

5 SEPTEMBER 2024

ASE 367K: FLIGHT DYNAMICS

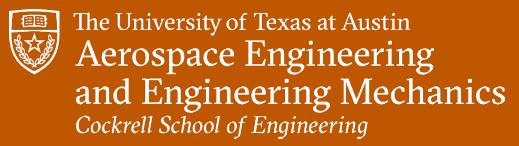
TTH 09:30-11:00
CMA 2.306

JOHN-PAUL CLARKE

Ernest Cockrell, Jr. Memorial Chair in Engineering, The University of Texas at Austin

Topics for Today

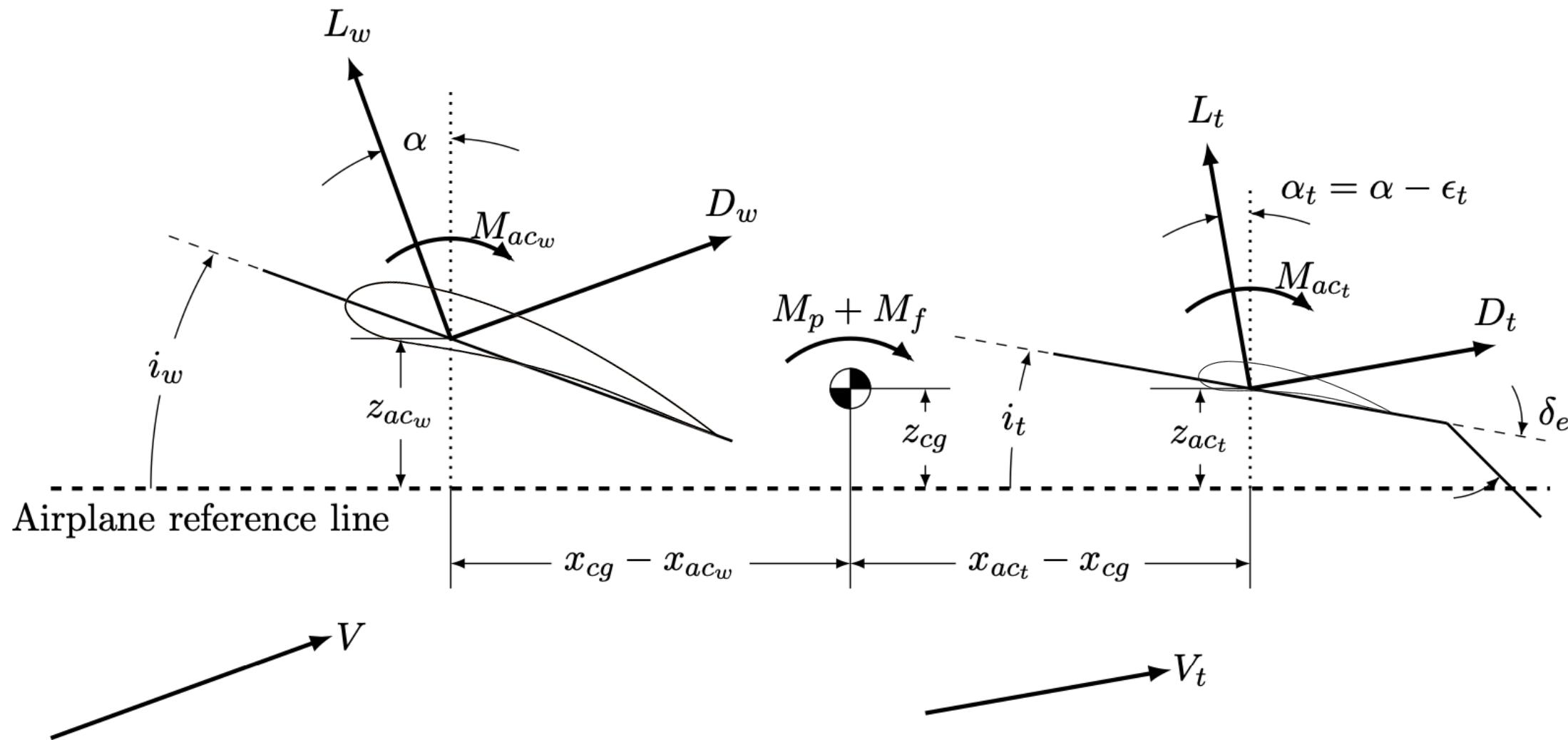
- Topic(s):
 - Lift of Aircraft + Moment about CG
 - Trim
 - Upside Down Flying Wing



LIFT OF AIRCRAFT + MOMENT ABOUT CG

JOHN-PAUL CLARKE

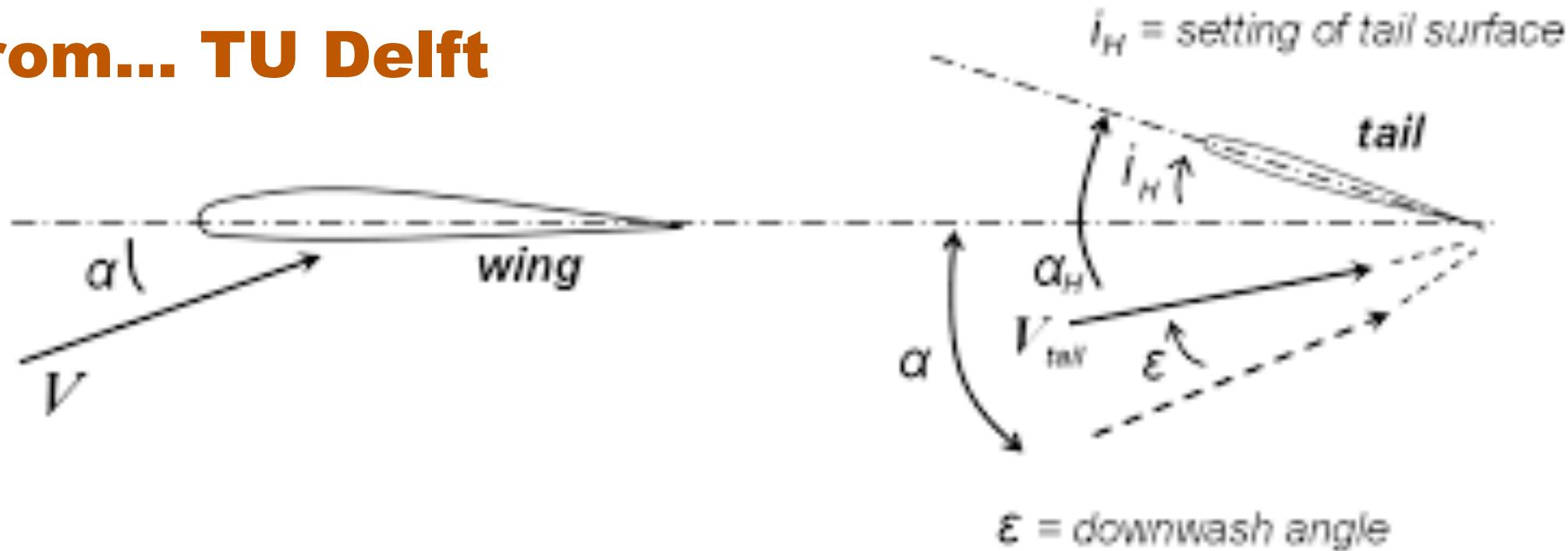
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NOTE:

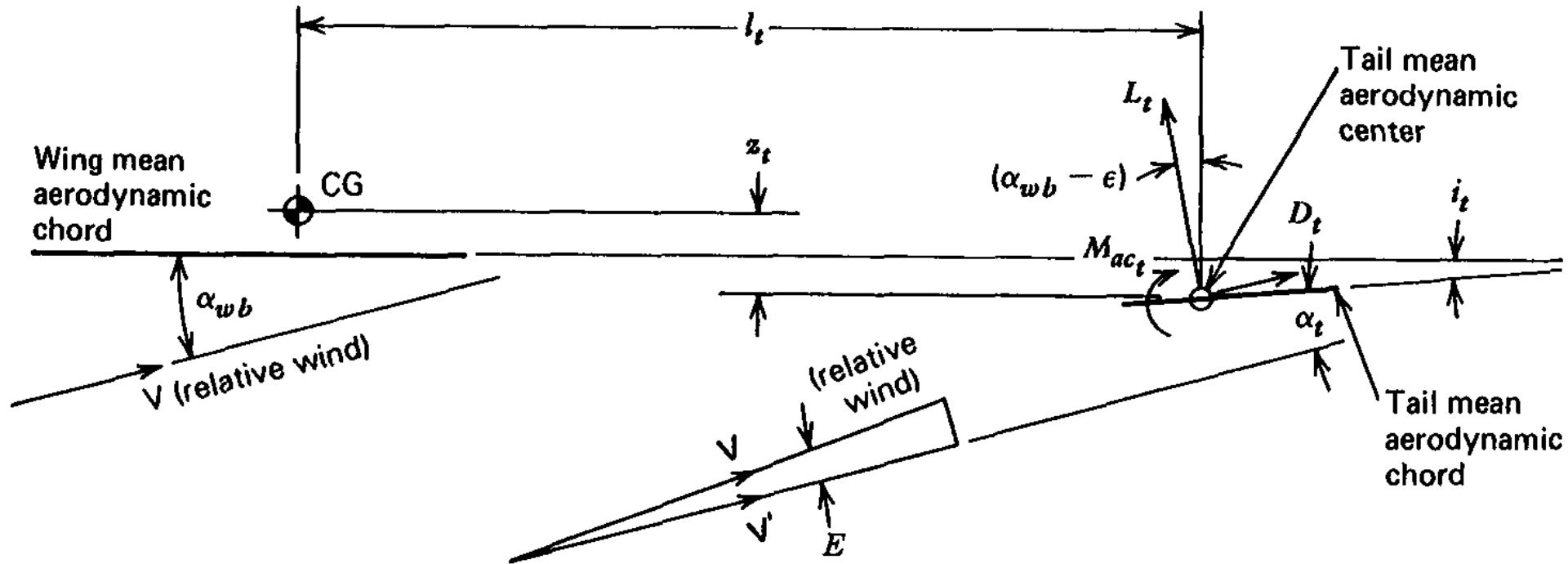
- (a) the angles of attack of the wing and horizontal tail are defined relative to the airplane reference line.
- (b) the incidence angles of the wing is the angle between the chord of the wing and the airplane reference line.
- (b) the incidence angles of the horizontal tail is the angle between the chord of the horizontal tail and the airplane reference line.

From... TU Delft

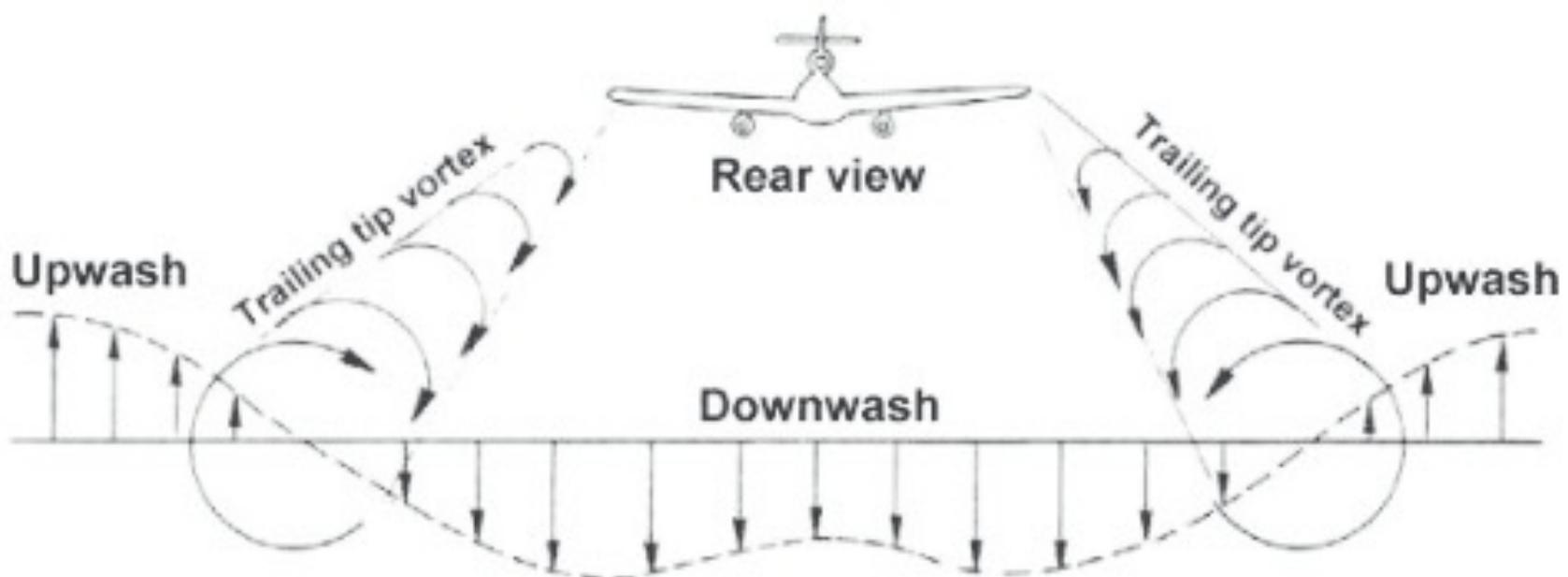
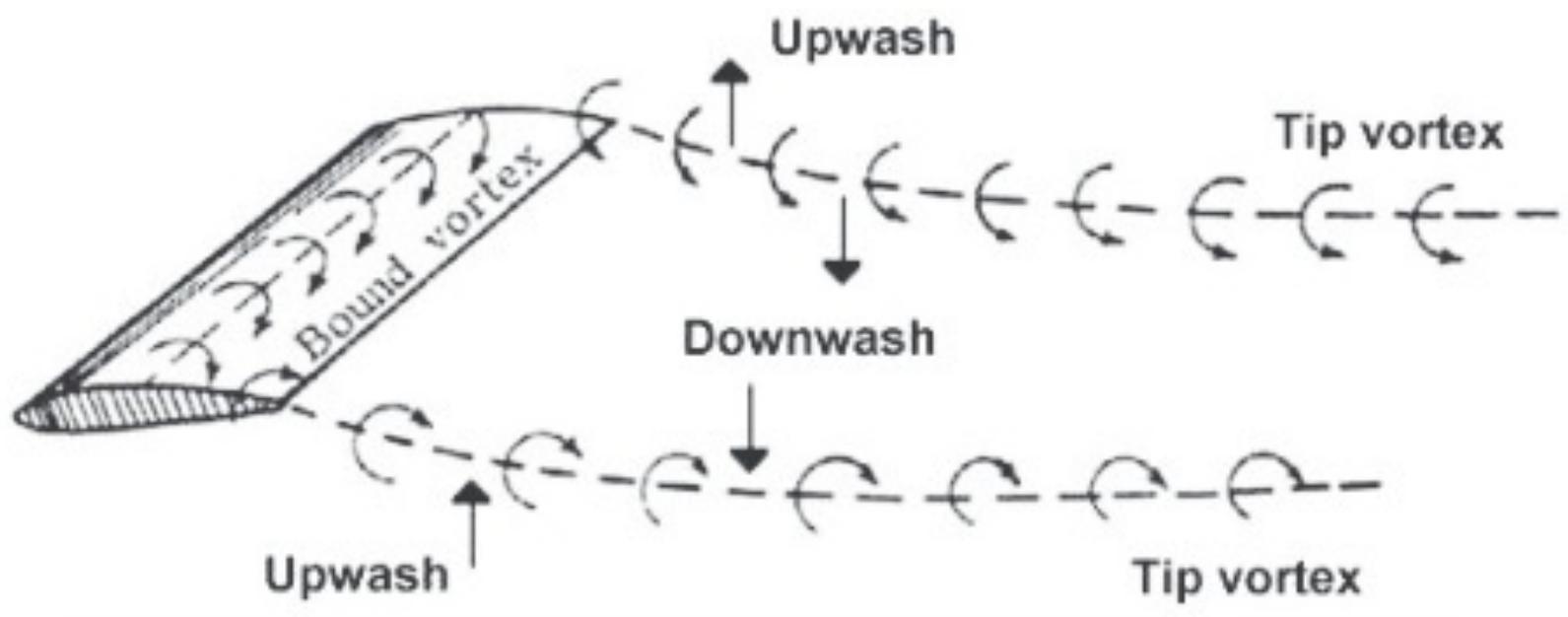


- NOTE:**
- (a) the chord of the wing and the aircraft reference line are colinear, thus the angle of attack of the wing is defined relative to the chord of the wing.
 - (b) the wing has no incidence angle.
 - (c) the angle of attack of the horizontal tail is defined relative to the aircraft reference line (or extended wing chord).
 - (d) the incidence angle of the tail is the angle between the chord of the horizontal tail and the aircraft reference line.

