

Homework #2 - Due date: 29<sup>th</sup> November 2019

Student: Oriol Barbany Mayor

## PROBLEM 1 - QUICK REVIEW OF CHAPTER 2

- (i) •  $A(x) := x * h_A$ ,  $x, h_A \in \ell^2$ . It's easy to check that  $A$  is a linear operator. Let  $y \in \ell^2$  and for the rest of the exercise let  $\alpha, \beta \in \mathbb{C}$ .

$$(A(\alpha x + \beta y))_n := ((\alpha x + \beta y) * h_A)_n := \sum_{k \in \mathbb{Z}} (\alpha x[k] + \beta y[k]) h_A[n - k] \quad (1)$$

$$= \alpha \sum_{k \in \mathbb{Z}} x[k] h_A[n - k] + \beta \sum_{k \in \mathbb{Z}} y[k] h_A[n - k] =: \alpha (A(x))_n + \beta (A(y))_n \quad (2)$$

Moreover,  $A$  is also shift invariant so it's LSI. To see this, let  $x'[n] := x[n - n_0]$ . Then,

$$(A(x'))_n := x' * h_A := \sum_{k \in \mathbb{Z}} x'[n - k] h_A[k] := \sum_{k \in \mathbb{Z}} x[n - k - n_0] h_A[k] =: (A(x))_{n - n_0} \quad (3)$$

- $B(x)(t) := x(t) + \text{sinc}(t)$ ,  $x \in \mathcal{L}^2(\mathbb{R})$  is clearly not shift invariant. For the rest of the exercise, let  $x'(t) := x(t - t_0)$ . In this case

$$B(x')(t) := x'(t) + \text{sinc}(t) := x(t - t_0) + \text{sinc}(t) \neq x(t - t_0) + \text{sinc}(t - t_0) =: B(x)(t - t_0) \quad (4)$$

hence  $B$  is not LSI.

- $C(x)(t) := x(2t)$ ,  $x \in \mathcal{L}^2(\mathbb{R})$ . Note that

$$C(x')(t) := x'(2t) := x(2t - t_0) \neq x(2(t - t_0)) =: C(x)(t - t_0) \quad (5)$$

hence  $C$  is not LSI.

- $D(x) := \frac{dx}{dt}$ ,  $x \in \mathcal{C}^\infty$ . It's well-known that the derivative is linear, but for completeness, let  $y \in \mathcal{C}^\infty$

$$D(\alpha x + \beta y) := \frac{d}{dt}(\alpha x + \beta y) = \alpha \frac{dx}{dt} + \beta \frac{dy}{dt} =: \alpha D(x) + \beta D(y) \quad (6)$$

so indeed linearity holds for  $D$ . By chain rule we have that

$$D(x')(t) := \frac{d}{dt} x'(t) := \frac{d}{dt} x(t - t_0) =: D(x)(t - t_0) \left[ \frac{d}{dt} (t - t_0) \right] = D(x)(t - t_0) \quad (7)$$

so  $D$  is also LSI.

- (iii) By definition of the adjoint operator, we have that

$$\langle C(x)(t), y(t) \rangle_{\mathcal{L}^2(\mathbb{R})} = \int_{-\infty}^{\infty} C(x)(t) y^*(t) dt := \int_{-\infty}^{\infty} x(2t) y^*(t) dt \quad (8)$$

$$= \langle x(t), C^*(y)(t) \rangle_{\mathcal{L}^2(\mathbb{R})} = \int_{-\infty}^{\infty} x(t) (C^*(y)(t))^* dt \quad (9)$$

so we can see that by letting  $t' := 2t$ ,

$$\int_{-\infty}^{\infty} x(2t) y^*(t) dt = \int_{-\infty}^{\infty} x(t') y^* \left( \frac{t'}{2} \right) \frac{1}{2} dt' =: \frac{1}{2} \int_{-\infty}^{\infty} x(t') (C^*(y)(t'))^* dt' \quad (10)$$

and hence  $C^*(y)(t) = \frac{1}{2} y \left( \frac{t}{2} \right)$ .

