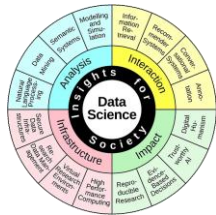


Self-Organising Systems

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- Introduction & Definitions of Self-organising Systems
- Cellular Automata
- Genetic algorithms
- Ant Colony Optimisations
 - *to be extended in swarm optimisation lectures*
- Agent Based Systems / Multi Agent Systems

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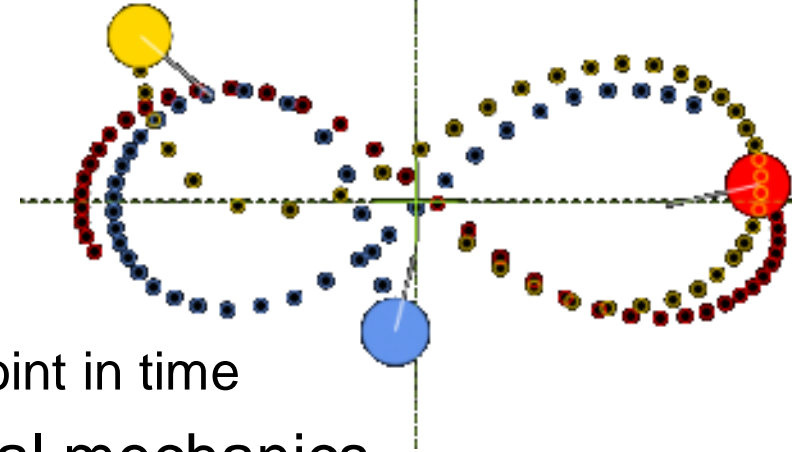
- Methods considered in this course are applicable to
 - Simulation tasks (e.g. Ants, Swarms, Agents, ..)
 - Optimisation problems (Swarms, Agents, GA, ...) / problem solving
 - Data analysis (SOM)
 - Some methods suited for more, some for just one of these tasks
- Especially for simulation: useful when the system to be modelled is ***complex***

- A system that exhibits some of these characteristics
 - Feedback loops
 - Emergent organization (appearance of unplanned organized behavior)
 - Numerosity
 - Hierarchical organization
 - Some degree of spontaneous order (robustness of the order)
 - Difficult to model top-down (e.g. with differential equations)

- Examples
 - Three-Body Problem
 - Weather Forecast
 - Ecosystems

■ Three-Body Problem

- E.g. sun, moon, earth
 - Initial set of positions, masses and velocities of the bodies, for particular point in time
- In accordance to the laws of classical mechanics
 - Newton's laws of motion and of universal gravitation
- Determining the motions of the three bodies
- No general analytical solution given by algebraic expressions and integrals; motion generally non-repeating (Henri Poincaré & Ernst Bruns, 1887)



■ Weather forecast

- Edward Lorenz in the 1950s: skeptical of appropriateness of linear statistical models in meteorology
 - Most atmospheric phenomena are non-linear

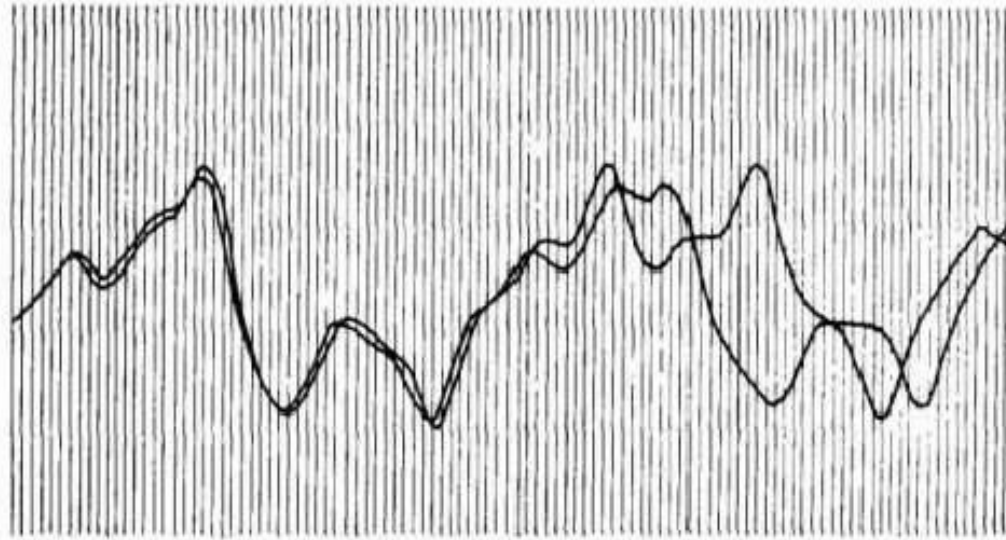
- Foundation of chaos theory: two states differing by imperceptible amounts may evolve into two considerably different states

- If there is any error in observing the present state: acceptable prediction of a future state may be impossible



■ Weather forecast

- Built a weather model based on 12 variables
 - Observed that minute changes in the initial state would create two very differing results
 - Initial state changed from 6-digit precision to 3-digit precision
 → final result not comparable anymore



