

GEANT4 GPU Port:

Test Report

Stuart Douglas – dougls2
Matthew Pagnan – pagnanmm
Rob Gorrie – gorrierw
Victor Reginato – reginavp

Version 0
March 20, 2016

Contents

| | | |
|----------|---|----------|
| 1 | Introduction | 2 |
| 1.1 | Purpose of the Document | 2 |
| 1.2 | Scope of the Testing | 2 |
| 1.3 | Organization | 2 |
| 1.4 | Usability Testing | 2 |
| 1.5 | Robustness Testing | 2 |
| | | |
| 2 | Unit Testing | 3 |
| 2.1 | Use of Automated Testing | 3 |
| 2.1.1 | Overview | 3 |
| 2.1.2 | Generating Test Results | 3 |
| 2.1.3 | Analyzing Test Results | 3 |
| 2.1.4 | Note About Random Results | 3 |
| 2.2 | Definition of Variables Used for Unit Testing | 4 |
| 2.3 | = (overloaded assignment operator) | 4 |
| 2.3.1 | Method Signature | 4 |
| 2.3.2 | Test Description | 4 |
| 2.3.3 | Test Inputs | 5 |
| 2.3.4 | Results | 5 |
| 2.3.5 | Performance | 5 |
| 2.4 | GetPoint | 5 |
| 2.4.1 | Method Signature | 5 |
| 2.4.2 | Test Description | 5 |
| 2.4.3 | Test Inputs | 5 |
| 2.4.4 | Test Results | 6 |
| 2.4.5 | Performance | 6 |
| 2.5 | GetX | 6 |
| 2.5.1 | Unit Tests | 6 |
| 2.5.2 | Accuracy | 7 |
| 2.5.3 | Performance | 7 |
| 2.6 | GetY | 7 |
| 2.6.1 | Unit Tests | 7 |
| 2.6.2 | Accuracy | 8 |
| 2.6.3 | Performance | 8 |
| 2.7 | GetXsec | 8 |
| 2.7.1 | Unit Tests | 8 |
| 2.7.2 | Accuracy | 9 |
| 2.7.3 | Performance | 9 |
| 2.8 | SetData | 9 |
| 2.8.1 | Unit Tests | 9 |
| 2.8.2 | Accuracy | 10 |
| 2.8.3 | Performance | 10 |

| | | |
|--------|---------------------------------|----|
| 2.9 | SetEnergy | 10 |
| 2.9.1 | Unit Tests | 10 |
| 2.9.2 | Accuracy | 11 |
| 2.9.3 | Performance | 11 |
| 2.10 | SetXsec | 11 |
| 2.10.1 | Unit Tests | 11 |
| 2.10.2 | Accuracy | 12 |
| 2.10.3 | Performance | 12 |
| 2.11 | SetX | 12 |
| 2.11.1 | Unit Tests | 12 |
| 2.11.2 | Accuracy | 13 |
| 2.11.3 | Performance | 13 |
| 2.12 | SetY | 13 |
| 2.12.1 | Unit Tests | 13 |
| 2.12.2 | Accuracy | 14 |
| 2.12.3 | Performance | 14 |
| 2.13 | Init | 14 |
| 2.13.1 | Unit Tests | 14 |
| 2.13.2 | Accuracy | 14 |
| 2.13.3 | Performance | 15 |
| 2.14 | SampleLin | 15 |
| 2.14.1 | Unit Tests | 15 |
| 2.14.2 | Accuracy | 15 |
| 2.14.3 | Performance | 15 |
| 2.15 | Integrate | 15 |
| 2.15.1 | Unit Tests | 15 |
| 2.15.2 | Accuracy | 15 |
| 2.15.3 | Performance | 16 |
| 2.16 | IntegrateAndNormalise | 16 |
| 2.16.1 | Unit Tests | 16 |
| 2.16.2 | Accuracy | 16 |
| 2.16.3 | Performance | 16 |
| 2.17 | Times | 16 |
| 2.17.1 | Unit Tests | 16 |
| 2.17.2 | Accuracy | 17 |
| 2.17.3 | Performance | 17 |
| 2.18 | ThinOut | 17 |
| 2.18.1 | Unit Tests | 17 |
| 2.18.2 | Accuracy | 17 |
| 2.18.3 | Performance | 18 |
| 2.19 | Sample | 18 |
| 2.19.1 | Unit Tests | 18 |
| 2.19.2 | Accuracy | 18 |
| 2.19.3 | Performance | 18 |

| | | |
|----------|--------------------------------------|-----------|
| 2.20 | SetPoint | 18 |
| 2.20.1 | Unit Tests | 18 |
| 2.20.2 | Accuracy | 19 |
| 2.20.3 | Performance | 19 |
| 2.21 | Get15percentBorder | 20 |
| 2.21.1 | Unit Tests | 20 |
| 2.21.2 | Accuracy | 20 |
| 2.21.3 | Performance | 20 |
| 2.22 | Get50percentBorder | 20 |
| 2.22.1 | Unit Tests | 20 |
| 2.22.2 | Accuracy | 20 |
| 2.22.3 | Performance | 20 |
| 3 | System Tests | 21 |
| 3.1 | Summary of Tests Performed | 21 |
| 3.2 | System Tests Results | 21 |
| 3.3 | System test # 39 | 22 |
| 3.3.1 | Accuracy | 22 |
| 3.3.2 | Performance | 24 |
| 3.4 | System test # 40 | 25 |
| 3.4.1 | Accuracy | 25 |
| 3.4.2 | Performance | 26 |
| 3.5 | System test # 41 | 26 |
| 3.5.1 | Accuracy | 26 |
| 3.5.2 | Performance | 28 |
| 4 | Traceability | 28 |
| 4.1 | Requirements | 28 |
| 4.2 | Modules | 29 |
| 5 | Changes after Testing | 29 |

Revision History

All major edits to this document will be recorded in the table below.

