```
clear;clc;close all;

% install Statistics and Machine Learning Toolbox

% activate vision toolbox by Peter Corke
addpath('rtb');
addpath('smtb');
addpath('vision');
addpath('Helpers');
run('./rtb/startup_rtb.m');



% % show points and optical flows
 ----------------------------------------
% figure(1);
% quiver(m(1,:), m(2,:), m_dot(1,:), m_dot(2,:),0);
% quiver(m5(1,:), m5(2,:), m5_dot(1,:), m5_dot(2,:));

num_trials = 21;
noise_max = 2;
noise_increment = .1;
noise_list = 0:noise_increment:noise_max;

w_true = [0.8;1.3;0.5];
v_true = [0;0;0.000001];
v_true_norm = v_true / (norm(v_true));
% v_true_norm = v_true;

v_error_buffer = zeros(1,num_trials);
w_error_buffer = zeros(1,num_trials);
v_error_list = zeros(1,length(noise_list));
w_error_list = zeros(1,length(noise_list));

for i = 1:(length(noise_list))

    noise = noise_list(i);

    for j = 1:num_trials

        [m, m_dot] = Create_M_and_Mdot(v_true,w_true,noise);    % find
 m and mdot using simulated points

        [v_est,w_est] = PoCo(m,m_dot); % call algorithm

%         v_est_norm = v_est;
        v_est_norm = v_est / norm(v_est); % normalize v answer
        if(v_est_norm(3)<0)
            v_est_norm = -v_est_norm;
        end
```

```
%         error_v = sqrt( (v_est_norm(1)-v_true_norm(1))^2
 + (v_est_norm(2)-v_true_norm(2))^2 + (v_est_norm(3)-
v_true_norm(3))^2 );
        error_v =1/pi*acos((v_est_norm'*v_true_norm));
        error_w = sqrt( (w_est(1)-w_true(1))^2 + (w_est(2)-
w_true(2))^2 + (w_est(3)-w_true(3))^2 );

        v_error_buffer(1, j) = error_v;
        w_error_buffer(1, j) = error_w;

    end

    i

    v_err = mean(v_error_buffer);
    w_err = mean(w_error_buffer);

    v_error_list(1,i) = v_err;
    w_error_list(1,i) = w_err;

end
```

```
- Robotics Toolbox for MATLAB (release 10.4)
Warning: Invalid file or directory
'/home/smerx/git/QEKF/dev/matlab/src/vest/rtb/java/DHFactor.jar'.
 - ARTE contributed code: 3D models for robot manipulators (/home/
smerx/git/QEKF/dev/matlab/src/vest/rtb/data/meshes)
creating new figure for camera

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             Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

h =

  Axes with properties:

              XLim: [0 1]
              YLim: [0 1]
            XScale: 'linear'
            YScale: 'linear'
     GridLineStyle: '-'
          Position: [0.1300 0.1100 0.7750 0.8150]
             Units: 'normalized'
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  Use GET to show all properties
```

```
make axes

i =

     2

creating new figure for camera

h =

  Axes with properties:

            XLim: [0 1]
            YLim: [0 1]
          XScale: 'linear'
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make axes
creating new figure for camera

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  Axes with properties:

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  Use GET to show all properties

make axes

i =

     3

creating new figure for camera

h =

  Axes with properties:

            XLim: [0 1]
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```

```
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           XScale: 'linear'
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    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

h =

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make axes

i =

     4

creating new figure for camera

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```

```
make axes
creating new figure for camera

h =

  Axes with properties:

             XLim: [0 1]
             YLim: [0 1]
           XScale: 'linear'
           YScale: 'linear'
    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
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make axes
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i =

     5

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make axes

i =

     6

creating new figure for camera

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    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

h =

  Axes with properties:
```

```
            XLim: [0 1]
            YLim: [0 1]
          XScale: 'linear'
          YScale: 'linear'
   GridLineStyle: '-'
        Position: [0.1300 0.1100 0.7750 0.8150]
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  Use GET to show all properties

make axes

i =

     7

creating new figure for camera

h =

  Axes with properties:

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make axes

i =

     8
```

```
creating new figure for camera

h =

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     9

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make axes

i =

    10

creating new figure for camera

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         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

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  Axes with properties:

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make axes

i =

    11

creating new figure for camera
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             YLim: [0 1]
           XScale: 'linear'
           YScale: 'linear'
    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

  Use GET to show all properties
```

```
make axes
creating new figure for camera

h =

  Axes with properties:

             XLim: [0 1]
             YLim: [0 1]
           XScale: 'linear'
           YScale: 'linear'
    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
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make axes

i =

    12

creating new figure for camera

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make axes

i =

    13

creating new figure for camera

h =

  Axes with properties:

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            Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

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  Axes with properties:

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           XScale: 'linear'
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  Use GET to show all properties

make axes

i =

    14

creating new figure for camera

h =

  Axes with properties:
```

```
             XLim: [0 1]
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```
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  Use GET to show all properties

make axes

i =

    15

creating new figure for camera

h =

  Axes with properties:

              XLim: [0 1]
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            XScale: 'linear'
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           XScale: 'linear'
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         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

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make axes

i =

    16

creating new figure for camera

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make axes
creating new figure for camera

h =

  Axes with properties:

             XLim: [0 1]
```

```
             YLim: [0 1]
           XScale: 'linear'
           YScale: 'linear'
    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

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            Units: 'normalized'

  Use GET to show all properties

make axes

i =

    17

creating new figure for camera

h =

  Axes with properties:

              XLim: [0 1]
              YLim: [0 1]
```

```
           XScale: 'linear'
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```

