

5 SEPTEMBER 2024

ASE 367K: FLIGHT DYNAMICS

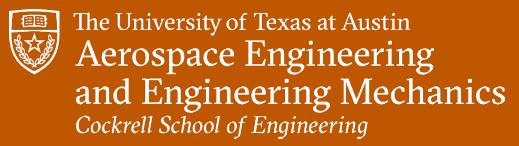
TTH 09:30-11:00
CMA 2.306

JOHN-PAUL CLARKE

Ernest Cockrell, Jr. Memorial Chair in Engineering, The University of Texas at Austin

Topics for Today

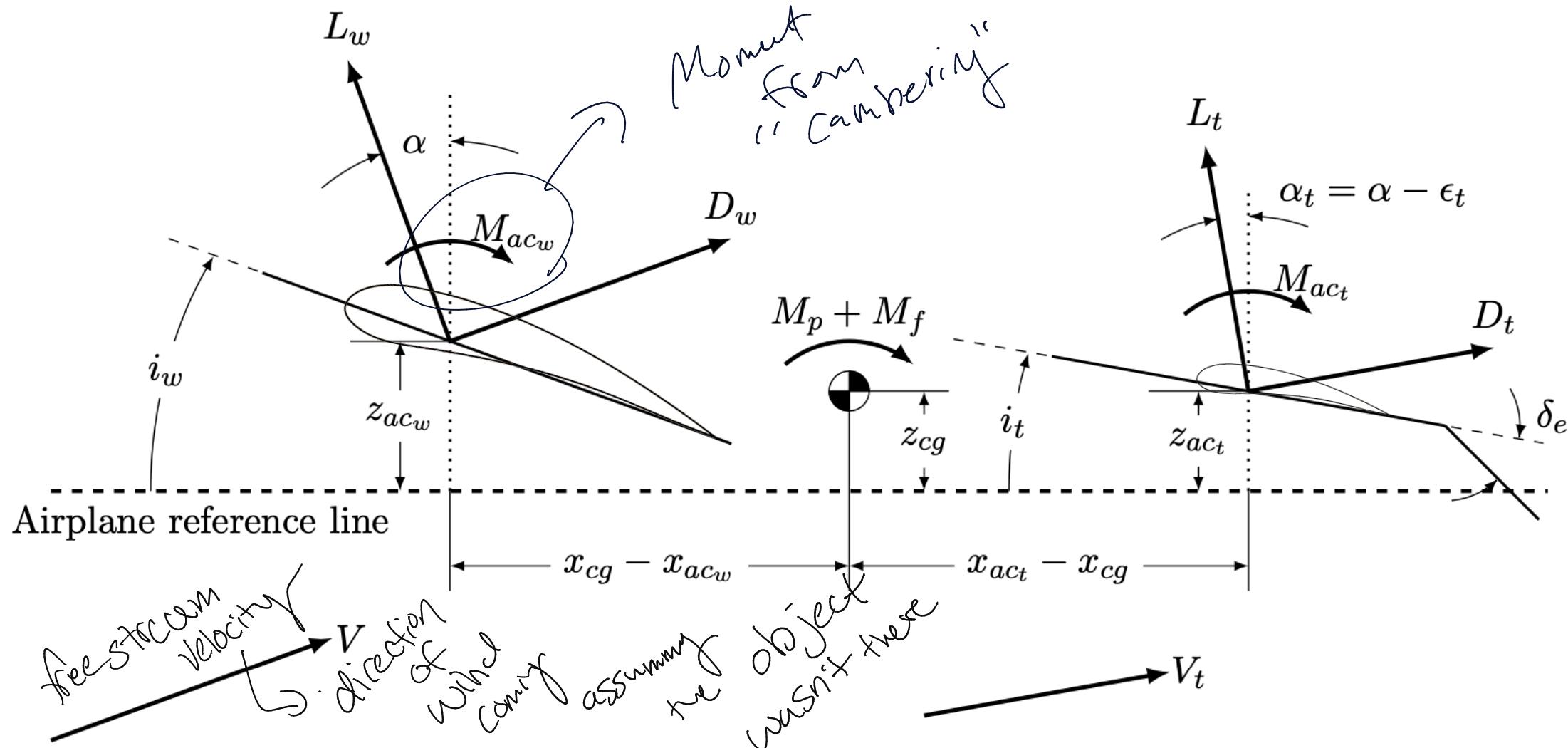
- Topic(s):
 - Lift of Aircraft + Moment about CG
 - Trim
 - Upside Down Flying Wing



LIFT OF AIRCRAFT + MOMENT ABOUT CG

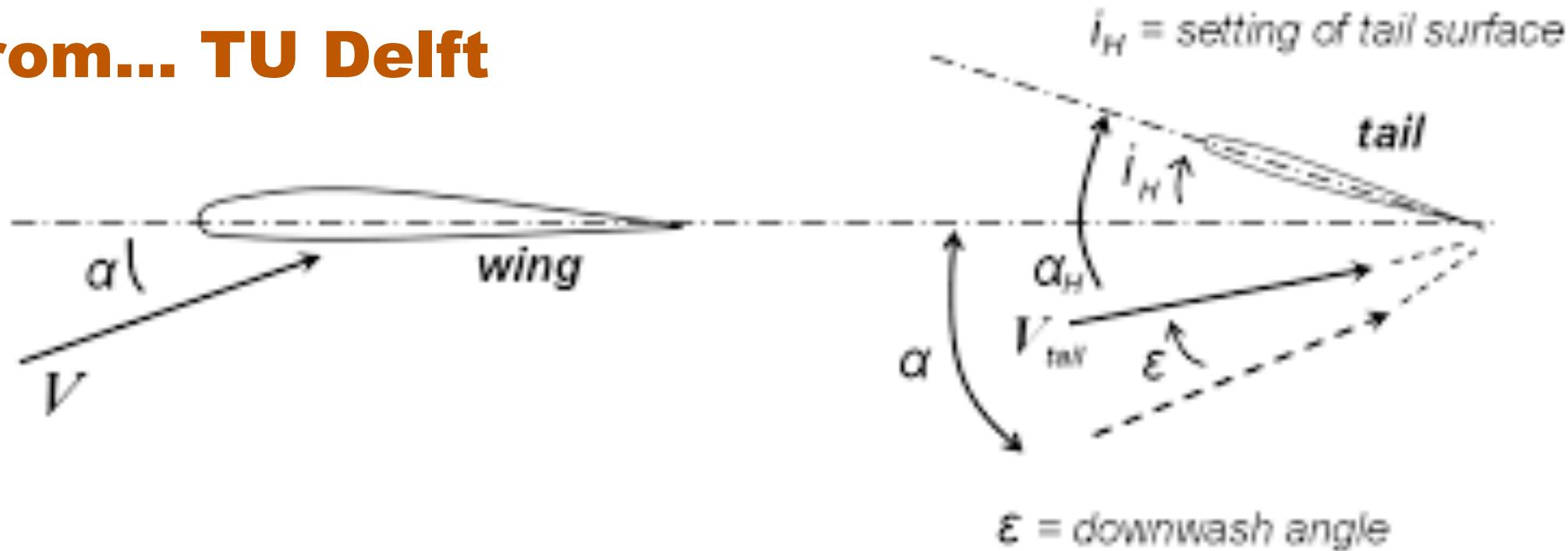
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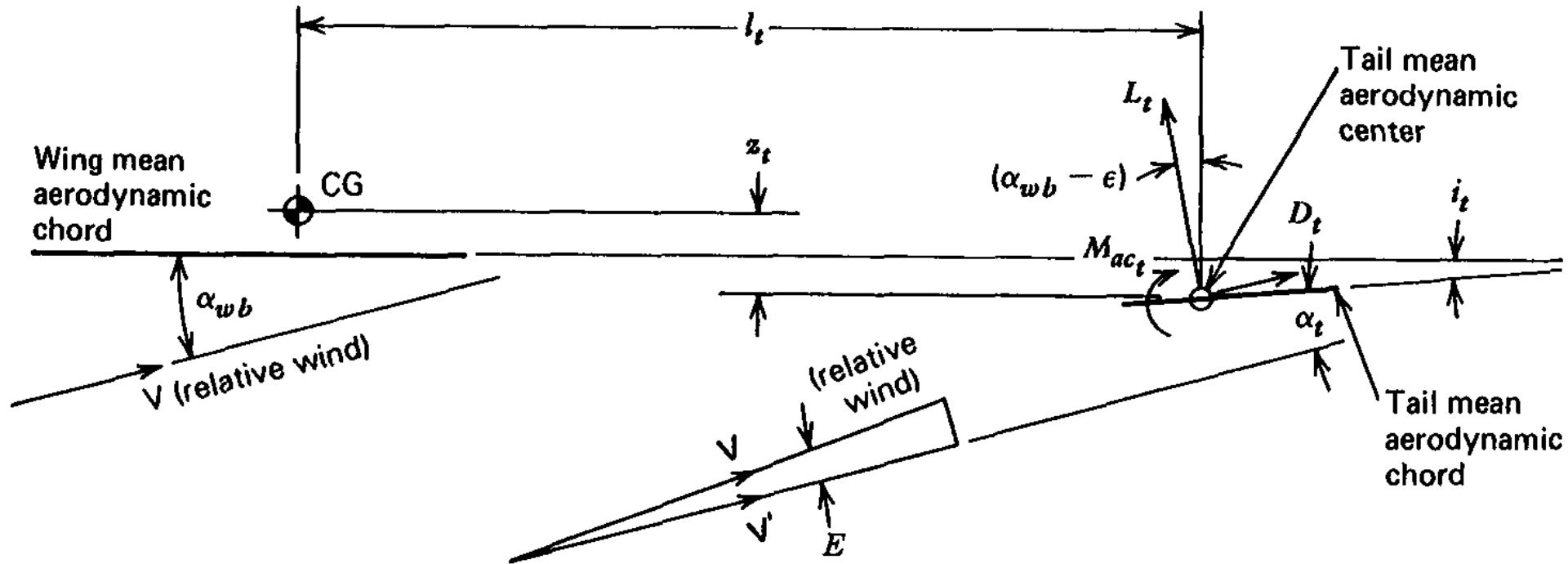
- NOTE:**
- (a) the angles of attack of the wing and horizontal tail are defined relative to the airplane reference line.
 - (b) the incidence angles of the wing is the angle between the chord of the wing and the airplane reference line.
 - (b) the incidence angles of the horizontal tail is the angle between the chord of the horizontal tail and the airplane reference line.

