



Introduction

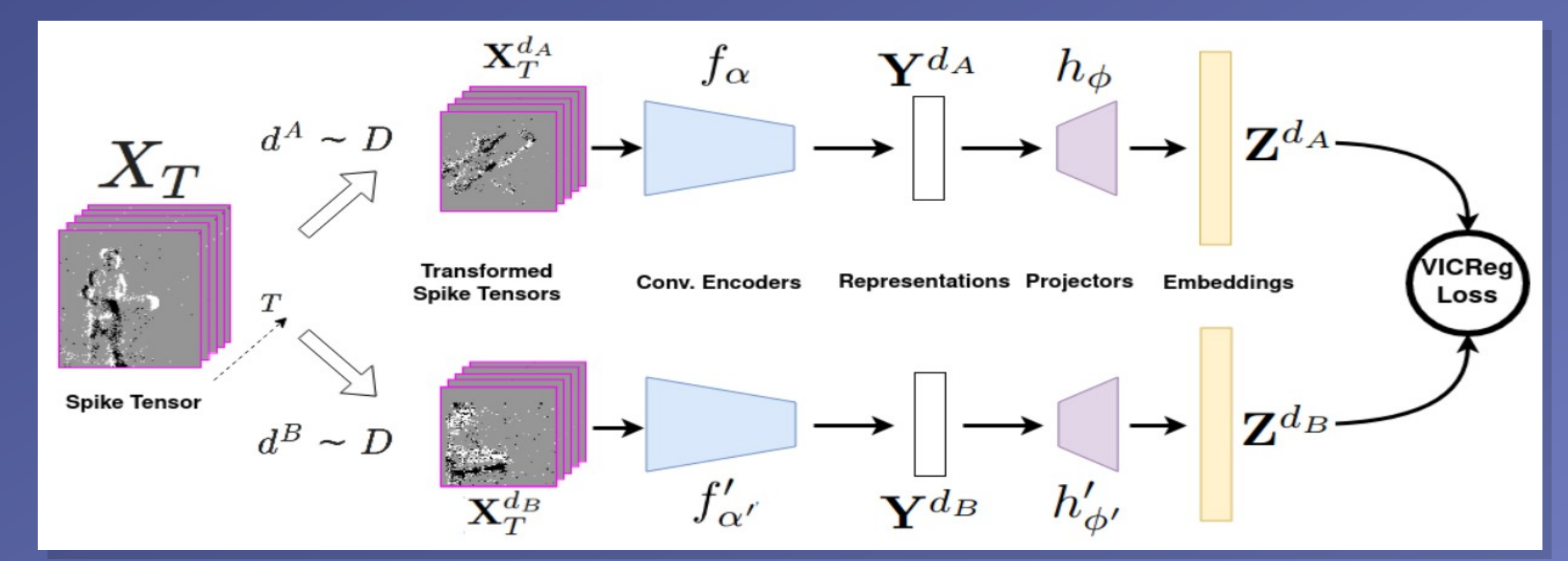
- Many event-based datasets have a limited number of labeled samples
- It presents challenges for the development of event vision algorithms
- Self-Supervised Representation Learning (SSRL) is a good solution for reducing the reliance on labeled data

Contributions

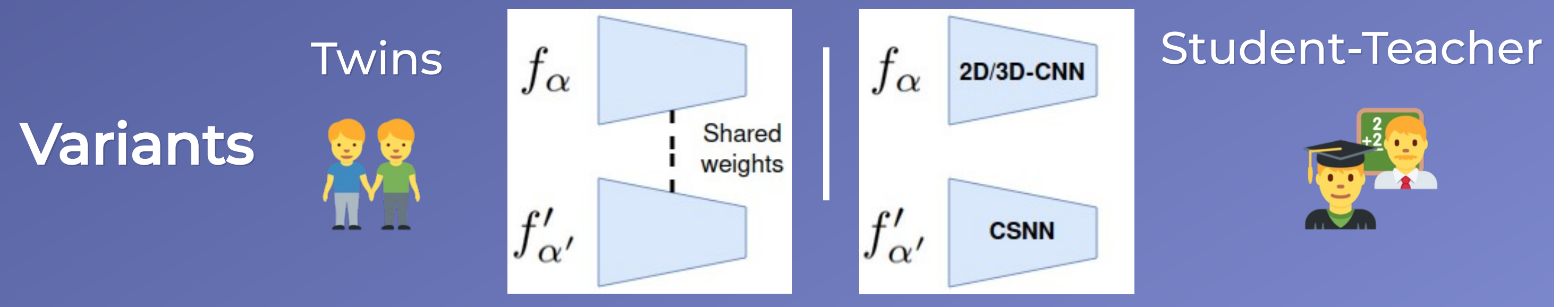
- Event-based SSRL framework
- Evaluation protocols
- Study on EDAs (Event Data Augmentation)
- Analysis of learned features

