# International Institute of Information Technology Bangalore

PROJECT ELECTIVE REPORT
AI-825

# Semantic Segmentation of 3D point cloud

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## 1 Objective

To develop a machine learning model for semantic segmentation of 3D point cloud.

### 2 Dataset

The dataset used for training the model is Hessigheim 3D (H3D) dataset. H3D dataset contains train folder and test folder for Mar2018 and Mar2019. Each folder contains .laz files of point clouds over a village in Germany.

It contains 11 classes namely Low Vegetation, Impervious Surface, Vehicle, Urban Furniture, Roof, Facade, Shrub, Tree, Soil, Vertical Surface and Chimney.

## 3 Segmentation Visualization Using Cloud Compare



Figure 1: Segmentation on portion of train dataset

Here I have used the classification values to separate each of the classes and manually gave custom colours to each of this classes and merge all the customly coloured classes.

#### 4 Feature Extraction

Cloud Compare offers an option to calculate several features of a point cloud like PCA, Eigen value, linearity etc. Feature extraction is performed on train data and stored in txt format for later use.

## 5 Training Classifier Cloud Compare's Canupo plugin

Cloud Compare offers Canupo plugin which can train classifier but the drawback is that is only a binary classifier. It works great for predicting classes like trees. For training multiple classes we will have to run the classifier nearly *logn* number of times where n is the number of classes. Clearly this approach is cumbersome.

## 6 Training Classifier with machine learning

#### **6.1** train - test split

For training a random forest we first need to convert into .txt format so that we can read this data in python and pass it to random forest model. Mar2019 data contains 119,029,358 number of points, training random forest on these many points results in my computer and kaggle to crash, so I have considered only a part of this data for train and test. Let the name of our train data be *miniTrain* as we are only choosing a part of the complete train data. All the lines containing NaN values were removed before passing into RandomForest.

### **6.2** Adding Features of neighbourhood radius r = 1

The following features were considered for training the random forest

Metrics	Results
Accuracy	0.57471
F1-score	0.54322

#### **6.3** Adding Features of neighbourhood radius r = 1 and r = 0.125

#### 6.3.1 Set max threshold for number of points for each class

• Allot only 200000 points per class, if any class has number of points lesser than 200000 retain it.

```
[26]: accuracy = accuracy_score(labels, y_pred)
print("Accuracy:", accuracy)

Accuracy: 0.5150105174661561
```

Allot only 200000 points per class, if any class has number of points lesser than 200000 than duplicates data belonging
to that class randomly until the number of points belonging to that class is 200000

```
[40]: accuracy = accuracy_score(labels, y_pred)
print("Accuracy:", accuracy)
Accuracy: 0.3622475
```

• Another attempt was to just set the threshold as the class having maximum number of points.

```
accuracy = accuracy_score(labels, y_pred)
print("Accuracy:", accuracy)

Accuracy: 0.34356716560814476
```

#### 6.4 Multi-Scale neighbourhood extraction

The following features were considered

Results:

Metrics	Results
Accuracy	0.705809
F1-score	0.680613

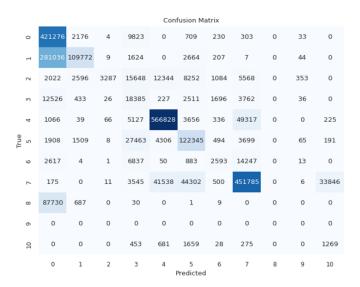


Figure 2: Confusion Matrix

Extending the features for r=2 and r=3

#### Results:

Metrics	Results
Accuracy	0.7223
F1-score	0.7056

### 6.5 Using XGBoost on miniTrain

Instead of training miniTrain with RandomForest, I tried training it with XGBoost with early stop rounds Results:

Metrics	Results
Accuracy	0.72719
F1-score	0.69322

#### 6.6 Using ensemble of random forest models

Since we can't pass the entire data of original train (kaggle crashes), I split the entire train data including features (27 GB) into 5 files and train random forest on each of these data separately. At the end for predicting classes on *test data* I take the majority vote among them.

5 models are generated namely model1, model2, model3, model4 and model5.

#### Results

Since the model1 had bad accuracy it wasn't involved in majority vote classifier.

Table 1: Model Evaluation

Model	Accuracy	F1 Score
model1	0.1724	0.0916
model2	0.6676	0.6683
model3	0.4681	0.4719
model4	0.7345	0.7080
model5	0.6471	0.6245
ensemble	0.7395	0.7292

	Confusion Matrix										
0	383067	15601	0	26061	5	22	9729	41	28	0	0
г	181532	188824	0	18631	0	55	5894	427	0	0	0
2	5740	1975	3	22852	13352	1238	2695	3267	0	32	0
m	5750	225	0	23154	62	158	5834	4419	0	0	0
4	41609	6398	29	10286	524881	6	759	42692	0	0	0
True 5	2545	1446	0	49638	2402	79117	3302	23538	0	0	0
9	1013	2	0	7273	35	17	10537	8368	0	0	0
7	60	1	0	3753	818	65	1920	569091	0	0	0
00	88255	4	0	10	0	0	188	0	0	0	0
6	0	0	0	0	0	0	0	0	0	0	0
10	0	0	0	68	191	163	0	3943	0	0	0
	0	1	2	3	4	5 Predicted	6 I	7	8	9	10

Figure 3: Confusion matrix of ensemble model  $\,$ 

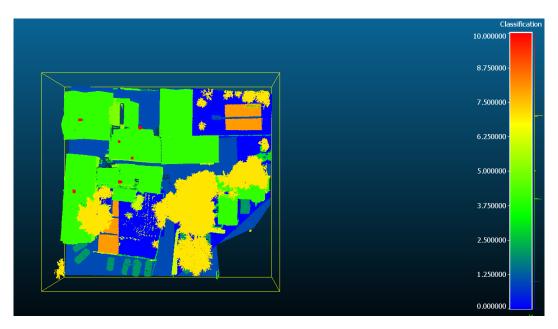


Figure 4: Original Test Data

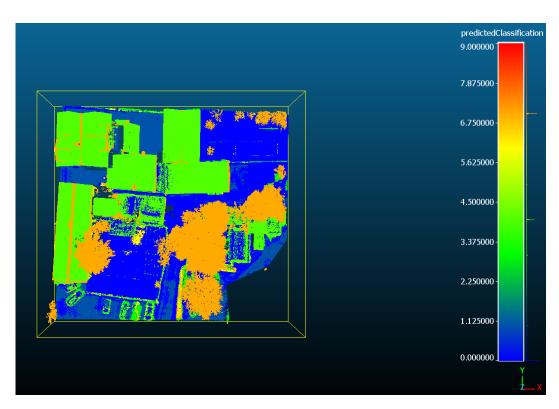


Figure 5: Ensemble model predictions

Overall the ensemble method gave the best accuracy and F1 score among all. The major drawback of this model is that it failes to identify classes 9,10 and 11.