

✓ Congratulations! You passed!

Grade received 80% Latest Submission Grade 80% To pass 80% or higher

Go to next item

1. When building a ConvNet, typically you start with some POOL layers followed by some CONV layers. True/False?

1 / 1 point

- ☐ True
- ☒ False

↗ Expand

✓ Correct

Correct. It is typical for ConvNets to use a POOL layer after some Conv layers; sometimes even one POOL layer after each CONV layer; but is not common to start with POOL layers.

2. In LeNet - 5 we can see that as we get into deeper networks the number of channels increases while the height and width of the volume decreases. True/False?

1 / 1 point

- ☒ True
- ☐ False

↗ Expand

✓ Correct

Correct, since in its implementation only valid convolutions were used, without padding, the height and width of the volume were reduced at each convolution. These were also reduced by the POOL layers, whereas the number of channels was increased from 6 to 16.

3. Training a deeper network (for example, adding additional layers to the network) allows the network to fit more complex functions and thus almost always results in lower training error. For this question, assume we're referring to "plain" networks.

1 / 1 point

- ☒ False
- ☐ True

↗ Expand

✓ Correct

Correct, Resnets are here to help us train very deep neural networks.

4. The computation of a ResNet block is expressed in the equation:

1 / 1 point

$$a^{[l+2]} = g \left(\underbrace{W^{[l+2]}}_{\text{C}} g \left(\underbrace{W^{[l+1]}}_{\text{A}} a^{[l]} + \underbrace{b^{[l+1]}}_{\text{A}} \right) + \underbrace{b^{[l+2]}}_{\text{B}} + \underbrace{a^{[l]}}_{\text{B}} \right)$$

Which part corresponds to the skip connection?

- ☐ The equation of ResNet.
- ☒ The term in the orange box, marked as B .
- ☐ The term in the blue box, marked as A .
- ☐ The term in the red box, marked as C .

 Expand

 Correct

Yes, this term is the result of the skip connection or shortcut.

5. Adding a ResNet block to the end of a network makes it deeper. Which of the following is true?

1 / 1 point

- ☐ It shifts the behavior of the network to be more like the identity function.
- ☒ The performance of the networks doesn't get hurt since the ResNet block can easily approximate the identity function.
- ☐ The number of parameters will decrease due to the shortcut connections.
- ☐ The performance of the networks is hurt since we make the network harder to train.

 Expand


 Correct

Yes, as noted in the lectures in a ResNet block the computations are given by $a^{[l+2]} = g(W^{[l+2]}a^{[l+1]} + b^{[l+2]} + a^{[l]})$ thus if $W^{[l+2]}$ and $b^{[l+2]}$ are zero then we get the identity function.


6. Suppose you have an input volume of dimension $n_H \times n_W \times n_C$. Which of the following statements do you agree with? (Assume that the “1x1 convolutional layer” below always uses a stride of 1 and no padding.)

1 / 1 point

- ☒ You can use a 2D pooling layer to reduce n_H , n_W , but not n_C .

 Correct
This is correct.

- ☐ You can use a 2D pooling layer to reduce n_H , n_W , and n_C .
- ☒ You can use a 1x1 convolutional layer to reduce n_C but not n_H and n_W .

 Correct
Yes, a 1x1 convolutional layer with a small number of filters is going to reduce n_C but will keep the dimensions n_H and n_W .

- ☐ You can use a 1x1 convolutional layer to reduce n_H , n_W , and n_C .

 Expand

 Correct

Great, you got all the right answers.

7. Which of the following are true about bottleneck layers? (Check all that apply)

0 / 1 point

- ☐ The bottleneck layer has a more powerful regularization effect than Dropout layers.
- ☒ Bottleneck layers help to compress the 1x1, 3x3, 5x5 convolutional layers in the inception network.

 This should not be selected

As the bottleneck layer doesn't regularize any of these different layers

no, the bottleneck layer doesn't combine any of these different layers.

- ☐ The use of bottlenecks doesn't seem to hurt the performance of the network.
- ☒ By adding these layers we can reduce the computational cost in the inception modules.

✓ **Correct**

Yes, by using the 1×1 convolutional layers we can reduce the depth of the volume and help reduce the computational cost of applying other convolutional layers with different filter sizes.

↗ **Expand**

✗ **Incorrect**

You didn't select all the correct answers

8. Which of the following are common reasons for using open-source implementations of ConvNets (both the model and/or weights)? Check all that apply.

1 / 1 point

- ☒ It is a convenient way to get working with an implementation of a complex ConvNet architecture.

✓ **Correct**

True

- ☐ A model trained for one computer vision task can usually be used to perform data augmentation for a different computer vision task.
- ☐ The same techniques for winning computer vision competitions, such as using multiple crops at test time, are widely used in practical deployments (or production system deployments) of ConvNets.
- ☒ Parameters trained for one computer vision task are often useful as pre-training for other computer vision tasks.

✓ **Correct**

True

↗ **Expand**

✓ **Correct**

Great, you got all the right answers.

9. Which of the following are true about Depth wise-separable convolutions? (Choose all that apply)

1 / 1 point

- ☒ They combine depthwise convolutions with pointwise convolutions.

✓ **Correct**

Correct, this combination is what we call depth wise separable convolutions.

- ☐ They are just a combination of a normal convolution and a bottleneck layer.
- ☒ They have a lower computational cost than normal convolutions.

✓ **Correct**

Yes, as seen in the lectures the use of the depthwise and pointwise convolution reduces the computational cost significantly.

- ☐ The result has always the same number of channels n_c as the input.

↗ **Expand**

✓ **Correct**

Great, you got all the right answers.

10. Suppose that in a MobileNet v2 Bottleneck block the input volume has shape $64 \times 64 \times 16$. If we use 32 filters for the expansion and 16 filters for the projection. What is the size of the input and output volume of the depthwise convolution, assuming a pad='same'?

0 / 1 point

- ☐ $32 \times 32 \times 32$ $32 \times 32 \times 32$
- ☐ $64 \times 64 \times 32$ $64 \times 64 \times 32$

☐ $64 \times 64 \times 32$ $64 \times 64 \times 16$

☒ $64 \times 64 \times 16$ $64 \times 64 \times 32$

[↗ Expand](#)



Incorrect

Incorrect, the input and output volume of the depthwise convolution are the same.