Value-at-Risk

Second Edition - by Glyn A. Holton



2.2.4 Functions

Notation to indicate that a function *f* maps elements of a set *A* to elements of a set *B* is:

$$f: A \to B$$
 [2.4]

A is the function's domain; B contains its range. We are primarily interested in three types of functions:

- functions from R to R,
- functions from \mathbb{R}^n to \mathbb{R} ,
- functions from \mathbb{R}^n to \mathbb{R}^m .

We call functions of the first form real—they map real numbers to real numbers. The natural logarithm function is a real function, which we denote log. We do not employ the logarithm base 10. If a function f has an inverse, we denote this f^{-1} . The derivative of a real function f may be indicated with differential notation or simply as f'. We indicate the value of a function f at a particular point a as either f(a) or $f|_a$. The former is read as "f of a". The latter is read as "f evaluated at a".

Consider $f: \mathbb{R}^p \to \mathbb{R}^m$ and $g: \mathbb{R}^n \to \mathbb{R}^p$. The **composition** of f and g is the function $f \circ g$ from \mathbb{R}^n to \mathbb{R}^m defined as

$$f \circ g(x) = f(g(x)) \tag{2.5}$$

The **gradient** ∇f and **Hessian** $\nabla^2 f$ of a function $f: \mathbb{R}^n \to \mathbb{R}$ are the vector of its first partial derivatives and matrix of its second partial derivatives:

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix} \text{ and } \nabla^2 f = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{pmatrix}$$
 [2.6]

The Hessian is symmetric if the second partials are continuous.

The **Jacobian** *Jf* of a function $f: \mathbb{R}^n \to \mathbb{R}^m$ is the matrix of its first partial derivatives.

$$Jf = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & & \frac{\partial f_2}{\partial x_n} \\ \vdots & & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$
[2.7]

Note that the Hessian of a function $f: \mathbb{R}^n \to \mathbb{R}$ is the Jacobian of its gradient.











