Assignment #3

Due dates:

Tests (for Parts 1 and 2): Monday, 12 February 2024, 8:00 pm Code (for Parts 1 and 2): Friday, 16 February 2024, 8:00 pm

- For all programming questions below, write your solutions in the dialect of C++ used in class. You may use the following libraries, and no others: iostream, string, cassert. You may not use vector this time.
- There are 4 Marmoset projects for this assignment. They are named a3p1t, a3p1c, a3p2t and a3p2t.
 - a3p1t and a3p2t will evaluate your tests using our solutions.
 - a3p1c and a3p2c will evaluate your solutions using our tests.
- As usual, test coverage will be assessed by running your tests on the staff code. For a3p2t the required coverage is 95% (the provided tests already get 89% coverage). For a3p1t the provided tests already achieve 100% coverage, but they contain memory leaks that you will have to fix in order to get full marks.
- For each question, 90% of your grade is your code/solution and 10% is your tests. This means your final grade for this assignment will be:

```
(a3p1c\_grade \times 0.9 + a3p1t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0.9 + a3p2t\_grade \times 0.1) \times 0.5 + (a3p2c\_grade \times 0
```

- Valgrind will be evaluated on this assignment. If you remove an element, nuke a list, or anything like that, don't forget to clean up after yourself.
 - The correctness test in the 't' Marmoset projects now run your code using Valgrind. To pass it your tests will have to be correct **and** not cause any Valgrind errors.
 - All the tests in the 'c' Marmoset projects now run your code using Valgrind as well. To pass the tests in the 'c' Marmoset projects your solution must produce the correct output **and** not cause any Valgrind errors.

To run your code with Valgrind, use the provided run_valgrind.sh script.

- The validity check functions (isValidNode, isValidStew and isValidStack) only have public tests on Marmoset. These functions are intended as tools to help you debug. Implement them well and they will save you a lot of time debugging.
- You need to write your unit tests using GTest framework. Give your tests some meaningful names to understand where you should look at in the case of test failures. The provided tests use the Given-When-Then approach for unit test naming, we recommend you do the same.

Key ideas in this assignment

- · Linked data structures
- · Procedure pre-conditions and post-conditions
- Data structure representational invariants (i.e., isValidXXX conditions)
- Engineering as proactive analysis of failure:
 - proactively identify invalid structures and embed them in test cases (done for you)
 - design isValidXXX checks to detect the invalid structures
 - use isValidXXX checks to prevent your operations from producing invalid structures

Part I: Stew (Inspired by Stack + Queue) - 50%

We're going to implement a doubly-linked list — let's call it a Stew, because it's a bit like both a Stack and a Queue — that allows new elements to be added / removed / peeked at both ends of the list. The Stew ADT supports the following operations: initStew, isEmpty, addFront, leaveFront, peekFront, addBack, leaveBack, peekBack, toString, and nuke. We will provide implementations for initStew and isEmpty; they do what you would expect. The next three operations operate on the front of the list, while the three that follow those operate on the back. toString creates a string version of the current contents (format info below), and nuke deletes all of the heap-based storage associated with a given Stew instance.

We're going to use Nodes that have links in both directions (forwards and backwards), plus we're going to keep two special pointers: one to the first element and one to the last element. A Stew with three elements, alpha, beta, gamma, will look like the following:

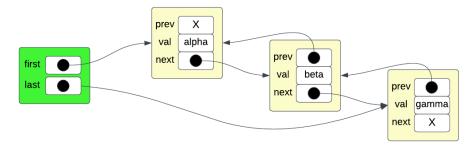


Figure 1: A doubly linked list.

Here are the struct definitions:

```
struct Node {
    std::string val;
    Node* next;
    Node* prev;
};
struct Stew {
    Node* first;
    Node* last;
};
```

Notes:

- You must implement the Stew as a doubly-linked list, building on the code we have provided.
- You may not use a vector or any other C++ library data structure to do the work for you.

Todo:

- 1. Define the validity check function isValidNode so that it passes the provided tests. Note that simply returning **true** will pass some tests, and simply triggering an assertion will pass some tests. The challenge is to pass all the tests. Examples of what you want to consider for a given Node n are:
 - (a) n.prev and n.next should not point back to n.
 - (b) If n.next is not nullptr, then n.next -> prev should point back to n.