Event-Based SSRL Framework

Joint embedding architecture



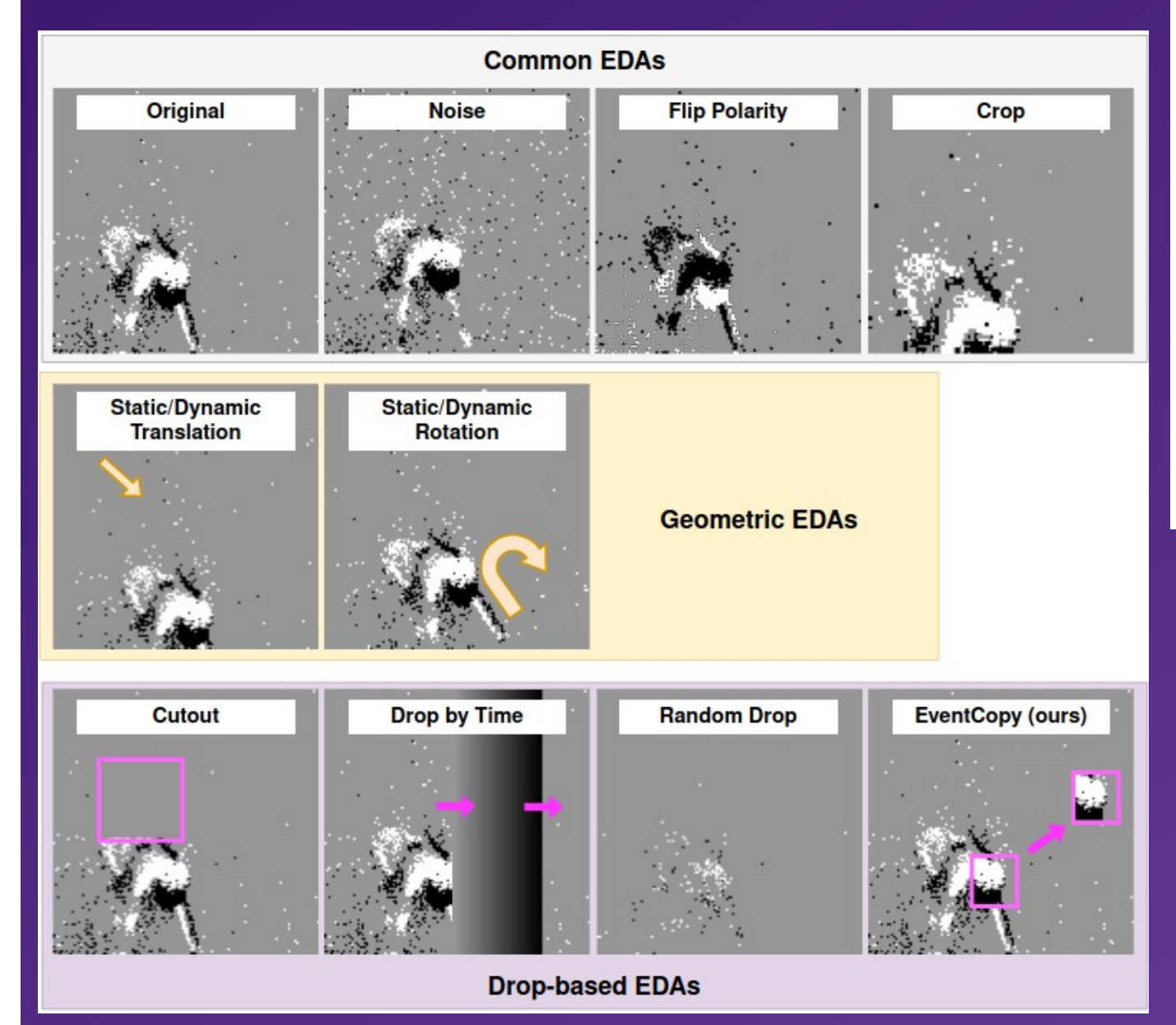
Three types of ConvEncs : 2D-CNN, 3D-CNN, CSNN



Study on Event Data Augmentations

How to design an effective EDA Distribution for pretraining?