Table 1: Revision History

| Description of Changes | Author | Date |
|---------------------------|---------------------------|------------|
| Initial draft of document | Matt, Rob, Victor, Stuart | 2016-03-18 |
| Template of document | Matt | 2016-03-15 |

List of Figures

Tables and figures for specific unit tests have been omitted in order to keep this document readable.

| Table # | Title |
|--------------------|-------------------------------------|
| 1 | Revision History |
| 2 | Definitions and Acronyms |
| 3 | General Unit Test Variables |
| 51 | Tests and Requirements Relationship |
| 52 | Tests and Modules Relationship |

Definitions and Acronyms

Table 2: Definitions and Acronyms

| Term | Description |
|------------|---|
| GEANT4 | Open-source software toolkit used to simulate the passage of particles through matter |
| GEANT4-GPU | GEANT4 with some computations running on the GPU |
| GPU | Graphics processing unit, well-suited to parallel computing tasks |
| CPU | Computer processing unit, general computer processor well-suited to serial tasks |
| CUDA | Parallel computing architecture for general purpose programming on GPU, developed by NVIDIA |

1 Introduction

1.1 Purpose of the Document

This document summarizes the testing and test conclusions of GEANT4-GPU. This document uses the implementation outlined in the test plan.

1.2 Scope of the Testing

The implemented tests are designed to give a general yet rigorous assessment of the components involved.

The tests are segregated into two categories: unit tests & system tests. The unit tests test function components of the G4ParticleVector module, and the system tests compare total system differences between CPU (original GEANT4) and GPU implementations. For both categories, performance and correctness are the key concerns.

Neither the unit tests nor the system tests are concerned with the correctness of original GEANT4 runs, as these runs are used as the baseline for the correctness of GEANT4-GPU modules.

A basic knowledge of programming concepts and command-line tools is assumed, as well as familiarity with GEANT4.

1.3 Organization

In Section 4 we provide an introduction to this report. Section 5 describes the test cases which are carried out on each function. Section 6 describes system test cases that were carried out by our team. In section 7 traceability matrices to requirements and modules are documented. Section 8 provides a summary of changes made in response to the testing results.

1.4 Usability Testing

GEANT4-GPU is a back end implementation of already existing GEANT4 modules. Therefore users will not be interacting with it directly. Since there is no direct user interaction with GEANT4-GPU. There are no usability test.

1.5 Robustness Testing

The GEANT4-GPU functions are meant to mimic the already existing GEANT4 functions. Therefore the GEANT4-GPU functions must also mimic the robustness of the GEANT4 functions. The accuracy section for unit tests has several unit tests designed to test the robustness of the functions.

2 Unit Testing

2.1 Use of Automated Testing

2.1.1 Overview

Our unit testing system is semi-automated. The user runs a program to generate a test results text file, inputting whether or not Geant4 was compiled with CUDA enabled or disabled. Then, they recompile Geant4 in the opposite configuration (i.e. with CUDA enabled if previously disabled, and vice versa) and run the test program again. At this point there will be two test results text files, one for CUDA enabled, and one for CUDA disabled. In addition, two text files containing runtimes of all computationally-intensive functions are produced. After generating the files, a program to analyze the results is run outputting whether each test case passed or failed, and creating an Excel document (.csv) with the running times.

2.1.2 Generating Test Results

`GenerateTestResults` first initializes several `G4ParticleHPVector` objects from data files included with Geant4 of varying numbers of entries, including the creation of one `G4ParticleHPVector` with 0 entries. After the vectors have been initialized, the unit-tested methods are tested with a variety of input values. These cover edge cases (i.e. negative index for array, index greater than number of elements etc.) as well as more “normal” cases. The result of each function is then written to the results text file. This can be a single value in the case of “clean” functions that simply return a value, or it could be the state of the `G4ParticleHPVector` object, that is the array of points stored by that object. For performance reasons, instead of writing out the entire array of points, a hash value is generated from the array and is outputted. The value of the input variable for each function call is also outputted, so the results for specific inputs can be analyzed.

2.1.3 Analyzing Test Results

After the above files are generated, the `AnalyzeTestResults` utility runs through both documents and for each unit test outputted its status. If it failed, then the result from the CPU and from the GPU are both printed out. After the analysis completes, the total number of tests passed is outputted. In addition, `AnalyzeTestResults` will read the files containing runtimes for each function and output them in .csv format to simplify performance analysis.