From... TU Delft

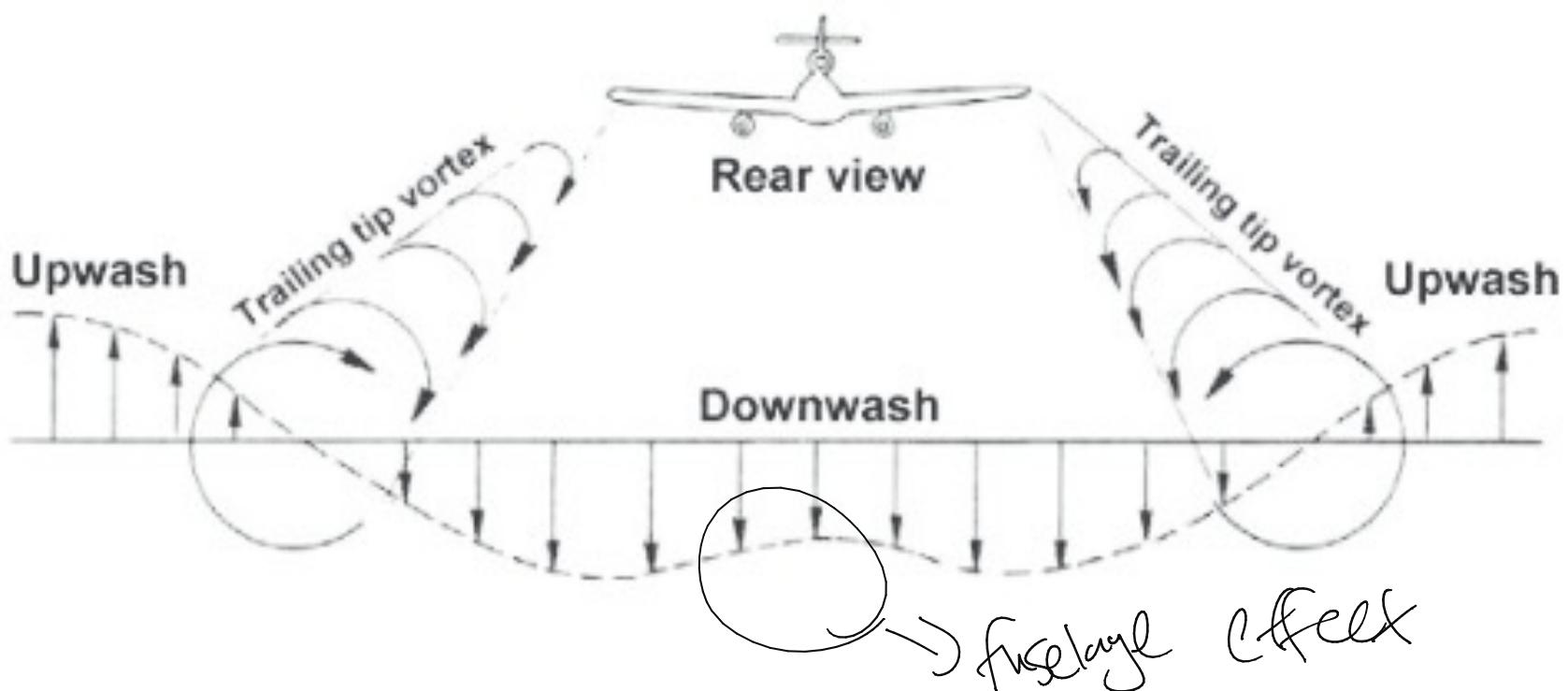
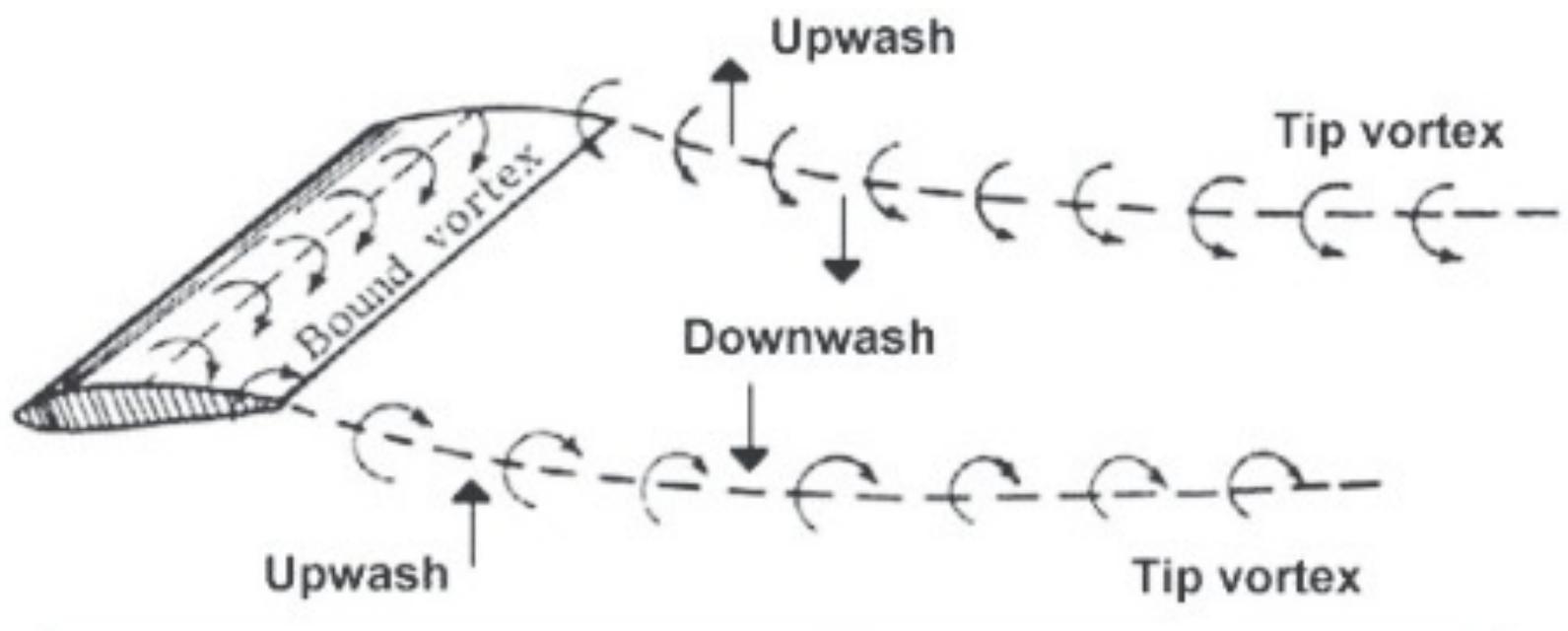


- NOTE:**
- (a) the chord of the wing and the aircraft reference line are colinear, thus the angle of attack of the wing is defined relative to the chord of the wing.
 - (b) the wing has no incidence angle.
 - (c) the angle of attack of the horizontal tail is defined relative to the aircraft reference line (or extended wing chord).
 - (d) the incidence angle of the tail is the angle between the chord of the horizontal tail and the aircraft reference line.

From... Etkin and Reid



- NOTE:**
- (a) the chord of the wing and the aircraft reference line are colinear, thus the angle of attack of the wing is defined relative to the chord of the wing.
 - (b) the wing has no incidence angle.
 - (c) the angle of attack of the horizontal tail is defined relative to the aircraft reference line (or extended wing chord).
 - (d) the incidence angle of the tail is the angle between the chord of the horizontal tail and the aircraft reference line.

