

---

# Pattern recognition system

## Exercise Project

---

### REPORT ASSIGNMENT N°1

**Student**

Antoine HONORÉ  
[honore@kth.se](mailto:honore@kth.se)

**Student**

Audrey BROUARD  
[brouard@kth.se](mailto:brouard@kth.se)



## I

Let us calculate  $P(S_t = j) \forall j \in \{1, 2\}$  and for  $t = 1, 2, 3, \dots$

We will do it for  $t = 1$  and  $t = 2$ , and notice that the probabilities are constant  $\forall t$ .

— For  $t = 1$ , the probabilities are given by the matrix  $q_j$ . Thus,  $P(S_1 = 1) = 0.75$  and  $P(S_1 = 2) = 0.25$ .

$\forall t \geq 2$ , we will use the following formula :

$$— P(S_t = j) = \sum_{i=1}^2 P(S_t = j, S_{t-1} = i) = \sum_{i=1}^2 P(S_t = j | S_{t-1} = i) P(S_{t-1} = i)$$

For the case  $t = 2$ , we have :

$$— P(S_t = j) = \sum_{i=1}^2 a_{ij} q_i$$

We thus obtain  $P(S_2 = 1) = 0.75$  and  $P(S_2 = 2) = 0.25$ . We immediately notice that

$$\forall i \ P(S_2 = i) = P(S_1 = i)$$

By recurrency, we have  $\forall t \ \Pr(S_t = j)$  constant.

## II

After we generated 10 000 state integers, we found the following probabilities :

$$\Pr(S_t = 1) = 0.7525 \text{ and } \Pr(S_t = 2) = 0.2475$$

## III @HMM/rand

### III.1 Theoretical calculation

Let us now calculate  $E[X_t]$  and  $Var[X_t]$ .

—  $E[X_t]$  : the book gives the formula  $E[X] = E_S[E_X[X|S]]$ , and according to the two different possible values of  $S$ ,  $X$  density probability function is either  $b_1$  or  $b_2$ .

Then, for  $j = 1$ ,  $E[X|S] = \mu_1$  ; and for  $j = 2$ ,  $E[X|S] = \mu_2$ .

$$E[X] = P(S = 1) * \mu_1 + P(S = 2) * \mu_2 = 0 + 3 * 0.25 = 0.75.$$

—  $Var[X_t]$  : according to the book,  $Var[X_t] = E_S[Var_X[X|S]] + Var_S[E_X[X|S]]$ .

Thanks to the same observation as before, the expression becomes :

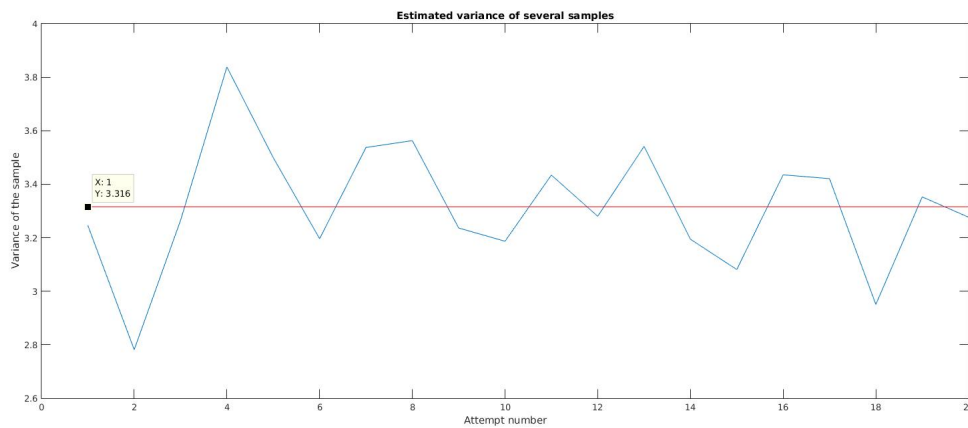
$$Var[X_t] = E_S[Var_X[X|S]] + E_S[(E_X[X|S])^2] - E_S[E_X[X|S]]^2$$

$$Var[X_t] = [0.75 * \sigma_1^2 + 0.25 * \sigma_2^2] + [0.75 * \mu_1^2 + 0.25 * \mu_2^2 - 0.75^2] = 1.75 + 0.25 * 9 - 0.75^2 = 3.4375.$$