2.1.4 Note About Random Results

Some of the tests run in `GenerateTestResults` are based off of random numbers, which differ between the CPU and GPU implementations. To counteract this, each of

those tests is run multiple times and the result is averaged. When analyzing results for those functions, they are only marked as failed if the difference in the values of the GPU and CPU results are more than a specified tolerance. There are some functions that depend on random numbers that modify the data array. Since a hash is outputted and will differ no matter how small the difference in the values of the array are, before hashing the values are all rounded to a lower precision.

2.2 Definition of Variables Used for Unit Testing

The following are variables that are used for multiple unit tests. Instead of defining them again for each unit test they are defined here only once. Other variables used for specific unit tests will be defined in their respective unit test sections

For all unit tests:

Table 3: General Unit Test Variables

| Name | Type | Description |
|------|--------------------|---|
| n | G4double | number of entries in the G4ParticleHPVector |
| r1 | G4double | -1.0 |
| r2 | G4double | 0.0 |
| r3 | G4double | 0.00051234 |
| r4 | G4double | 1.5892317 |
| r5 | G4double | 513.18 |
| vec0 | G4ParticleHPVector | 0 entries |
| vec1 | G4ParticleHPVector | 80 entries |
| vec2 | G4ParticleHPVector | 1509 entries |
| vec3 | G4ParticleHPVector | 8045 entries |
| vec4 | G4ParticleHPVector | 41854 entries |
| vec5 | G4ParticleHPVector | 98995 entries |
| vec6 | G4ParticleHPVector | 242594 entries |

2.3 = (overloaded assignment operator)

2.3.1 Method Signature

`G4ParticleHPVector & operator = (const G4ParticleHPVector & right)`

2.3.2 Test Description

Create a new, temporary G4ParticleHPVector object and assign the current vector to it. Outputs the data and the integral from the new vector.

2.3.3 Test Inputs

Table 4: Unit Tests - = (overloaded assignment operator)

| Test # | Inputs |
|--------|----------------|
| | right |
| 1 | Current vector |

2.3.4 Results

Table 5: Test results - = (overloaded assignment operator)

| Test # | Test Result | | | | | | |
|--------|-------------|------|------|------|------|------|------|
| | vec0 | vec1 | vec2 | vec3 | vec4 | vec5 | vec6 |
| 1 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |

2.3.5 Performance

This method is not computationally heavy, so performance data was not included.

2.4 GetPoint

2.4.1 Method Signature

```
const G4ParticleHPDataPoint GetPoint(G4int i)
```

2.4.2 Test Description

Returns the G4ParticleHPDataPoint at index *i* in the current vector. The *x* and *y* values of the point are outputted.

2.4.3 Test Inputs

Table 6: Unit Tests - GetPoint

| Test # | Inputs |
|--------|----------|
| | <i>i</i> |
| 2 | -1 |
| 3 | 0 |
| 4 | $n/2$ |
| 5 | $n-1$ |
| 6 | n |

2.4.4 Test Results

Table 7: Test Results – GetPoint

| Test # | Test Result | | | | | | |
|--------|-------------|------|------|------|------|------|------|
| | vec0 | vec1 | vec2 | vec3 | vec4 | vec5 | vec6 |
| 2 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |
| 3 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |
| 4 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |
| 5 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |
| 6 | Pass | Pass | Pass | Pass | Pass | Pass | Pass |

2.4.5 Performance

This method is not computationally heavy, so performance data was not included.

2.5 GetX

2.5.1 Unit Tests

Table 8: Unit Tests

| Test # | Code | Description |
|--------|----------------|--|
| 7 | Empty.GetX(-1) | Set an xSec at a negative index of an empty vector |
| 8 | Empty.GetX(0) | Set an xSec at a the first index of an empty vector |
| 9 | Empty.GetX(1) | Set an xSec at an index out of bounds of an empty vector |
| 10 | D.GetX(-1) | Set an xSec at a negative index |
| 11 | D.GetX(0) | Set an xSec at a the first index |
| 12 | D.GetX(n/2) | Set an xSec at an index within the vector |
| 13 | D.GetX(n-1) | Set an xSec at the last index |
| 14 | D.GetX(n) | Set an xSec at an index our of bounds |

2.5.2 Accuracy

Table 9: Accuracy

| Test # | Status |
|--------|--------|
| 7 | Pass |
| 8 | Pass |
| 9 | Pass |
| 10 | Pass |
| 11 | Pass |
| 12 | Pass |
| 13 | Pass |
| 14 | Pass |

2.5.3 Performance

This method is not computationally heavy, so performance data was not included.

2.6 GetY

2.6.1 Unit Tests

Table 10: Unit Tests

| Test # | Code | Description |
|--------|----------------|--|
| 15 | Empty.GetY(-1) | Get a point at a negative index of an empty vector |
| 16 | Empty.GetY(0) | Get a point at a the first index of an empty vector |
| 17 | Empty.GetY(1) | Get a point at an index out of bounds of an empty vector |
| 18 | D.GetY(-1) | Get a point at a negative index |
| 19 | D.GetY(0) | Get a point at a the first index |
| 20 | D.GetY(n/2) | Get a point at an index within the vector |
| 21 | D.GetY(n-1) | Get a point at the last index |
| 22 | D.GetY(n) | Get a point at an index our of bounds |

2.6.2 Accuracy

Table 11: Accuracy

| Test # | Status |
|--------|--------|
| 15 | Pass |
| 16 | Pass |
| 17 | Pass |
| 18 | Pass |
| 19 | Pass |
| 20 | Pass |
| 21 | Pass |
| 22 | Pass |

2.6.3 Performance

This method is not computationally heavy, so performance data was not included.