Incremental experiments: we keep the best-performing EDA configuration from the previous stage



Stage 1: Common EDAs				Twins				Student-Teacher			
Noise	Crop	PolFlip		CSNN	2D	3D		CSNN	2D	CSNN	3D
✓	✓	✓		12.12	11.36	57.95		59.47	61.36	58.33	55.68
				60.23	74.24	69.70		62.12	64.02	68.26	60.23
				56.44	81.82	74.62		73.86	76.89	69.32	64.02
				56.44	83.33	76.52		73.11	74.62	70.63	67.80

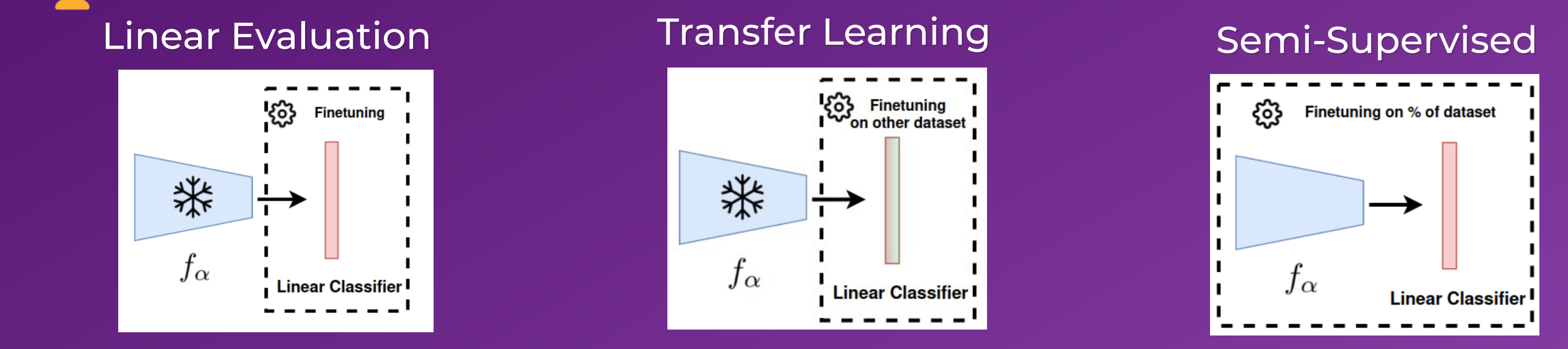
Stage 2: Geometric EDAs				Twins				Student-Teacher			
StatTran	StatRot	DynTran	DynRot	CSNN	2D	3D		CSNN	2D	CSNN	3D
✓	✓	✓	✓	49.24	77.65	65.15		60.98	68.18	65.53	62.5
				68.56	75.38	76.14		74.24	73.11	72.73	67.05
				68.94	79.55	77.27		67.05	70.45	71.97	68.18

Stage 3: Drop-based EDAs				Twins				Student-Teacher			
Cutout	EventDrop	Event-Copy Drop	EventCopyDrop	CSNN	2D	3D		CSNN	2D	CSNN	3D
✓	✓	✓	✓	71.59	85.11	88.64		71.59	72.35	68.56	65.91
				68.18	87.12	75		75	76.52	76.52	76.14
				65.16	81.82	83.33		76.52	77.52	73.86	68.94
				70.83	87.12	89.39		76.89	75.76	75	73.48

Accuracy on DVSGesture (Linear Eval. Protocol)

- A good EDA distribution consists of :
 - More common EDAs
 - Strictly one Geometric and one Drop-based EDA
 - One of functions (e.g., EventCopyDrop, StatDynGeo,...)

Evaluation Protocols



Dataset	Protocol	CSNN	2D	3D	CSNN _{2D}	CSNN _{3D}
DVSGesture	Linear	70.83	87.12	89.39	76.89	76.52
	SemiSup-10%	60.98	75.52	81.44	66.67	69.31
	SemiSup-25%	75.00	87.12	90.15	76.14	80.30
N-Caltech101	Linear	64.29	64.39	69.46	62.34	65.67
	SemiSup-10%	56.72	64.64	62.80	53.96	53.50
	SemiSup-25%	66.02	72.79	71.64	62.22	59.93
ASL-DVS	Linear	95.32	99.38	98.68	97.87	97.30
	SemiSup-05%	95.66	97.06	96.62	93.54	95.66
	SemiSup-10%	99.51	99.64	99.70	99.48	99.48

Metric: classification accuracy (%)