From... Etkin and Reid

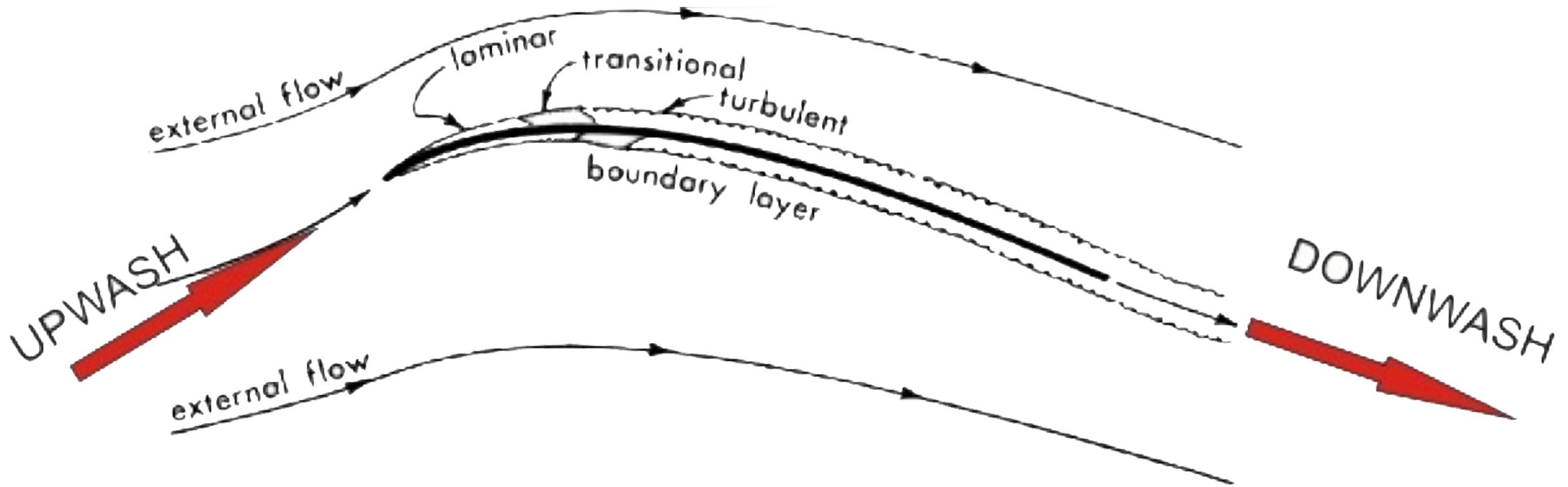


- NOTE:**
- (a) the chord of the wing and the aircraft reference line are colinear, thus the angle of attack of the wing is defined relative to the chord of the wing.
 - (b) the wing has no incidence angle.
 - (c) the angle of attack of the horizontal tail is defined relative to the aircraft reference line (or extended wing chord).
 - (d) the incidence angle of the tail is the angle between the chord of the horizontal tail and the aircraft reference line.



Downwash

$$\epsilon_t = \epsilon_{0t} + \epsilon_{\alpha t} \alpha$$

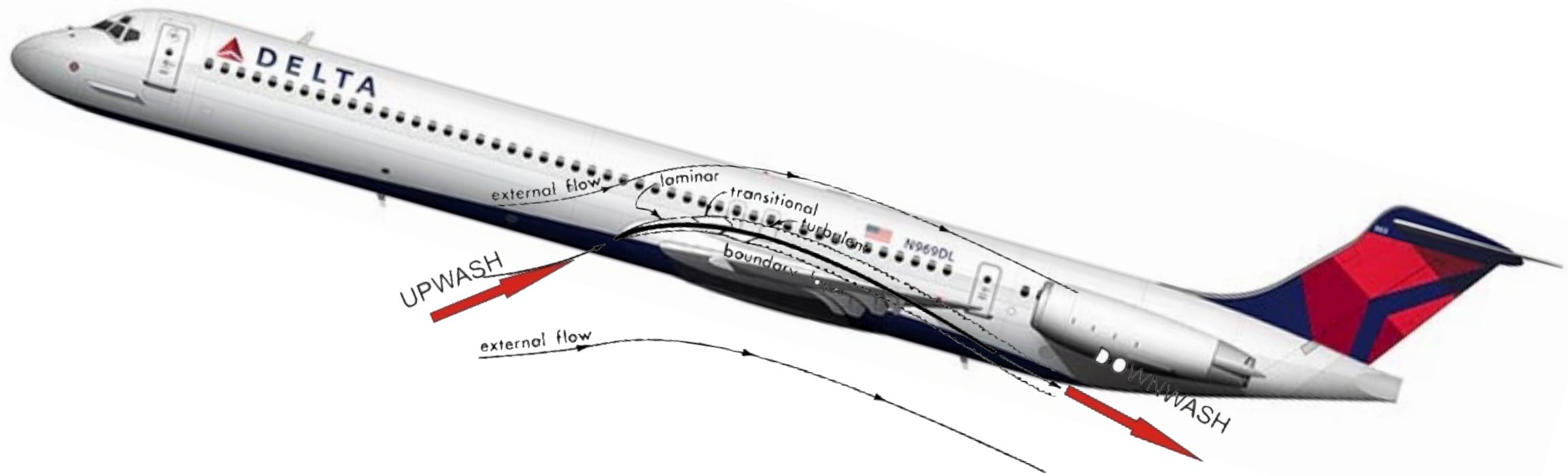


The downwash ϵ_0 at $\alpha_{wb} = 0$ results from the induced velocity field of the body and from wing twist; the latter produces a vortex wake and downwash field even at zero total lift. The constant derivative $\partial\epsilon/\partial\alpha$ occurs because the main contribution to the downwash at the tail comes from the wing trailing vortex wake, the strength of which is, in the linear case, proportional to C_L .









Total Lift Summary

$$C_L = C_{L_0} + C_{L_\alpha} \alpha + C_{L_{i_t}} i_t + C_{L_{\delta_e}} \delta_e$$

where $C_{L_0} = C_{L_{0w}} + C_{L_{\alpha w}} i_w + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (C_{L_{0t}} - C_{L_{\alpha t}} \epsilon_{0t})$

$$C_{L_\alpha} = C_{L_{\alpha w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t})$$

$$C_{L_{i_t}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\alpha t}}$$

$$C_{L_{\delta_e}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} C_{L_{\delta_e t}}$$

Pitch Moment Summary

$$C_{M_r} = C_{M_{0r}} + C_{M_{\alpha r}} \alpha + C_{M_{i_{tr}}} i_t + C_{M_{\delta_{er}}} \delta_e$$

$$\begin{aligned} C_{M_{0r}} &= C_{M_{acw}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} \frac{\bar{c}_t}{\bar{c}} C_{M_{act}} + C_{M_{0p}} + C_{M_{0f}} + (\bar{x}_r - \bar{x}_{acw}) (C_{L_{0w}} + C_{L_{\alpha w}} i_w) \\ &\quad + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) (C_{L_{0t}} - C_{L_{\alpha t}} \epsilon_{0t}) \end{aligned}$$

$$C_{M_{\alpha r}} = C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_r - \bar{x}_{acw}) C_{L_{\alpha w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\alpha t}} (1 - \epsilon_{\alpha t})$$

$$C_{M_{i_{tr}}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\alpha t}}$$

$$C_{M_{\delta_{er}}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_r - \bar{x}_{act}) C_{L_{\delta_{et}}}$$

Aerodynamic Center of Aircraft

- What is so unique about the aerodynamic center?

