

Machine Learning

Semi-Supervised Learning



- Semi-supervised learning refers to learning from data where part contains desired output information and the other part does not
 - Mostly applied to supervised learning problems (classification/regression) with partially labeled data
 - Sometimes partially labeled data is also used to solve unsupervised learning problems (semiunsupervised learning)
 - Labeled data provides constraints
- Generally unlabeled data is easier to find and more abundant than labeled data



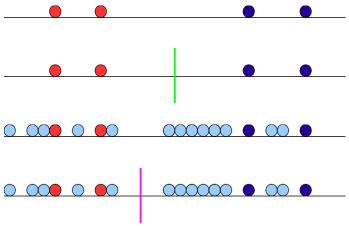
- The goal of most semi-supervised learning is to learn a better classifier/regression function than from only the labeled data
 - Training data can be divided into two sets

$$D_{s} = \{ (x^{(i)}, y^{(i)}) : i \in [1..n_{s}] \}, D_{u} = \{ (x^{(i)}) : i \in [n_{s} + 1..n] \}$$
$$D = D_{s} \cup D_{u}$$

- Learn $h_D(x)$ that has a higher expected performance on test data than $h_{Ds}(x)$
- Sometimes only labeling of the unlabeled data is required – transductive learning



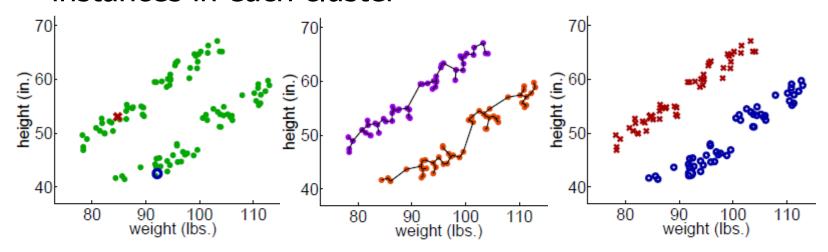
- The main benefit of unsupervised data in semisupervised learning is by providing information about the structure of the overall data
 - Assumption: labeled and unlabeled data come from the same distribution





Cluster and Label

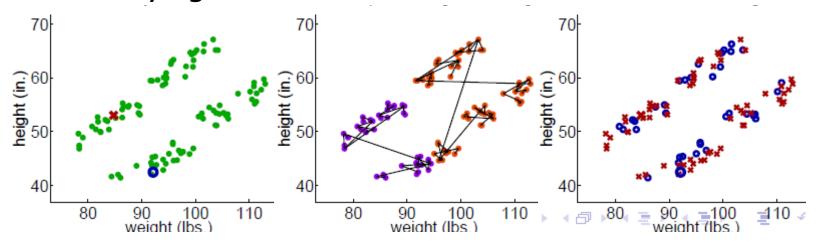
- Cluster and Label is the simplest form of semisupervised learning
 - First apply clustering to all data
 - Then apply supervised learning on the labeled instances in each cluster





Cluster and Label

 But: works only if the cluster structure matches the underlying class structure



- We can also use unsupervised feature learning to derive new features for supervised learning
 - Requires that feature criteria match class structure

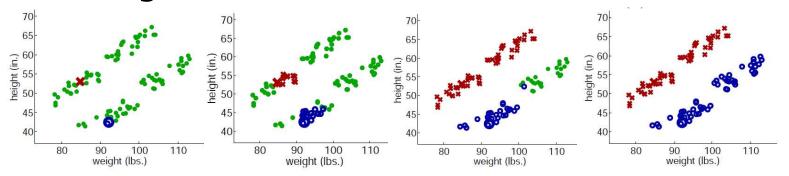


Self-Training

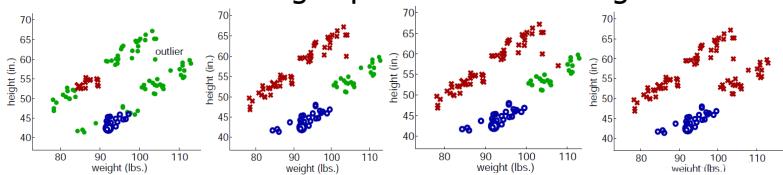
- Self-training can be applied to any supervised learning algorithm that has a measure for confidence of a label assignment
 - E.g.: MLE, MAP, or maximum margin approaches
- Basic idea is to incrementally augment labeled set with self-labeled instances
 - Apply supervised learner to the labeled data
 - Apply learned hypothesis to the unlabeled data
 - Move k highest confidence samples to labeled set
 - Repeat until all data is labeled



