

CFA 2025 - 27-30 avril 2025, Paris



# INFLUENCE DE LA DYNAMIQUE DES PARAMÈTRES DE CONTRÔLE ET PHÉNOMÈNE DE BASCULEMENT DANS UN MODÈLE SIMPLE D'INSTRUMENT À ANCHE

**Baptiste BERGEOT<sup>a</sup>**, Soizic TERRIEN<sup>b</sup> and Christophe VERGEZ<sup>c</sup>

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## OUTLINE

## 1. INTRODUCTION

**CONTEXT.** Understanding the link between musician gesture and resulting regime produced by a single-reed instrument within the framework within the framework of nonlinear dynamical systems

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Single-reed musical instruments:

Saxophones



Clarinets



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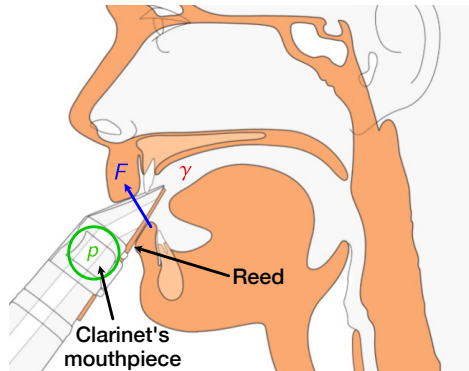
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- Modeled by nonlinear dynamical systems linking control parameters (mouth pressure  $\gamma$ , lip force  $F$ ) to output variables (acoustic pressure  $p$  inside the mouthpiece)



$\gamma$ : mouth pressure

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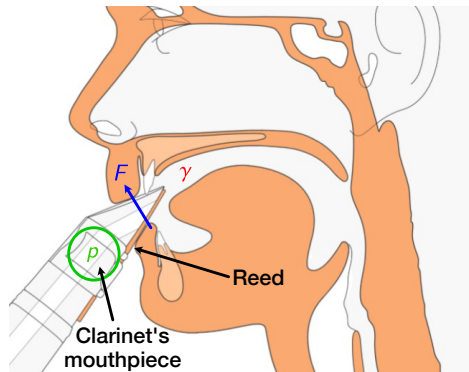
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- ▶ Modeled by nonlinear dynamical systems linking control parameters (mouth pressure  $\gamma$ , lip force  $F$ ) to output variables (acoustic pressure  $p$  inside the mouthpiece)
- ▶ Previous theoretical studies on sound production performed with control parameters constant in time show that:
  - Appearance of sound = Hopf bifurcation of the trivial equilibrium (silence, i.e.,  $p = 0$ ) to a stable periodic solution (musical note)
  - Several stable solutions coexist in general = Multistability



$\gamma$ : mouth pressure

$F$ : force applied by the lip on the reed

## OBSERVATION

During transients the musician **varies the control parameters in time**

## RESEARCH QUESTIONS

- In the context of musical acoustics: during transient phases, when the control parameters vary in time:

Do the dynamic characteristics of the control parameters impact the sound produced by the instrument?  
If they do, in what way?

- Open problems in nonlinear dynamics: behavior of multistable nonlinear dynamical systems with time-varying parameters

How can Critical transition (or tipping, see e.g. [Ashwin et al. (2012), Philos Trans R Soc Lond, A]) be predicted?

## PRESENTED WORK

Predicting the global dynamic behavior (i.e., tipping or not) of a simple bistable model in the case of an attack transient, i.e., when **only the mouth pressure  $\gamma$  increases** in time.

$$\dot{\gamma} = rg(\gamma)$$

$g(\gamma)$ : describes the shape of the time profile of  $\gamma$

$r$ : rate of growth

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2. THE CHOSEN SIMPLIFIED MODEL OF SINGLE-REED INSTRUMENT
3. PREVIOUS RESULTS: ANALYSIS OF THE MODEL WITH CONSTANT CONTROL PARAMETER
4. NOVEL RESULTS: ANALYSIS OF THE MODEL WITH TIME-VARYING CONTROL PARAMETER
5. CONCLUSIONS AND PERSPECTIVES

