

view_frames Result
Recorded at time: 1741448427.6051238

map

Broadcaster: default authority
Average rate: 5.251
Buffer length: 3.999
Most recent transform: 24.001
Oldest transform: 20.002

robot_0/odom

Broadcaster: default authority
Average rate: 10.055
Buffer length: 3.978
Most recent transform: 23.154
Oldest transform: 19.176

robot_0/base_link

Broadcaster: default authority
Average rate: 333.58
Buffer length: 4.05
Most recent transform: 23.154
Oldest transform: 19.104

Broadcaster: default authority
Average rate: 333.58
Buffer length: 4.05
Most recent transform: 23.154
Oldest transform: 19.104

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Most recent transform: 0.0
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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_0/left_wheel

robot_0/right_wheel

robot_0/base_footprint

robot_0/bump_front_center

robot_0/bump_front_left

robot_0/bump_front_right

robot_0/bump_left

robot_0/bump_right

robot_0/bumper

robot_0/front_caster_link

robot_0/front_left_bottom_weight_block

robot_0/front_left_top_weight_block

robot_0/shell_link

robot_0/front_right_bottom_weight_block

robot_0/front_right_top_weight_block

robot_0/imu_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_0/front_left_tower_standoff

robot_0/front_right_tower_standoff

robot_0/oakd_camera_bracket

robot_0/rear_left_tower_standoff

robot_0/rear_right_tower_standoff

robot_0/rplidar_link

robot_0/tower_sensor_plate

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_0/oakd_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_0/oakd_imu_frame

robot_0/oakd_left_camera_frame

robot_0/oakd_rgb_camera_frame

robot_0/oakd_right_camera_frame

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_0/oakd_left_camera_optical_frame

robot_0/oakd_rgb_camera_optical_frame

robot_0/oakd_right_camera_optical_frame