2.7 GetXsec

2.7.1 Unit Tests

Table 12: Unit Tests

| Test # | Code | Description |
|--------|-------------------|---|
| 23 | Empty.GetXsec(-1) | Get an xSec with a negative energy from an empty vector |
| 24 | Empty.GetXsec(0) | Get a xSec with an energy of zero from an empty vector |
| 25 | Empty.GetXsec(r1) | Get a xSec with a normal energy from an empty vector |
| 26 | D.GetXsec(-1) | Get a xSec with a negative energy |
| 27 | D.GetXsec(0) | Get a xSec with a zero energy |
| 28 | D.GetXsec(r0) | Get a xSec with a small energy |
| 29 | D.GetXsec(r1) | Get a xSec with a normal energy |
| 30 | D.GetXsec(r2) | Get a xSec with a large energy |

2.7.2 Accuracy

Table 13: Accuracy

| Test # | Status |
|--------|--------|
| 23 | Pass |
| 24 | Pass |
| 25 | Pass |
| 26 | Pass |
| 27 | Pass |
| 28 | Pass |
| 29 | Pass |
| 30 | Pass |

2.7.3 Performance

This method is not computationally heavy, so performance data was not included.

2.8 SetData

2.8.1 Unit Tests

Table 14: Unit Tests

| Test # | Code | Description |
|--------|---------------------------|--|
| 31 | Empty.SetData(-1, r1, r2) | Set a point at a negative index of an empty vector |
| 32 | Empty.SetData(0, r1, r2) | Set a point at a the first index of an empty vector |
| 33 | Empty.SetData(1, r1, r2) | Set a point at an index out of bounds of an empty vector |
| 34 | D.SetData(-1, r1, r2) | Set a point at a negative index |
| 35 | D.SetData(0, r1, r2) | Set a point at a the first index |
| 36 | D.SetData(n/2, r1, r2) | Set a point at an index within the vector |
| 37 | D.SetData(n-1, r1, r2) | Set a point at the last index |
| 38 | D.SetData(n, r1, r2) | Set a point at an index our of bounds |
| 39 | D.SetData(0, -1, -1) | Set a point with a negative energy and xSec |
| 40 | D.SetData(0, 0, 0) | Set a point with a zero energy and xSec |

2.8.2 Accuracy

Table 15: Accuracy

| Test # | Status |
|--------|--------|
| 31 | Pass |
| 32 | Pass |
| 33 | Pass |
| 34 | Pass |
| 35 | Pass |
| 36 | Pass |
| 37 | Pass |
| 38 | Pass |
| 39 | Pass |
| 40 | Pass |

2.8.3 Performance

This method is not computationally heavy, so performance data was not included.

2.9 SetEnergy

2.9.1 Unit Tests

Table 16: Unit Tests

| Test # | Code | Description |
|--------|-------------------------|---|
| 41 | Empty.SetEnergy(-1, r1) | Set an energy at a negative index of an empty vector |
| 42 | Empty.SetEnergy(0, r1) | Set an energy at a the first index of an empty vector |
| 43 | Empty.SetEnergy(1, r1) | Set an energy at an index out of bounds of an empty vector |
| 44 | D.SetEnergy(-1, r1) | Set an energy at a negative index |
| 45 | D.SetEnergy(0, r1) | Set an energy at a the first index |
| 46 | D.SetEnergy(n/2, r1) | Set an energy at an index within the vector |
| 47 | D.SetEnergy(n-1, r1) | Set an energy at the last index |
| 48 | D.SetEnergy(n, r1) | Set an energy at an index our of bounds |
| 49 | D.SetEnergy(0, -1) | Set an energy at an index within the vector to a negative value |
| 50 | D.SetEnergy(0, 0) | Set an energy at an index within the vector to a zero value |

2.9.2 Accuracy

Table 17: Accuracy

| Test # | Status |
|--------|--------|
| 41 | Pass |
| 42 | Pass |
| 43 | Pass |
| 44 | Pass |
| 45 | Pass |
| 46 | Pass |
| 47 | Pass |
| 48 | Pass |
| 49 | Pass |
| 50 | Pass |

2.9.3 Performance

This method is not computationally heavy, so performance data was not included.