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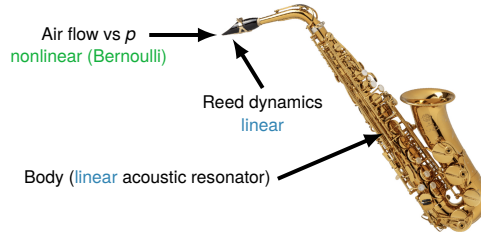
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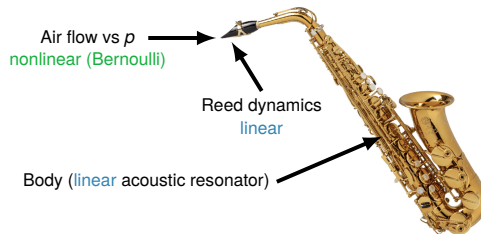
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## REFINED PHYSICAL MODEL

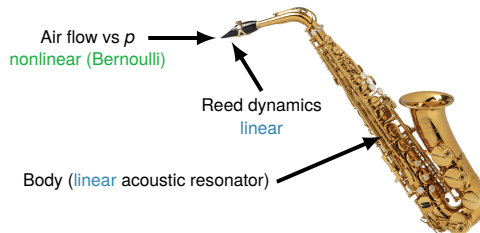


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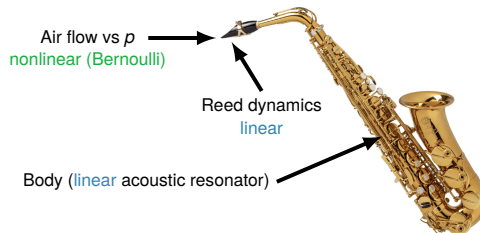
⇒ One-dimensional ODE:

$$\dot{x} = f(x, \gamma)$$

$x$ : amplitude of the mouthpiece pressure  $p$

$\gamma$ : control (or bifurcation) parameter

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► Silence:  $x = 0$

► Musical note:  $x = \text{constant}$



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Computing the equilibria  $x^e$  of the model solving  $f(x, \gamma) = 0$ , they can be:

- ▶ **Zero** (silence) or **nonzero** (musical note)
- ▶ **Stable** (if  $\frac{\partial f(x^e, \gamma)}{\partial x} < 0$ ) or **unstable** (if  $\frac{\partial f(x^e, \gamma)}{\partial x} > 0$ )

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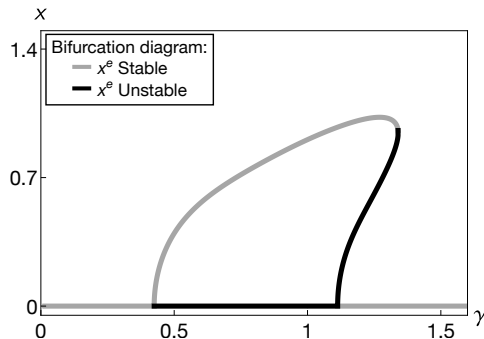
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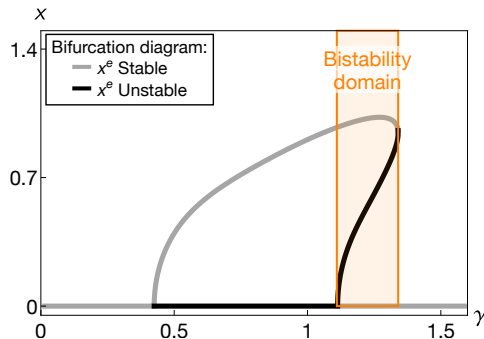
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**Bistability domain** with coexistence:

- ▶ **Two stable equilibria** (silence/musical note)
- ▶ **One unstable equilibrium** (musical note)

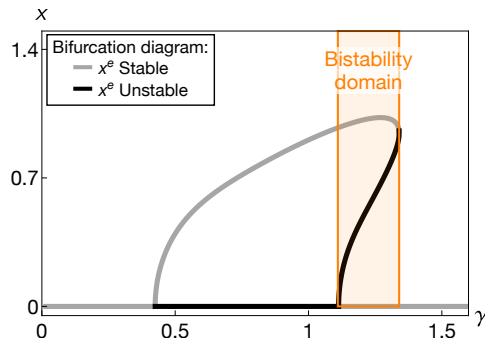
# BASIN OF ATTRACTION

## DEFINITION (BASIN OF ATTRACTION)

For a **given stable equilibrium**, the **basin of attraction** (BA) is the set of initial conditions leading to this equilibrium.