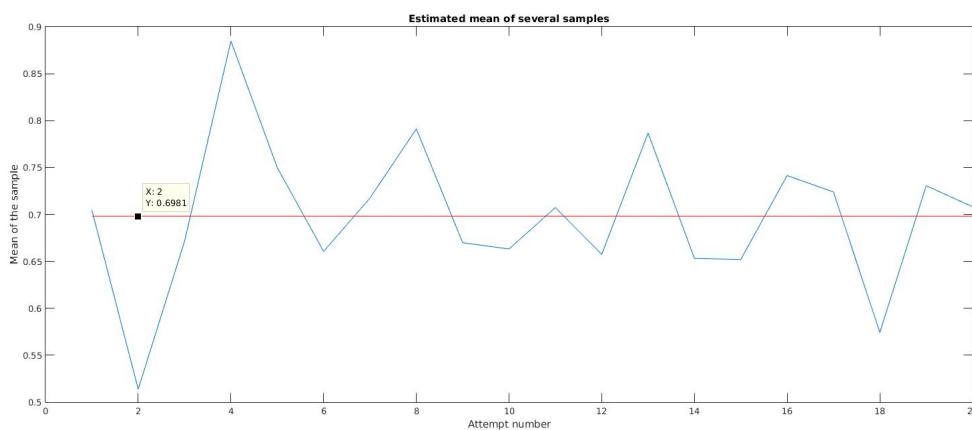
### III.2 Measures

One point on a graph represent the mean (figure 1b) and the variance (figure 1a) of  $T=10000$  scalar output. There is 20 points on each graph. This shows that the experimental values are close from the theoretical ones

As we can see on the figures the experimental values are close from the theoretical ones.



(a) Variance of 10000 samples computed 20 times  $E(Var(X)) \simeq 3.316$



(b) Mean of 10000 samples computed 20 times  $E(E(X)) \simeq 0.6981$

FIGURE 1 – Validation of @HMM/rand

Blue : Plot of the 20 attempts  
Red : Mean over the 20 attempts

## IV HMM behavior 1/2

For this part, we changed the behavior of the @HMM/rand function, in order to get a vector from  $b_1$  (not a scalar like the previous question). So here, each sample is a vector  $x_t \sim N(\mu_j, \sigma_j^2)$  of size 500 (where  $j=1$  or  $2$ ).

The following figure shows the vector plotted for different values of  $t$ .