$$C_{M_{\alpha ac}} = 0$$

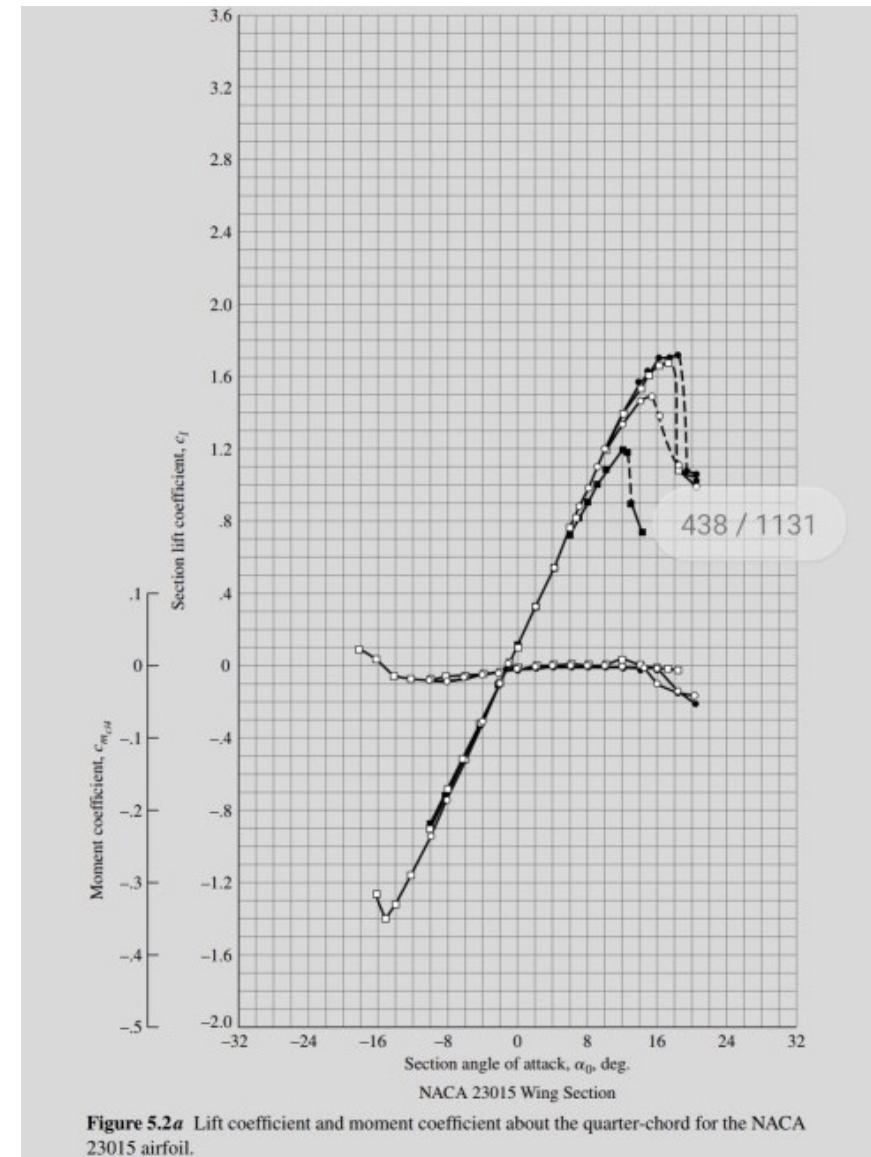


Figure 5.2a Lift coefficient and moment coefficient about the quarter-chord for the NACA 23015 airfoil.

Aerodynamic Center of Aircraft

- How do we determine the aerodynamic center?

$$\bar{x}_r = \bar{x}_{ac}$$

$$C_{M_{\alpha ac}} = C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_{ac} - \bar{x}_{ac_w}) C_{L_{\alpha w}} + \frac{q_t S_t}{qS} (\bar{x}_{ac} - \bar{x}_{ac_t}) C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) = 0$$

$$\rightarrow \bar{x}_{ac} \left[C_{L_{\alpha w}} + \frac{q_t S_t}{qS} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) \right] = \bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha t}} (1 - \epsilon_{\alpha t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}}$$

$$\rightarrow \bar{x}_{ac} C_{L_{\alpha}} = \bar{x}_{ac_w} C_{L_{\alpha_w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha_t}} (1 - \epsilon_{\alpha_t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}}$$

$$\rightarrow \bar{x}_{ac} = \frac{1}{C_{L_{\alpha}}} \left[\bar{x}_{ac_w} C_{L_{\alpha_w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha_t}} (1 - \epsilon_{\alpha_t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}} \right]$$

Pitch Moment about the CG

$$C_M = C_{M_0} + C_{M_\alpha} \alpha + C_{M_{i_t}} i_t + C_{M_{\delta_e}} \delta_e$$

$$C_{M_0} = C_{M_{ac_w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} \frac{\bar{c}_t}{\bar{c}} C_{M_{act}} + C_{M_{0_p}} + C_{M_{0_f}} + (\bar{x}_{cg} - \bar{x}_{ac_w}) (C_{L_{0_w}} + C_{L_{\alpha_w}} i_w)$$

$$+ \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) (C_{L_{0_t}} - C_{L_{\alpha_t}} \epsilon_{0_t})$$

$$C_{M_\alpha} = C_{M_{\alpha_p}} + C_{M_{\alpha_f}} + (\bar{x}_{cg} - \bar{x}_{ac_w}) C_{L_{\alpha_w}} + \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\alpha_t}} (1 - \epsilon_{\alpha_t})$$

$$C_{M_{i_t}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\alpha_t}}$$

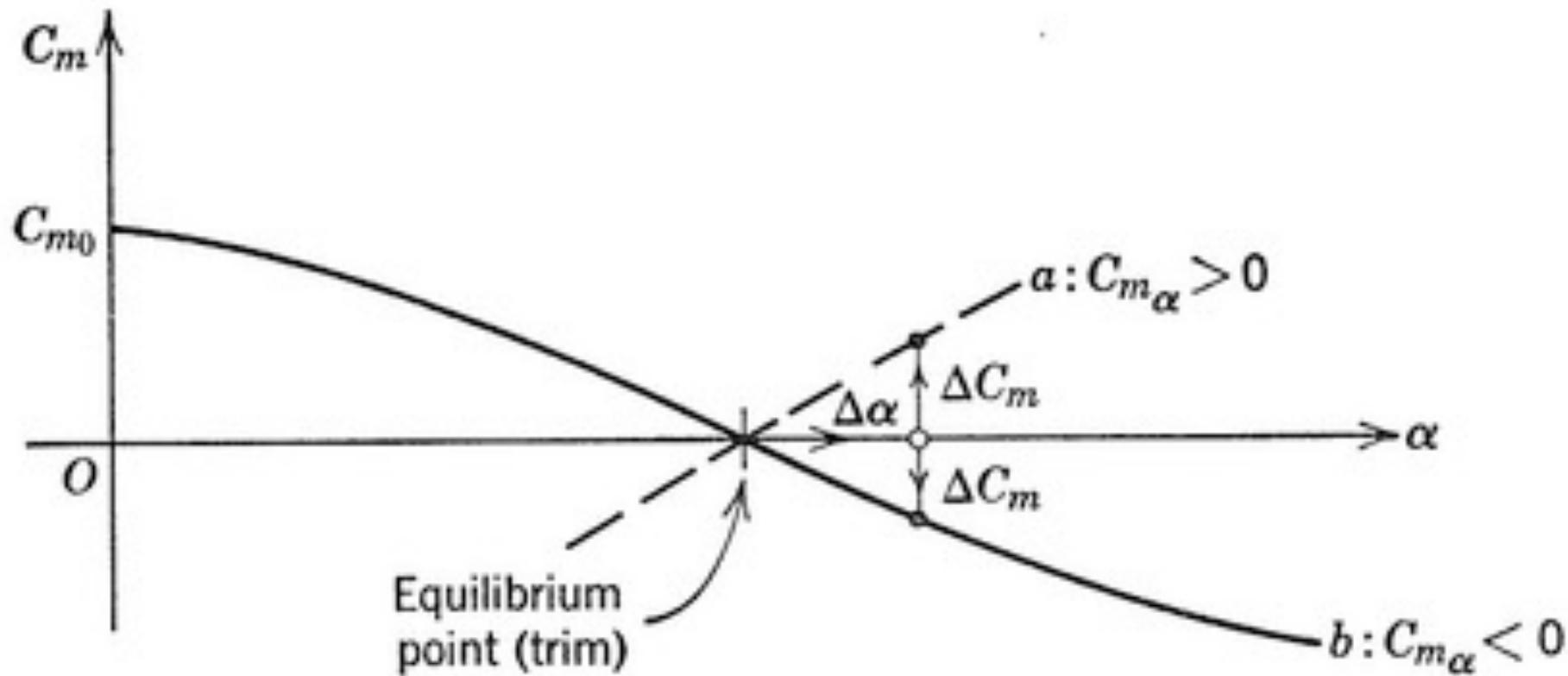
$$C_{M_{\delta_e}} = \frac{\bar{q}_t}{\bar{q}} \frac{S_t}{S} (\bar{x}_{cg} - \bar{x}_{act}) C_{L_{\delta_{e_t}}}$$

Static Margin

- Can we simplify the equation for C_{M_α} ?

$$\begin{aligned} C_{M_\alpha} &= C_{M_{\alpha p}} + C_{M_{\alpha f}} + (\bar{x}_{cg} - \bar{x}_{ac_w})C_{L_{\alpha w}} + \frac{q_t S_t}{qS} (\bar{x}_{cg} - \bar{x}_{ac_t})C_{L_{\alpha t}}(1 - \epsilon_{\alpha_t}) \\ &= \bar{x}_{cg} \left[C_{L_{\alpha w}} + \frac{q_t S_t}{qS} C_{L_{\alpha t}}(1 - \epsilon_{\alpha_t}) \right] - \left[\bar{x}_{ac_w} C_{L_{\alpha w}} + \frac{q_t S_t}{qS} \bar{x}_{ac_t} C_{L_{\alpha t}}(1 - \epsilon_{\alpha_t}) - C_{M_{\alpha p}} - C_{M_{\alpha f}} \right] \\ &= \bar{x}_{cg} C_{L_\alpha} - \bar{x}_{ac} C_{L_\alpha} \\ &= -(\bar{x}_{ac} - \bar{x}_{cg}) C_{L_\alpha} \\ &= -SM \cdot C_{L_\alpha} \quad \text{where SM is the "Static Margin"} \end{aligned}$$

Why is the Static Margin important?



Why is the Static Margin important?

- Which of the following aircraft is stable?