## DEFINITION (SEPARATRIX BETWEEN 2 BAs)

Boundary in phase space separating two BAs.



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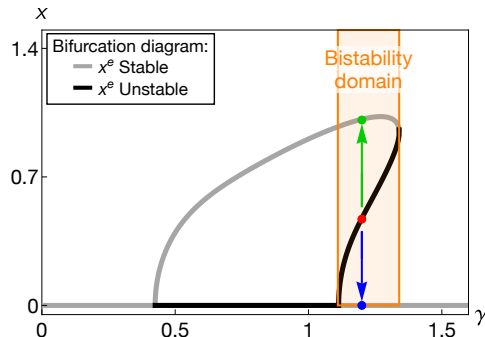
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**Unstable equilibrium**



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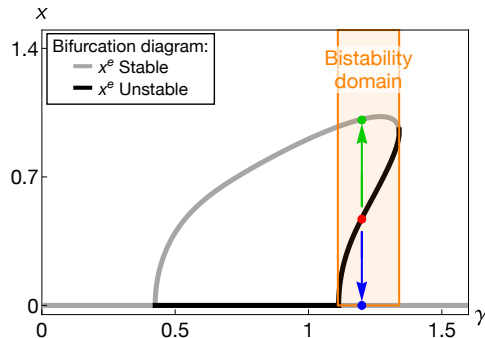
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## DEFINITION (SEPARATRIX BETWEEN 2 BAs)

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## NATURE OF THE SEPARATRIX

**Unstable equilibrium**



## QUESTION

Can we define a **basin of attraction** and a **separatrix** when  $\gamma$  increases over time to reach a **target value within the bistability domain**?



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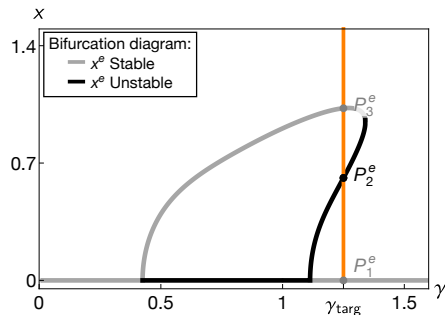
$$\dot{x} = f(x, \gamma)$$
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- ▶  $g(\gamma) = \gamma(1 - \gamma/\gamma_{\text{targ}})$  (tanh-like profile)
- ▶  $\lim_{t \rightarrow \infty} \gamma(t) = \gamma_{\text{targ}}$  (always the same) with  $g(\gamma_{\text{targ}}) = 0$

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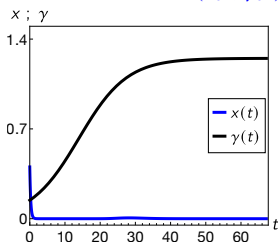
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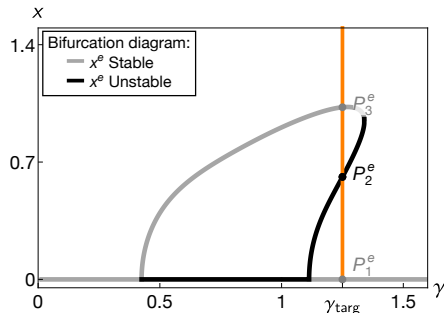
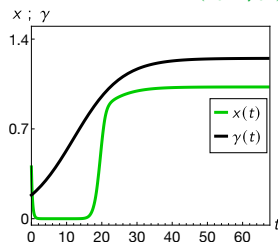
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### EXAMPLE 1: THE RATE OF GROWTH $r$ IS FIXED AND THE INITIAL CONDITION IS CHANGED