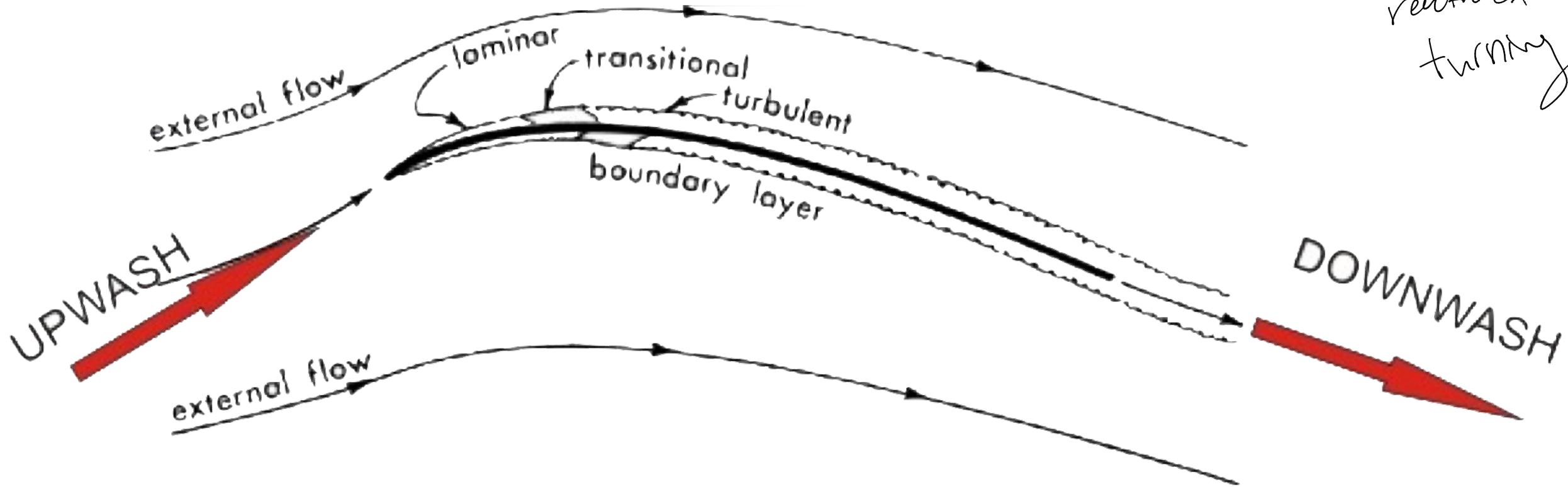


Downwash

increasing angle of attack
brings up the separation point
more downwash

$$\epsilon_t = \epsilon_{0t} + \epsilon_{at}\alpha$$

Lift ↑
Speed ↑
Downwash
verts of
turning



The downwash ϵ_0 at $\alpha_{wb} = 0$ results from the induced velocity field of the body and from wing twist; the latter produces a vortex wake and downwash field even at zero total lift. The constant derivative $\partial\epsilon/\partial\alpha$ occurs because the main contribution to the downwash at the tail comes from the wing trailing vortex wake, the strength of which is, in the linear case, proportional to C_L .

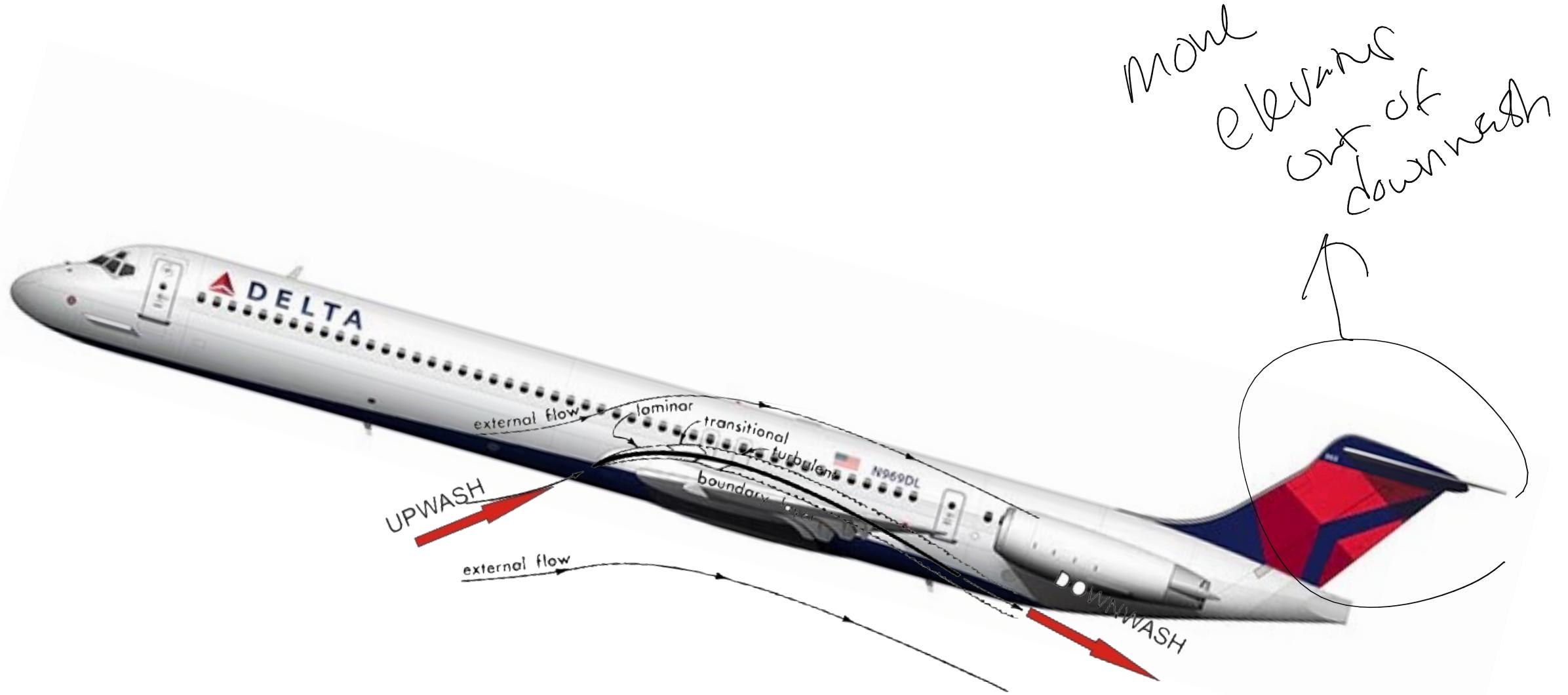


Away from main stream



Put Center
of pressure back
to counter act
engine weight





Total Lift Summary

$$C_L = C_{L_0} + C_{L_\alpha} \alpha + C_{L_{i_t}} i_t + C_{L_{\delta_e}} \delta_e$$

where α at $\alpha=0$

$$C_{L_0} = C_{L_{0w}} + C_{L_{\alpha w}} i_w + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (C_{L_{0t}} - C_{L_{\alpha t}} \epsilon_{0t})$$

$$C_{L_\alpha} = C_{L_{\alpha w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t})$$

Gradients

$$C_{L_{i_t}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\alpha t}}$$

$$C_{L_{\delta_e}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\delta_{et}}}$$

constnt partial derivative wrt. α
 wrt i_t
 wrt δ_e

doesn't change

Not constant

Pitch Moment Summary

$$C_{M_r} = C_{M_{0r}} + C_{M_{\alpha r}} \alpha + C_{M_{i_{tr}}} i_t + C_{M_{\delta_{er}}} \delta_e$$

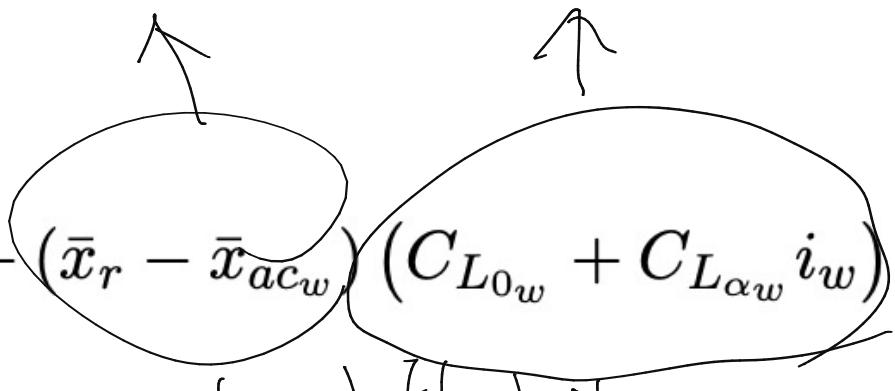
A \downarrow
at
ref point

$$C_{M_{0r}} = C_{M_{acw}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} \frac{\bar{c}_t}{\bar{c}} C_{M_{act}} + C_{M_{0p}} + C_{M_{0f}} + (\bar{x}_r - \bar{x}_{acw}) (C_{L_{0w}} + C_{L_{\alpha w}} i_w)$$

$$+ \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) (C_{L_{0t}} - C_{L_{\alpha t}} \epsilon_{0t})$$

Moment arm

baseline lift



baseline lift + tail

$$C_{M_{\alpha r}} = C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_r - \bar{x}_{acw}) C_{L_{\alpha w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\alpha t}} (1 - \epsilon_{\alpha t})$$

$$C_{M_{i_{tr}}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\alpha t}}$$

$$C_{M_{\delta_{er}}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\delta_{et}}}$$

Propulsion

fuselage

Change in
wing lift

Δ in tail lift

Aerodynamic Center of Aircraft

- What is so unique about the aerodynamic center?

(a)

a.c.
 C_M is 0.