- (iv) Let  $x, y \in \mathcal{H}$  and let  $c \geq 0$  be such that  $x(t) = 0$  for  $|t| \geq c$  and  $d \geq 0$  such that  $y(t) = 0$  for  $|t| \geq d$ . Now by definition of the adjoint operator,

$$\langle D(x)(t), y(t) \rangle_{\mathcal{H}} = \int_{\mathcal{H}} D(x)(t) y^*(t) dt := \int_{-d}^d \frac{dx}{dt}(t) y^*(t) dt \quad (11)$$

$$= \langle x(t), D^*(y)(t) \rangle_{\mathcal{H}} = \int_{\mathcal{H}} x(t) (D^*(y)(t))^* dt \quad (12)$$

Using integration by parts, we get that

$$\int_{-d}^d \frac{dx}{dt}(t) y^*(t) dt = x(t) y^*(t) \Big|_{-\min(c,d)}^{\min(c,d)} - \int_{\mathcal{H}} x(t) \frac{dy^*}{dt}(t) dt \quad (13)$$

$$= - \int_{\mathcal{H}} x(t) \frac{dy^*}{dt}(t) dt =: \int_{\mathcal{H}} x(t) (D^*(y)(t))^* dt \quad (14)$$

where the penultimate equality follows since  $\mathcal{H} \subset \mathcal{L}^2(\mathbb{R})$ , so  $y^* = y$ , and  $x(\pm \min(c, d)) y(\pm \min(c, d)) = 0$  by the finite support property of  $\mathcal{H}$  and the definition of  $c, d$ . So  $D^*(y)(t) = -\frac{dy}{dt}(t)$ .

## PROBLEM 2 - LCMV AND GSC DERIVATION

- (i) First of all, note that  $\arg \max \|\mathbf{x}\| = \arg \max \|\mathbf{x}\|^2 = \arg \max \frac{1}{2} \|\mathbf{x}\|^2$ . We can analytically find the local maximum of a function subject to an equality constraint as in this case by using Lagrange multipliers. Let  $\mathbf{y}$  be the Lagrange multiplier

$$\mathcal{L}(\mathbf{x}, \mathbf{y}) = \frac{1}{2} \|\mathbf{x}\|^2 + \mathbf{y}^* (\mathbf{b} - A\mathbf{x}) \quad (15)$$

which has its maximum attained at the critical point

$$\nabla_{\mathbf{x}} \mathcal{L}(\mathbf{x}, \mathbf{y}) = \mathbf{x} - A^* \mathbf{y} = 0 \iff \mathbf{x} = A^* \mathbf{y} \quad (16)$$

By imposing the constraint,  $A\mathbf{x} = AA^* \mathbf{y} = \mathbf{b}$ .

- (ii) When  $M \leq N$  and  $A$  is of full rank, the matrix  $AA^*$  is invertible and hence

$$\mathbf{y} = (AA^*)^{-1} \mathbf{b} \implies \mathbf{x} = A^* (AA^*)^{-1} \mathbf{b} \quad (17)$$

- (iii) Using again the same trick as before, one can use the equivalent objective function  $\frac{1}{2} \mathbf{h}^* R_x \mathbf{h}$ , which gives a Lagrangian of

$$\mathcal{L}(\mathbf{h}, \mathbf{y}) = \frac{1}{2} \mathbf{h}^* R_x \mathbf{h} + \mathbf{y}^* (\mathbf{f} - C^* \mathbf{h}) \quad (18)$$

$$\nabla_{\mathbf{h}} \mathcal{L}(\mathbf{h}, \mathbf{y}) = R_x \mathbf{h} - C \mathbf{y} = 0 \iff R_x \mathbf{h} = C \mathbf{y} \quad (19)$$

Note that  $R_x$  is invertible since  $R_x \succ 0$ , so  $\mathbf{h} = R_x^{-1} C \mathbf{y}$ . Again we can find the value of the Lagrange multiplier by imposing the constraint

$$C^* \mathbf{h} = C^* R_x^{-1} C \mathbf{y} = \mathbf{f} \quad (20)$$

**Assumption 1.** The matrix  $C$  is full rank and  $P \leq M$ , meaning that  $\dim(\mathcal{R}(C)) = \min(M, P) = P$ .