0.506127 → 0.506

Introduction: Complex Systems

- Weather forecast

- Butterfly effect

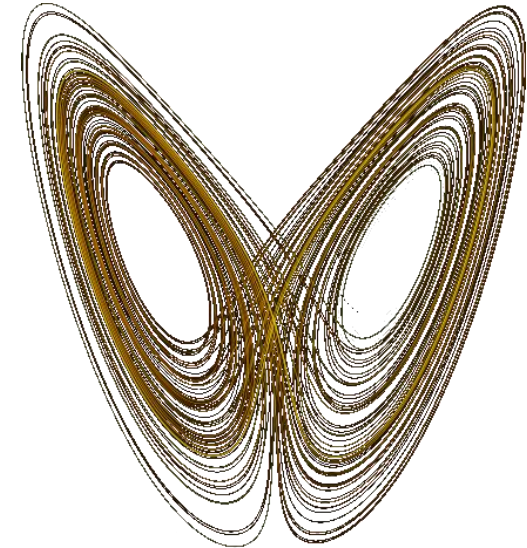
- Not the 2004 movie 😊



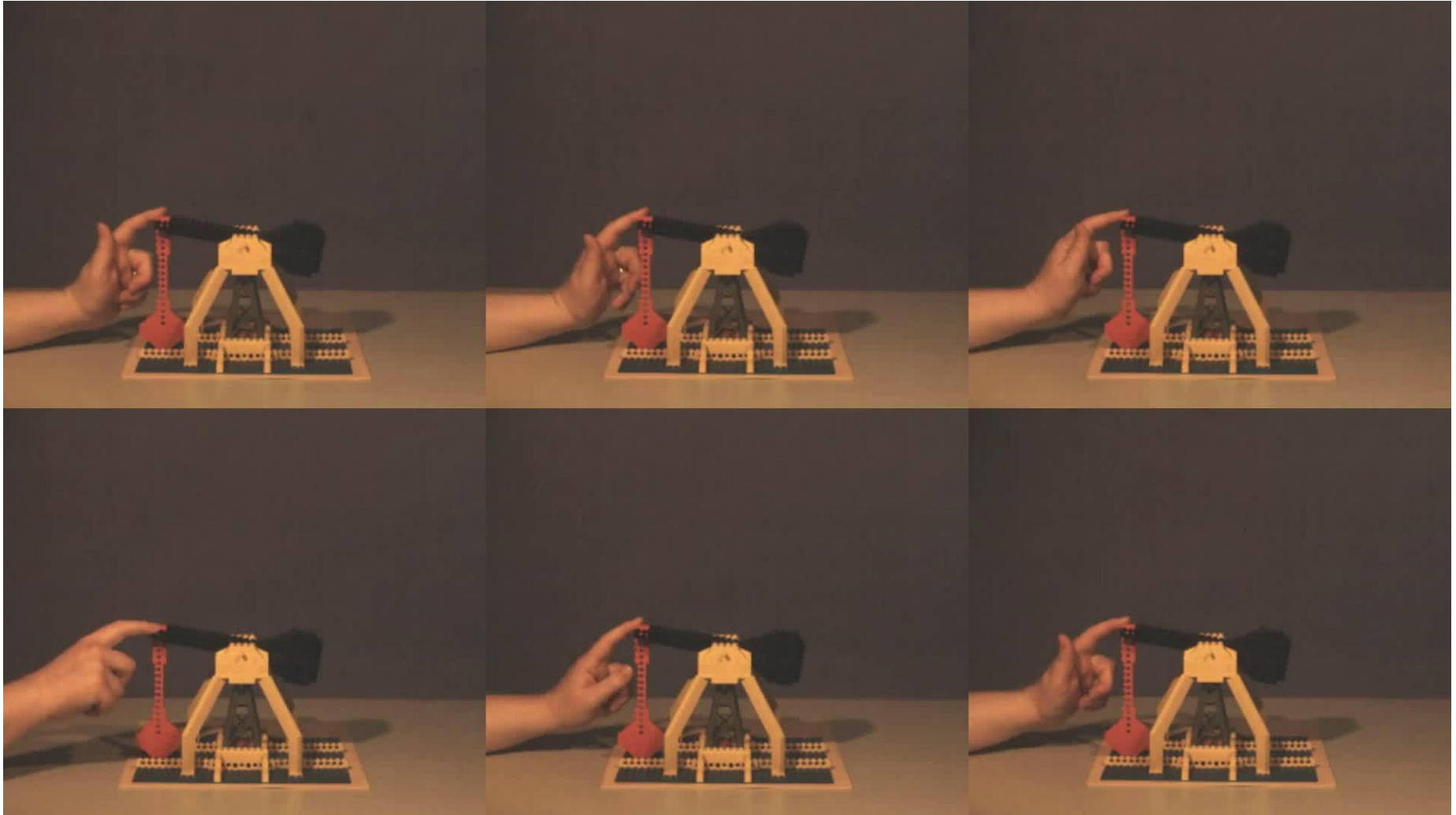
- Butterfly effect (1969):
small changes in initial state
➔ (potentially) very different final state

- Inevitable inaccuracy and incompleteness of observations
➔ precise long-range forecasting seem nonexistent

- “Does the flap of a butterfly’s wings in Brazil set off a tornado in Texas?”

