



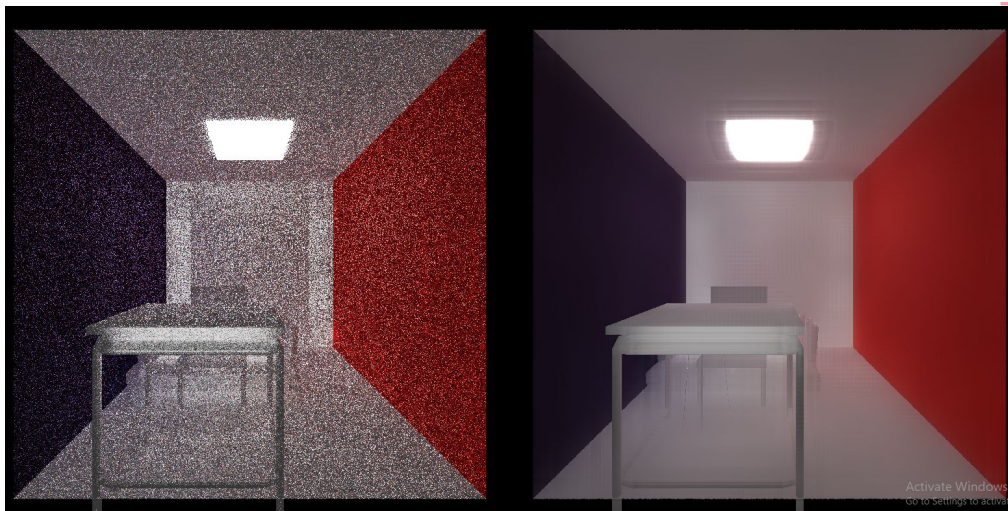
Path Tracing Denoiser

CIS 565 Final Project Milestone 2

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Overview

- Two major research areas for denoising are
 - Machine Learning
 - Hybrid Rendering
- Our project will try to implement denoising methods in both categories and compare the results.

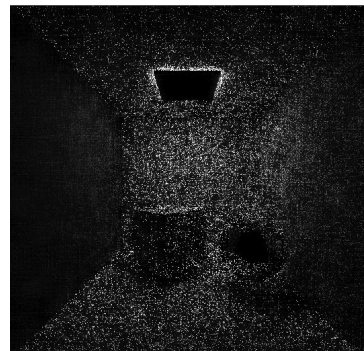


- Light 1: 26,804
- Light 2: 32,884
- Sofa: 469,348
- Chair: 924

```
KD tree finised  
Iter:1, Time:15627.9, Avg Time:15627.9  
Iter:2, Time:73793.9, Avg Time:44710.9  
Iter:3, Time:73879.9, Avg Time:54433.9
```

