

## robotics @ MARYLAND

## SONAR CRIB SHEET

## 1. Constants

Table 1. Physical Constants

Symbol	Quantity	$\approx$ Metric value
$v_a$	Speed of sound in air	343  m/s
$v_w$	Speed of sound in water	1500  m/s
$Z_a$	Acoustic impedance of air (STP)	$420~\mathrm{MPa~s/m}$
$Z_w$	Acoustic impedance of water	$1.5~\mathrm{MPa~s/m}$

Table 2. AUVSI Specific Parameters

Symbol	Quantity	$\approx$ Metric value
$T_{ping}$	Ping duration	1.3 ms
$\nu_{ping}$	Ping frequency	$22 \text{ kHz} < \nu_{ping} < 30 \text{ kHz}$
$d_{ping}$	Ping wave train length	$1.95 \mathrm{m}$

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## 2. Surface echoes

A source and receiver are at depth z separated by distance R. The source emits a ping at time t=0 and arrives at the receiver at time  $t_{ping}=R/v_w$ . Then the first surface echo arrives at a time  $t_{ping}+\Delta t_{echo}$ :

$$\Delta t_{echo}(z,R) = (2\sqrt{z^2 + (R/2)^2} - R)/v_w.$$

Table 3.  $\Delta t_{echo}$  at a depth of z=3 meters

R (m)	$\Delta t_{echo} (ms)$
0	4.0
10	1.0
20	0.6
30	0.4
40	0.3
50	0.2