Moment won't change

A.C. = the Neutral point.
by No control authority

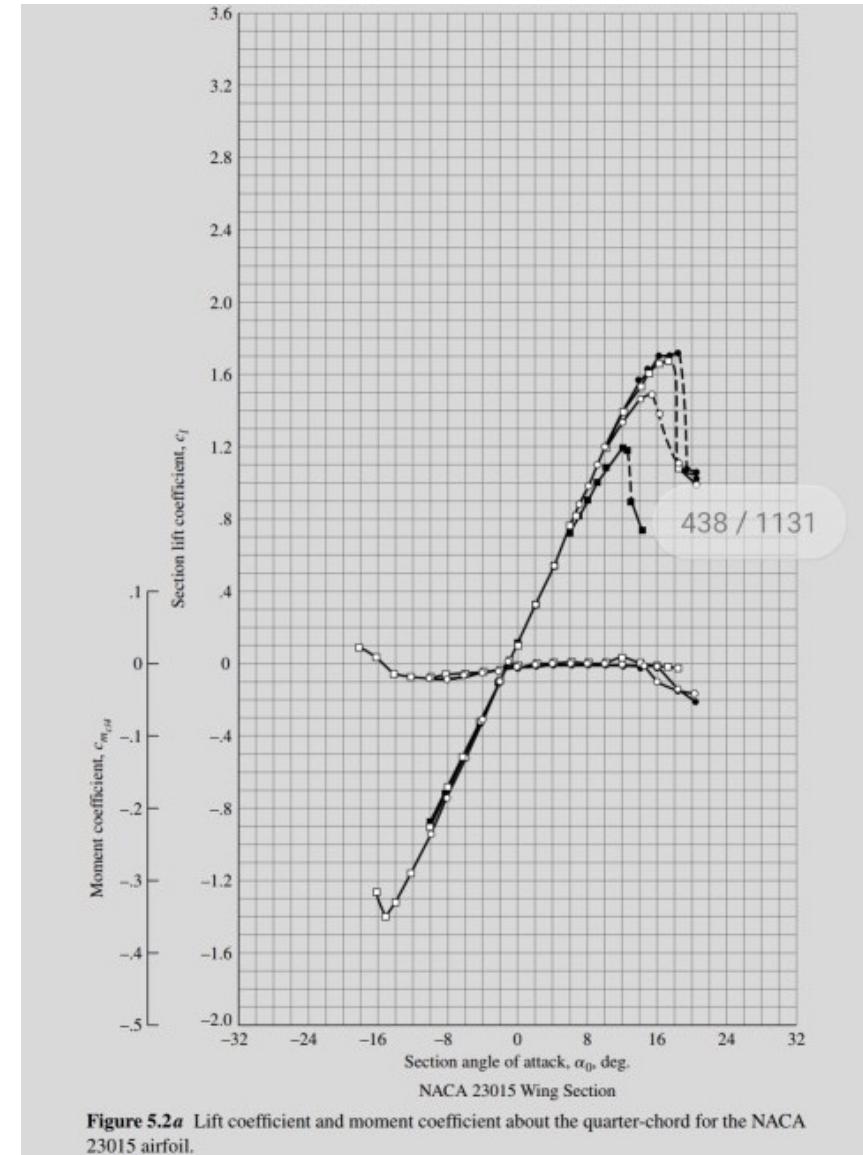


Figure 5.2a Lift coefficient and moment coefficient about the quarter-chord for the NACA 23015 airfoil.

Aerodynamic Center of Aircraft

- How do we determine the aerodynamic center?

$$\bar{x}_r = \bar{x}_{ac}$$

$$C_{M_{\alpha ac}} = C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_{ac} - \bar{x}_{ac_w}) C_{L_{\alpha w}} + \frac{q_t S_t}{qS} (\bar{x}_{ac} - \bar{x}_{ac_t}) C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) = 0$$

→ $\bar{x}_{ac} \left[C_{L_{\alpha w}} + \frac{q_t S_t}{qS} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) \right] = \bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}}$

On the point
where a horizontal
gradient
becomes zero.

→ $\bar{x}_{ac} C_{L_{\alpha}} = \bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}}$

→ $\bar{x}_{ac} = \frac{1}{C_{L_{\alpha}}} \left[\bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}} \right]$

↓ distance from nose to acx



Pitch Moment about the CG

$$C_M = C_{M_0} + C_{M_\alpha} \alpha + C_{M_{i_t}} i_t + C_{M_{\delta_e}} \delta_e$$

$$C_M \approx C_U \ell h^k$$

$$\begin{aligned} C_{M_0} &= C_{M_{ac_w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} \frac{\bar{c}_t}{\bar{c}} C_{M_{act}} + C_{M_{0_p}} + C_{M_{0_f}} + (\bar{x}_{cg} - \bar{x}_{ac_w}) (C_{L_{0_w}} + C_{L_{\alpha_w}} i_w) \\ &\quad + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) (C_{L_{0_t}} - C_{L_{\alpha_t}} \epsilon_{0_t}) \end{aligned}$$

$$C_{M_\alpha} = C_{M_{\alpha_p}} + C_{M_{\alpha_f}} + (\bar{x}_{cg} - \bar{x}_{ac_w}) C_{L_{\alpha_w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\alpha_t}} (1 - \epsilon_{\alpha_t})$$

$$C_{M_{i_t}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\alpha_t}}$$

$$C_{M_{\delta_e}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\delta_e t}}$$

Static Margin

- Can we simplify the equation for C_{M_α} ?

$$C_{M_\alpha} = C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_{cg} - \bar{x}_{ac_w}) C_{L_{\alpha w}} + \frac{q_t S_t}{qS} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\alpha t}} (1 - \epsilon_{\alpha t})$$

$$= \bar{x}_{cg} \left[C_{L_{\alpha w}} + \frac{q_t S_t}{qS} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) \right] - \left[\bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{act} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}} \right]$$

$$= \bar{x}_{cg} C_{L_\alpha} - \bar{x}_{ac} C_{L_\alpha}$$

$$= -(\bar{x}_{ac} - \bar{x}_{cg}) C_{L_\alpha}$$

Need to be positive A.C. further back than C.g.

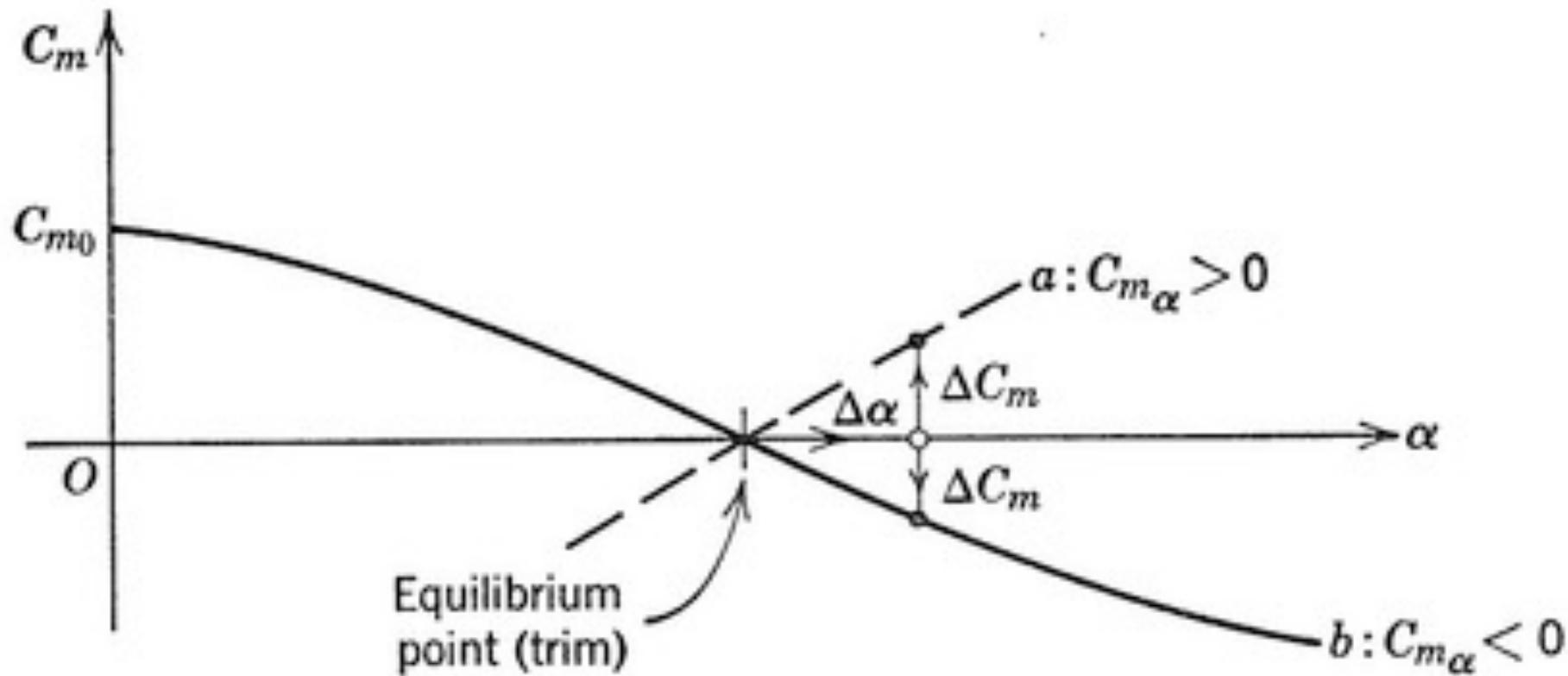
$$= -SM \cdot C_{L_\alpha}$$

where SM is the "Static Margin"

counter acts C_{L_α}

C_M to be 0.

Why is the Static Margin important?



Why is the Static Margin important?

- Which of the following aircraft is stable?