SVGF Progress

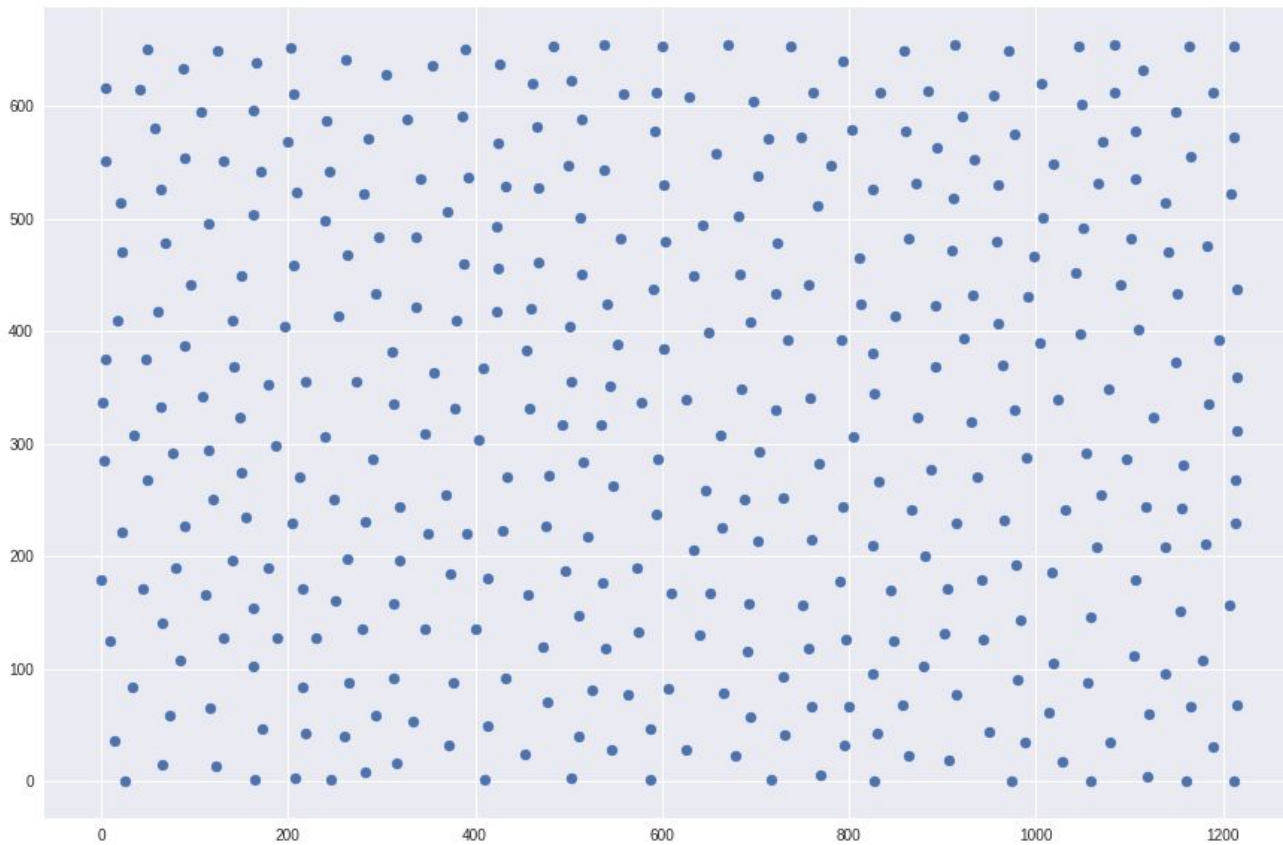
- Last MS: Spatial Filtering
 - A-Trous Wavelet Transform
- This MS: Temporal Accumulation + Variance Estimation
 - Level 1 wavelet filter updates the color history buffer.
 - Exponential moving average: $C'_i = \alpha \cdot C_i + (1 - \alpha)C'_{i-1}$
 - Variance guiding: blur more if variance is high, blur less if variance is low.
 - Approximate variance with first and second raw moment: $\sigma_i'^2 = \mu_{2_i}' - \mu_{1_i}'^2$
 - Reject samples if mesh IDs, position or normal not consistent
- Next MS: Back Projection
 - Compare current and previous NDC coordinates for each vertex.
 - Usually done in vertex shader
 - Challenge: How to find pixel correspondence between procedural shapes?