Initial condition:  $N_1 = (x_{01}, \gamma_{01})$



Initial condition:  $N_2 = (x_{02}, \gamma_{02})$



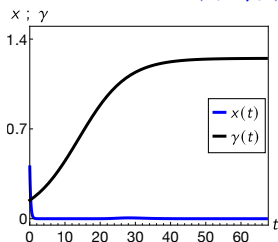
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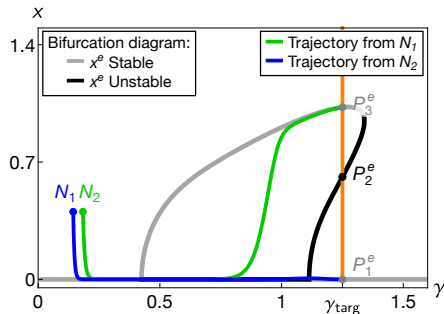
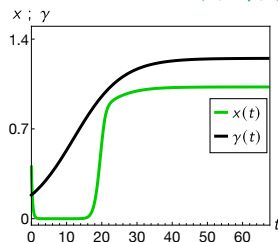
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▶  $N_1$ : **no sound** is produced  $\Rightarrow$  **NO TIPPING**

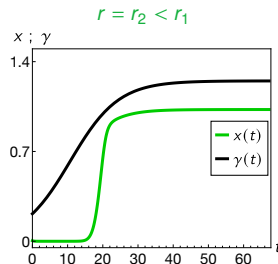
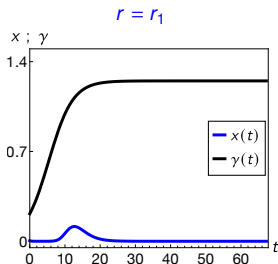
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### EXAMPLE 2: THE INITIAL CONDITION IS FIXED AND THE RATE OF GROWTH $r$ IS CHANGED



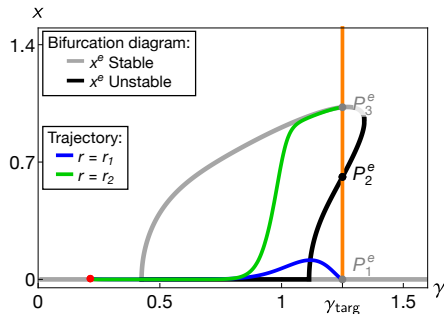
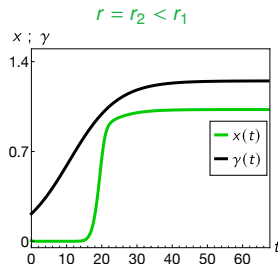
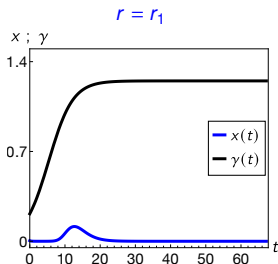
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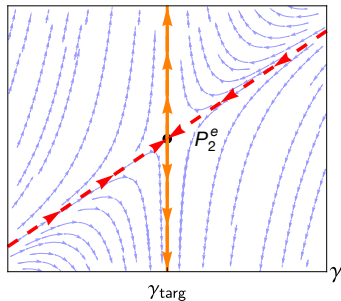
# PREDICTING TIPPING

## TIPPING SEPARATRIX

$P_2^e$  is a **saddle equilibrium point** with:

- Unstable manifold
- - - Stable manifold

x



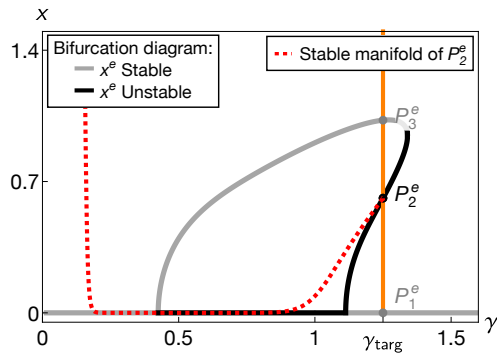
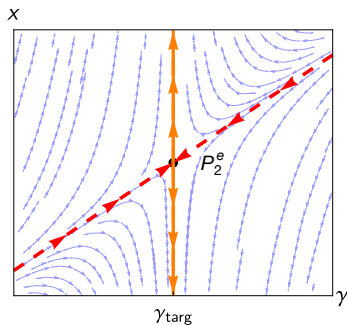


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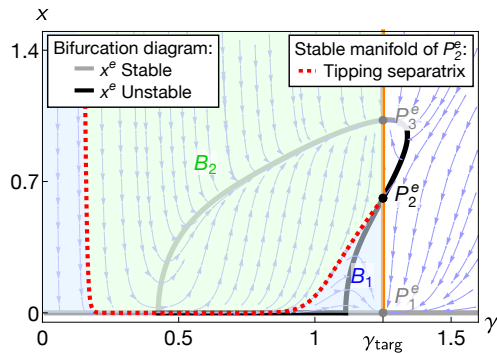
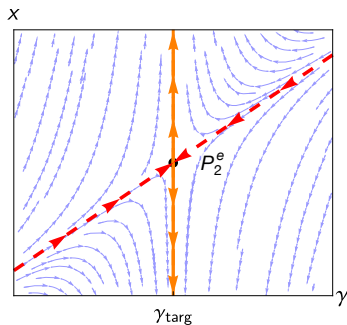


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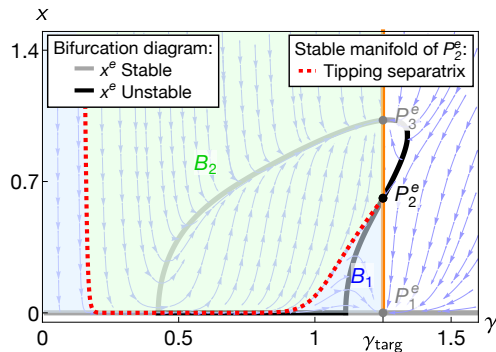
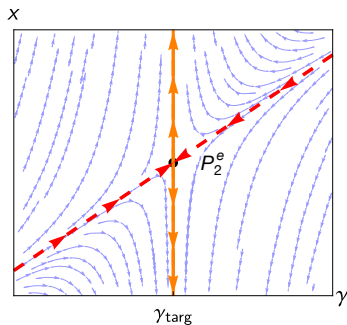
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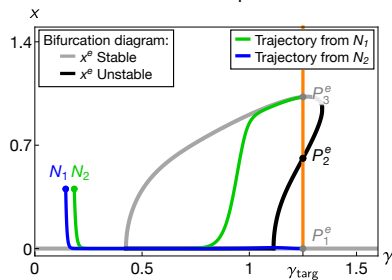
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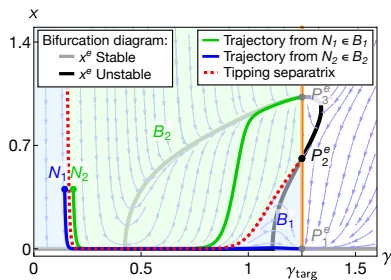
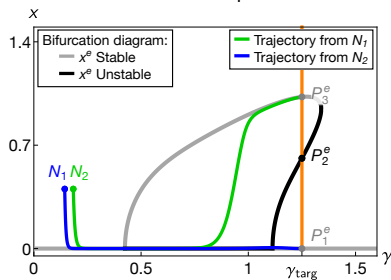


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- $\Rightarrow$  Stable manifold of  $P_2^e$  = **TIPPING SEPARATRIX**

