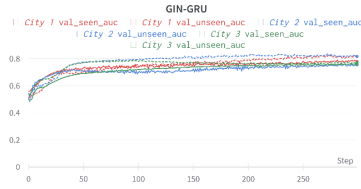


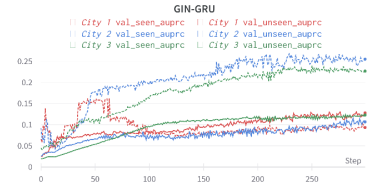
Appendix A Convergence plots



(a) City 1

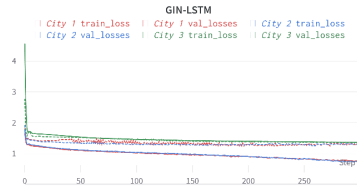


(b) City 2

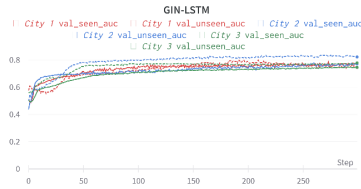


(c) City 3

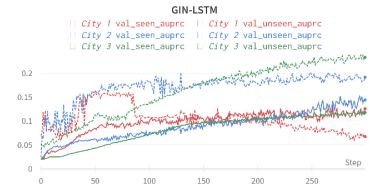
Fig. 1: GIN-GRU



(a) City 1

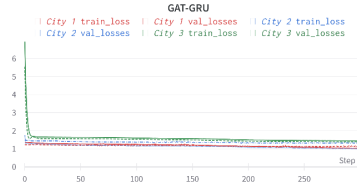


(b) City 2

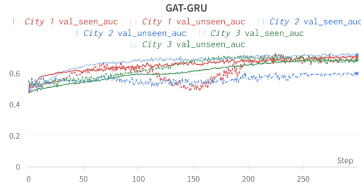


(c) City 3

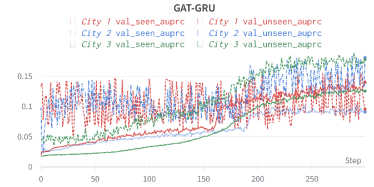
Fig. 2: GIN-LSTM



(a) City 1



(b) City 2

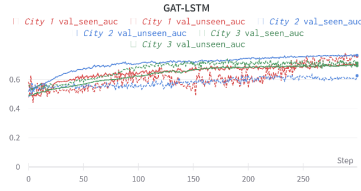


(c) City 3

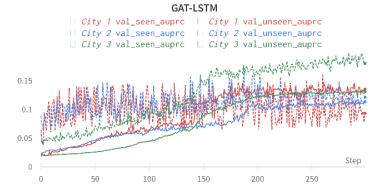
Fig. 3: GAT-GRU



(a) City 1

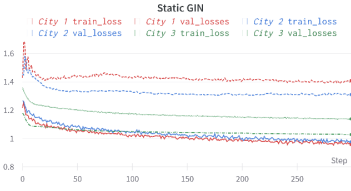


(b) City 2

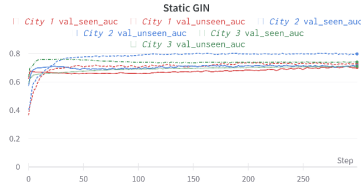


(c) City 3

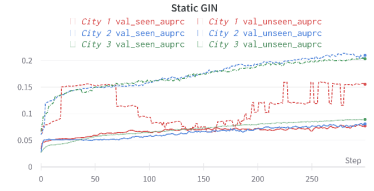
Fig. 4: GAT-LSTM



(a) City 1

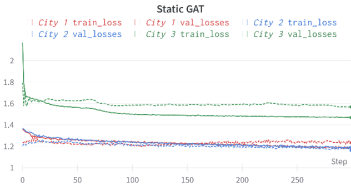


(b) City 2

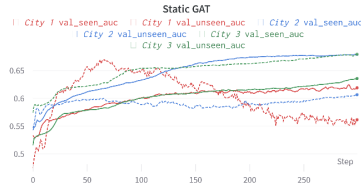


(c) City 3

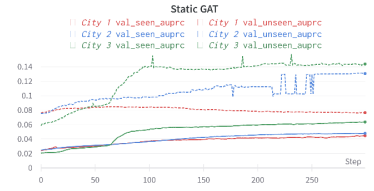
Fig. 5: Static GIN



(a) City 1

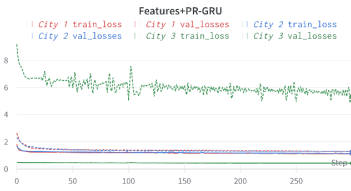


(b) City 2

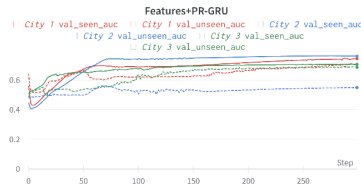


(c) City 3

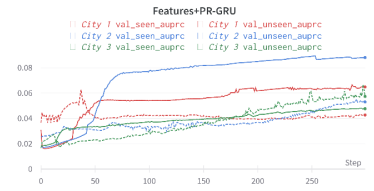