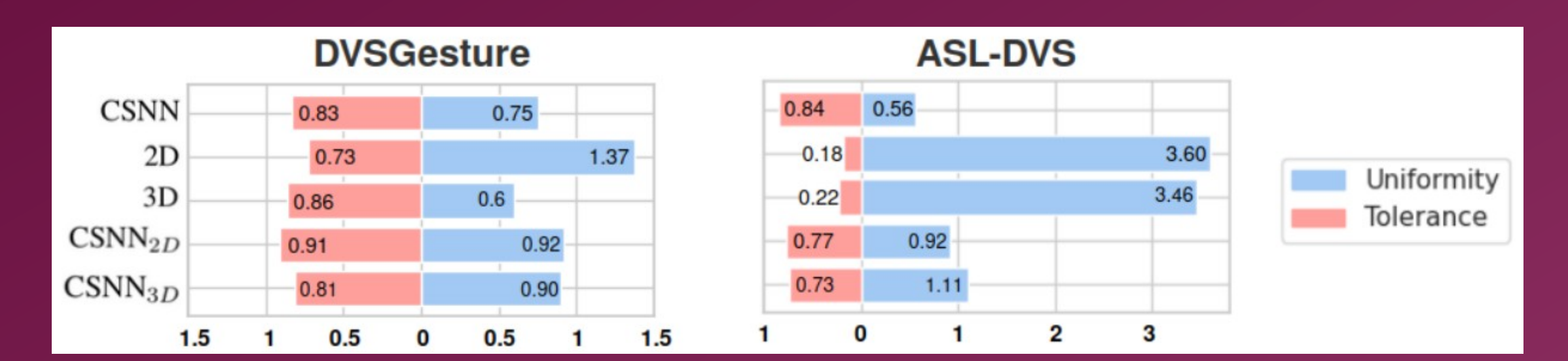
Transfer learning protocol

Datasets		CSNN	2D	3D	CSNN _{2D}	CSNN _{3D}
Pretrain	Linear	77.93	88.28	84.83	91.03	87.59
DVSGesture	DailyAction-DVS	92.81	94.61	95.64	93.30	93.35
ASL-DVS	N-CARS					

Analysis of Learned Features

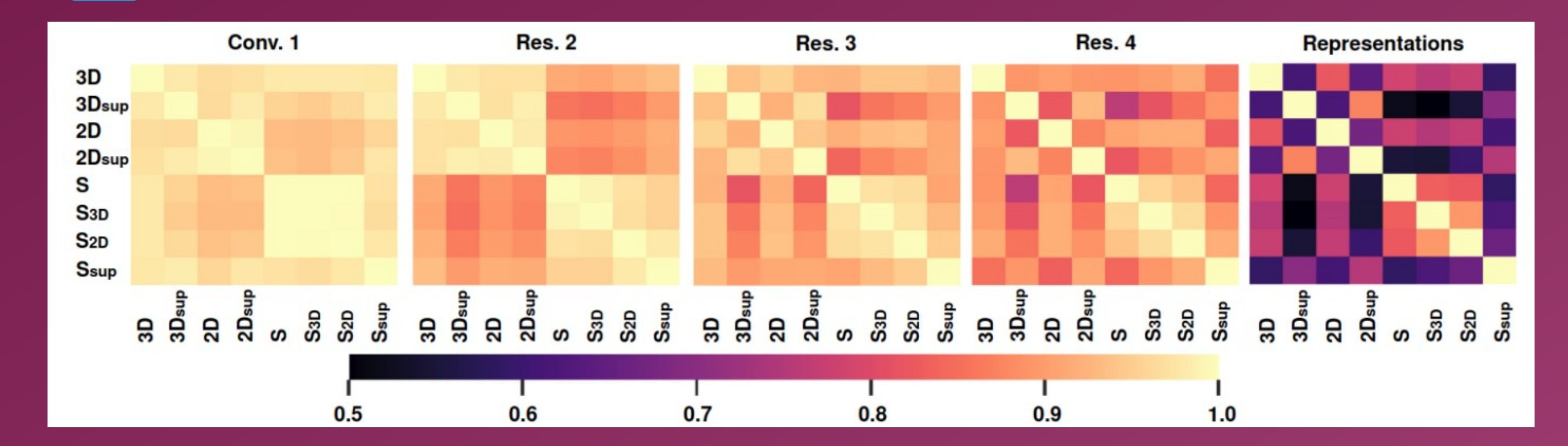
1 Uniformity - Tolerance Trade-Off

Assumption from frame-based vision: balanced values of Uniformity and Tolerance result in optimal representation quality



- The original assumption does not prevail
- Student-Teacher variant increases the tolerance of the CSNNs

2 Linear CKA for Similarity Assessment



- The divergence increases with deeper layers
- The impact of Student-Teacher variants on the learned features of CSNNs

Conclusion

- We propose a method for **event-based SSRL** that utilizes a joint embedding architecture and event data augmentations
- The **evaluation protocols** established in this study emphasize the efficiency and transferability of the learned features, as well as the reduced dependence on labeled data facilitated by our framework
- We thoroughly **investigate the impacts of popular EDAs** and introduce **additional methods** to achieve an optimal distribution for event-based SSRL
- Our method creates exciting possibilities for designing future event-based vision applications that do not require large-scale training sets