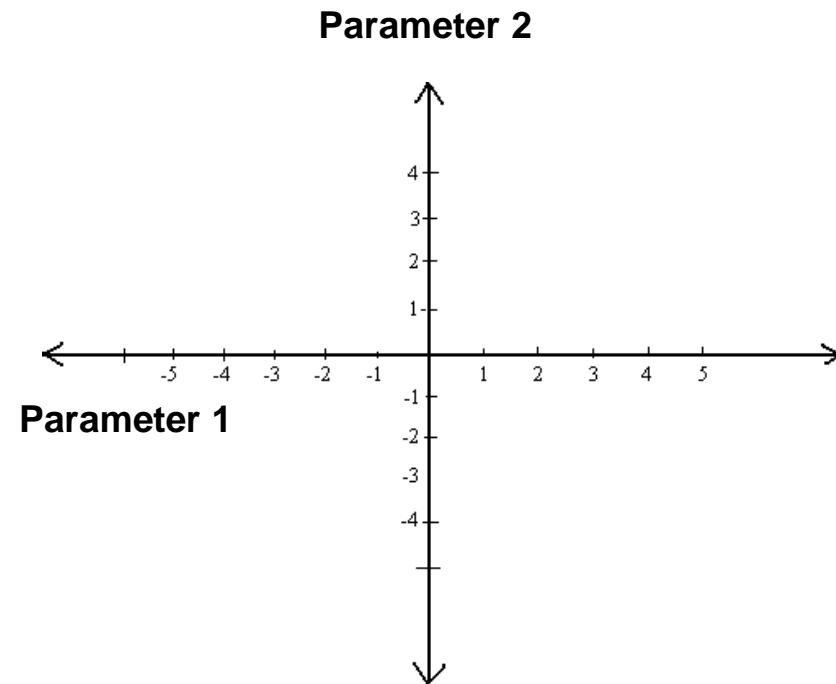


Introduction: Complex Systems



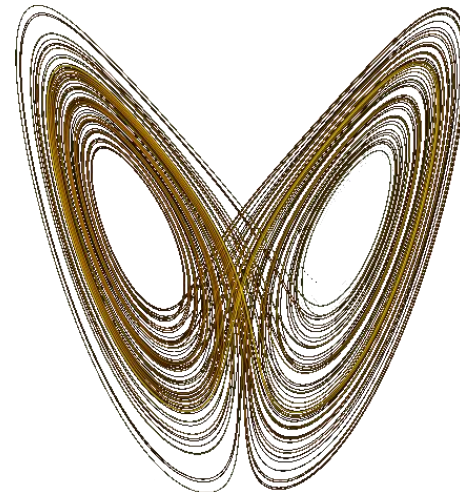
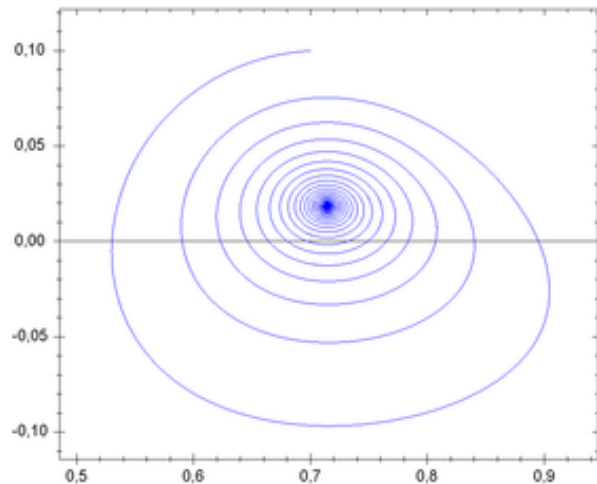
- Multiple double pendulums, differing slightly in initial state

- Phase Space is the n -dimensional space that is spanned by the relevant parameters of a system



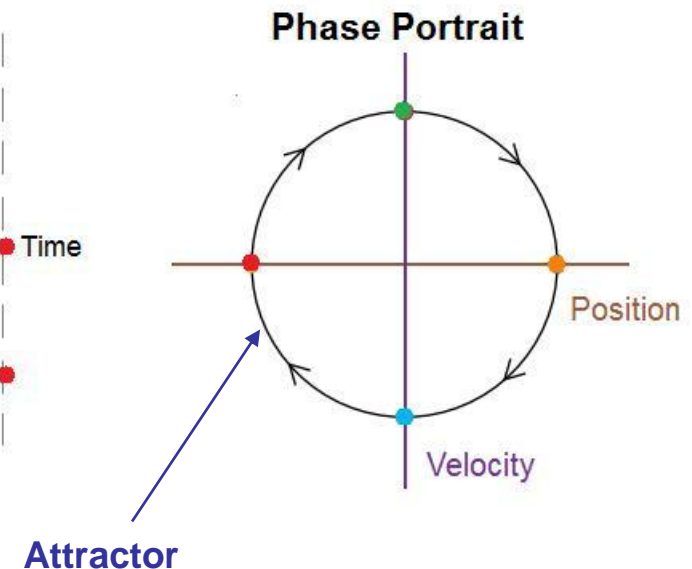
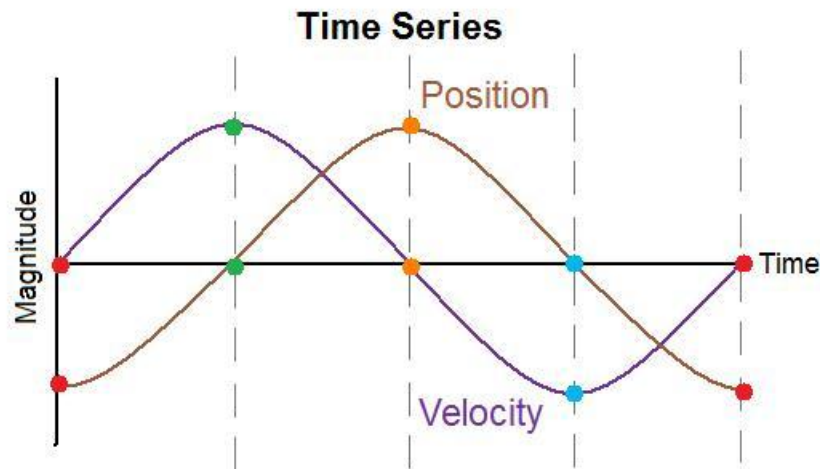
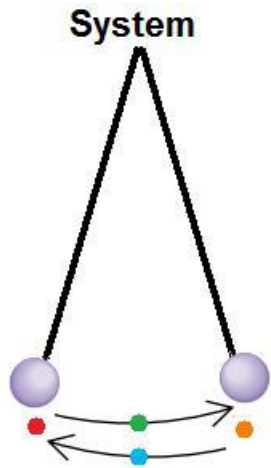
Phase Space

- Phase Space is the n -dimensional space that is spanned by the relevant parameters of a system
 - Space in which all possible states of a system are represented
 - System's evolving state (over time) traces a path



Phase plots: Attractors

- Space in which all possible states of a system are represented
- Example: Pendulum