Finally, we have that  $C^*R_x^{-1}C$  is invertible if Assumption 1 holds. To proof this, I will proceed in a few steps.

First of all note that  $R_x^{-1} \succ 0$ . This is easier to see when analysing the eigenvalue decomposition of  $R_x$ . Given that the covariance matrix is hermitian, it can be written as  $R_x = U\Lambda U^*$ , where  $U$  is a unitary matrix and  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$  is a diagonal matrix. Given that  $R_x$  is positive definite,  $R_x^{-1} = U\Lambda^{-1}U^*$  is also positive definite and hence invertible since  $\Lambda^{-1} = (\lambda_1^{-1}, \dots, \lambda_n^{-1})$  and  $\lambda_i > 0 \implies \lambda_i^{-1} > 0$ . Note that invertibility is trivial to see since  $(R_x^{-1})^{-1} = R_x$ .

By definition of positive definiteness, we say that  $R_x^{-1} \succ 0$  if  $\mathbf{x}R_x^{-1}\mathbf{x} > 0 \quad \forall \mathbf{x} \in \mathbb{R}^M \setminus \{\mathbf{0}\}$ . The projection  $\tilde{\mathbf{x}} := C\mathbf{y}$  is non-zero  $\forall \mathbf{y} \in \mathbb{R}^N \setminus \{\mathbf{0}\}$  since the nullspace of  $C$  is trivial by the rank-nullity theorem. In this case, this translates to  $\dim(\mathcal{N}(C)) + \dim(\mathcal{R}(C)) = P$ , meaning that  $\dim(\mathcal{N}(C)) = 0$ . Hence,

$$\tilde{\mathbf{x}} := C\mathbf{y} = \mathbf{0} \iff \mathbf{y} = \mathbf{0} \quad (21)$$

Now we can see that  $\tilde{\mathbf{x}}^*R_x^{-1}\tilde{\mathbf{x}} > 0 \quad \forall \tilde{\mathbf{x}} \neq \mathbf{0}$  following from the fact that  $R_x^{-1} \succ 0$ . So using the latter and the equivalence of (21),

$$\mathbf{y}^*C^*R_x^{-1}C\mathbf{y} := \tilde{\mathbf{x}}^*R_x^{-1}\tilde{\mathbf{x}} > 0 \quad \forall \mathbf{y} \in \mathbb{R}^N \setminus \{0\} \quad (22)$$

and thus  $C^*R_x^{-1}C \succ 0$  and hence invertible.

So we can write

$$\mathbf{y} = (C^*R_x^{-1}C)^{-1}\mathbf{f} \implies \mathbf{h} = R_x^{-1}C(C^*R_x^{-1}C)^{-1}\mathbf{f} \quad (23)$$

Just as a sanity check, note that by setting  $R_x = I$ ,  $A = C^*$  and  $\mathbf{f} = \mathbf{b}$ , we recover the solution found in section (ii):

$$R_x^{-1}C(C^*R_x^{-1}C)^{-1}\mathbf{f} = A^*(AA^*)^{-1}\mathbf{b} = \mathbf{x} \quad (24)$$

which can be computed if Assumption 1 holds.

- (iv) In this last case we have an unconstrained problem so we can use simple derivation of the objective function to find where its minimum is attained.

$$f(\mathbf{h}_n) := (\mathbf{h}_0 - C_n\mathbf{h}_n)^*R_x(\mathbf{h}_0 - C_n\mathbf{h}_n) \quad (25)$$

Note that we also need Assumption 1 to hold, since computing  $\mathbf{h}_0$  needs the matrix  $C^*C$  to be invertible. Given that a covariance matrix is hermitian,

$$\nabla_{\mathbf{h}_n} f(\mathbf{h}_n) = 2C_n^*R_x(C_n\mathbf{h}_n - \mathbf{h}_0) = 0 \iff C_n^*R_xC_n\mathbf{h}_n = C_n^*R_x\mathbf{h}_0 \quad (26)$$

Moreover, by previous observation and under Assumption 1,  $C_n^*R_xC_n$  is invertible, so

$$\mathbf{h}_n = (C_n^*R_xC_n)^{-1}C_n^*R_x\mathbf{h}_0 \quad (27)$$

as claimed.