2.10 SetXsec

2.10.1 Unit Tests

Table 18: Unit Tests

| Test # | Code | Description |
|--------|-----------------------|--|
| 51 | Empty.SetXsec(-1, r1) | Set an xSec at a negative index of an empty vector |
| 52 | Empty.SetXsec(0, r1) | Set an xSec at a the first index of an empty vector |
| 53 | Empty.SetXsec(1, r1) | Set an xSec at an index out of bounds of an empty vector |
| 54 | D.SetXsec(-1, r1) | Set an xSec at a negative index |
| 55 | D.SetXsec(0, r1) | Set an xSec at a the first index |
| 56 | D.SetXsec(n/2, r1) | Set an xSec at an index within the vector |
| 57 | D.SetXsec(n-1, r1) | Set an xSec at the last index |
| 58 | D.SetXsec(n, r1) | Set an xSec at an index our of bounds |
| 59 | D.SetXsec(0, -1) | Try to set a negative xSec |
| 60 | D.SetXsec(0, 0) | Try to set a zero xSec |

2.10.2 Accuracy

Table 19: Accuracy

| Test # | Status |
|--------|--------|
| 51 | Pass |
| 52 | Pass |
| 53 | Pass |
| 54 | Pass |
| 55 | Pass |
| 56 | Pass |
| 57 | Pass |
| 58 | Pass |
| 59 | Pass |
| 60 | Pass |

2.10.3 Performance

This method is not computationally heavy, so performance data was not included.

2.11 SetX

2.11.1 Unit Tests

Table 20: Unit Tests

| Test # | Code | Description |
|--------|--------------------|--|
| 61 | Empty.SetX(-1, r1) | Set an energy at a negative index of an empty vector |
| 62 | Empty.SetX(0, r1) | Set an energy at a the first index of an empty vector |
| 63 | Empty.SetX(1, r1) | Set an energy at an index out of bounds of an empty vector |
| 64 | D.SetX(-1, r1) | Set an energy at a negative index |
| 65 | D.SetX(0, r1) | Set an energy at a the first index |
| 66 | D.SetX(n/2, r1) | Set an energy at an index within the vector |
| 67 | D.SetX(n-1, r1) | Set an energy at the last index |
| 68 | D.SetX(n, r1) | Set an energy at an index our of bounds |
| 69 | D.SetX(0, -1) | Set a negative energy |
| 70 | D.SetX(0, 0) | Set a zero energy |

2.11.2 Accuracy

Table 21: Accuracy

| Test # | Status |
|--------|--------|
| 61 | Pass |
| 62 | Pass |
| 63 | Pass |
| 64 | Pass |
| 65 | Pass |
| 66 | Pass |
| 67 | Pass |
| 68 | Pass |
| 69 | Pass |
| 70 | Pass |

2.11.3 Performance

This function is not computationally heavy, so performance data was not included.

2.12 SetY

2.12.1 Unit Tests

Table 22: Unit Tests

| Test # | Code | Description |
|--------|--------------------|--|
| 71 | Empty.SetY(-1, r1) | Set an xSec at a negative index of an empty vector |
| 72 | Empty.SetY(0, r1) | Set an xSec at a the first index of an empty vector |
| 73 | Empty.SetY(1, r1) | Set an xSec at an index out of bounds of an empty vector |
| 74 | D.SetY(-1, r1) | Set an xSec at a negative index |
| 75 | D.SetY(0, r1) | Set an xSec at a the first index |
| 76 | D.SetY(n/2, r1) | Set an xSec at an index within the vector |
| 77 | D.SetY(n-1, r1) | Set an xSec at the last index |
| 78 | D.SetY(n, r1) | Set an xSec at an index our of bounds |
| 79 | D.SetY(0, -1) | Set a negative xSec |
| 80 | D.SetY(0, 0) | Set a zero xSec |

2.12.2 Accuracy

Table 23: Accuracy

| Test # | Status |
|--------|--------|
| 71 | Pass |
| 72 | Pass |
| 73 | Pass |
| 74 | Pass |
| 75 | Pass |
| 76 | Pass |
| 77 | Pass |
| 78 | Pass |
| 79 | Pass |
| 80 | Pass |

2.12.3 Performance

This function is not computationally heavy, so performance data was not included.

2.13 Init

2.13.1 Unit Tests

Table 24: Unit Tests

| Test # | Code | Description |
|--------|--------------|----------------------|
| 81 | Empty.Init() | Init an empty Vector |
| 82 | D.Init() | Init a Vector |

2.13.2 Accuracy

Table 25: Accuracy

| Test # | Status |
|--------|--------|
| 81 | Pass |
| 82 | Pass |

2.13.3 Performance

2.14 SampleLin

2.14.1 Unit Tests

Table 26: Unit Tests

| Test # | Code | Description |
|--------|-------------------|------------------------|
| 83 | Empty.SampleLin() | Sample an empty Vector |
| 84 | D.SampleLin() | Sample a Vector |

2.14.2 Accuracy

Table 27: Accuracy

| Test # | CPU | GPU |
|--------|------------|------------|
| 83 | CPU result | GPU result |
| 84 | CPU result | GPU result |

2.14.3 Performance

This function is not computationally heavy, so performance data was not included.

2.15 Integrate

2.15.1 Unit Tests

Table 28: Unit Tests

| Test # | Code | Description |
|--------|-------------------|---------------------------|
| 85 | Empty.Integrate() | Integrate an empty Vector |
| 86 | D.Integrate() | Integrate a Vector |

2.15.2 Accuracy

Table 29: Accuracy

| Test # | Status |
|--------|--------|
| 85 | Pass |
| 86 | Pass |

2.15.3 Performance

This method is not computationally heavy, so performance data was not included.