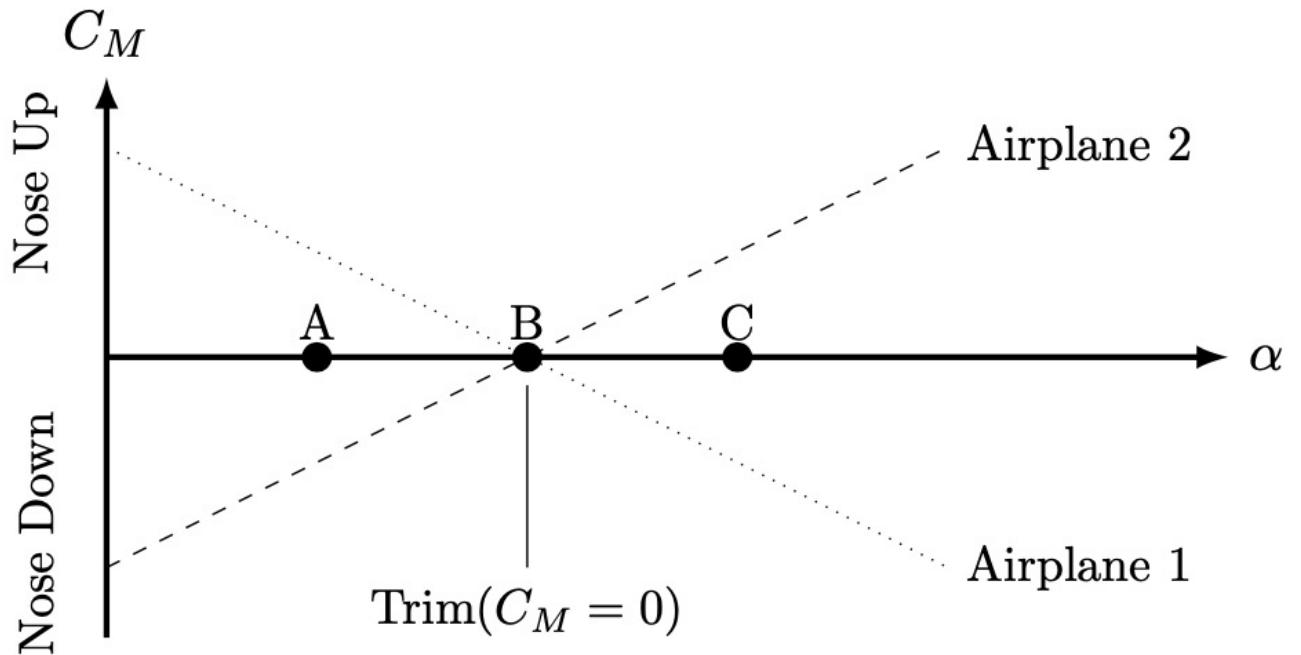


Figure 3.4: Pitch moment coefficient vs. angle of attack

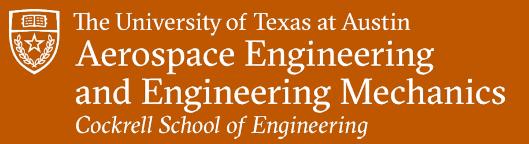
For a trimmed aircraft...

1. If $C_{M\alpha}$ (the slope of the line) is positive, then an increase in pitch (and thus in the angle of attack) results in a nose up pitching moment.
2. If $C_{M\alpha}$ is negative, then an increase in pitch (and thus in the angle of attack) results in a nose down pitching moment.
3. Thus, for the aircraft have longitudinal static stability we need $C_{M\alpha}$ to be negative.
4. Because $C_{L\alpha}$ is positive...
5. The SM must also be positive, and...
6. The center of gravity must be ahead, i.e., closer to the nose than the aerodynamic center of the aircraft.

**Weight on nose to move the c.g.
forward for longitudinal stability**



the static margin should be positive to achieve longitudinal static stability;
this also means that the center of gravity should be ahead of the aerodynamic center to achieve
longitudinal static stability

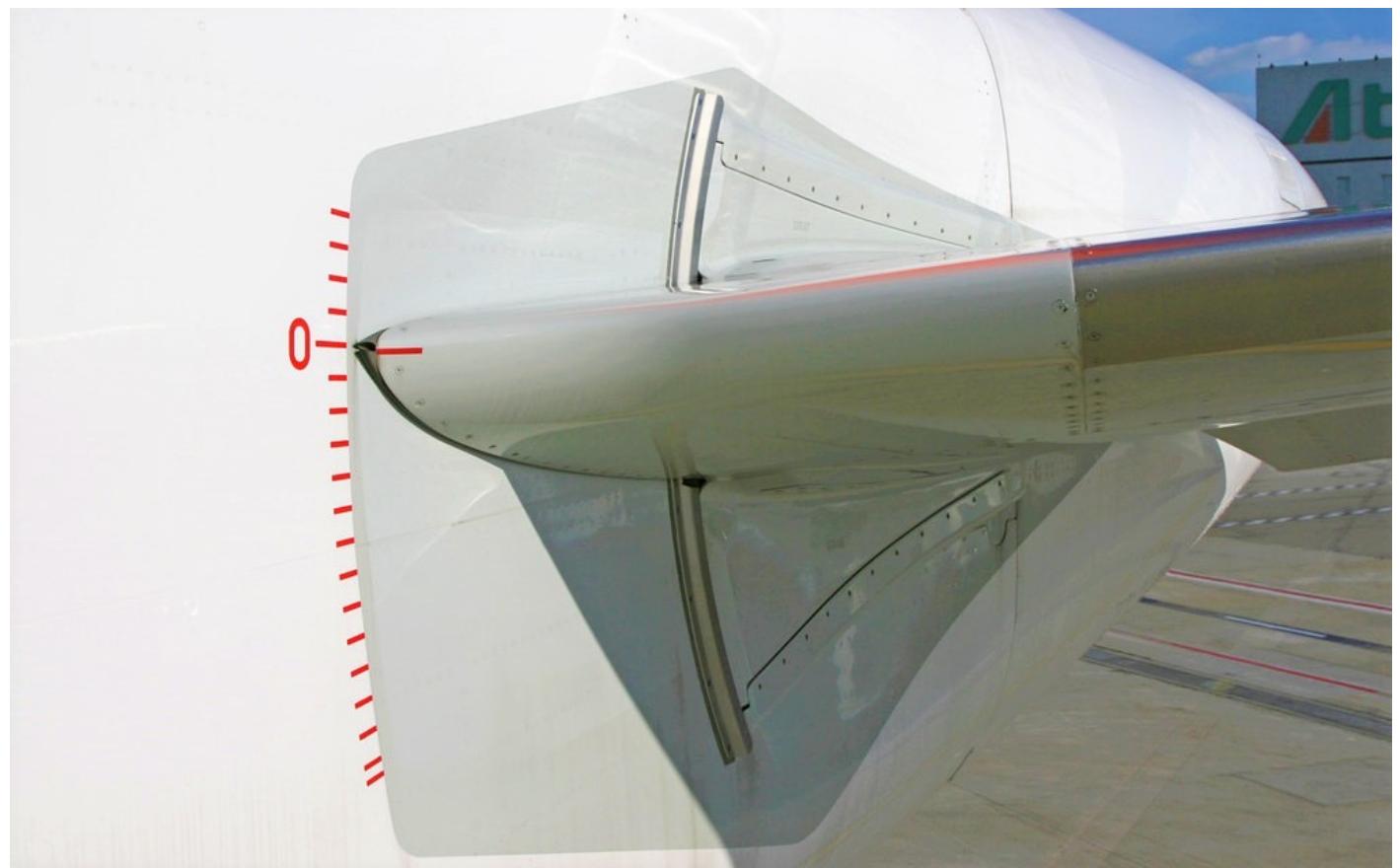
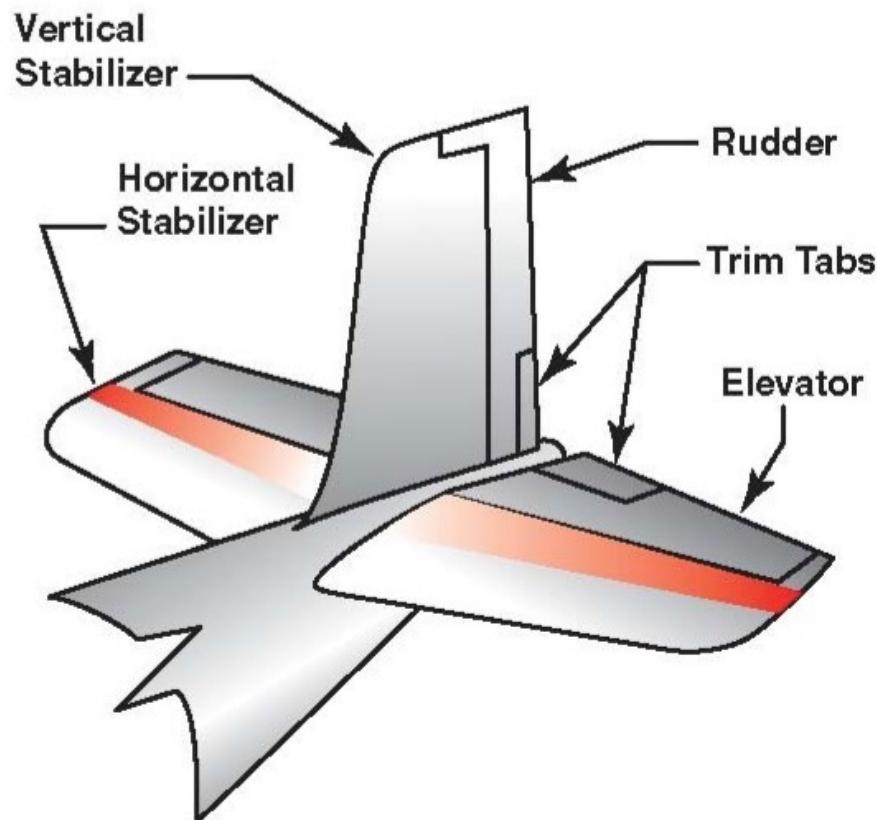


