

Summary

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September 19, 2021
Seminar on Continual Learning
Robotic Vision Lab

Unified Probabilistic Deep Continual Learning
through Generative Replay and Open Set Recognition

This would be the first line. Please read [1].

References

- [1] R. Mur-Artal, J. M. M. Montiel, and J. D. Tardos, “Orb-slam: a versatile and accurate monocular slam system,” *IEEE transactions on robotics*, vol. 31, no. 5, pp. 1147–1163, 2015.