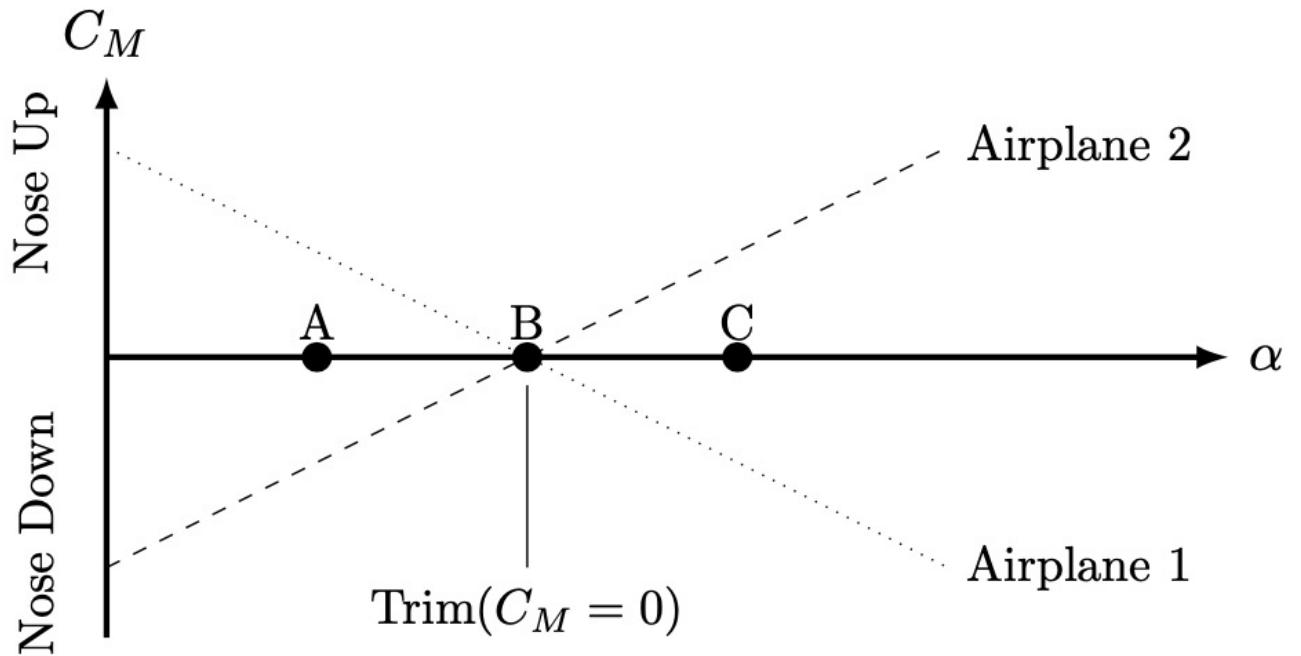


Figure 3.4: Pitch moment coefficient vs. angle of attack

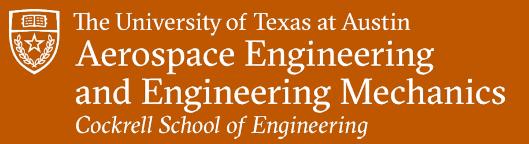
For a trimmed aircraft...

1. If $C_{M\alpha}$ (the slope of the line) is positive, then an increase in pitch (and thus in the angle of attack) results in a nose up pitching moment.
2. If $C_{M\alpha}$ is negative, then an increase in pitch (and thus in the angle of attack) results in a nose down pitching moment.
3. Thus, for the aircraft have longitudinal static stability we need $C_{M\alpha}$ to be negative.
4. Because $C_{L\alpha}$ is positive...
5. The SM must also be positive, and...
6. The center of gravity must be ahead, i.e., closer to the nose than the aerodynamic center of the aircraft.

**Weight on nose to move the c.g.
forward for longitudinal stability**



the static margin should be positive to achieve longitudinal static stability;
this also means that the center of gravity should be ahead of the aerodynamic center to achieve
longitudinal static stability



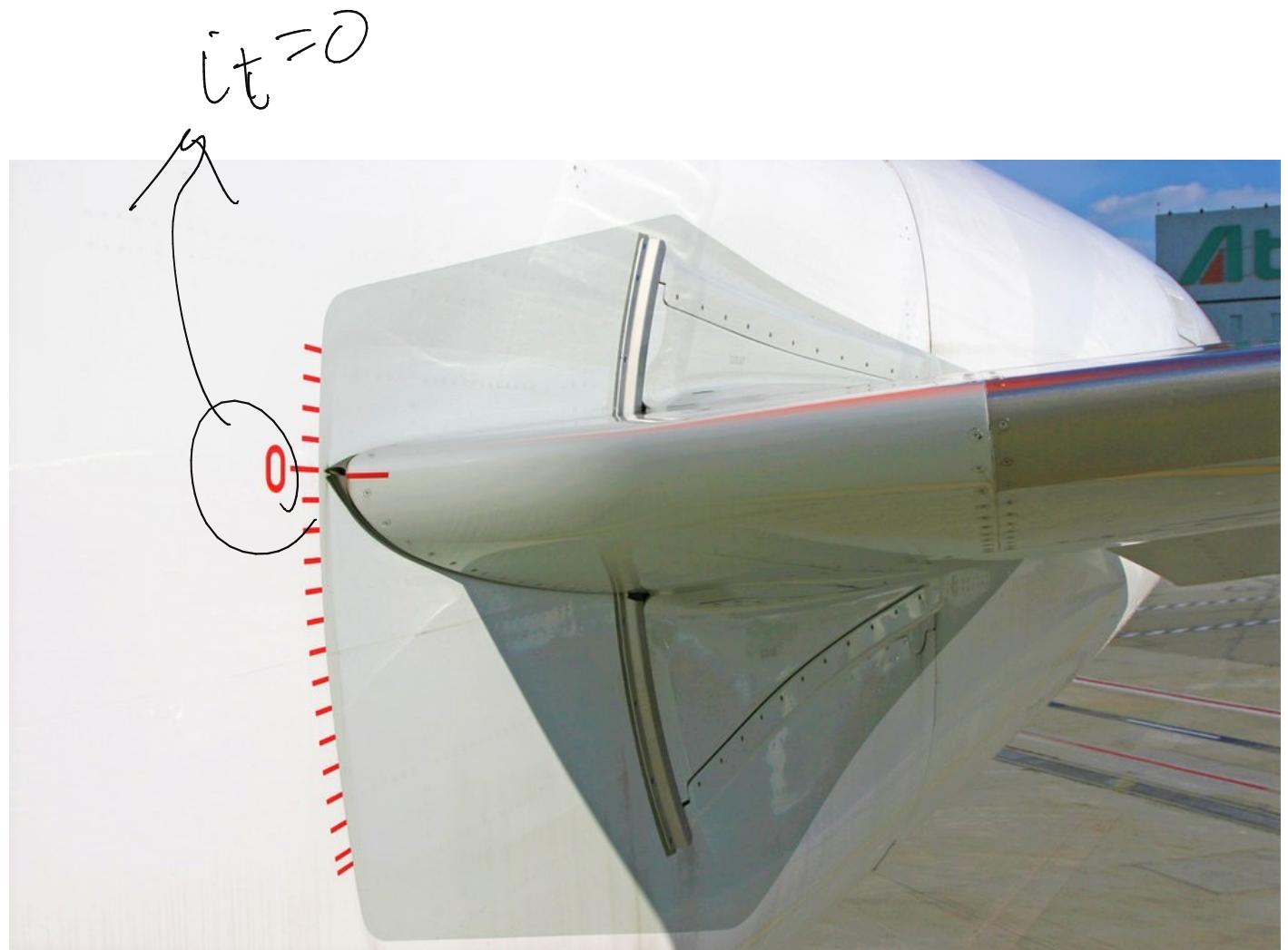
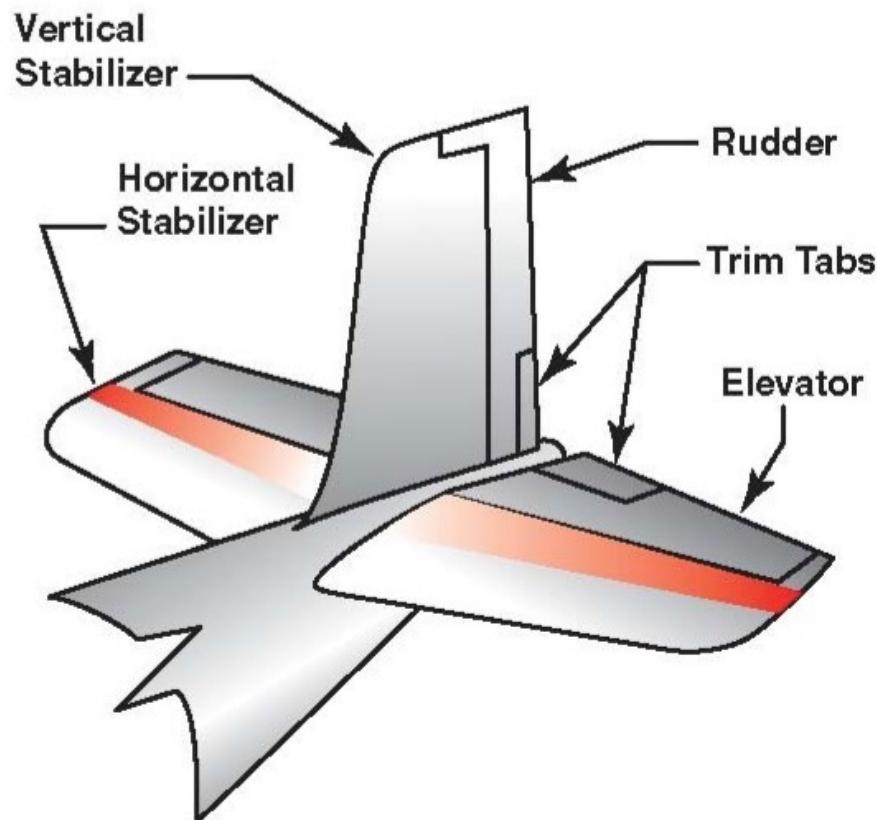
Cockrell School of Engineering