The provided tests in a3p1Test.cc contains more about what is expected for inValidNode. There are no secret tests for this function.

2. Define isValidStew so that it passes the provided tests. Ditto about passing all the tests. Note that every node in a valid Stew should be a valid node. There are no secret tests for this function.

3. Define nuke which takes a Stew, deletes all of the internal Nodes, and sets the first and last pointers of the Stew instance to nullptr. nuke's pre-condition is assert (isValidStew(s)), and its post-condition is assert (isEmpty(s)).

4. Define addFront, leaveFront, and peekFront similar to how they were done in class, but make sure you adjust all pointers appropriately and delete no longer needed struct instances. The pre-conditions (first lines) and post-conditions (last lines) of each procedure should be some appropriate combination of:

```
assert(isEmpty(s)); assert(!isEmpty(s)); assert(isValidStew(s));
```

5. Define addBack, leaveBack, and peekBack similar to how they were done in class, but make sure you adjust all pointers appropriately and delete any struct instances which are no longer needed. Note that addBack adds new elements to the *end* of the list. The pre-conditions (first lines) and post-conditions (last lines) of each procedure should be some appropriate combination of:

```
assert(isEmpty(s)); assert(!isEmpty(s)); assert(isValidStew(s));
```

6. Define toString which takes a Stew and a single char (the direction: 'f' for forward and 'r' for reverse), and returns a string that represents the Stew's current state given the specified reading direction; the string representation should be enclosed in square brackets and the values separated by commas. For example, if a Stew s contains the elements ape, bat, and cat in order, then toString (s, 'f') should return "[ape, bat, cat]". If the direction passed in is not 'f' or 'r', then it should returns a (string) error message as the value of the function containing the (illegal) direction. e.g., toString(s, 'k') should return as its value: "Error, illegal direction: (k)". If an illegal direction is detected, just return that message; don't try to iterate over the Stew instance, and don't make an assertion that could cause the program to abort.

Part II: ChunkyStack (Inspired by B-Trees) - 50%

In considering the various ways of implementing data structures, we have tended to prefer linked list approaches over, say, statically allocated approaches. For example, if we were limited to only statically allocated storage, then one way to implement a stack would be by using an array to hold the elements, and keeping track of the top element by keeping an integer index to the top element, as depicted in Figure 2.

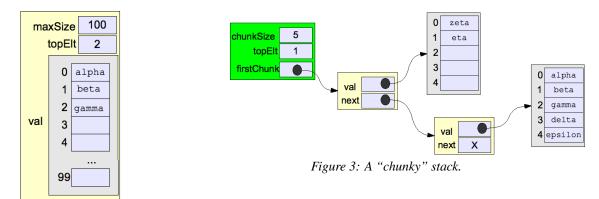


Figure 2: A stack implemented by a statically allocated array.

The obvious disadvantage of this approach is that there is an upper bound on how many elements the stack can hold at the same time (here, the bound is 100). Additionally, you must allocate the whole array at once; if you were using only a small percentage of the available elements most of the time, then you could be wasting a lot of space depending on how big the array was.¹ The advantages of this approach over a linked list are simplicity and speed: linked lists are easy to get wrong, and with an array you have direct access to all elements (that's not much of an advantage for a stack, but it would be if the ADT required immediate access to any given element).

Compare this to using a linked list approach as done in class. Each element is stored in its own node, so there is a storage overhead of one pointer (typically, about four bytes) per element. Also, while creating and deleting new nodes are constant time operations in principle, if real-time performance is a big concern they can be relatively expensive operations compared to just accessing an array element.

We're going to investigate a hybrid approach inspired by B-trees (which you will learn about in later courses), which we're going to call a Chunky Stack. Basically, we're going to use a linked list approach, but instead of just one element each node will contain an array of chunkSize elements, for some constant chunkSize. This means that the stack will be unbounded, but that there will be an storage overhead of only one pointer per chunkSize elements (instead of one per element). Of course, this might mean some wasted space, but that will amount to at most chunkSize-1 elements at any given moment. The second diagram shows an example of a Chunk Stack with seven elements and a chunkSize of 5. The order of insertion was: alpha, beta, gamma, delta, epsilon, zeta, eta.