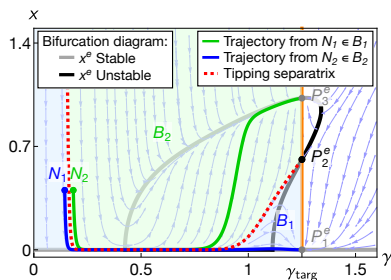
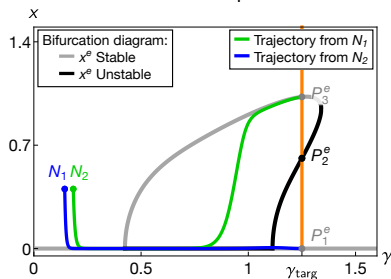
## Back to Example 1



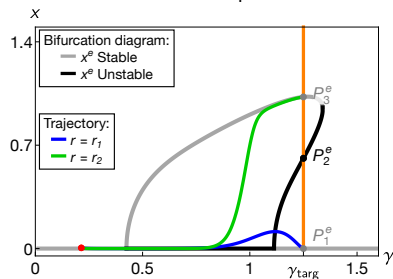
## Back to Example 1



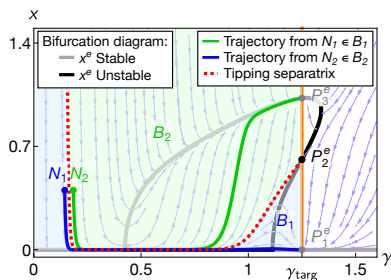
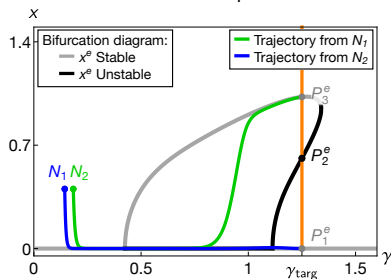
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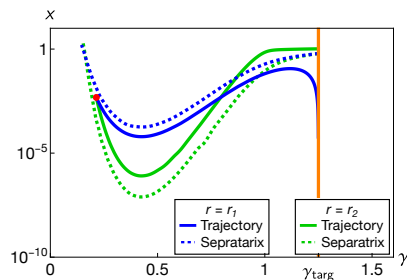
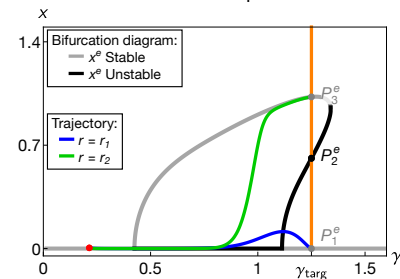
## Back to Example 2



## Back to Example 1



## Back to Example 2



# OUTLINE

1. INTRODUCTION
2. THE CHOSEN SIMPLIFIED MODEL OF SINGLE-REED INSTRUMENT
3. PREVIOUS RESULTS: ANALYSIS OF THE MODEL WITH CONSTANT CONTROL PARAMETER
4. NOVEL RESULTS: ANALYSIS OF THE MODEL WITH TIME-VARYING CONTROL PARAMETER
5. CONCLUSIONS AND PERSPECTIVES



# CONCLUSION

Results from [Bergeot *et al.* (2024), *Chaos: An Interdisciplinary Journal of Nonlinear Science*]

Chaos

ARTICLE

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B. Bergeot,<sup>1,a)</sup> S. Terrien,<sup>2,b)</sup> and C. Vergez<sup>2,c)</sup> 

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- ▶ The case where the **bistability domain is crossed** without any saturation occurring within it is also considered:

A **more complex mathematical framework** must be used (*Geometric Singular Perturbation Theory*) to define the tipping separatrix

- ▶ In both cases:

The **knowledge of the single solution (the tipping sepratrix)** can be used to describe the **global behavior of the model**

- ▶ **Final objective:** to understand and predict the content of the transient when multiple multistability domains are crossed before saturation

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# PERSPECTIVES

## ► Multistability in more refined model of reed instruments

- Equivalent of the tipping separatrix in the case of a bistability between musical notes or tristability
- Compute separatrices using advanced numerical methods like continuation, machine learning (talk of S. Terrien)
- The tipping separatrix can correspond to very small amplitude values for some ranges of the mouth pressure:
  - The effect of noise must be taken into account

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Thank you for your attention

Questions?