TRIM

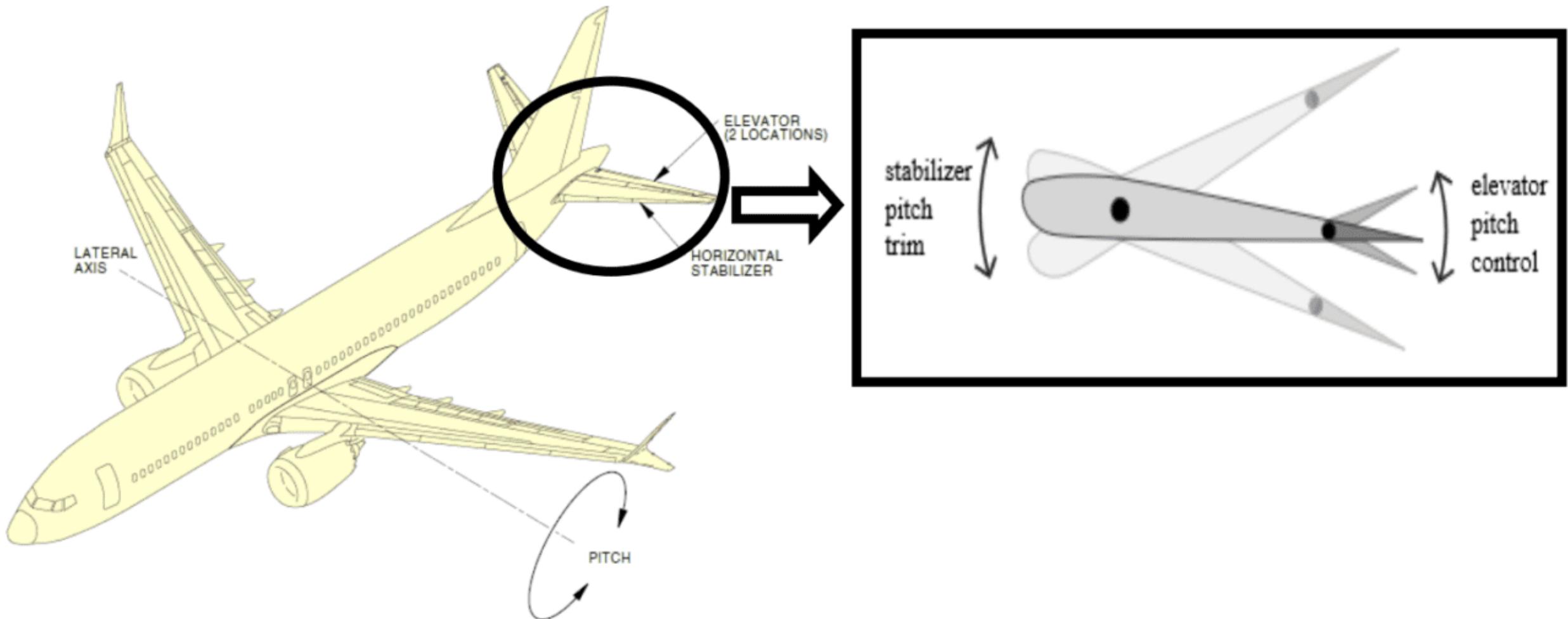
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Fixed v. Variable-Position Horizontal Stabilizer



Variable-Position Horizontal Stabilizer (1)



Variable-Position Horizontal Stabilizer (2)

1. Set desired speed, V , and fix $\bar{q} = \rho V^2/2$. Assume that $\delta_e = 0$ at this speed.
2. Determine α_{trim} and $i_{t_{\text{trim}}}$ from

$$\frac{W \cos \gamma}{\bar{q} S} = C_{L_0} + C_{L_\alpha} \alpha + C_{L_{i_t}} i_t$$
$$0 = C_{M_0} + C_{M_\alpha} \alpha + C_{M_{i_t}} i_t$$

which is equivalent to solving the linear system of equations

$$\begin{bmatrix} C_{L_\alpha} & C_{L_{i_t}} \\ C_{M_\alpha} & C_{M_{i_t}} \end{bmatrix} \begin{bmatrix} \alpha_{\text{trim}} \\ i_{t_{\text{trim}}} \end{bmatrix} = \begin{bmatrix} \frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \\ -C_{M_0} \end{bmatrix}$$

Variable-Position Horizontal Stabilizer (3)

and has the solution

$$\alpha_{\text{trim}_{\delta_e=0}} = - \frac{C_{M_{i_t}} \left(\frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \right) + C_{L_{i_t}} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

$$i_{t_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \right) + C_{L_\alpha} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

- With $i_{t_{\text{trim}}}$ determined for the specified \bar{q} , define C'_{L_0} and C'_{M_0} as

$$C'_{L_0} = C_{L_0} + C_{L_{i_t}} i_{t_{\text{trim}}}$$

$$C'_{M_0} = C_{M_0} + C_{M_{i_t}} i_{t_{\text{trim}}}$$

Variable-Position Horizontal Stabilizer (4)

4. Determine δ_e to trim at other \bar{q} 's. That is, solve

$$\begin{bmatrix} C_{L\alpha} & C_{L\delta_e} \\ C_{M\alpha} & C_{M\delta_e} \end{bmatrix} \begin{bmatrix} \alpha \\ \delta_e \end{bmatrix} = \begin{bmatrix} \frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \\ -C'_{M_0} \end{bmatrix}$$

to find α_{trim} and $\delta_{e_{\text{trim}}}$, which gives

Now much
I need
 x_0 deflt

$$\alpha_{\text{trim}} = -\frac{C_{M\delta_e} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L\delta_e} C'_{M_0}}{C_{M\alpha} C_{L\delta_e} - C_{M\delta_e} C_{L\alpha}}$$

$$\delta_{e_{\text{trim}}} = \frac{C_{M\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L\alpha} C'_{M_0}}{C_{M\alpha} C_{L\delta_e} - C_{M\delta_e} C_{L\alpha}}$$

Let's do some number crunching...

- The aircraft is in level flight.
- The gravitational acceleration is $32.174 \text{ [ft/s}^2\text{]}$.
- The wing and horizontal stabilizer are trapezoidal surfaces.
- The cg of the aircraft is at $x_{cg} = 10.56 \text{ [ft]}$.
- The weight of the aircraft is $W = 9,500 \text{ [lb]}$.
- The propulsive moment coefficients are $C_{M_{0p}} = 0.0$ and $C_{M_{\alpha p}} = 0.0$.
- The fuselage moment coefficients are $C_{M_{0f}} = 0.0$ and $C_{M_{\alpha f}} = 0.0$.
- The atmospheric density is $0.002378 \text{ [slugs/ft}^3\text{]}$.
- The horizontal tail incidence can only be set between -0.5 and -7 [deg] .

	Wing	Horizontal Stabilizer
S	$232.00 \text{ [ft}^2\text{]}$	$S = 54.00 \text{ [ft}^2\text{]}$
\bar{c}	7.04 [ft]	$\bar{c} = 3.83 \text{ [ft]}$
$x_{ac/le}$	4.07 [ft]	$x_{ac/le} = 2.79 \text{ [ft]}$
x_{le}	16.40 [ft]	$x_{le} = 36.90 \text{ [ft]}$
i	1.00 [deg]	
C_{L_0}	-0.0443	$C_{L_0} = 0.0000$
C_{L_α}	5.0800	$C_{L_\alpha} = 4.2600$
$C_{M_{ac}}$	-0.0175	$C_{M_{ac}} = 0.0000$
$C_{L_{\delta_{et}}}$		$C_{L_{\delta_{et}}} = 1.8000$
ϵ_0		$\epsilon_0 = 0.642 \text{ [deg]}$
ϵ_α		$\epsilon_\alpha = 0.426$
η		$\eta = 0.9$

half way
on
fuselage

$$\eta = \frac{q_t}{q}$$

Number Crunching (1)

How to determine
CG?

1. Set desired speed, V , and fix $\bar{q} = \rho V^2 / 2$. Assume that $\delta_e = 0$ at this speed.

Let's assume aircraft is flying at ... 500 knots = 843.9 ft/s

given $\rho = 0.002378 \text{ slugs}/\text{ft}^3$ then $q = 846.8 \text{ lb}/\text{ft}^2$

Number Crunching (2)

2. Determine α_{trim} and $i_{t_{\text{trim}}}$ from

$$\alpha_{\text{trim}_{\delta_e=0}} = -\frac{C_{M_{i_t}} \left(\frac{W \cos \gamma}{\bar{q}S} - C_{L_0} \right) + C_{L_{i_t}} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

$$i_{t_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C_{L_0} \right) + C_{L_\alpha} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

First we compute the things we don't have ... $C_{L_{i_t}}$, $C_{M_{i_t}}$, C_{M_0}

... then we “*plug and chug*”

Number Crunching (3)

- With $i_{t_{\text{trim}}}$ determined for the specified \bar{q} , define C'_{L_0} and C'_{M_0} as

$$C'_{L_0} = C_{L_0} + C_{L_{i_t}} i_{t_{\text{trim}}}$$

$$C'_{M_0} = C_{M_0} + C_{M_{i_t}} i_{t_{\text{trim}}}$$

Number Crunching (4)

4. Determine δ_e to trim at other \bar{q} 's. That is, solve

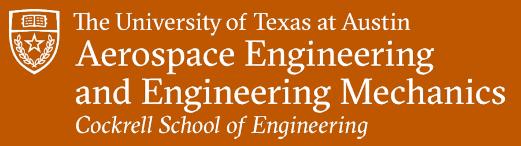
$$\alpha_{\text{trim}} = - \frac{C_{M_{\delta_e}} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L_{\delta_e}} C'_{M_0}}{C_{M_\alpha} C_{L_{\delta_e}} - C_{M_{\delta_e}} C_{L_\alpha}}$$

$$\delta_{e_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L_\alpha} C'_{M_0}}{C_{M_\alpha} C_{L_{\delta_e}} - C_{M_{\delta_e}} C_{L_\alpha}}$$

Why is this all important?