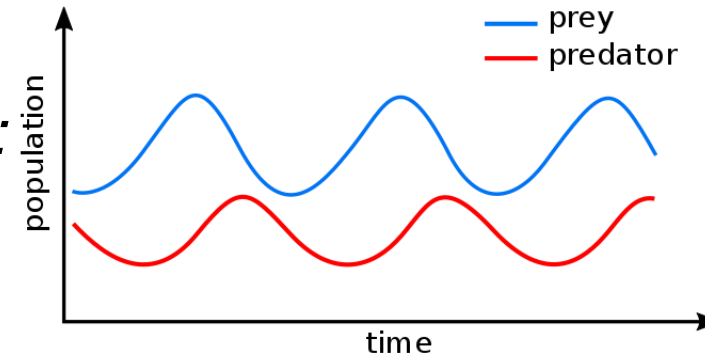


Tipping Point

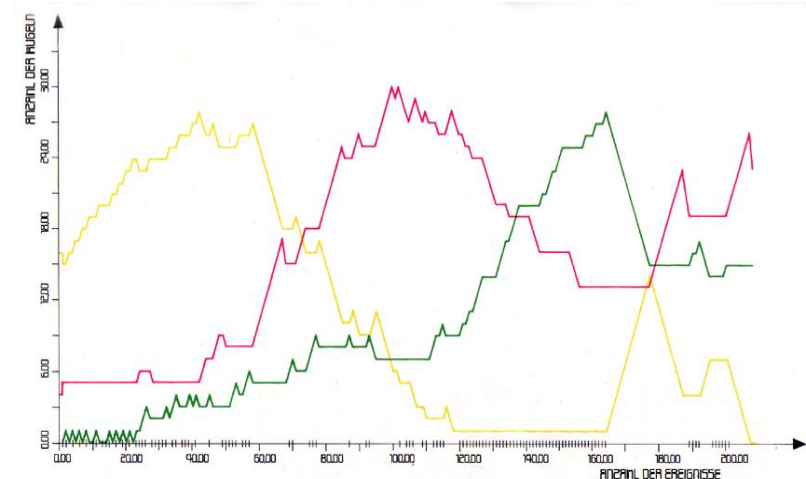
- Systems can have different attractors
- Stability within a certain range of parameters (self-stabilisation)
- If range is exceeded, systems can “switch” to other attractor
 - ➔ Tipping Point

- Systems can have different attractors
- Stability within a certain range of parameters (self-stabilisation)
- If range is exceeded, systems can “switch” to other attractor
→ Tipping Point
- **Example: Climate System of the Earth**
 - To a certain degree self-stabilising over certain range of parameters
 - If e.g. global temperature rises over tipping point: “runaway greenhouse effect”
 - Positive feedback loops can be induced
 - Melting of Greenland ice
 - Methane release from Siberian unfreezing
 - Eventually stabilisation at different attractor

- Well-known model of biological system: **predator/prey** (*Lotka–Volterra equations*): dynamics of two species



- More complex Ecosystems
 - Community of living organisms (plants, animals & microbes)
 - In conjunction with nonliving components of their environment
 - air, water, mineral soil, ...
 - Interacting as a system
 - Becomes difficult to model as analytical model
 - Numerical simulation model



- Top Down
 - “Traditional”
 - Differential Equation

- Bottom Up
 - Simulation using Simple Rules
 - Complexity Emerges by Interaction

- What is self-organisation?
 - **Process** where some form of **global order** (or coordination) arises out of **local interactions** between components of an **initially disordered** system
 - Process is **spontaneous**: **not directed** or **controlled** by any agent or subsystem inside or outside of the system
 - Often triggered by **random fluctuations**, amplified by **positive feedback**
 - **Rules** followed by process may be chosen or caused by an agent
 - Formative and constraining influences are **decided by the elements** of the system itself.

System develops towards state of equilibrium (**attractor**)

 - If close enough to the attractor: remain close even if disturbed
 - Survive / self-repair substantial damage or perturbations

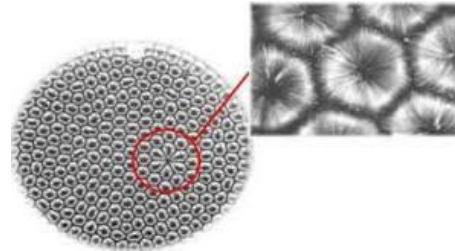
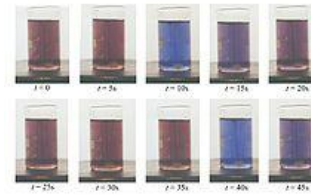
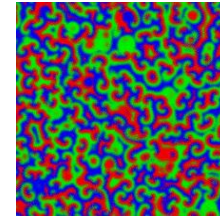
Self-Organisation: Properties

- Strong dynamical non-linearity
 - Often involving (positive and/or negative) feedback
- Multiple interactions (between elements)
- Complex: elements are interlinked by many & constantly changing relations
 - Elements can change as well → hinders prediction of state
- Self-referring: behaviour has impact on the system and future behaviour
- Autonomous: interactions are defined by the system itself

- Self-organization occurs in a variety of *physical, chemical, biological, social and cognitive* systems

- Common examples

- Crystallization, chemical clocks / oscillators
- Swarming in groups of animals
- Convection patterns



- Inspired

- Economics, collective intelligence, ...
- Mathematical and computational simulations & models

- Cellular automata
- Random graphs
- Evolutionary computation (genetic algorithms, genetic programming) and artificial life

- Swarm intelligence: emergent behavior
 - Emergence: the way complex systems and patterns arise out of a multiplicity of relatively simple interactions.

- Agents / Multi-agent systems

Self-organising systems

- A bit of unsupervised learning (no labels)
- A bit of reinforcement learning (reward / penalise for action)
- Often applied to
 - Simulation tasks (e.g. Ants, Swarms, Agents, ..)
 - Optimisation problems (Swarms, Agents, GA, ...) / problem solving
 - Data analysis

Complex vs. complicated system

- ?

Complex vs. complicated system

- Complicated systems / problems
 - Scale of the problem
 - Increased requirements around coordination or specialised expertise
 - Relatively high degree of certainty of outcome repetition
 - E.g.: sending a rocket to space

- Complex systems
 - Based on relationships, self-organisation and evolution
 - Formula have limited application
 - Experience & expertise contribute but are neither necessary nor sufficient to assure success

- Introduction & Definitions of Self-organising Systems
- Cellular Automata
- Genetic algorithms
- Ant Colony Optimisations
 - *to be extended in swarm optimisation lectures*
- Agent Based Systems / Multi Agent Systems

- *A CA is an array of identically programmed automata, or cells, which interact with one another in a neighbourhood and have definite state*
- **Microscopic** modelling approach
- Topics
 - Roots of the Cellular Automata Idea
 - Building Cellular Automata
 - Examples of well-known CAs
 - Behaviour of CAs
 - Applications

- Origins in the 1940s
 - John von Neumann, Stanislaw Ulam, Norbert Wiener
 - Theory of Computation, Automata Theory
 - Simulation of Complex Systems by Interaction of using “Simple” Rules

- 1970s: Game of Life
 - John Horton Conway

- 1980s – present: Stephen Wolfram & others
 - creator of Mathematica & Wolfram Alpha
(<http://www.wolframalpha.com/>)

