```
from skimage.io import imread
from skimage.data import camera
from scipy.ndimage import map coordinates
import numpy as np
import matplotlib.pyplot as plt
import time
def linear polar(img, o=None, r=None, output=None, order=1, cont=0, verbose =
0):
   if o is None: o = np.array(img.shape[:2])/2 - 0.5
   if r is None: r = (np.array(img.shape[:2])**2).sum()**0.5/2
   if output is None:
        shp = int(round(r)), int(round(r*2*np.pi))
        output = np.zeros(shp, dtype=img.dtype)
   elif isinstance(output, tuple):
        output = np.zeros(output, dtype=img.dtype)
   out h, out w = output.shape
   out_img = np.zeros((out_h, out_w), dtype=img.dtype)
    rs = np.linspace(0, r, out h)
   ts = np.linspace(0, np.pi*2, out w)
   xs = rs[:,None] * np.cos(ts) + o[1]
   ys = rs[:,None] * np.sin(ts) + o[0]
   # breakpoint()
   map coordinates(img, (ys, xs), order=order, output=output)
   if verbose == 0:
        return output
   elif verbose > 0:
        return output, rs, ts, o, r, out_h, out_w
def polar linear(img, o=None, r=None, output=None, order=1, cont=0):
   if r is None: r = imq.shape[0]
   if output is None:
        output = np.zeros((r*2, r*2), dtype=img.dtype)
   elif isinstance(output, tuple):
        output = np.zeros(output, dtype=img.dtype)
   if o is None: o = np.array(output.shape)/2 - 0.5
   out h, out w = output.shape
   ys, xs = np.mgrid[:out h, :out w] - o[:,None,None]
    rs = (ys**2+xs**2)**0.5
   # breakpoint()
   ts = np.arccos(xs/rs)
   ts[ys<0] = np.pi*2 - ts[ys<0]
   ts *= (img.shape[1]-1)/(np.pi*2)
   map_coordinates(img, (rs, ts), order=order, output=output)
    return output
def map pixel(i,j, img, o=None, r=None, output=None, order=1, cont=0, debug =
False, out h = None, out w = None):
    if o is None: o = np.array(img.shape[:2])/2 - 0.5
   if r is None: r = (np.array(img.shape[:2])**2).sum()**0.5/2
    if out h is None or out w is None or debug:
        if output is None:
            shp = int(round(r)), int(round(r*2*np.pi))
            output = np.zeros(shp, dtype=img.dtype)
        elif isinstance(output, tuple):
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1 of 3 11/23/22, 3:38 PM

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53
                output = np.zeros(output, dtype=img.dtype)
 54
            out h, out w = output.shape
 55
        y = i
 56
        x = j
 57
        y oriq = o[0]
 58
        x \text{ orig} = o[1]
 59
 60
        rad = np.sqrt((x- x orig)**2 + (y - y orig)**2)
        theta = (2*np.pi+(np.arctan2((y-y_orig), (x-x_orig))))%(2*np.pi)#(y-y_orig)
 61
    y orig)/(x-x \text{ orig})) #(2*np.pi + np.arctan((y-y \text{ orig})/(x-x \text{ orig})))%(2*np.pi)
 62
        # print(theta, y- y_orig, x-x_orig)
 63
 64
        rs = np.linspace(0, r, out h)
 65
        ts = np.linspace(0, np.pi*2, out_w)
 66
        # breakpoint()
 67
        r index = np.digitize(rad, rs)
 68
        theta index = np.digitize(theta, ts)
 69
 70
        if debug:
 71
            xs = rs[:,None] * np.cos(ts) + o[1]
 72
            ys = rs[:,None] * np.sin(ts) + o[0]
 73
            map coordinates(img, (ys, xs), order=order, output=output)
 74
            print(r index, theta index)
 75
            print(ys[r index, theta index], xs[r index, theta index], i, j)
 76
            # print(, i, j)
 77
            print(output[r_index, theta_index])
 78
            print(img[y,x])
 79
            print(img[i,j])
 80
        return r_index, theta_index, theta
 81
        # breakpoint()
82 def unmap pixel(radius, theta idx, img, theta = None, o=None, r=None,
    output=None, order=1, cont=0, debug = False, out h = None, out w = None):
 83
        if r is None: r = img.shape[0]
 84
        if output is None:
 85
            output = np.zeros((r*2, r*2), dtype=img.dtype)
 86
        elif isinstance(output, tuple):
 87
            output = np.zeros(output, dtype=img.dtype)
 88
        if o is None: o = np.array(output.shape)/2 - 0.5
 89
        out h, out w = output.shape
 90
        if theta == None:
 91
            ts = np.linspace(0, 2*np.pi, img.shape[1])
 92
            theta = ts[theta idx]
 93
        x = radius*np.cos(theta) + o[1]
 94
        y = radius*np.sin(theta) + o[0]
 95
 96
        return int(np.round_(y)), int(np.round_(x))#r_index, theta_index, theta
 97 if
       __name__ == '_ main ':
 98
        img = camera()
99
        ax = plt.subplot(311)
100
        ax.imshow(img)
101
102
        out, rs, ts,o, r, out h, out w = linear polar(img, verbose = 1)
103
        print(time.time())
104
105
        oldtime = time.time()
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2 of 3 11/23/22, 3:38 PM

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106
       coords = (120,1)
107
       test =map_pixel(coords[0], coords[1],img[255:,:], o = o, r =r, out_h =
   out h, out w = out w, debug= False )
       original_args = unmap_pixel(test[0], test[1], out, output = img.shape,
108
   theta = test[2]
109
       print(coords, original_args)
110
       newtime = time.time()
111
       print(newtime- oldtime)
112
113
       ax = plt.subplot(312)
114
       ax.imshow(out)
115
       img = polar_linear(out, output=img.shape)
       ax = plt.subplot(313)
116
       ax.imshow(img)
117
118
       nlt.show()
```

3 of 3 11/23/22, 3:38 PM