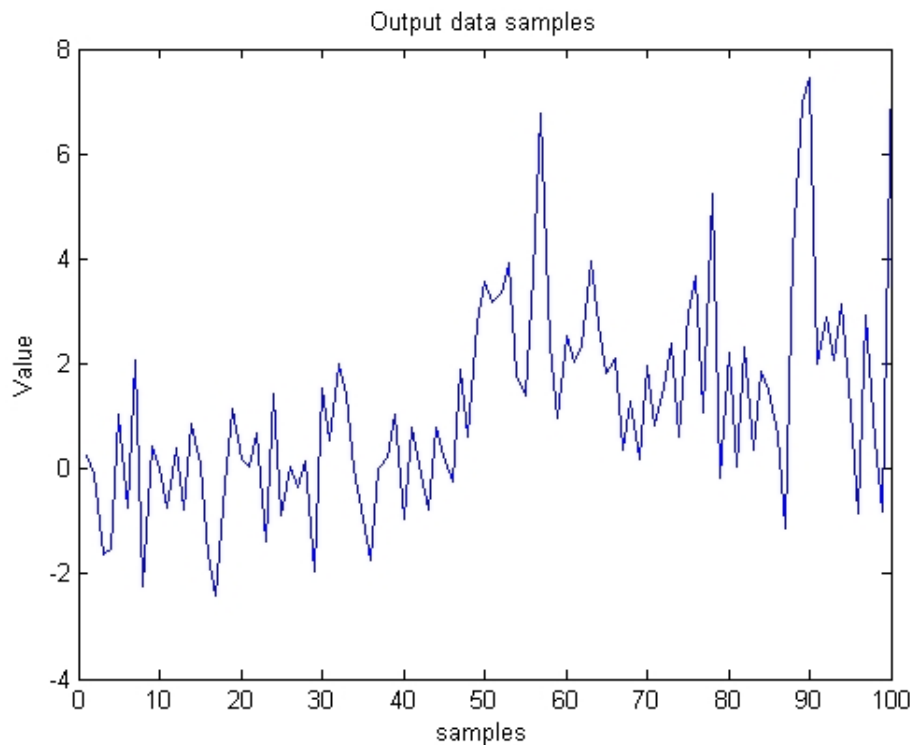


FIGURE 2 – Output data sample for two different means

### Observation

It is easy to find out in which state the system was when the 500 samples were produced. On the figure 3 the samples have very different means and variances.

## V HMM behavior 2/2

We now modify the mean of  $b_2$ ,  $\mu_2$  so that it is equal to  $\mu_1$  :  $\mu_1 = \mu_2 = 0$ .

We can easily notice a change with the previous HMM. On the figure below are represented a sample produced while the state was 1 in blue, and when the state was 2 in red :

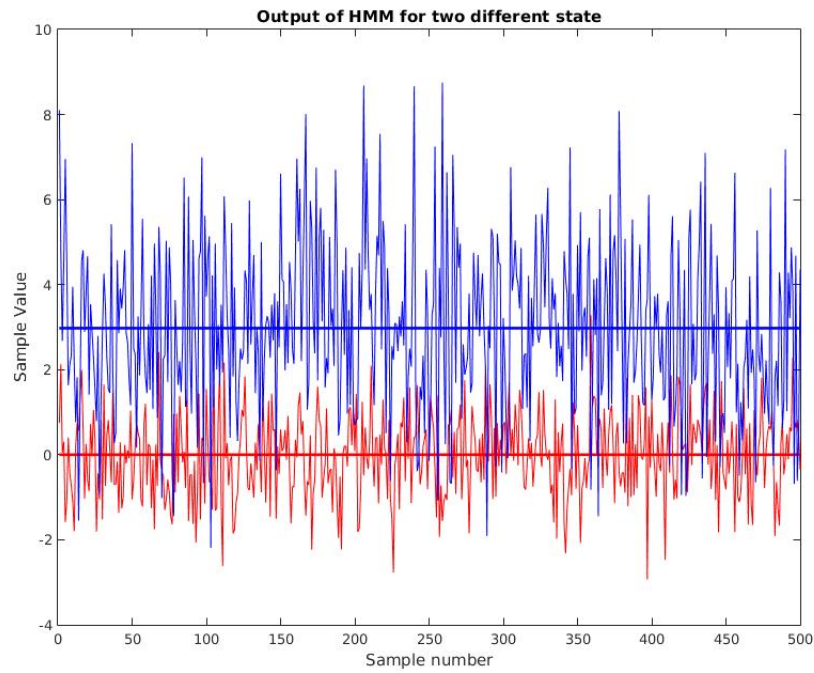


FIGURE 3 – Blue : Sample at a time  $t_1$ .  $\mu = -0.0065$  and  $\sigma^2 = 0.985$   
 Red : Sample at a time  $t_2$ .  $\mu = 2.9759$  and  $\sigma^2 = 3.8953$   
 The width lines represent the mean of the samples