Fig. 6: Static GAT



(a) City 1

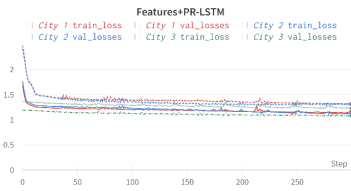


(b) City 2

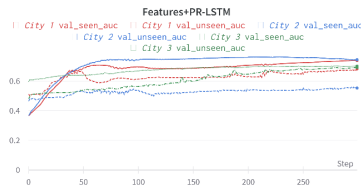


(c) City 3

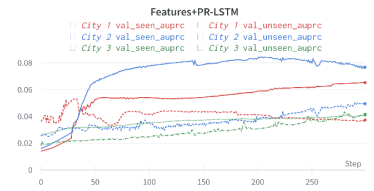
Fig. 7: Features+PR-GRU



(a) City 1

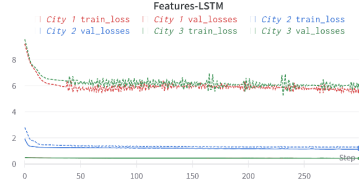


(b) City 2

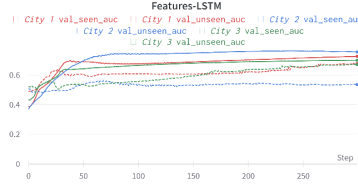


(c) City 3

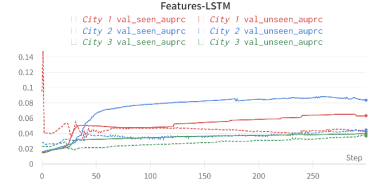
Fig. 8: Features+PR-LSTM



(a) City 1

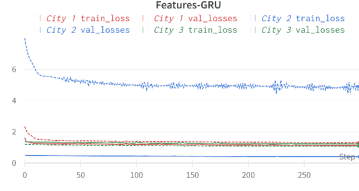


(b) City 2

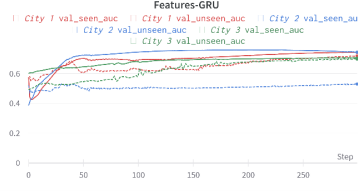


(c) City 3

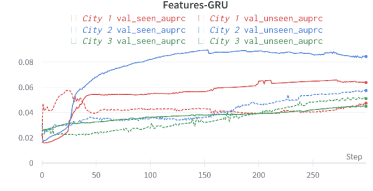
Fig. 9: Features-LSTM



(a) City 1



(b) City 2



(c) City 3

Fig. 10: Features-GRU

Appendix B Best model configurations

Table 1: Model configurations

Model	#layers GNN	#emb. GNN	#hid.dim. GNN	SMOTE rate	#layers RNN	#hid.dim. RNN	Loss
GIN-LSTM	2	512	512	0	1	256	Focal
GIN-GRU	2	512	512	0	1	512	Focal
GAT-LSTM	2	256	256	0	1	512	Focal
GAT-GRU	2	256	256	0	2	256	Focal
Features+PR-LSTM	/	/	/	0	1	512	BCE
Features+PR-GRU	/	/	/	0.5	1	512	Focal
Features-LSTM	/	/	/	0.5	1	256	Focal
Features-GRU	/	/	/	0	1	512	BCE
Static GAT	4	256	512	0.5	/	/	Focal
Static GIN	2	512	512	0.5	/	/	BCE