Matt MacLeod

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 macleod-matt

SUMMARY

Ambitious Embedded Systems Engineer with 5 years' experience writing code and over 3+ years of professional experience contributing to all aspects of product development across a wide range of industries. Professionally, I've worked on many different projects with teams of varying sizes and currently I'm leading the software team of 4 at Rainhouse, where I have had the opportunity to get in on the ground floor of product development, being heavily involved in all aspects of design—from Schematic/PCB design to full stack software engineering and AI development. As such, I am intimately familiar with contributing to a codebase in a team setting and comfortable with collaboration flows such as: pull requests, code reviews, automated pipelines, code formatters/linters and QA testing. I have a proven track record of effective communication with teammates and clients alike to ensure that the code produced is robust, on time and to specification.

SKILLS

Languages & Protocols: C, C++, Python, CMake, Bash, git

Embedded Systems: Microprocessors: (Armv8-M, Armv7E-M, Avr), RTOS: (Zephyr, FreeRTOS), Interfaces: (SPI, I2C, UART, CAN)

Hardware: Design Software (Eagle, Altium, LTspice), Debug Tools: (gdb, RTT)

Lab Equipment: Oscilloscope, Logic analyzer, Digital Multimeter, Signal Generator, Power Supplies

WORK EXPERIENCE

Embedded Firmware Engineer

JULY 2021 - PRESENT

Rainhouse

Victoria, BC, Canada

- Lead electronics team in start-up (team of 4), to deliver all required hardware, embedded firmware, and full stack software for a wireless IoT, SMART CNC machine tool product line. Resulted in successful delivery of TRL-7 prototype, SDK, and the filing of 2 international patents.
- Wrote optimized, multi-threaded embedded software (in C) for 2 dual core ARM SoCs, to facilitate the real-time transmission
 and reception of 7 independent sensors over Bluetooth low energy at 1Mbps throughput.
- Experience with full board bring up of embedded ARM SoC including PCB design, bootloader configuration, debugging hardware peripherals and writing embedded software.
- Wrote the full stack IoT architecture encompassing gRPC streams to achieve 99.99% signal transmission over upper limit of Bluetooth low energy.
- Wrote **embedded Linux**, Zephyr **RTOS** based drivers (in **C**) for the nrf5340 ARM SoC to interface accelerometer ICs, ADC controller ICs, PCM microphones, thermocouples, and force sensors for high performance data collection.

Electrical Systems Design Engineer (Internship)

JAN 2020 – AUG 2020 (8 MO)

Motorola Solutions

Vancouver, BC, Canada

- Developed a software for hardware, automation framework (using C++/python) to characterize the IO performance of SSDs, HDDS and raid controllers over a temperature hysteresis profile. Final solution resulted in a 12x faster test procedure and improved the storage device characterization accuracy by 50%.
- Spearheaded the board bring up, **hardware re-design** (using Altium) and **debug** of a PoE controller board for an NVR product family. Resulted in successful delivery of first-generation rugged NVR product line.

Electrical Engineer (Internship)

MAY 2019 – AUG 2019 (4 MO)

Seaspan ULC

Vancouver, BC, Canada

- Collaborated across multi-disciplinary teams and managed sub-contractors to deliver electrical single line diagrams for Canadian Coast Guard and Naval vessels.
- Sourced several major electrical instruments that became standard among a replenishment ship for the Canadian Navy.

Jr Autonomous Systems Engineer (Internship)

SEPT 2018 - DEC 2018 (4 MO)

InDro Robotics

Ganges, BC, Canada

- Designed, built and tested a working TRL-7 prototype of an after-market payload deployment mechanism that could be actuated
 through the DJI hand controller and mounts externally onto DJI's M210 drone. Resulted in the solution becoming a part of the
 company's product line.
- Programmed embedded Linux flight controllers using C++ to integrate third party sensors and cameras with OEM drones for remote sensing operations.

Electrical Engineer (Internship)

AML Oceanographic

JAN 2018 – APR 2018 (4 MO)

Sidney, BC, Canada

- · Tasked with using limited resources to improve the existing quality control process of PCBs before the next stage of manufacturing
- Automated the testing procedure of raw circuit boards using a combination of custom PCBs, test jigs and firmware validation scripts to yield a 5x faster quality control process

PERSONAL PROJECTS

Nissan Leaf Battery Analytics Framework (RP2040, C++, python)

- Goal: Decode the CanBus messages to persist intrinsic battery pack sensors from a depleted Nissan leaf pack to a cloud storage system for predictive analytics in a remote, off grid storage system.
- Embedded Systems: See custom can bus decoding library

Al Home Security Guard (Raspberry Pi Zero W, C++):

- Goal: Create a device that utilizes facial and voice recognition methods to unlock door based on person's identity
- Hardware: Raspberry Pi Camera, USB Microphone, Bluetooth intercom System, Metal Gear Servo driven actuator to unlock door
- Embedded Systems: OpenCV Eigenfaces method for facial recognition, Voice to speech recognition algorithm used for user interface.

More Coming soon. For now, check out my GitHub!

PATENTS

- Sensor-based Smart Tooling for Machining Process Online Measurement and Monitoring (Pending)
- Real-Time DAS and SDK for Machine Parameter Online Measurement and Monitoring (Pending)

EDUCATION

Bachelor of Electrical Engineering (Digital and Embedded Systems Specialization) **University of Victoria**

SEPT 2016 – AUG 2021 Victoria, BC, Canada