- Air Midwest Flight 5481
 - <https://www.youtube.com/watch?v=MMsbpLjfWlo>
 - <https://www.youtube.com/watch?v=CHj9Lmjo2Ng>

- Crash at Bagram Air Base
 - <https://www.youtube.com/watch?v=5fpxm0D46iQ>
 - https://www.youtube.com/watch?v=wXJ_MfAnjgQ



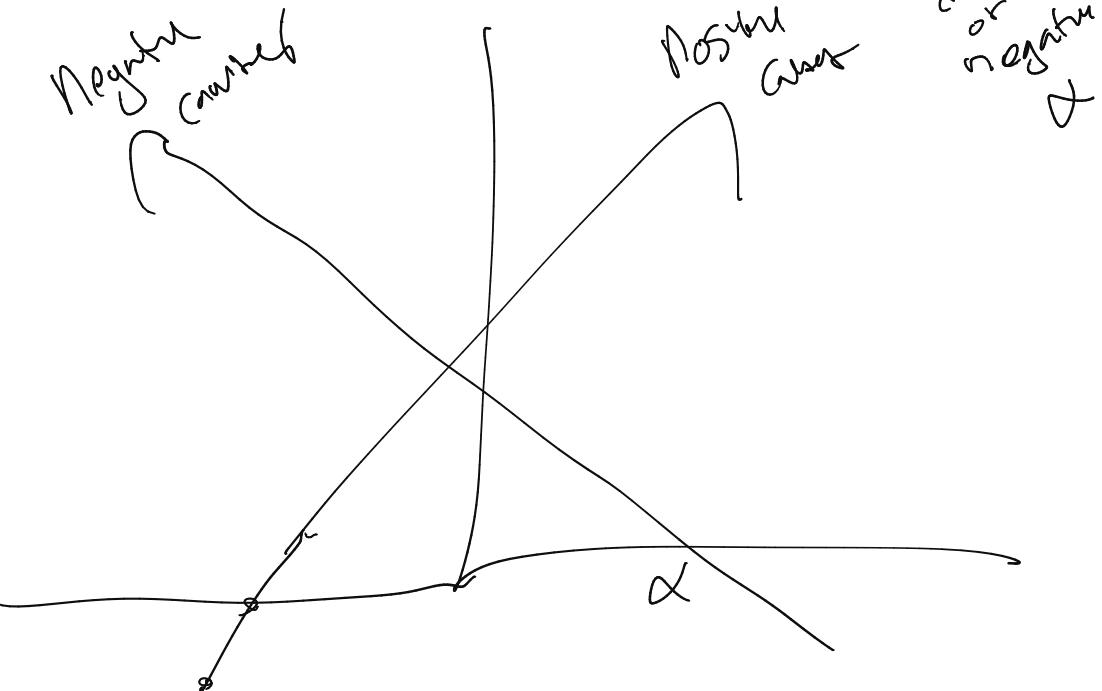
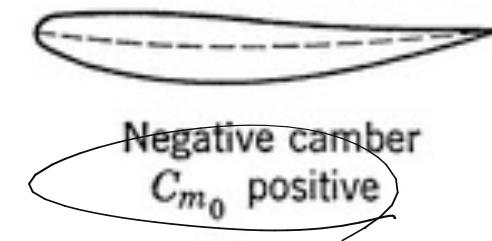
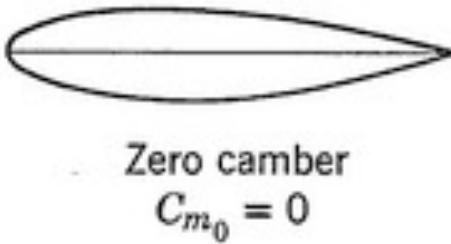
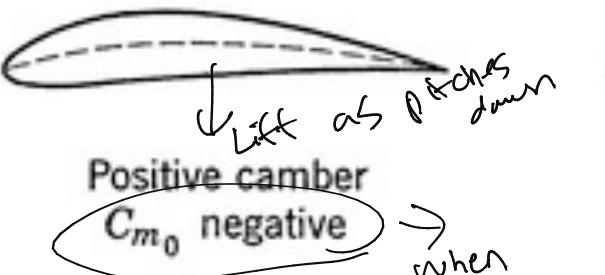
UPSIDE DOWN FLYING WING

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Moment of Wing Alone

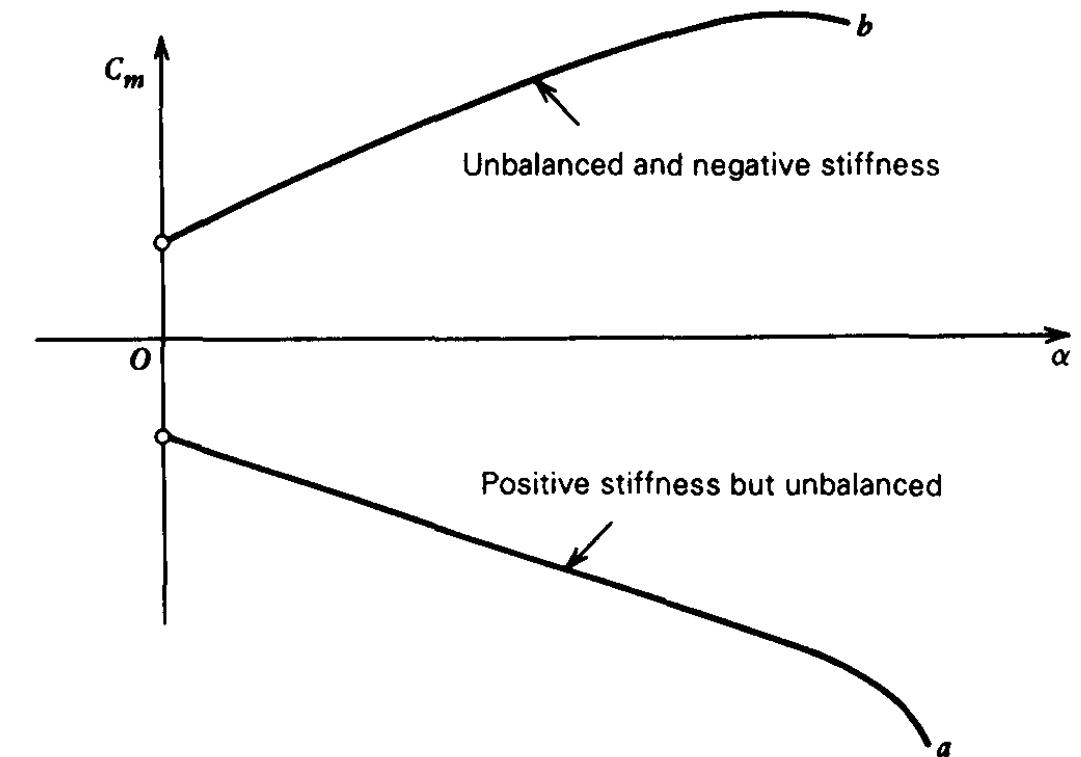
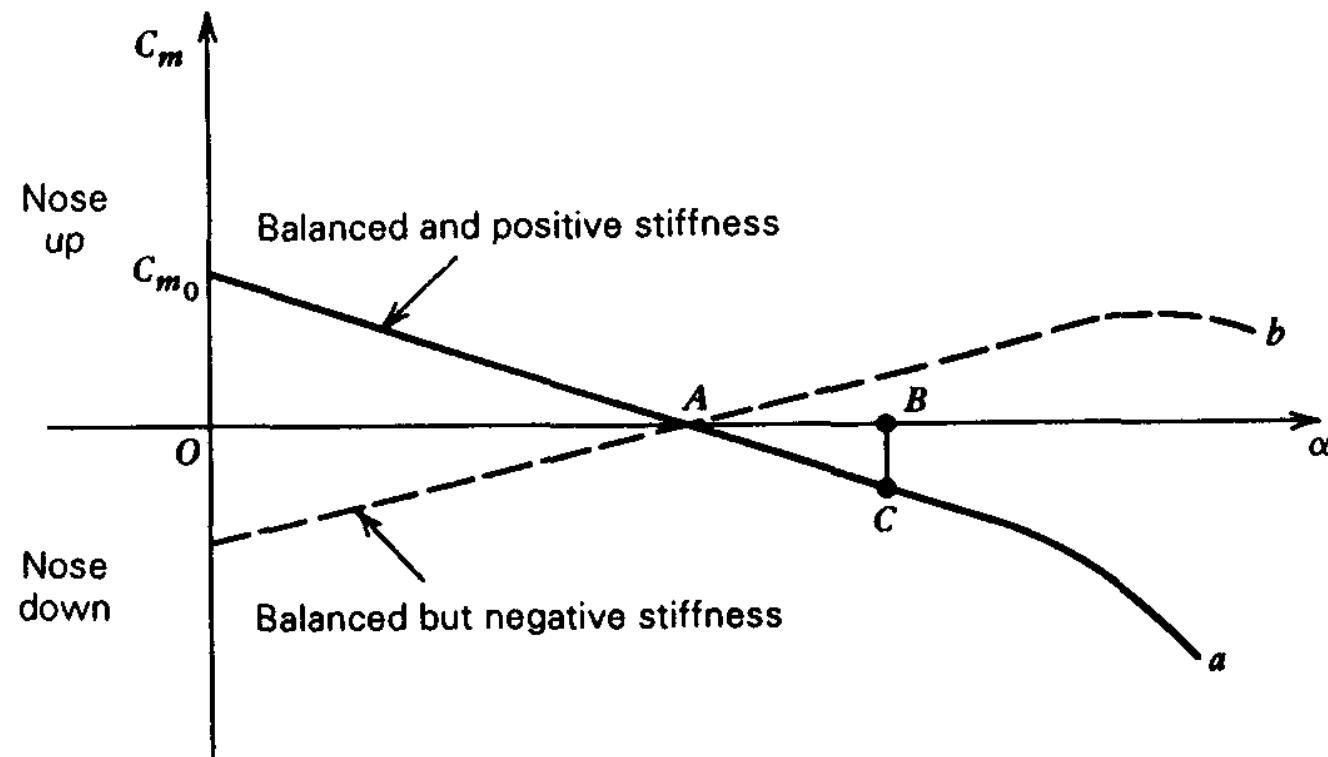
When it's upside down



