# Section 5.4 – Properties of Discretisation Schemes

In computational fluid dynamics (CFD), a good discretisation scheme must ensure **physical reliability** of the solution. Three essential properties are:

#### 5.4.1 Conservativeness

- Definition: A scheme is conservative if the net flux entering a control volume equals the net flux leaving adjacent volumes.
- Importance: Ensures global and local conservation of quantities like mass, momentum, or energy.
- Achieved When: The flux at a shared face between two control volumes is identically calculated from both sides (e.g., same interpolation).
- Central differencing is conservative under structured grids and steady conditions.

#### ♦ 5.4.2 Boundedness

- **Definition**: A discretisation scheme is bounded if the computed solution stays **within physical limits** (e.g.,  $0 \le \phi \le 1$ ).
- Why It Matters: Prevents unphysical oscillations and negative values.
- Mathematically: For boundedness, all coefficients in the discretised equation should be positive, and source terms non-negative or handled correctly.

⚠ Central differencing **can violate boundedness** for high convection (large Peclet number), leading to overshoots or undershoots.

#### 5.4.3 Transportiveness

- **Definition**: A scheme is transportive if it respects the **direction of flow** and accurately propagates transported quantities.
- Concept: The scheme must bias the interpolation in the direction of the flow (upstream influence).
- Failure Consequences: If a scheme lacks transportiveness, the solution smears and doesn't represent sharp gradients.

▲ Central differencing is not transportive — it doesn't prioritize upstream information.

# Section 5.5 – Assessment of the Central Differencing Scheme

This section evaluates how central differencing performs when applied to convection-diffusion problems.

#### Main Points:

- Second-order Accurate: It is mathematically more accurate in regions where the solution varies smoothly.
- 2. Fails for High Convection (Peclet Number Pe > 2):

- · Leads to non-physical oscillations.
- Cannot maintain boundedness.
- Becomes numerically unstable.
- 3. Ideal Only for Diffusion-dominant Flows:
  - Central differencing works best when convection is weak and diffusion is strong.
  - For pure convection, it's inadequate.
- 4. Alternatives Preferred for Convection-Dominant Problems:
  - Upwind scheme (first-order accurate but bounded).
  - Hybrid or QUICK schemes for better balance.

#### **✓** Conclusion of Section 5.5

While **central differencing** is attractive for its accuracy in smooth flows, it **fails the key physical properties**—boundedness and transportiveness—under high-convection conditions. Therefore, it's **not suitable** for general-purpose CFD in convection-dominated problems.

Would you like a visual mind map of these concepts or a comparison table between central, upwind, and other schemes?

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I am Not getting youre intention please explain and give the related info to the example Example 5.1

Great — let's connect these **theoretical properties** directly to **Example 5.1** so you can understand how they apply practically. I'll explain each concept in the **context of the example**.

# Quick Recap: Example 5.1 – 1D Convection-Diffusion Problem

You're solving:

$$\frac{d}{dx}(\rho u\phi) = \frac{d}{dx}\left(\Gamma\frac{d\phi}{dx}\right)$$

with:

- Domain:  $x \in [0, 1]$
- $\phi(0) = 1, \phi(1) = 0$
- Uniform grid
- Using central differencing
- Cases:
  - $u = 0.1 \rightarrow \text{diffusion-dominant}$
  - $u = 2.5 \rightarrow \text{convection-dominant}$

Now let's analyze the discretisation properties in context of this example:

### 1. Conservativeness in Example 5.1

#### ✓ What It Means:

The flux leaving one control volume face must equal the flux entering the adjacent cell at that face.

#### ✓ In This Example:

- You're using finite volume method.
- Central differencing ensures the same interpolation is used at shared faces.
- Hence, Example 5.1 is conservative.
- It respects the **local conservation of**  $\phi$  (whatever goes out of one cell enters the next).
- Conservativeness is satisfied in both low and high velocity cases.

# ♦ 2. Boundedness in Example 5.1

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The solution  $\phi$  should stay within physical bounds.

For this example:

$$0 \le \phi \le 1$$

#### ♠ In This Example:

- When  $u = 0.1 \rightarrow$  solution is smooth and stays within [0, 1].
- When  $u = 2.5 \rightarrow$  central differencing leads to:
  - Negative coefficients in the discretised matrix.
  - Overshoot/undershoot (you saw values like  $\phi \ge 1$ , even negative or > 1).
  - Violates boundedness.
- Central differencing is NOT bounded when convection dominates.

# 3. Transportiveness in Example 5.1

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The scheme should reflect the **direction of the flow** (from left to right) by giving **more weight to upstream** values.

### ▲ In This Example:

- Central differencing treats upstream and downstream faces symmetrically.
- Doesn't account for the direction of the flow.
- When u = 2.5, the solution does **not transport information** properly from left to right.
- Instead, the scheme becomes oscillatory or unstable.
- Transportiveness fails for high velocity in central differencing.

# In Summary (Applied to Example 5.1):

Property	Low Velocity ( $u = 0.1$ )	High Velocity ( $u = 2.5$ )	Status
Conservativeness	Yes (FVM ensures it)	✓ Yes	<b>✓</b> OK
Boundedness	✓ Solution is smooth	X Overshoots	<u></u> Violated
Transportiveness	▲ Symmetric but OK	✗ Not directional	Violated

### **♀** So What Does This Tell You?

- In Example 5.1:
  - Central differencing is fine for low velocities (diffusion-dominated problems).
  - $\bullet \quad \hbox{It fails for convection-dominated flows} \ -- \ \hbox{producing unstable, unphysical solutions}.$
- That's why the book **criticizes central differencing** in Section 5.5.