Building Cellular Automata

- Basic building blocks

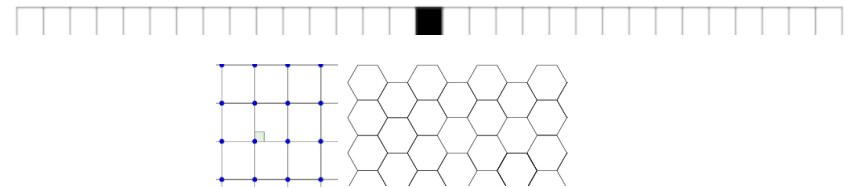
- The Cell (Node)

- States

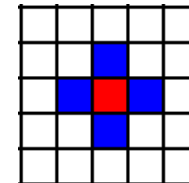


- The Lattice

- Cell Arrangement



- Neighbourhoods



- Transition Rules

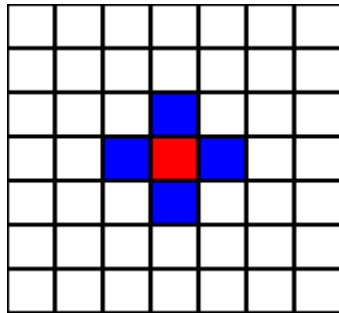


Building Cellular Automata

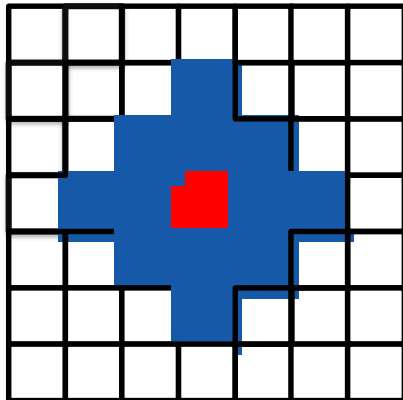
- CA consists of a regular grid of cells (lattice)
 - Each cell is in one of a finite number of states (simplest case: on/off)
- Grid can be in any finite number of dimensions
 - often 1D / 2D (especially if spatial aspect is relevant)
- Neighbourhood of a cell: set relative to a specified cell
- *Generation* creation
 - Initial state $t=0$ with cell assignment
 - Subsequent states ($t=1, \dots, n$) created with **rules** that define the state of each cell
 - ➔ Discrete modelling

- Neighbourhoods

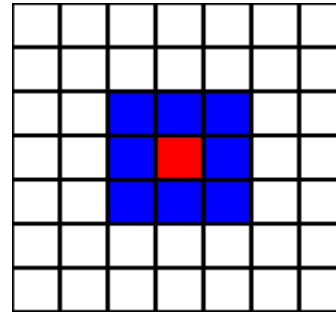
2-D



von Neumann Neighbourhood



Extended Neighbourhood
(2nd order)



Moore Neighbourhood

1-D

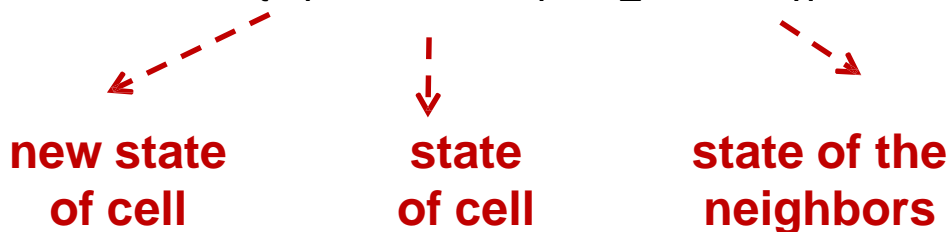


Building Cellular Automata

- Rules: mathematical functions; generally:
 - One rule applicable to **all** cells
 - Applied to all cells **at the same time**
 - Order is not important
 - Does not change over time
 - Exceptions, e.g. asynchronous cellular automaton

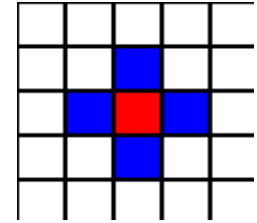
- Update rule

- $S_{t+1} = f(s, s_1, s_2, \dots, s_n)$



Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



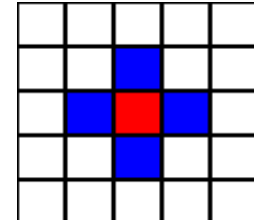
Old state

1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

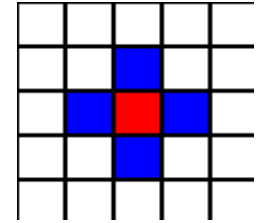
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

			?			

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

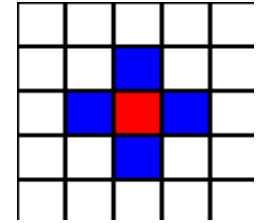
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

			1			

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

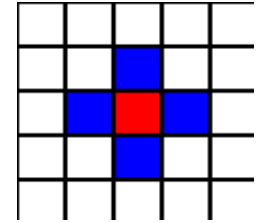
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

			1			
				?		

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

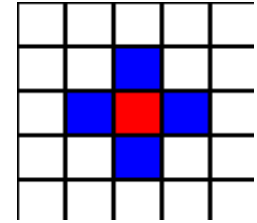
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

			1			
				0		

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

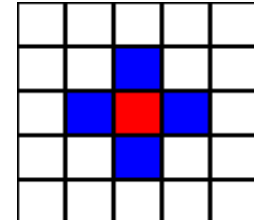
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

						?
			1			
				0		

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 2$



Old state

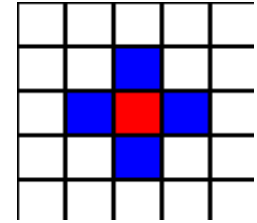
1	0	1	0	0	1	1
0	1	1	0	1	1	1
0	0	1	0	0	0	1
1	0	1	1	1	1	1
0	1	0	0	0	0	0
0	0	1	1	1	1	1
0	0	0	0	1	1	0

New state

						0
			1			
				0		

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 4$



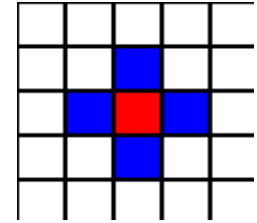
Old state

1	2	1	0	2	1	1
2	3	1	2	3	1	1
0	2	1	2	0	2	1
3	2	1	1	1	5	1
0	1	2	0	2	2	0
2	0	1	1	1	3	1
2	2	0	2	3	1	2