$$C_m \alpha = \text{negative}$$



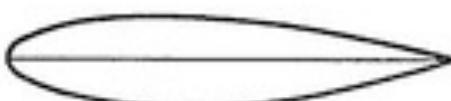
Balance and Stiffness



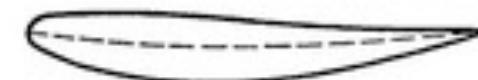
Moment of Wing Alone



Positive camber
 C_{m_0} negative



Zero camber
 $C_{m_0} = 0$



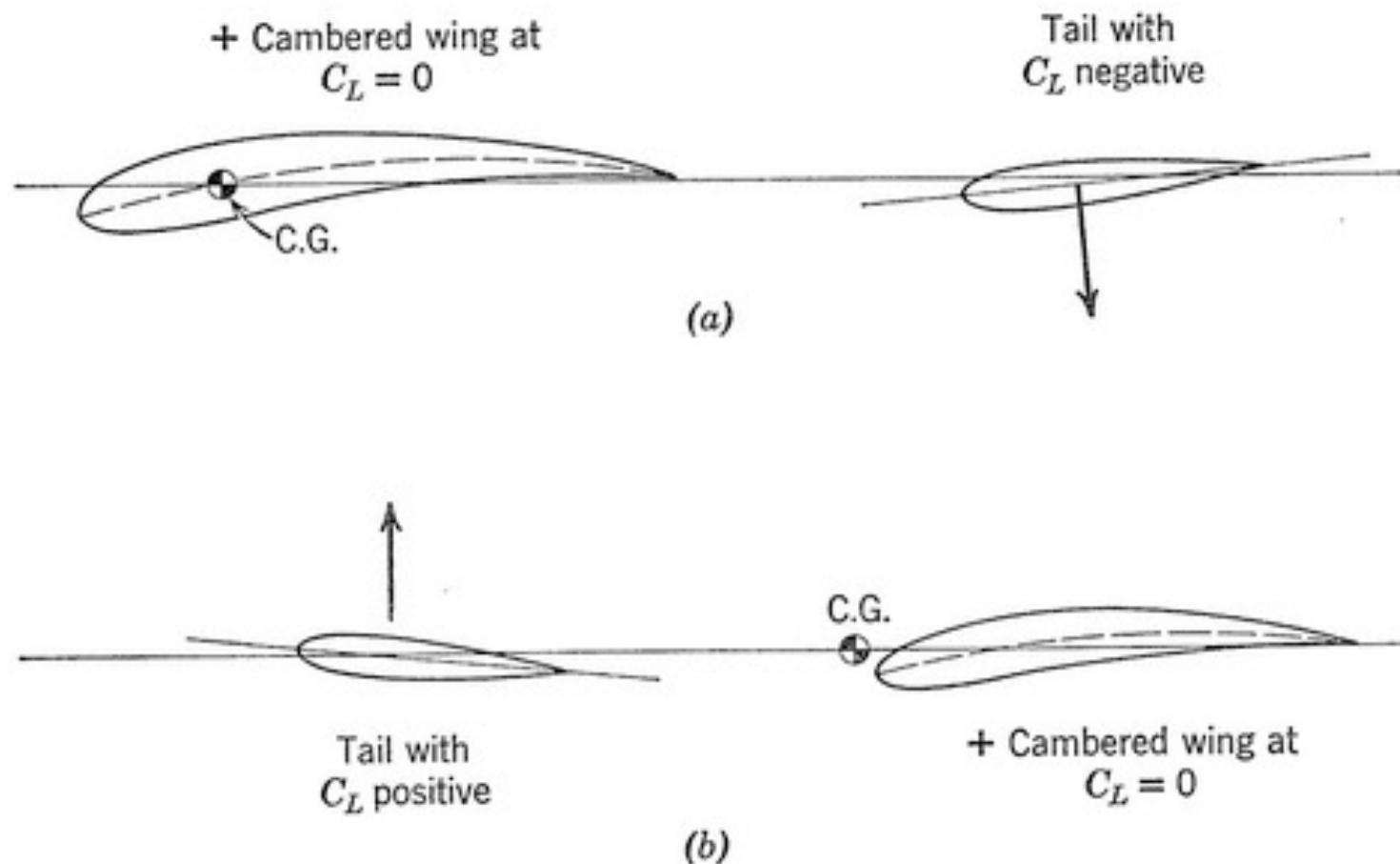
Negative camber
 C_{m_0} positive

Negative camber—flight possible at $\alpha > 0$; i.e. $C_L > 0$.

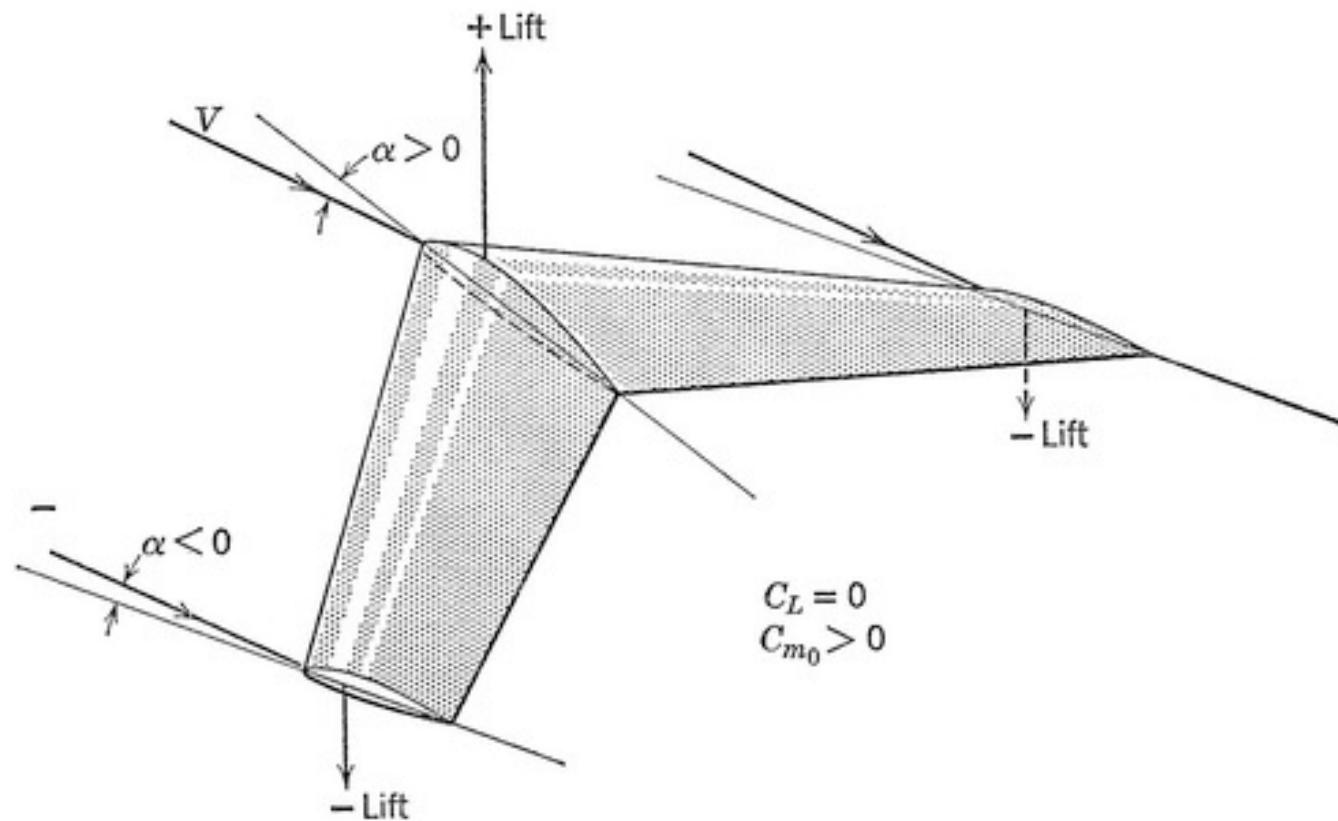
Zero camber—flight possible only at $\alpha = 0$, or $C_L = 0$.

Positive camber—flight not possible at any positive α or C_L .

Positive Pitch Stiffness - Tails + Canards



Positive Pitch Stiffness – Sweep + Twisted Tips





The University of Texas at Austin
Aerospace Engineering
and Engineering Mechanics
Cockrell School of Engineering