2.16 IntegrateAndNormalise

2.16.1 Unit Tests

Table 30: Unit Tests

| Test # | Code | Description |
|--------|-------------------------------|---|
| 87 | Empty.IntegrateAndNormalise() | Integrate and normalize an empty Vector |
| 88 | D.IntegrateAndNormalise() | Integrate normalize a Vector |

2.16.2 Accuracy

Table 31: Accuracy

| Test # | Status |
|--------|--------|
| 30 | Pass |
| 30 | Pass |

2.16.3 Performance

This method is not computationally heavy, so performance data was not included.

2.17 Times

2.17.1 Unit Tests

Table 32: Unit Tests

| Test # | Code | Description |
|--------|-----------------|--|
| 89 | Empty.Times(-1) | Times an empty vector by a negative factor |
| 90 | Empty.Times(0) | Times an empty vector by zero |
| 91 | Empty.Times(1) | Times an empty vector by 1 |
| 92 | Empty.Times(r1) | Times an empty vector by a random factor |
| 93 | D.Times(-1) | Times a vector by a negative factor |
| 94 | D.Times(0) | Times a vector by zero |
| 95 | D.Times(1) | Times a vector by 1 |
| 96 | D.Times(r1) | Times a vector by a random factor |

2.17.2 Accuracy

Table 33: Accuracy

| Test # | Status |
|--------|--------|
| 89 | Pass |
| 90 | Pass |
| 91 | Pass |
| 92 | Pass |
| 93 | Pass |
| 94 | Pass |
| 95 | Pass |
| 96 | Pass |

2.17.3 Performance

2.18 ThinOut

2.18.1 Unit Tests

Table 34: Unit Tests

| Test # | Code | Description |
|--------|-------------------|---|
| 97 | Empty.ThinOut(r1) | ThinOut an empty Vector |
| 98 | D.ThinOut(-1) | ThinOut a Vector using a negative value |
| 99 | D.ThinOut(0) | ThinOut a Vector using a zero value |
| 100 | D.ThinOut(r0) | ThinOut a Vector using a small value |
| 101 | D.ThinOut(r1) | ThinOut a Vector using a normal value |
| 102 | D.ThinOut(r2) | ThinOut a Vector using a large value |

2.18.2 Accuracy

Table 35: Accuracy

| Test # | Status |
|--------|--------|
| 97 | Pass |
| 98 | Pass |
| 99 | Pass |
| 100 | Pass |
| 101 | Pass |
| 102 | Pass |

2.18.3 Performance

This method is not computationally heavy, so performance data was not included.

2.19 Sample

2.19.1 Unit Tests

Table 36: Unit Tests

| Test # | Code | Description |
|--------|----------------|------------------------|
| 103 | Empty.Sample() | Sample an empty Vector |
| 104 | D.Sample() | Sample a Vector |

2.19.2 Accuracy

Table 37: Accuracy

| Test # | CPU | GPU |
|--------|------------|------------|
| 103 | CPU result | GPU result |
| 104 | CPU result | GPU result |

2.19.3 Performance

This method is not computationally heavy, so performance data was not included.

2.20 SetPoint

2.20.1 Unit Tests

- “rPoint” is a random G4ParticleHPDataPoint
- “nPoint” is a negative G4ParticleHPDataPoint
- “zPoint” is a zero G4ParticleHPDataPoint

Table 38: Unit Tests

| Test # | Code | Description |
|--------|----------------------------|--|
| 105 | Empty.SetPoint(-1, rPoint) | Set a point at a negative index of an empty vector |
| 106 | Empty.SetPoint(0, rPoint) | Set a point at a the first index of an empty vector |
| 107 | Empty.SetPoint(1, rPoint) | Set a point at an index out of bounds of an empty vector |
| 108 | D.SetPoint(-1, rPoint) | Set a point at a negative index |
| 109 | D.SetPoint(0, rPoint) | Set a point at a the first index |
| 110 | D.SetPoint(n/2, rPoint) | Set a point at an index within the vector |
| 111 | D.SetPoint(n-1, rPoint) | Set a point at the last index |
| 112 | D.SetPoint(n, rPoint) | Set a point at an index our of bounds |
| 113 | D.SetPoint(0, nPoint) | Set a negative point |
| 114 | D.SetPoint(0, zPoint) | Set a zero point |

2.20.2 Accuracy

Table 39: Accuracy

| Test # | Status |
|--------|--------|
| 105 | Pass |
| 106 | Pass |
| 107 | Pass |
| 108 | Pass |
| 109 | Pass |
| 110 | Pass |
| 111 | Pass |
| 112 | Pass |
| 113 | Pass |
| 114 | Pass |

2.20.3 Performance

This method is not computationally heavy, so performance data was not included.

2.21 Get15percentBorder

2.21.1 Unit Tests

Table 40: Unit Tests

| Test # | Code | Description |
|--------|----------------------------|--|
| 115 | Empty.Get15percentBorder() | Get 15 percent Border of an empty vector |
| 116 | D.Get15percentBorder() | Get 15 percent Border of a vector |

2.21.2 Accuracy

Table 41: Accuracy

| Test # | Status |
|--------|--------|
| 115 | Pass |
| 116 | Pass |

2.21.3 Performance

This method is not computationally heavy, so performance data was not included.