New state

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 4$



Old state

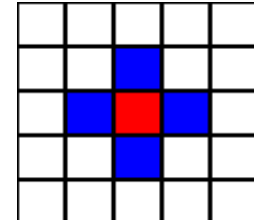
1	2	1	0	2	1	1
2	3	1	2	3	1	1
0	2	1	2	0	2	1
3	2	1	1	1	5	1
0	1	2	0	2	2	0
2	0	1	1	1	3	1
2	2	0	2	3	1	2

New state

			1			

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 4$



Old state

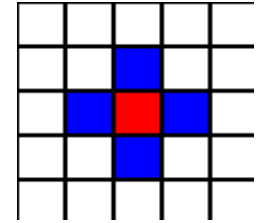
1	2	1	0	2	1	1
2	3	1	2	3	1	1
0	2	1	2	0	2	1
3	2	1	1	1	5	1
0	1	2	0	2	2	0
2	0	1	1	1	3	1
2	2	0	2	3	1	2

New state

			1			
				2		

Update rule: simple example

Update rule: $f(s, s_1, s_2, s_3, s_4) = \sum s \bmod 4$



Old state

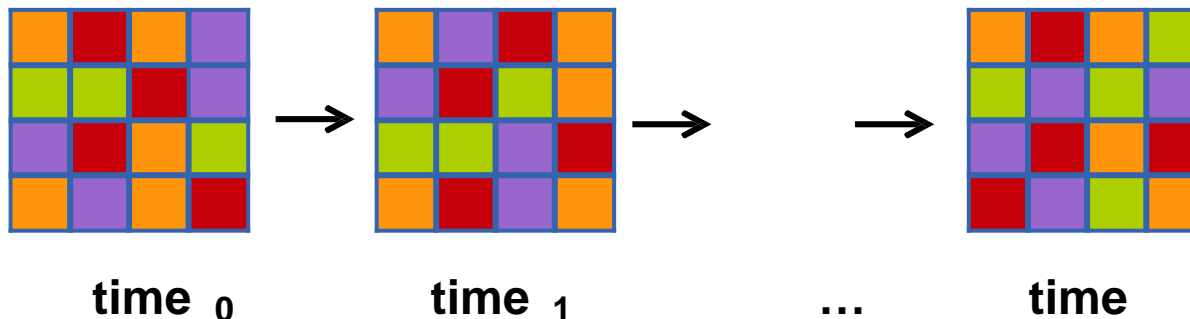
1	2	1	0	2	1	1
2	3	1	2	3	1	1
0	2	1	2	0	2	1
3	2	1	1	1	5	1
0	1	2	0	2	2	0
2	0	1	1	1	3	1
2	2	0	2	3	1	2

New state

						0
			1			
				2		

- Updates happen to all cells simultaneously
 - Neighborhoods are all computed from the same system state
 - Update order of cells is irrelevant

- Steps in one iteration
 - Determine neighbors of all cells
 - Compute state updates for all cells (and store them)
 - Apply the updated states



Rule Types

- **Explicit Rules:** every group of states of the neighbourhood cells is related to a state of the core cell
 - E.g. 1-D CA: a rule could be "011 \rightarrow x0x"
 - Core cell becomes 0 in the next time step **if left cell** is 0, **right cell** is 1 **and core cell** is 1. *Every possible state has to be described.*

- **Totalistic Rules:** state of the core cell only dependent upon a *function of the states* (often: sum) of the neighbourhood cells
 - E.g. If sum of adjacent cells is 4 \rightarrow state of the core cell is 1; in all other cases the state of the core cell is 0.

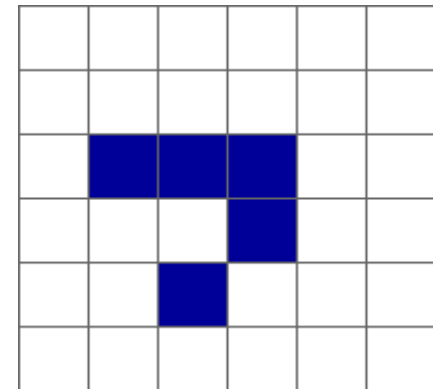
- **Legal Rules:** Subset of all *possible* rules
 - Those that produce no 1s from 0-state lattices, and provide symmetry (e.g. 110 \rightarrow 1 and 011 \rightarrow 1)

Algorithm properties

- CAs develop in space and time
- Cells arranged to n-dimensional lattices
- Finite and discrete cell states
- Cells have identical properties and transition rules
- Future state of cell only depending on
 - Neighbourhood of cell and
 - Defined transition rules
- Discrete Simulation Method

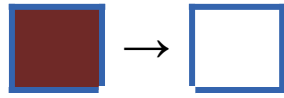
Conway's Game of Life

- John Horton Conway, 1970
- Eight neighbours (Moore neighbourhood)
- Rules
 - A cell that is dead becomes alive at time $t+1$ if exactly three cells are alive (reproduction)
 - A cell that is alive at time t dies at time $t+1$ if at time t
 - less than two (under-population) or
 - more than three cells are alive (over-crowding)
 - All instances of Game of Life follow same rule
 - Difference is in initial state

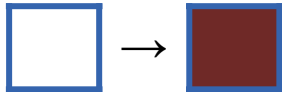


Conway's Game of Life

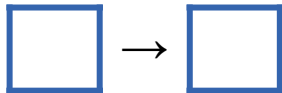
- Rules:



An alive cell with fewer than two or more than three alive neighbors dies (“under-population” or “overcrowding”)



A dead cell with exactly three alive neighbors becomes alive (“reproduction”)



Cells keep their state in any other case



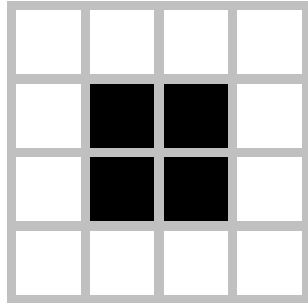
Conway's Game of Life

- A very simple example
 - Well suited to show the **concepts** of CAs
- Well studied
 - Pattern analysis of the Game of Life became its own science