TRIM

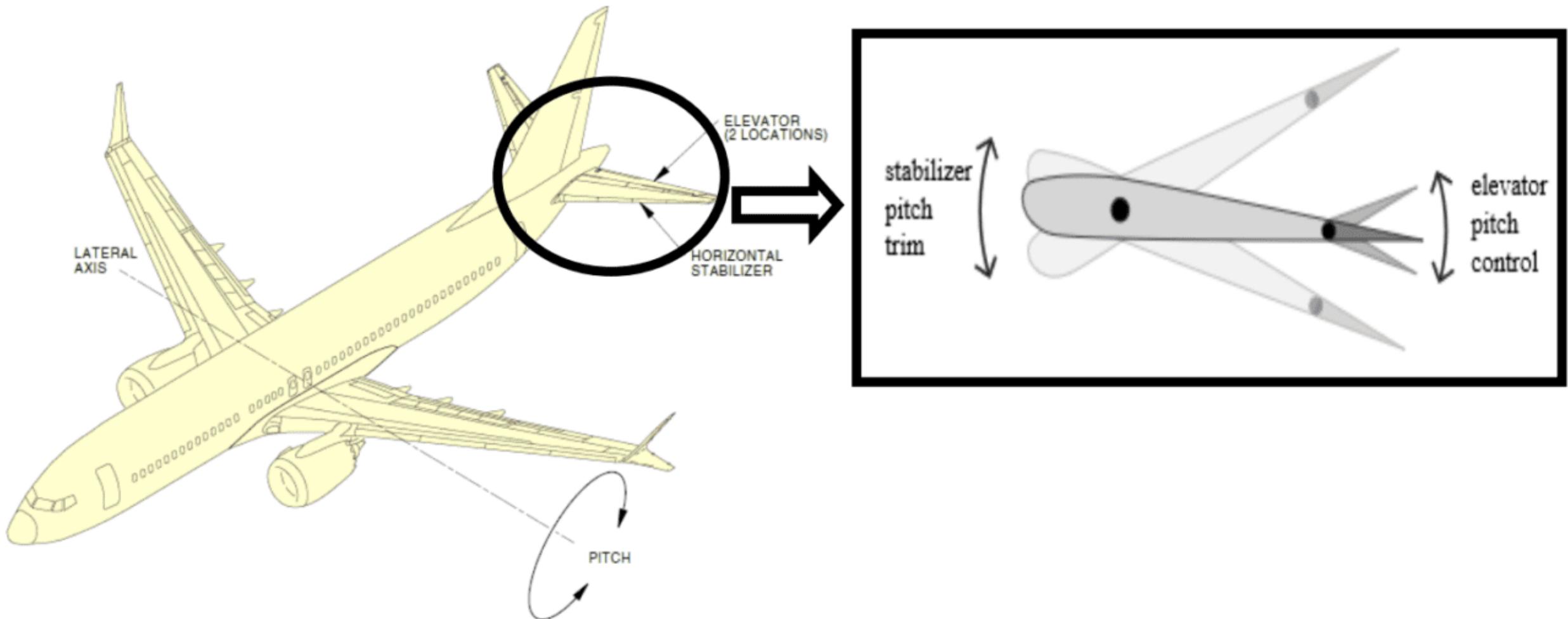
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Fixed v. Variable-Position Horizontal Stabilizer



Variable-Position Horizontal Stabilizer (1)



Variable-Position Horizontal Stabilizer (2)

1. Set desired speed, V , and fix $\bar{q} = \rho V^2/2$. Assume that $\delta_e = 0$ at this speed.
2. Determine α_{trim} and $i_{t_{\text{trim}}}$ from

$$\frac{W \cos \gamma}{\bar{q} S} = C_{L_0} + C_{L_\alpha} \alpha + C_{L_{i_t}} i_t$$
$$0 = C_{M_0} + C_{M_\alpha} \alpha + C_{M_{i_t}} i_t$$

which is equivalent to solving the linear system of equations

$$\begin{bmatrix} C_{L_\alpha} & C_{L_{i_t}} \\ C_{M_\alpha} & C_{M_{i_t}} \end{bmatrix} \begin{bmatrix} \alpha_{\text{trim}} \\ i_{t_{\text{trim}}} \end{bmatrix} = \begin{bmatrix} \frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \\ -C_{M_0} \end{bmatrix}$$

Variable-Position Horizontal Stabilizer (3)

and has the solution

$$\alpha_{\text{trim}_{\delta_e=0}} = - \frac{C_{M_{i_t}} \left(\frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \right) + C_{L_{i_t}} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

$$i_{t_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q} S} - C_{L_0} \right) + C_{L_\alpha} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

- With $i_{t_{\text{trim}}}$ determined for the specified \bar{q} , define C'_{L_0} and C'_{M_0} as

$$C'_{L_0} = C_{L_0} + C_{L_{i_t}} i_{t_{\text{trim}}}$$

$$C'_{M_0} = C_{M_0} + C_{M_{i_t}} i_{t_{\text{trim}}}$$

Variable-Position Horizontal Stabilizer (4)

4. Determine δ_e to trim at other \bar{q} 's. That is, solve

$$\begin{bmatrix} C_{L\alpha} & C_{L\delta_e} \\ C_{M\alpha} & C_{M\delta_e} \end{bmatrix} \begin{bmatrix} \alpha \\ \delta_e \end{bmatrix} = \begin{bmatrix} \frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \\ -C'_{M_0} \end{bmatrix}$$

to find α_{trim} and $\delta_{e_{\text{trim}}}$, which gives

$$\alpha_{\text{trim}} = -\frac{C_{M\delta_e} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L\delta_e} C'_{M_0}}{C_{M\alpha} C_{L\delta_e} - C_{M\delta_e} C_{L\alpha}}$$

$$\delta_{e_{\text{trim}}} = \frac{C_{M\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L\alpha} C'_{M_0}}{C_{M\alpha} C_{L\delta_e} - C_{M\delta_e} C_{L\alpha}}$$

Let's do some number crunching...

- The aircraft is in level flight.
- The gravitational acceleration is $32.174 \text{ [ft/s}^2\text{]}$.
- The wing and horizontal stabilizer are trapezoidal surfaces.
- The cg of the aircraft is at $x_{cg} = 10.56 \text{ [ft]}$.
- The weight of the aircraft is $W = 9,500 \text{ [lb]}$.
- The propulsive moment coefficients are $C_{M_{0p}} = 0.0$ and $C_{M_{\alpha p}} = 0.0$.
- The fuselage moment coefficients are $C_{M_{0f}} = 0.0$ and $C_{M_{\alpha f}} = 0.0$.
- The atmospheric density is $0.002378 \text{ [slugs/ft}^3\text{]}$.
- The horizontal tail incidence can only be set between -0.5 and -7 [deg] .