Note that because we want to be flexible about the chunk size, you will have to use a dynamically allocated array as discussed in class (and *not* a vector!). We are also going to be using two different kinds of structs, one called Stack for the stack itself (the green box) and one called NodeChunk for the various nodes (the pale yellow boxes) that store the elements (or more precisely, store pointers to the dynamic arrays that store the elements).

Provided in your repository:

```
struct NodeChunk {
    // val is a ptr to array of strings
    std::string* val;
    NodeChunk* next;
};

void initStack(const int chunkSize, Stack& s);
bool isEmpty(const Stack& s);
NodeChunk* createNewNodeChunk(const int chunkSize);
struct Stack{
    int chunkSize;
    int topElt;
    NodeChunk* firstChunk;
};
```

Tests for isValidStack(s) are provided in your repository.

Todo:

- 1. Implement isValidStack(s) to pass the provided tests. There are no secret tests for isValidStack(s).
- 2. Write pre-conditions and post-conditions where appropriate. In some cases there might be no pre-conditions or post-conditions. In some cases they must just be assert (isValidStack(s)). Be cautious about using other operations in pre-conditions or post-conditions maybe save that for tests. The operations are:

```
void nuke(Stack& s);
void push(std::string val, Stack& s);
void pop(Stack& s);
int size(const Stack& s);
void swap(Stack& s);
std::string toString(const Stack& s);
std::string top(const Stack& s);
```

¹Yes, vectors don't have these problems, but they use dynamically allocated storage under the hood.

Notes:

• Two different chunky stacks can have different chunk sizes. Within a chunky stack all chunks will have the same size.

```
Stack s1;
initStack(5,s1);  // all chunks in s1 will be size 5
Stack s2;
initStack(100,s2); // all chunks in s2 will be size 100
```

- The nuke function should take a Stack and delete all of its internal NodeChunks and their dynamic arrays. Once all the heap allocated memory has been freed, it should then set s.firstChunk to nullptr and s.topElt to-1. Do not change the value of s.chunkSize. The post-conditions of nuke should be isValidStack and isEmpty. The pre-condition should be isValidStack. Nuking an empty stack shouldn't do anything.
- The procedures push and top do what you expect. However, push needs to check if the current first NodeChunk is full; if so, another NodeChunk needs to be allocated and linked in place.
- When a NodeChunk is initialized, every element in the val array points to the special value UNUSED_SLOT defined as a macro in a3p2.h. When an element is popped off the stack then the array index in val that referred to it should be reset to UNUSED_SLOT. You do not need to **delete** the string objects as they are popped off the stack.
- The procedure pop needs to check if the element being removed is the last one in the current first NodeChunk; if so, that NodeChunk should be deleted (and so should its dynamic array), and the appropriate links should be adjusted. An empty Chunky Stack should have firstChunk = nullptr.
- The procedure size should return the current number of elements in the Stack; it would return 7 for the example in the diagram. This is going to require traversing the chunks and adding things up.
- The procedure swap should swap the top two elements. In the example shown in the diagram zeta and eta would change positions. In general, there is one tricky case you have to consider. Note that it's an error if swap is called when there are fewer than two elements; you should use assert to check this pre-condition.

Implementation strategies:

There are at least two ways to go about implementing these procedures:

- 1. First, implement all procedures for the simple case where the data fits within a single chunk. When those are tested, verified, committed, and pushed, then start thinking about larger data that spreads across multiple chunks.
- 2. Choose one procedure at a time and implement it for both the small case (data fits within a chunk) and the large case (data spread across multiple chunks). Think strategically about the order in which to implement the procedures.

Whichever implementation strategy you choose, you should always:

- Implement the validity check first. We have provided you some tests for this so you can see what it looks like to design tests for test-driven development. Each test we provided basically corresponds to a line of our implementation.
- Put appropriate pre-conditions and post-conditions in every procedure first.
- Work in a **test-driven** manner (**TDD**). Don't write code until you have the test cases ready. Then write code to pass those test cases (while not failing previous passing test cases). This way you won't write bugs. Build solid code incrementally.