## Milnor's Definition of a Manifold

The aim of this document is to compare the definitions of an n-manifold as in [MS74] and [Lee00]. For convenience, we shall refer to smooth n-manifolds according to [MS74] "Milnor n-manifolds". What we call a "chart n-manifold" is precisely a smooth n-manifolds according to, for example, [Lee00] except that we do not assume the underlying topological space to be second countable.

Convention 1.  $\mathbb{R}^n$  will be viewed both as a chart n-manifold and a Milnor n-manifold with the singleton chart and the singleton local parametrisation respectively.

**Notation 2.** For topological spaces A and B, " $A \subseteq_{o} B$ " means "A is an open subspace of B".

**Notation 3.** Given a chart n-manifold M, let  $F_M$  denote the set of smooth (in the "chart sense") real valued functions on M. Let  $i: M \to \mathbb{R}^{F_M}$  denote the evaluation map.

**Proposition 4.** Let M be a chart n-manifold. Then, i(M) is canonically a Milnor manifold.

*Proof.* Fix  $x \in M$ . Let  $\alpha : \mathbb{R}^n \to U \subseteq_{o} M$  be a chart around x in the maximal atlas of M. We claim that the composition

$$\beta: \mathbb{R}^n \xrightarrow{\alpha} U \xrightarrow{i} i(U) \subseteq \mathbb{R}^{F_M}$$

is a local parametrisation around i(x). In order to prove this, it is sufficient to show the following:

- (1)  $\beta$  is smooth.
- (2) For all  $y \in \mathbb{R}^n$ ,  $D\beta|_y$  has rank n.
- (3)  $Im(\beta)$  is open and  $\beta$  is a homeomorphism onto its image.

For  $f \in F_M$ , let  $\pi_f : \mathbb{R}^{F_M} \to \mathbb{R}$  denote the projection to the  $f^{\text{th}}$  coordinate. Then, for any  $f \in F_M$ ,  $\pi_f \circ \beta = f|_U \circ \alpha$ , which is smooth. Hence,  $\beta$  is smooth.

For  $i=1,\ldots,n$ , let  $\psi_i:U\to\mathbb{R}$  such that  $\psi_i\circ\alpha=\pi_i$ . Clearly,  $\psi_i$  is smooth on U. Fix  $y\in\mathbb{R}^n$ . Let  $g_i\in F_M$  such that  $g_i$  agrees with  $\psi_i$  in an open neighbourhood of  $\alpha(y)$ . Consider the composition

$$\mathbb{R}^n \xrightarrow{\beta} i(M) \subseteq \mathbb{R}^{F_M} \xrightarrow{\pi_{g_1}, \dots, \pi_{g_n}} \mathbb{R}^n$$

whose components are clearly  $g_i \circ \alpha$ . Thus,

$$\left. \frac{\partial}{\partial u_j} (g_i \circ \alpha) \right|_y = \left. \frac{\partial}{\partial u_j} (\psi_i \circ \alpha) \right|_y = \left. \frac{\partial u_i}{\partial u_j} \right|_y = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

This proves (2). Lastly, suppose that  $V \subseteq_0 U$ . For all  $v \in V$ , let  $g_v \in F_M$  such that  $g_v(v) > 0$  and  $\operatorname{supp}(g_v) \subseteq V$ . Let  $\pi_{g_v}: \mathbb{R}^{F_M} \to \mathbb{R}$  denote the projection to the  $g_v^{\mathrm{th}}$  coordinate. Then,

- $\pi_{g_v}^{-1}(\mathbb{R}\setminus\{0\})\subseteq_{\mathrm{o}}\mathbb{R}^{F_M}$ .
- $i(v) \in \pi_{g_v}^{-1}(\mathbb{R} \setminus \{0\}) \cap i(M) \subseteq_{o} i(M)$ .  $i(m) \notin \pi_{g_v}^{-1}(\mathbb{R} \setminus \{0\}) \cap i(M)$  for all  $m \in M \setminus V$ .

Hence,

$$i(V) = \bigcup_{v \in V} \pi_{g_v}^{-1}(\mathbb{R} \setminus \{0\}) \cap i(M) \subseteq_{\mathrm{o}} i(M)$$

This proves (3).

**Remark 5.** In the proof of Proposition 4, we might as well have relaxed the assumption that the domain of  $\alpha$  is  $\mathbb{R}^n$  and the same argument could have been used to construct a local parametrisation. The constructed Milnor manifold structure is said to be canonical as any chart translates to a local parametrisation by pre-composition.

**Remark 6.** Proposition 4 essentially says that a chart n-manifold admits a smooth embedding into  $\mathbb{R}^A$  for some set A.

**Remark 7.** Conversely, given a Milnor n-manifold N, the local parametrisations on the underlying topological space provide an atlas for N, making it a chart n-manifold. It is also easy to see, under this correspondence, that the definitions of smooth functions (see [MS74, P.17] and [Lee00, P.34]) coincide.

## REFERENCES

[MS74] John Milnor and James Stasheff. Characteristic Classes.

[Lee00] John Lee. Introduction to Smooth Manifolds.