Wing	Horizontal Stabilizer
$S = 232.00 \text{ [ft}^2\text{]}$	$S = 54.00 \text{ [ft}^2\text{]}$
$\bar{c} = 7.04 \text{ [ft]}$	$\bar{c} = 3.83 \text{ [ft]}$
$x_{ac/le} = 4.07 \text{ [ft]}$	$x_{ac/le} = 2.79 \text{ [ft]}$
$x_{le} = 16.40 \text{ [ft]}$	$x_{le} = 36.90 \text{ [ft]}$
$i = 1.00 \text{ [deg]}$	
$C_{L_0} = -0.0443$	$C_{L_0} = 0.0000$
$C_{L_\alpha} = 5.0800$	$C_{L_\alpha} = 4.2600$
$C_{M_{ac}} = -0.0175$	$C_{M_{ac}} = 0.0000$
	$C_{L_{\delta_{et}}} = 1.8000$
	$\epsilon_0 = 0.642 \text{ [deg]}$
	$\epsilon_\alpha = 0.426$
	$\eta = 0.9$

$$\eta = \frac{q_t}{q}$$

Number Crunching (1)

1. Set desired speed, V , and fix $\bar{q} = \rho V^2 / 2$. Assume that $\delta_e = 0$ at this speed.

Let's assume aircraft is flying at ... 500 *knots* = 843.9 *ft/s*

given $\rho = 0.002378 \text{ slugs}/\text{ft}^3$ then $q = 846.8 \text{ lb}/\text{ft}^2$

Number Crunching (2)

2. Determine α_{trim} and $i_{t_{\text{trim}}}$ from

$$\alpha_{\text{trim}_{\delta_e=0}} = -\frac{C_{M_{i_t}} \left(\frac{W \cos \gamma}{\bar{q}S} - C_{L_0} \right) + C_{L_{i_t}} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

$$i_{t_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C_{L_0} \right) + C_{L_\alpha} C_{M_0}}{C_{M_\alpha} C_{L_{i_t}} - C_{M_{i_t}} C_{L_\alpha}}$$

First we compute the things we don't have ... $C_{L_{i_t}}$, $C_{M_{i_t}}$, C_{M_0}

... then we “*plug and chug*”

Number Crunching (3)

3. With $i_{t_{\text{trim}}}$ determined for the specified \bar{q} , define C'_{L_0} and C'_{M_0} as

$$C'_{L_0} = C_{L_0} + C_{L_{i_t}} i_{t_{\text{trim}}}$$

$$C'_{M_0} = C_{M_0} + C_{M_{i_t}} i_{t_{\text{trim}}}$$

Number Crunching (4)

4. Determine δ_e to trim at other \bar{q} 's. That is, solve

$$\alpha_{\text{trim}} = - \frac{C_{M_{\delta_e}} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L_{\delta_e}} C'_{M_0}}{C_{M_\alpha} C_{L_{\delta_e}} - C_{M_{\delta_e}} C_{L_\alpha}}$$

$$\delta_{e_{\text{trim}}} = \frac{C_{M_\alpha} \left(\frac{W \cos \gamma}{\bar{q}S} - C'_{L_0} \right) + C_{L_\alpha} C'_{M_0}}{C_{M_\alpha} C_{L_{\delta_e}} - C_{M_{\delta_e}} C_{L_\alpha}}$$

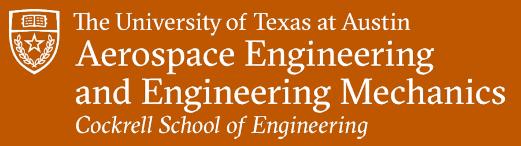
Why is this all important?

- Air Midwest Flight 5481

- <https://www.youtube.com/watch?v=MMsbpLjfWlo>
 - <https://www.youtube.com/watch?v=CHj9Lmjo2Ng>

- Crash at Bagram Air Base

- <https://www.youtube.com/watch?v=5fpxm0D46iQ>
 - https://www.youtube.com/watch?v=wXJ_MfAnjgQ

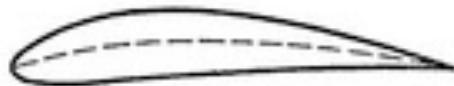


UPSIDE DOWN FLYING WING

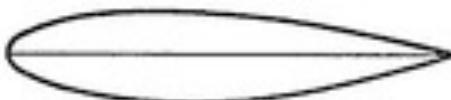
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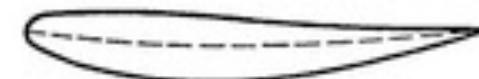
Moment of Wing Alone



Positive camber
 C_{m_0} negative

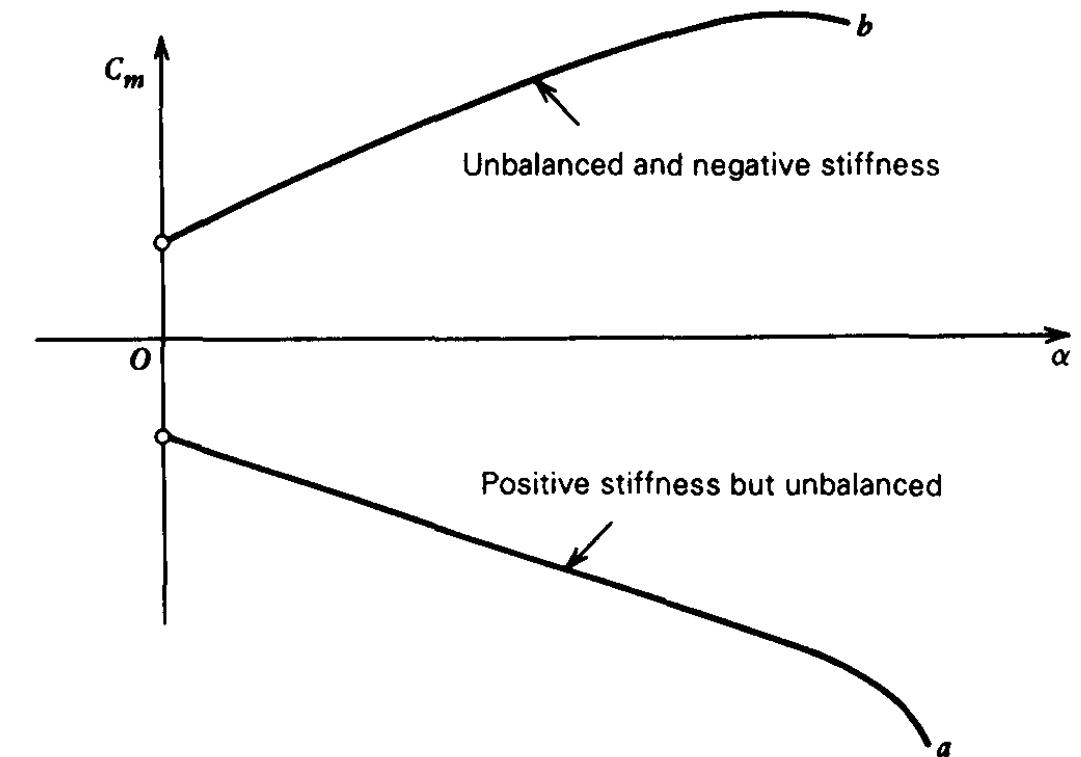
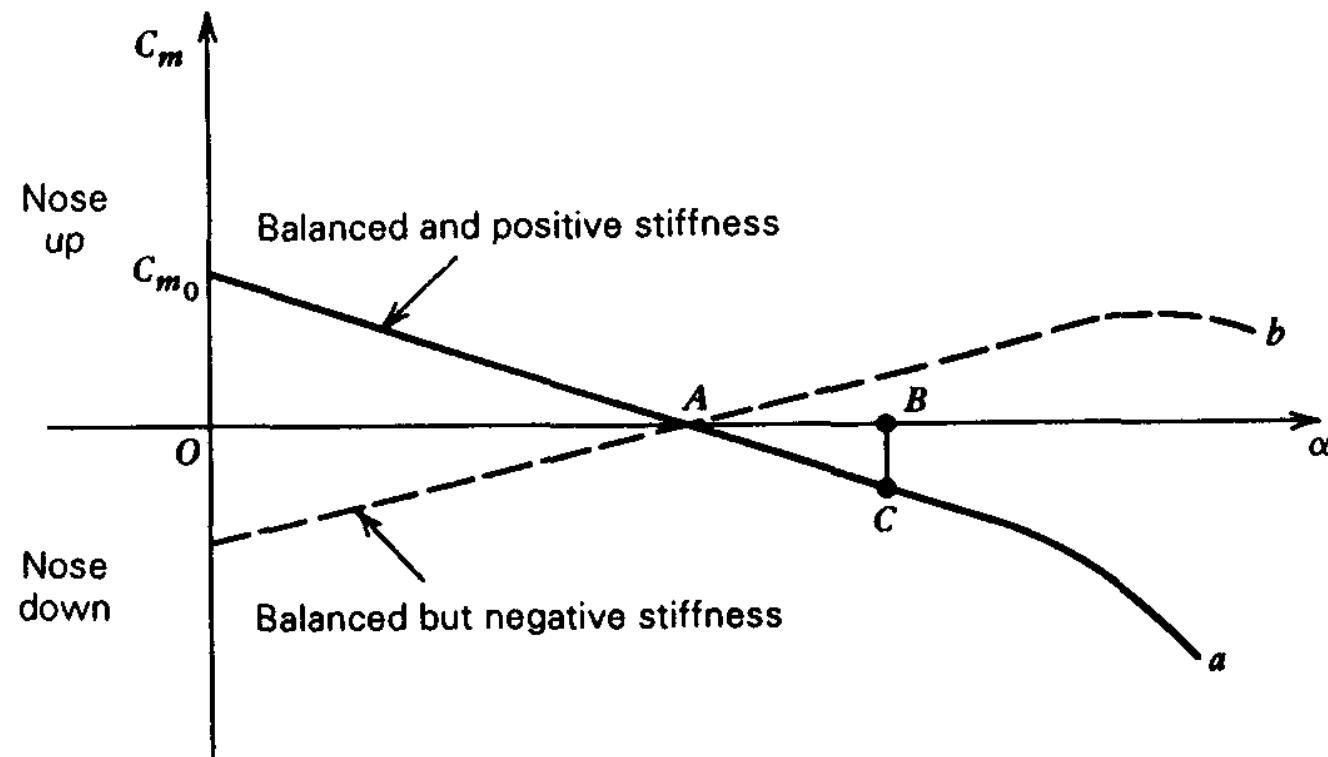


