

1. Write about two level resource allocation architecture

A two level Architecture application controllers and cloud controller work in concert

Application SLA1 SLA2 application application 1 application 2
Vm Vm Vm Vm

Application
Controller

application
Controller

monitor

monitor

decider

decider

cloud Controller

actuator

actuator

cloud platform

- * The main components of a control system are inputs
- * The control system computes and the outputs
- * The inputs in such models are the offered workload and the policies for admission control, the capacity allocation, the load balancing, the energy optimization and the qos guarantees in the cloud.

* There are three main sources

- 1) The delay in getting the system reaction after a control action



2) The quantity of the control, the fact that a small change enacted by the controller leads to very large changes of the output.

3) Oscillations which occur when the change of the input are too large and the control is too weak, such that the changes of the input propagate directly to output. Two types of policies are used in automatic systems

- i) Threshold based policies and
 - ii) Sequential decision policies
- Based on decision models

2) Explain Fair Querying?

Fair Querying:-

Computing and communication on a cloud are intimately related

Therefore it should be no surprise that the first algorithm we discuss can be used for scheduling packet transmission as well as threads

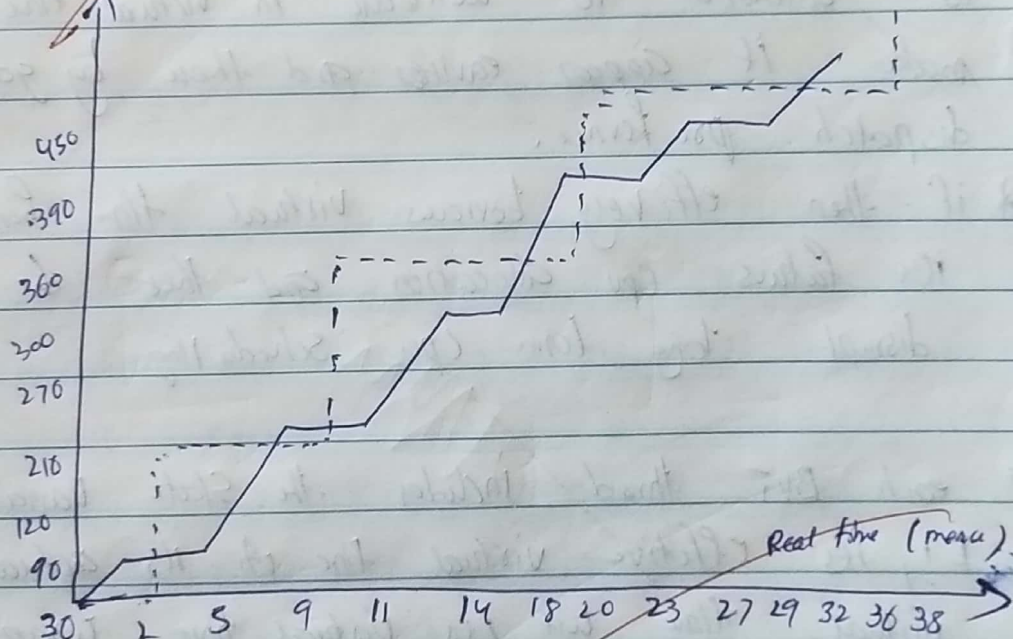
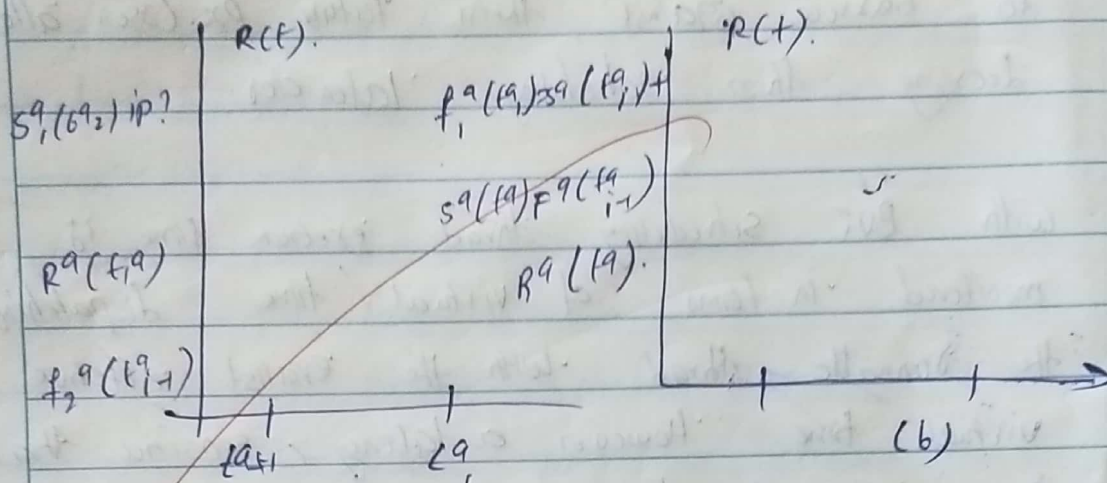
The Fair Querying (FG) algorithm proposes a solution to this problem.