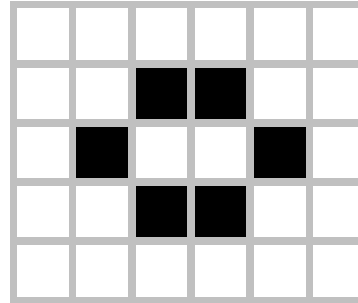
Conway's Game of Life: Examples

- dead → alive: exactly three cells are alive
- alive → dead: less than two or more than three cells are alive

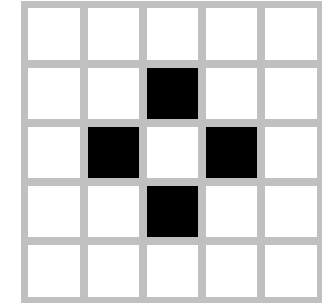
■ Still / static



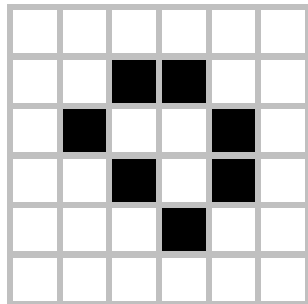
Block



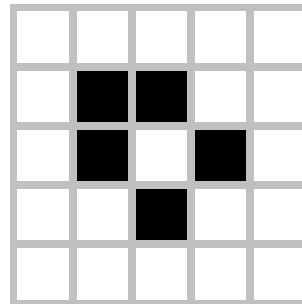
Beehive



Tub



Loaf

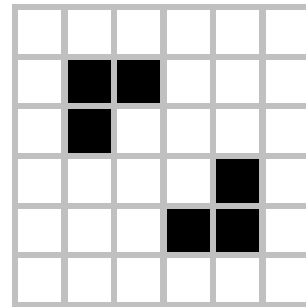
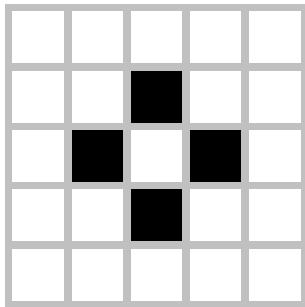
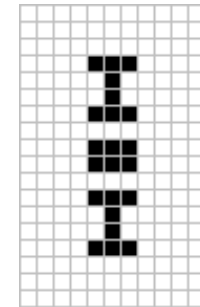
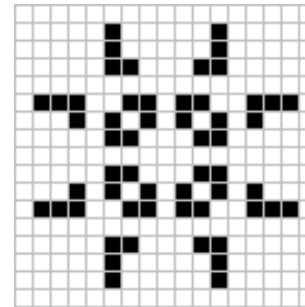
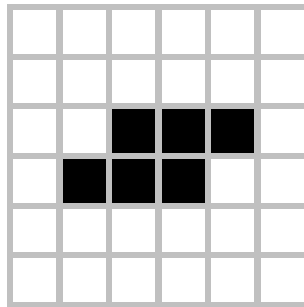
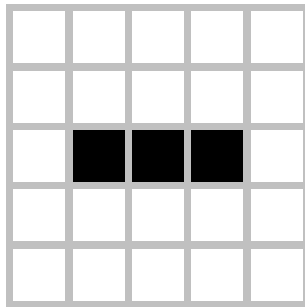


Boat

Conway's Game of Life: Examples

■ Oscilating

- dead → alive: exactly three cells are alive
- alive → dead: less than two or more than three cells are alive



2 cycles

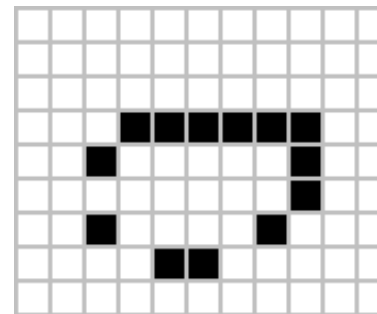
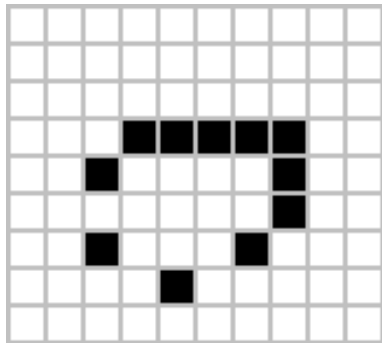
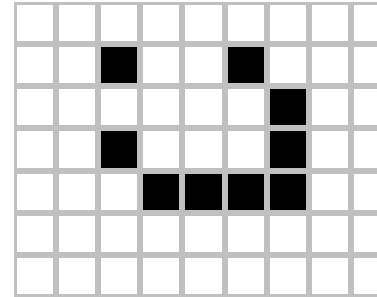
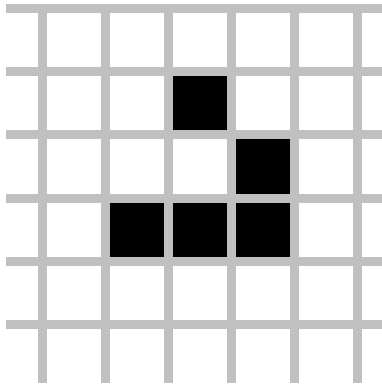
3 cycles

15 cycles

Conway's Game of Life: Examples

■ Spaceships

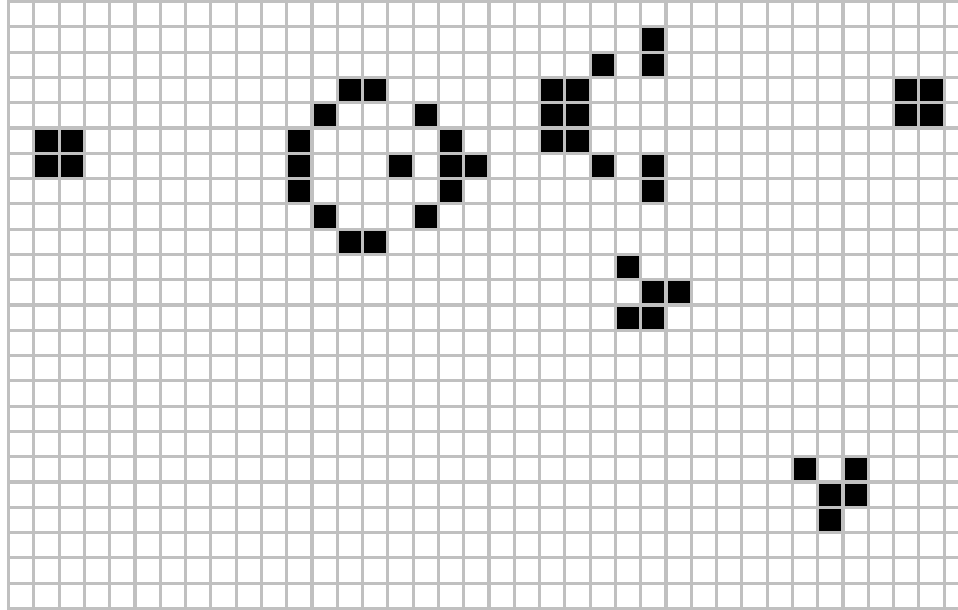
- dead → alive: exactly three cells are alive
- alive → dead: less than two or more than three cells are alive