2.22 Get50percentBorder

2.22.1 Unit Tests

Table 42: Unit Tests

| Test # | Code | Description |
|--------|----------------------------|--|
| 117 | Empty.Get50percentBorder() | Get 50 percent Border of an empty vector |
| 118 | D.Get50percentBorder() | Get 50 percent Border of a vector |

2.22.2 Accuracy

Table 43: Accuracy

| Test # | Status |
|--------|--------|
| 117 | Pass |
| 118 | Pass |

2.22.3 Performance

This method is not computationally heavy, so performance data was not included.

3 System Tests

3.1 Summary of Tests Performed

System tests will be performed by running the sample code packaged with the GEANT4 installation. The Hadr04 example will be run with different materials (i.e water, uranium) and number of events. The values and conditions that are changed per test are detailed in the table below.

Table 44: System Tests

| Test # | Initial State | Inputs | Outputs | Description |
|--------|----------------|---|-------------------------------------|---|
| 119 | Fresh start up | Events = 2000 Material = Water | Same output as non-GPU GEANT4 | HADR04 no changes |
| 120 | Fresh start up | Events = 2000 Material = Uranium | Same output as non-GPU GEANT4 | HADR04 – basic example |
| 121 | Fresh start up | Events = 600 Material = Water | Same output as non-GPU GEANT4 | HADR04 – Shorter test |
| 122 | Fresh start up | Events = 600 Material = Uranium | Same output as non-GPU GEANT4 | HADR04 – Shorter test |
| 123 | Fresh start up | Events = 20000 Material = Uranium | Same output as non-GPU GEANT4 | HADR04 – Long simulation stress Test |
| 124 | Fresh start up | Events = 0 Material = Uranium | Same output as non-GPU GEANT4 | HADR04 – no runs, Edge case |

3.2 System Tests Results

This section will summarize all of the results from running tests 39 through 44. Each test has an accuracy section as well as a performance section. The accuracy of the results will be based on how well the values generated on the GPU match up with the

values generated on the CPU. The performance metrics used will include user, system and real time required to run each system test.

3.3 System test # 39

This test simply runs the Hadr04 example on both the GPU and the CPU without changing the source files. The code for this example is bundled with the GEANT4 installation.

3.3.1 Accuracy

Table 45: Accuracy Test #39

| Data | CPU Values | GPU Values | Difference |
|-------------------------------------|------------|------------|------------|
| Process Calls | | | |
| hadElastic | NA | NA | NA |
| nCapture | NA | NA | NA |
| neutronInelastic | NA | NA | NA |
| Parcours of incident neutron | | | |
| collisions | NA | NA | NA |
| track length | NA | NA | NA |
| time of flight | NA | NA | NA |
| Generated particles | | | |
| C14 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| O16 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| O17 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| O18 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Alpha | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Deuteron | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Gamma | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Proton | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |

3.3.2 Performance

Table 46: Performance Test #39

| Type | CPU Time | GPU Time |
|--------|----------|----------|
| User | NA | NA |
| Real | NA | NA |
| System | NA | NA |

3.4 System test # 40

This test simply runs the Hadr04 example on both the GPU and the CPU without changing the source files. The code for this example is bundled with the GEANT4 installation.

3.4.1 Accuracy

Table 47: Accuracy Test #40

| Data | CPU Values | GPU Values | Difference |
|-------------------------------------|------------|------------|------------|
| Process Calls | | | |
| hadElastic | NA | NA | NA |
| nCapture | NA | NA | NA |
| neutronInelastic | NA | NA | NA |
| Parcours of incident neutron | | | |
| collisions | NA | NA | NA |
| track length | NA | NA | NA |
| time of flight | NA | NA | NA |
| Generated particles | | | |
| U235 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| U238 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| U239 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Gamma | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Neutron | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |

3.4.2 Performance

Table 48: Performance Test #40

| Type | CPU Time | GPU Time |
|--------|----------|----------|
| User | NA | NA |
| Real | NA | NA |
| System | NA | NA |

3.5 System test # 41

This test simply runs the Hadr04 example on both the GPU and the CPU without changing the source files. The code for this example is bundled with the GEANT4 installation.

3.5.1 Accuracy

Table 49: Accuracy Test #41

| Data | CPU Values | GPU Values | Difference |
|-------------------------------------|------------|------------|------------|
| Process Calls | | | |
| hadElastic | NA | NA | NA |
| nCapture | NA | NA | NA |
| neutronInelastic | NA | NA | NA |
| Parcours of incident neutron | | | |
| collisions | NA | NA | NA |
| track length | NA | NA | NA |
| time of flight | NA | NA | NA |
| Generated particles | | | |
| O16 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| O17 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| O18 | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Alpha | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Gamma | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |
| Proton | | | |
| # of particles | NA | NA | NA |
| Emean | NA | NA | NA |
| Range | NA | NA | NA |

3.5.2 Performance

Table 50: Performance Test #41

| Type | CPU Time | GPU Time |
|--------|----------|----------|
| User | NA | NA |
| Real | NA | NA |
| System | NA | NA |

4 Traceability

The following section is used to highlight the relations of implemented test cases to requirements and modules. In doing so, we hope to draw clear reasoning upon the inclusion of such tests.