call $t + a$, the time when the packet of flow of size p_a bits arrives and call p_a bits arrives. and call of s_f and p_a the value of R_{t+1} when

the first and the last bit respectively of the packet of flow a are transmitted then.

$$t_1^a \geq s_1^a, t_p^a \text{ and } s_1^a = \max \{F_1^a, R_c, t_1^a\}$$

$$R(t) \leq p? \text{ when } i \in \max (V(t) \leq t)$$



* The effective virtual time and the real time of thread a and b with weights $w_a = w_b$ when the actual virtual time is incremented in steps.

The two threads are allowed to execute in parallel to their weight.



3) What is Borrowed virtual time explain?

Borrowed virtual time:—

The Borrowed virtual time scheduler is a proportional share scheduler that allows selected threads to borrow against their future processor allocation, decreasing their scheduling latency.

With BVT scheduling thread execution time is monitored in terms of virtual time dispatching the runnable thread with the earliest effective virtual time. However a latency sensitive thread is allowed to wait back in virtual time to make it appear earlier and then by gain dispatch preference.

* if the thread effectively borrows virtual time from its future CPU allocation and thus does not disrupt long term CPU scheduling.

* each BVT thread includes the state variable E_i , its effective virtual time A_i its actual virtual time W_i if its virtual time wrap, $WrapBack$ is if wrap is enabled.

$$E_i \leftarrow A_i + (wrap ? W_i : 0)$$

where wrap is determined as default false. Later the scheduler accounts for running time in units of minimum charging unit.

4. what is map reduce scheduling?

map reduce scheduling:-

mapreduce application on the cloud subject to deal like several options for scheduling like Hadoop, an open-source implementation of the mapreduce algorithm are:-

- * The default FIFO scheduler.
- * The Fair scheduler.
- * The capacity scheduler.
- * The dynamic proportional scheduler.

The system is homogeneous:-

This means that in and p_i the cost of processing a unit data by the map and the reduce task respectively are the same for all servers.

- * under the conditions the duration of the job J with input of size a is

$$E(m, n, s) = s \left[\frac{p_m}{n m} + \phi \left[\frac{p_r}{n r} + v \right] \right]$$

Thus the condition that every $\theta(A, \sigma, D)$ with arrival time A meets the deadline D can be expressed as

$$[m + v \left[\frac{p_m}{n m} + \phi \left[\frac{p_r}{n r} + v \right] \right] \leq A + D.$$



$$t_{o, \max} = A + n \cdot \sigma \left(\frac{p_r}{p_r} + v \right).$$

* We now plug the expression of the maximum value for the start-up time of the reducer task into the condition to meet the deadline

$$t_{o, \max} + \sigma \frac{p_m}{n_m} \leq t_{i, \max}$$

It follows immediately that n_m^{\min} , the minimum no. of slots for map task

$$n_m^{\min} > \frac{\sigma p_m}{t_{i, \max} - t_{o, \max}}$$

Thus,

$$n_m^{\min} = \left\lceil \frac{\sigma p_m}{t_{i, \max} - t_{o, \max}} \right\rceil$$