2 & 3 & | & -4 \\ -4 & -1 & -5 & | & 12 \\ -2 & 4 & 0 & | & 10 \end{pmatrix} \longrightarrow \begin{pmatrix} 2 & 2 & 3 & | & -4 \\ 0 & 3 & 1 & | & 4 \\ 0 & 6 & 3 & | & 6 \end{pmatrix}$$
$$\longrightarrow \begin{pmatrix} 2 & 2 & 3 & | & -4 \\ 0 & 3 & 1 & | & 4 \\ 0 & 0 & 1 & | & -2 \end{pmatrix}$$
$$\begin{pmatrix} 2 & 2 & 3 & | & -4 \\ 0 & 3 & 1 & | & 4 \\ 0 & 0 & 1 & | & -2 \end{pmatrix}$$

Backward substitution:

$$x_3 = -2$$
  
 $3x_2 + x_3 = 4$   $\rightarrow x_2 = 2$   
 $2x_1 + 2x_2 + 3x_3 = -4$   $\rightarrow x_1 = -1$ 

# Rank, Determinant

The following operations do not change the rank of a matrix A:

- Interchanging 2 rows of A.
- Multiplying a row of A by a scalar  $\lambda \neq 0$ .
- Adding a scalar multiple of a row to another row.
- The determinant doesn't change if we add a scalar multiple of a row to another row.
- If we interchange 2 rows of A, then the sign of the determinant changes.
- The determinant of a triangular matrix is the product of the elements of the main diagonal.
- $\implies$  Gaussian elimination can be used for computation of rank(A) and det(A).

### Example

Calculate rank(A) and det(A).

$$A = \left(\begin{array}{rrr} 3 & 5 & -6 \\ -1 & -2 & 1 \\ 2 & 6 & 5 \end{array}\right)$$

# **Solution:**

$$A = \begin{pmatrix} 3 & 5 & -6 \\ -1 & -2 & 1 \\ 2 & 6 & 5 \end{pmatrix} \longrightarrow \begin{pmatrix} -1 & -2 & 1 \\ 3 & 5 & -6 \\ 2 & 6 & 5 \end{pmatrix} \longrightarrow \begin{pmatrix} -1 & -2 & 1 \\ 0 & -1 & -3 \\ 0 & 2 & 7 \end{pmatrix}$$

$$\longrightarrow \begin{pmatrix} -1 & -2 & 1 \\ 0 & -1 & -3 \\ 0 & 0 & 1 \end{pmatrix} \implies \operatorname{rank}(A) = 3$$

The determinant of the last matrix is  $(-1)(-1)\cdot 1 = 1$ . During the calculations we interchanged the rows of A only once, so  $\det(A) = -1$ .