Zero camber
 $C_{m_0} = 0$



Negative camber
 C_{m_0} positive

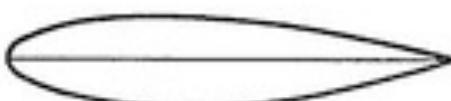
Balance and Stiffness



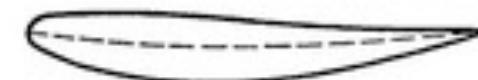
Moment of Wing Alone



Positive camber
 C_{m_0} negative



Zero camber
 $C_{m_0} = 0$



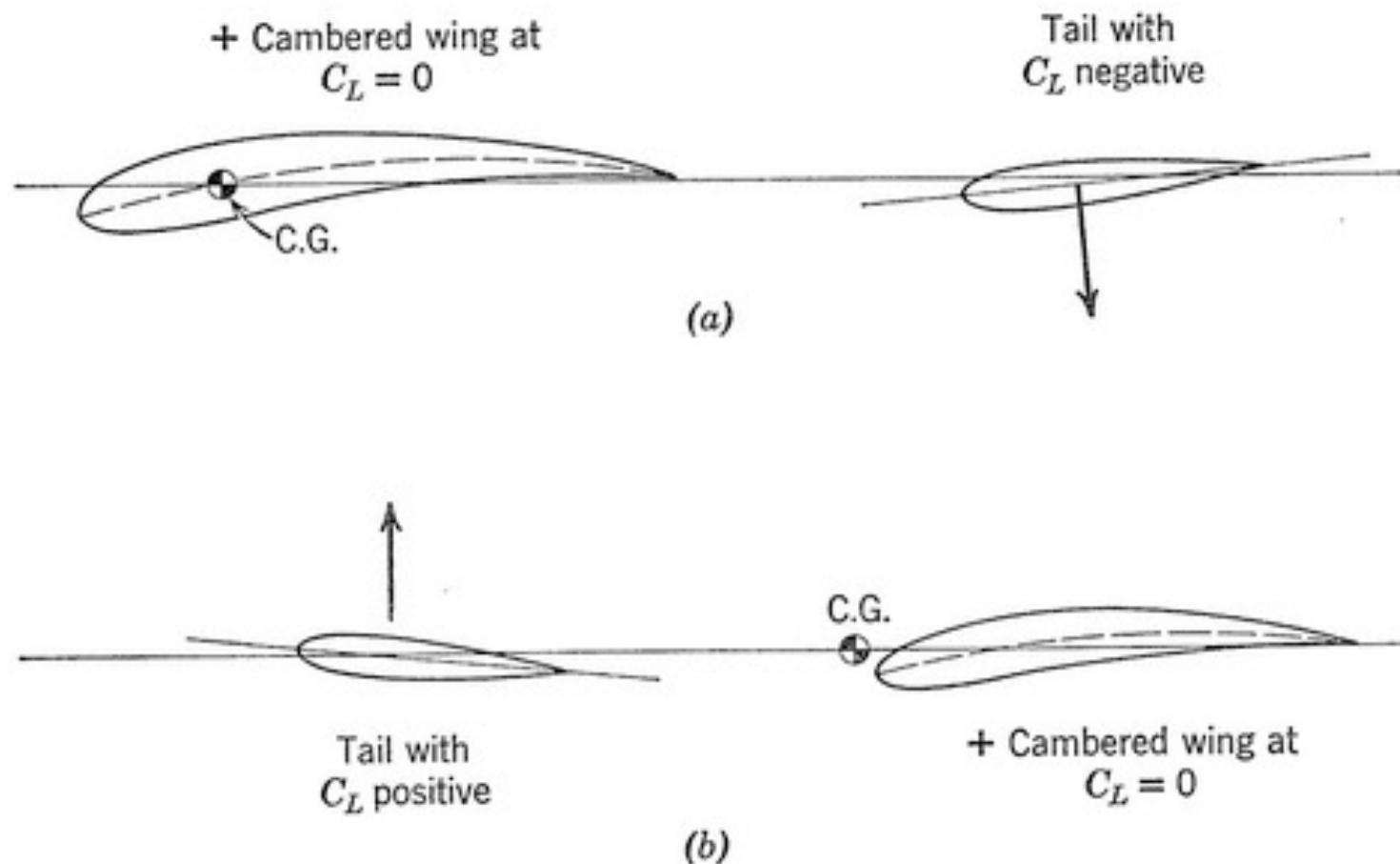
Negative camber
 C_{m_0} positive

Negative camber—flight possible at $\alpha > 0$; i.e. $C_L > 0$.

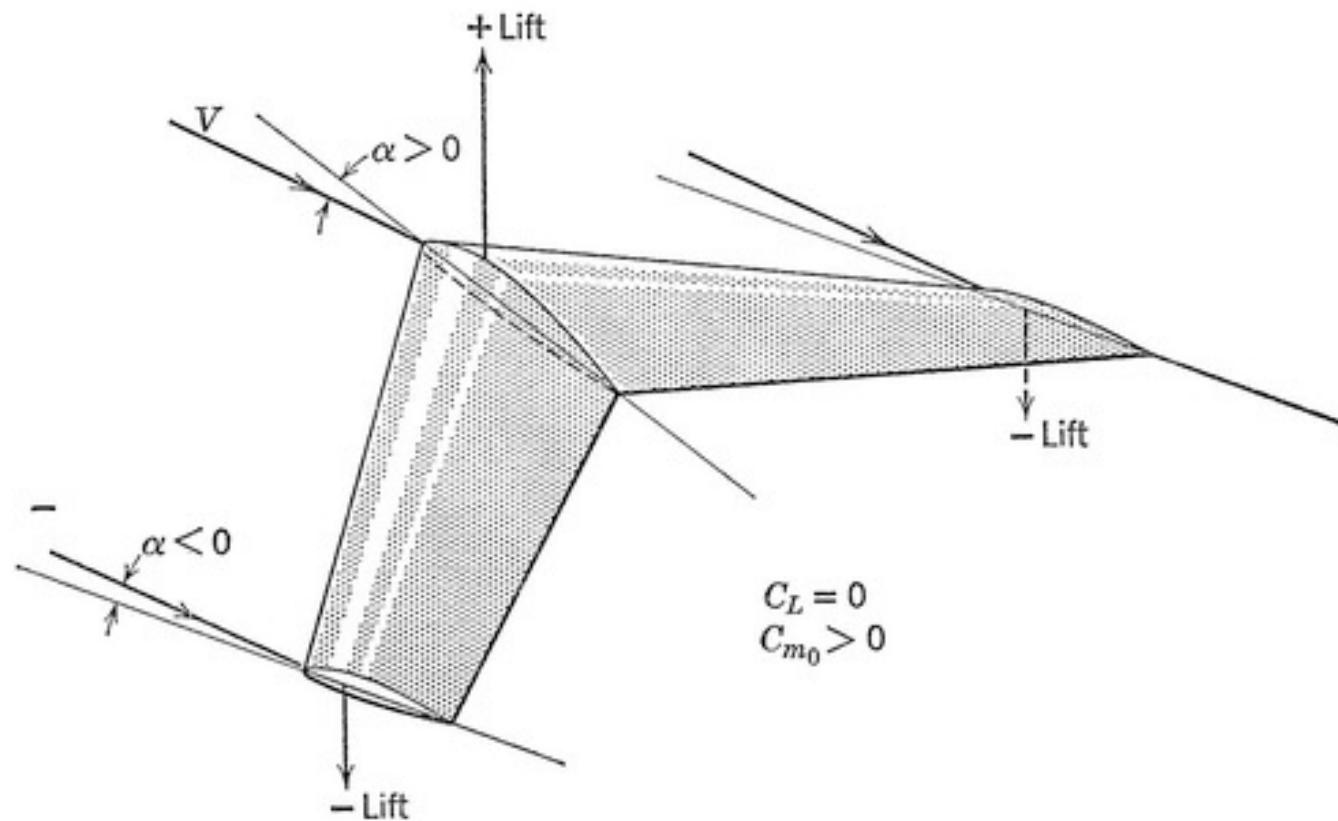
Zero camber—flight possible only at $\alpha = 0$, or $C_L = 0$.

Positive camber—flight not possible at any positive α or C_L .

Positive Pitch Stiffness - Tails + Canards



Positive Pitch Stiffness – Sweep + Twisted Tips





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Aerospace Engineering
and Engineering Mechanics
Cockrell School of Engineering