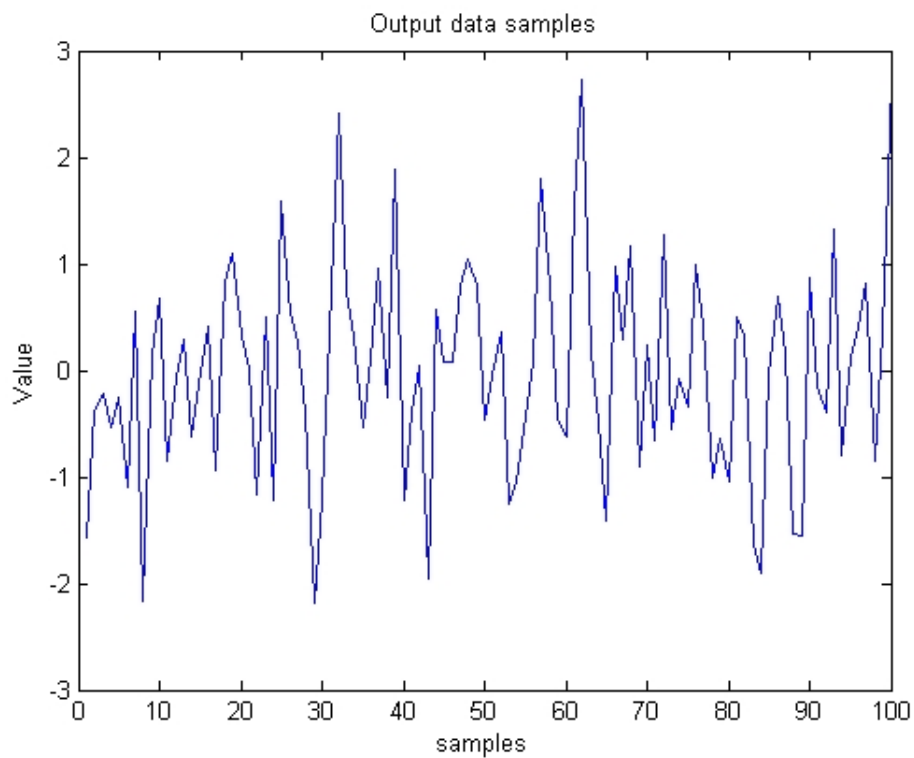
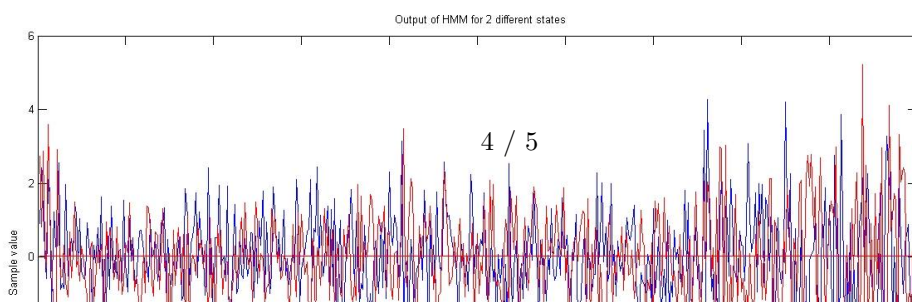


FIGURE 4 – Output data samples for two equal means



Here, we can see that both means are mingled so it seems impossible to determine whether the observation sample was produced under the state 1 or 2. Even if the standard deviations are different, it is not sufficient to spot the state at the moment the sample was produced.

## VI Finite-duration HMMs

The implementation works with finite duration Markov chain.

We defined a transition matrix  $A = \begin{pmatrix} 0.6 & 0.3 & 0.1 \\ 0.5 & 0.4 & 0.1 \end{pmatrix}$  for a Markov chain, then a HMM based on this Markov chain, and the call to @HMM/rand returns the correct information. The difference is that we don't know how long the sequence will be since we don't know precisely when the system will enter the exit state. The system enter the exit state for T=20 which makes sense considering the probability.

## VII Output vectors

The @HMM/rand function has been tested and works good when the Output Distributions returns both vectors and scalars.