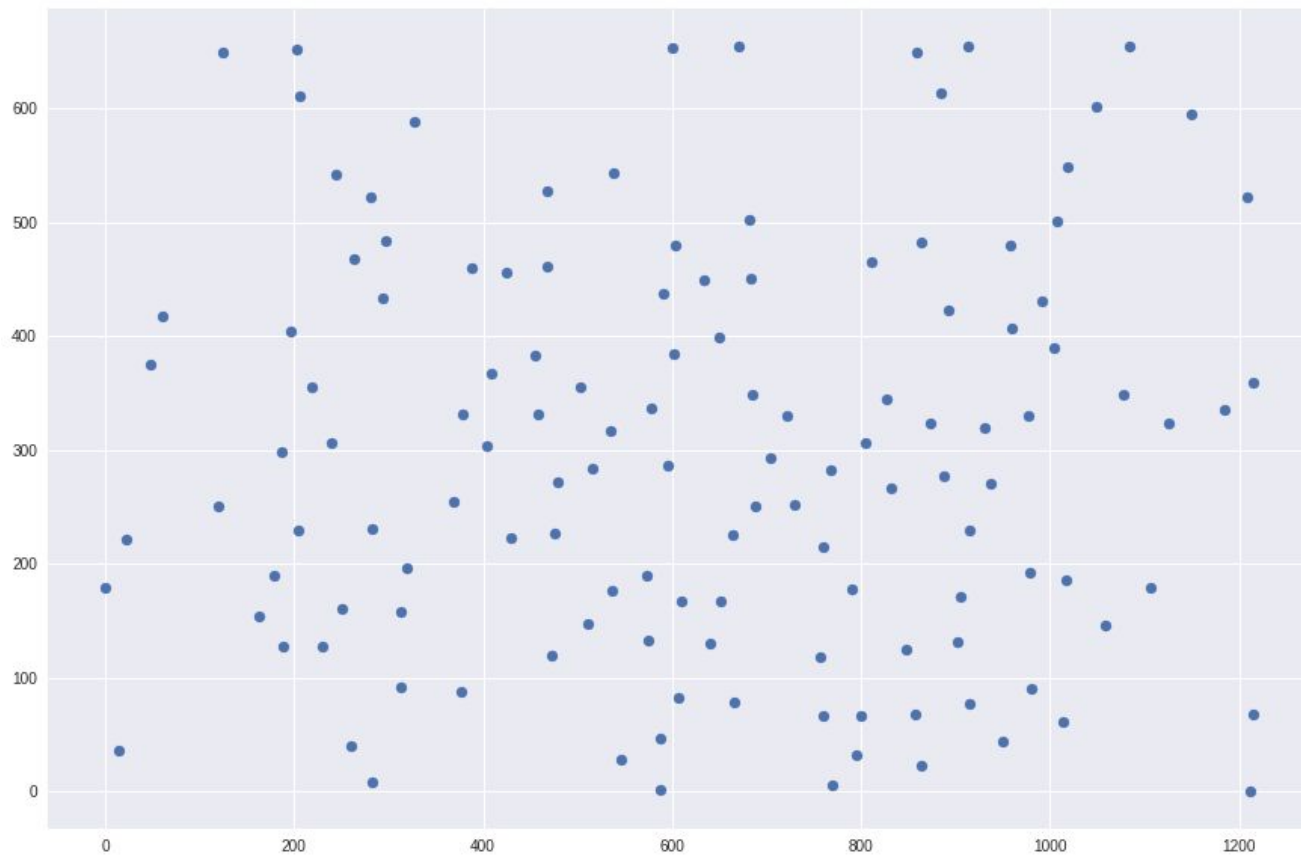
Data Preprocess

- Diffuse - Divided by albedo
- Specular - Logarithmic Transform
- Depth - Linear scaled
- Gradient in both directions