4.1 Requirements

Below is a traceability table outlining test cases and the requirements they are related to:

Table 51: Tests and Requirements Relationship

| Test # | Description | Requirement |
|--------|-------------------------------|--|
| 1 | Performance test of functions | Req. # 4 (Speed and Latency) |
| 2 | InitializeVector | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 3 | SettersandGetters | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 4 | GetXSec | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 5 | ThinOut | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 6 | Merge | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 7 | Sample | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 8 | GetBorder | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |

| | | |
|----|-------------|--|
| 9 | Integral | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 10 | Times | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 11 | Assignment | Req # 5 & 6 & 7 (Precision & Reliability & Robustness) |
| 12 | System Test | Req # 1 & 2 & 8 & 11 (Adjacent Systems & Access) |

4.2 Modules

Similarly, the following is a traceability table explicitly relating test cases to modules:

Table 52: Tests and Modules Relationship

| Test # | Description | Module |
|--------|-------------------------------|---|
| 1 | Performance test of functions | G4ParticleVector |
| 2 | InitializeVector | G4ParticleVector |
| 3 | SettersandGetters | G4ParticleVector |
| 4 | GetXSec | G4ParticleVector |
| 5 | ThinOut | G4ParticleVector |
| 6 | Merge | G4ParticleVector |
| 7 | Sample | G4ParticleVector |
| 8 | GetBorder | G4ParticleVector |
| 9 | Integral | G4ParticleVector |
| 10 | Times | G4ParticleVector |
| 11 | Assignment | G4ParticleVector |
| 12 | System Test | G4NeutronHPDataPoint & G4ParticleVector & CMake Files |

5 Changes after Testing

Developing the unit testing system illuminated a variety of bugs and changes that needed to be made. These were predominantly related to edge cases – trying to access

indices in arrays that are negative or greater than the number of elements was a common theme. In some of these cases the same case was not covered by Geant4 itself, so the change was made there as well.

Figure 1: Performance results for `Init` function

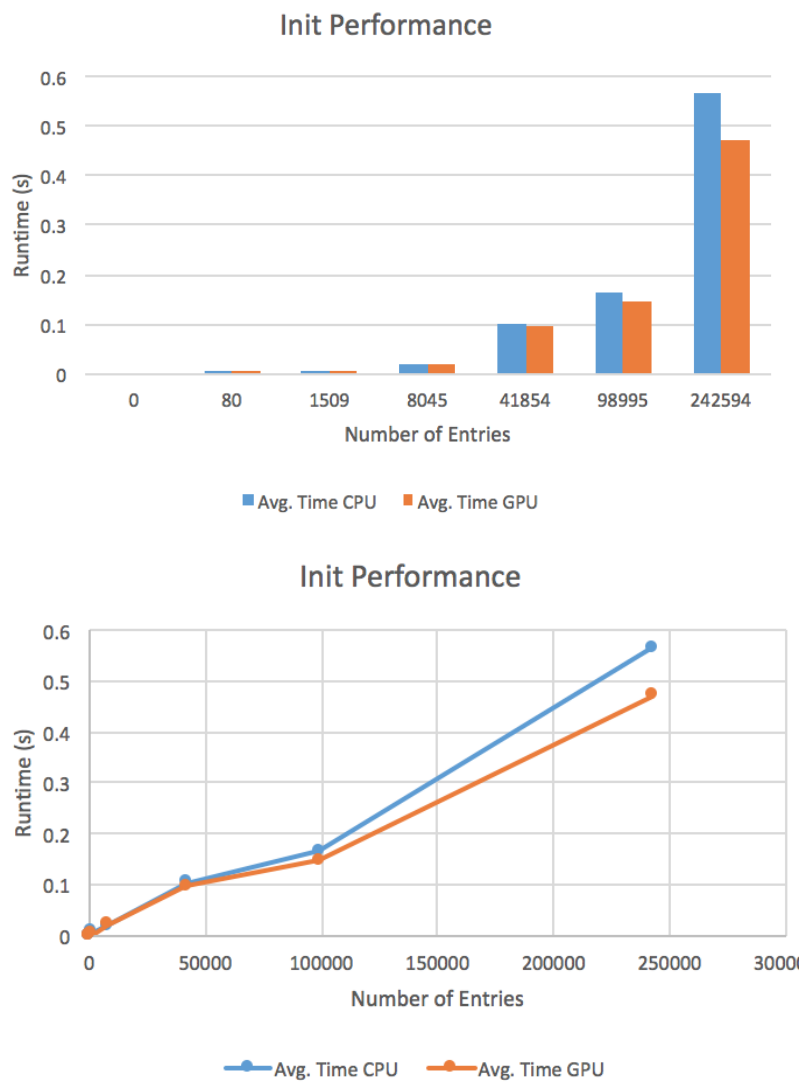


Figure 2: Performance results for Times function