Conway's Game of Life: gun

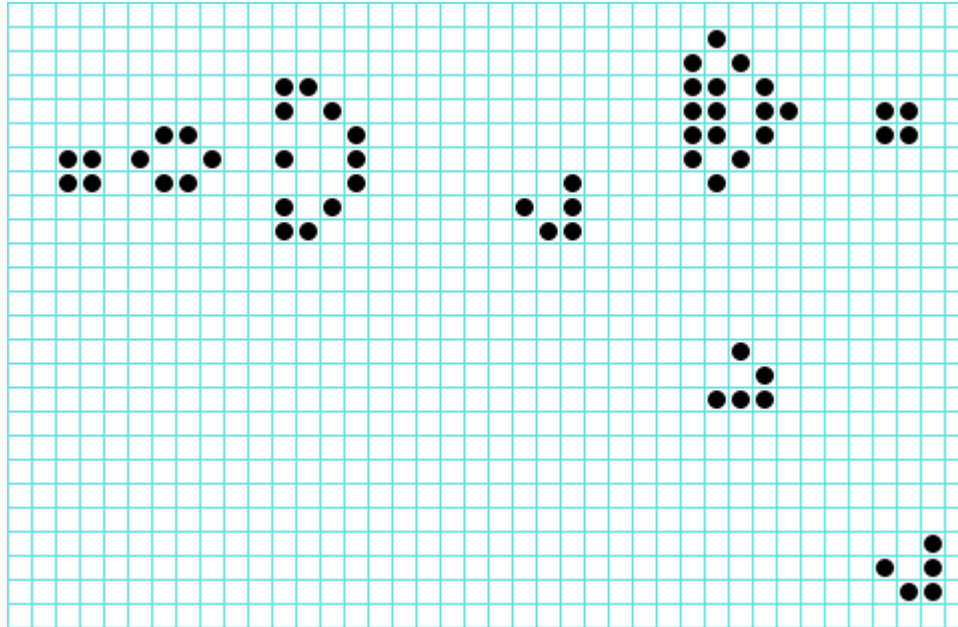
- Infinite growth: pattern that exhibit infinite growth, population is unbounded
 - Conway initially considered that impossible
- First example: Gosper glider gun, found by Bill Gosper (1970)
- Gun: main part that oscillates and periodically emits “spaceships”

Conway's Game of Life: gun



- Source: <http://www.conwaylife.com>

Conway's Game of Life: gun

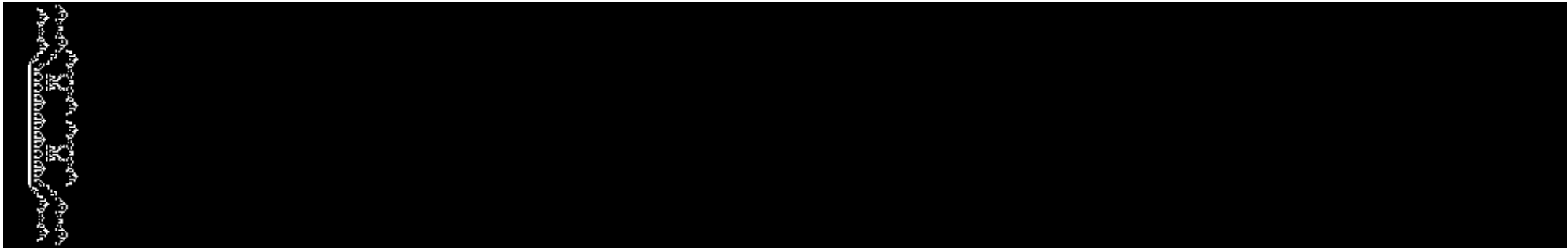


- Source: <http://www.numericana.com>

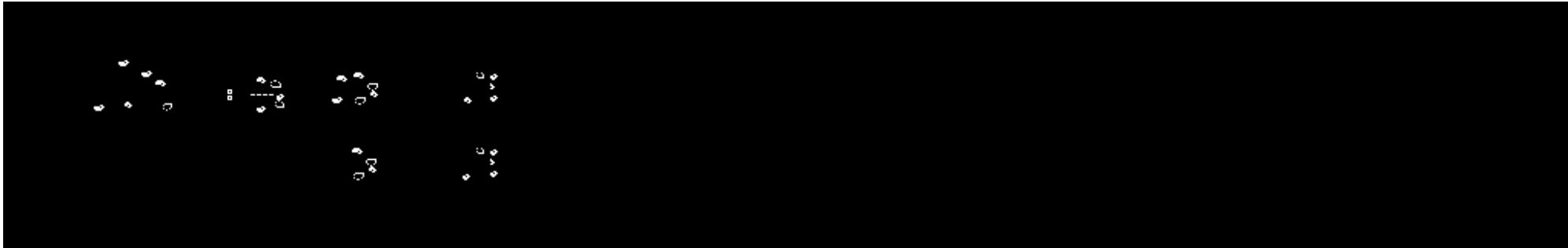
Conway's Game of Life: “Breeder”



Conway's Game of Life: “Puffer train”



Conway's Game of Life: “Rake”



Conway's Game of Life

- A very simple example
 - Well suited to show the **concepts** of CAs
- Well studied
 - Pattern analysis of the Game of Life became its own science
- But - doesn't demonstrate the **full power** of CAs