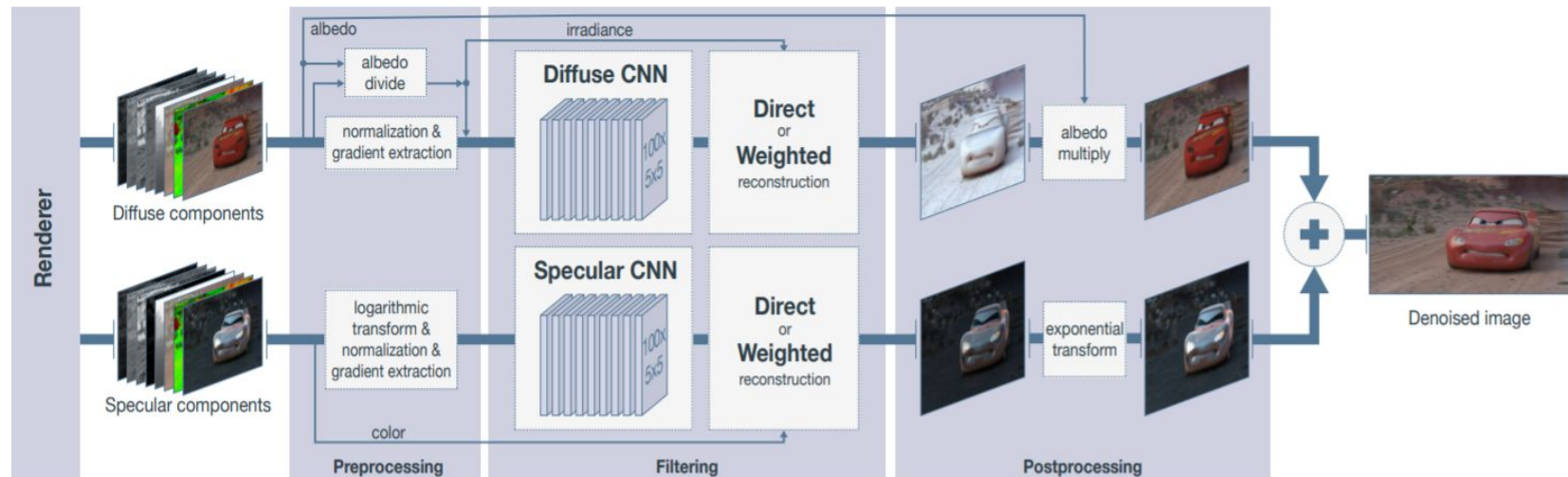
Uniform Sampling



Pruned patches



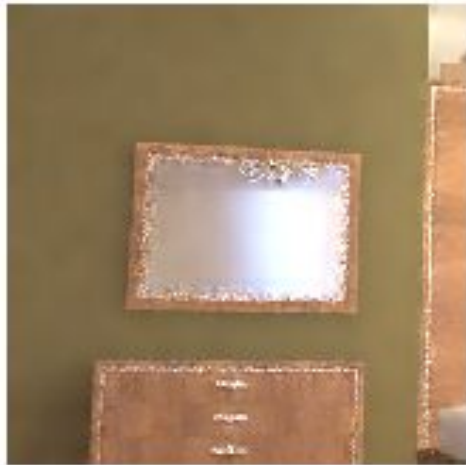
Denoising Network



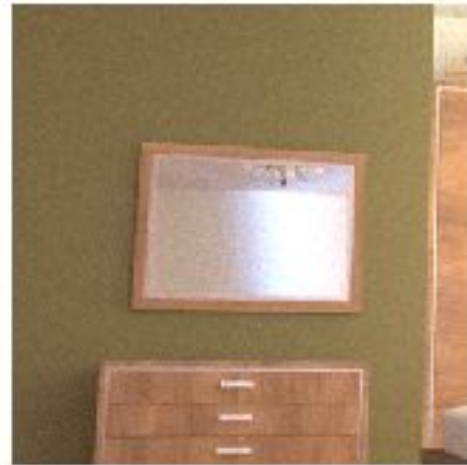
Noisy Input



Network Output



Reference



Proposed Timeline

- Milestone 1

- Revised codes from hw3 to generate data for next milestone
- Write nn framework code
- Write basic spatial filter

- Milestone 2

- **Add texture to the path tracer** and generate image data from path tracer
- Build and train denoising neural network on PyTorch first for proof of concept
- **Pytorch C++ API**
- Continue SVGF(face some problems)

- Milestone 3

- Unfinished part from milestone 2(red), blue noise
- SVGF Finish(?)
- Achieve real-time denoising for static scenes

- Final Presentation

- Different environment
- Optimization