```
  Use GET to show all properties

make axes

i =

    18

creating new figure for camera

h =

  Axes with properties:

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            YLim: [0 1]
          XScale: 'linear'
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    GridLineStyle: '-'
         Position: [0.1300 0.1100 0.7750 0.8150]
            Units: 'normalized'

  Use GET to show all properties

make axes
creating new figure for camera

h =

  Axes with properties:

             XLim: [0 1]
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  Use GET to show all properties

make axes

i =

    19

creating new figure for camera

h =

  Axes with properties:

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  Use GET to show all properties

make axes

i =

    20

creating new figure for camera

h =

  Axes with properties:

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          XScale: 'linear'
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```

```
make axes

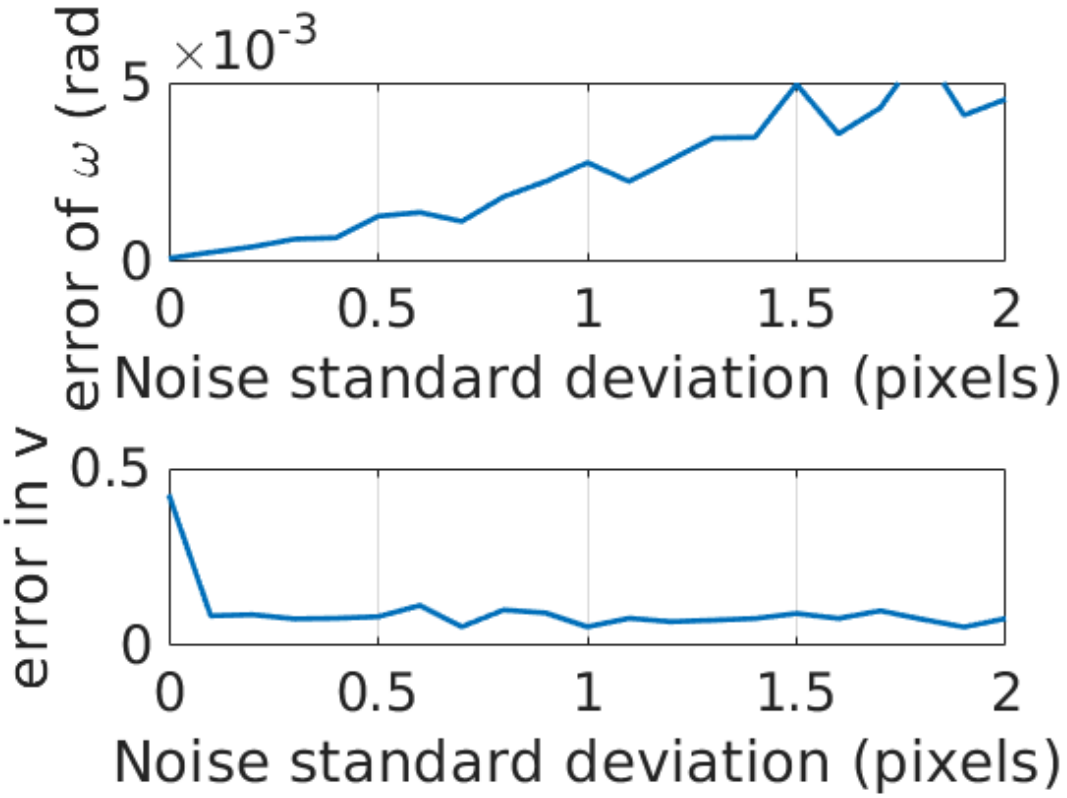
i =

    21
```

plot error data

```
figure(1)
subplot(2,1,1)
plot(noise_list, w_error_list,'linewidth',2);
xlabel('Noise standard deviation (pixels)');
ylabel('error of \omega (rad/s)');
set(gca,'fontsize',20)
ylim([0,0.005])
%title('angular estimation error with pixel noise', 'FontSize', 14);
grid on

subplot(2,1,2)
plot(noise_list, v_error_list,'linewidth',2);
xlabel('Noise standard deviation (pixels)');
ylabel('error in v');
set(gca,'fontsize',20)
ylim([0,0.5])
% title('linear estimation error with pixel noise', 'FontSize', 14);
grid on
```



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