Self-training basically generates its own training data



But: self-training is prone to reinforcing mistakes





Co-Training

- Self-training is a simple algorithm that often works well
 - Can produce worse results even on labeled data than training only on the labeled data
- Co-training follows a similar idea but tries to reduce the self-reinforcement problem
 - Requires two views of the same data
 - Each data point exists in two representations $x^{(i)} = \begin{bmatrix} x_{(1)}^{(i)}, x_{(2)}^{(i)} \end{bmatrix}$

 Each view contains all the data but in a different representation (ideally conditionally independent)



Co-Training

- Operation of co-training is similar to selftraining
 - In each view, run supervised learner on labeled data
 - In each view, label unlabeled data using hpothesis
 - In each view, identify k most confident unlabeled instances, remove them from unlabeled set in this view and add them to labeled data set of other view
 - Repeat until all unlabeled data has been labeled
 - Form final classifier/regression function by combining the learned classifiers
 - Averaging or voting are most commonly used



Co-Training and Multi-View

- Co-training has fewer problems with reinforcing errors than self-training
 - Lower probability of picking the same item mistakenly in both views
- Multi-view learning generalizes this concepts of learning multiple classifiers with different views
 - Views are achieved either through different data representations or through the use of different supervised learners
 - Use of assigned labels on unlabeled data requires that multiple classifiers agree



Expectation Maximization

- Another way to limit self-reinforcing errors would be to allow them to be undone later
- Expectation maximization can be used for this with any probabilistic supervised learner

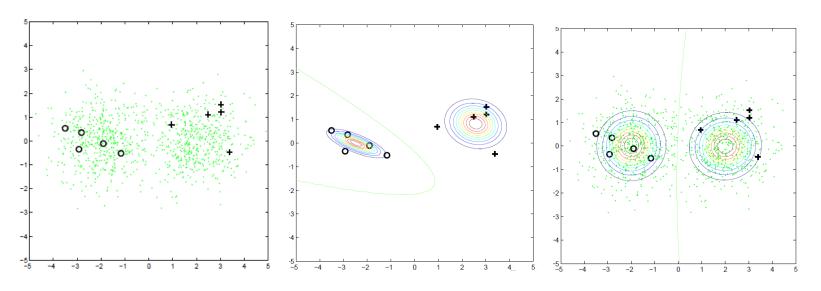
$$\operatorname{argmax}_{\theta} P(D_{s}, D_{u} \mid \theta) = \operatorname{argmax}_{\theta} \sum_{Y_{u}} P(D_{s}, D_{u}, Y_{u} \mid \theta)$$

- Apply supervised learner to labeled data
- Use current hypothesis to compute the expectation (probability) of the label for the unlabeled data
- Re-train the supervised learner using labeled and unlabeled data with assigned expected label
- Repeat from step 2 until convergence



Example: Gaussian Mixture

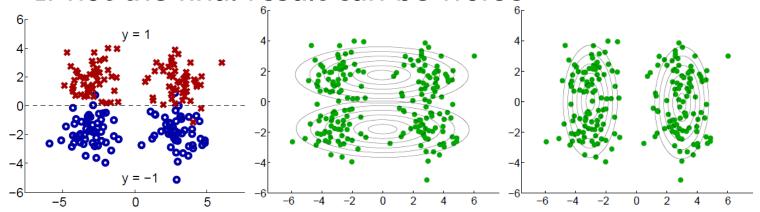
- Hypothesis space for generative classifier is Gaussian in each class
 - Corresponds to Gaussian mixture model clustering if no labeled data is available





Example: Gaussian Mixture

- Requires that the underlying assumption of the hypothesis space (i.e. in this case of the generative model) is approximately correct
 - If not the final result can be worse



- Can use mixture within each class
- Can change weight of unlabeled data in likelihood function



Expectation Maximization

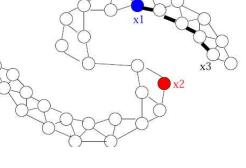
- Expectation maximization will generally work well with probabilistic algorithms if the hypothesis space is appropriate
 - Locally optimizes the marginal data probability starting from the supervised data solution
- A slightly different approach is to look at unsupervised data largely in terms of regularization
 - Unsupervised data is not part of the main performance function but of the regularization term



- Use label smoothness as a regularization term
 - Label smoothness implies that similar data items should have similar labels
- Graph regularization uses a weighted graph
 - Nodes in the graph are all data points
 - Weighted edges connect nodes and convey similarity between two nodes
 - Fully connected graph with weights representing similarity
 - K-nearest neighbor graph to reduce edge number
 - Weighted ε-distance graph (only close nodes connected)
 - Similarity propagates along the graph structure



- Graph regularization uses the data graph structure to define and propagate similarity
 - Similarity in terms of label can be established / propagated using a sequence of similar nodes
 - Items that are not similar in feature space can be close in the graph
 - Label smoothness over the graph propagates based on data items, not based on pure feature similarity







'indirectly' similar with stepping stones



- Graph regularization represents label smoothness over the graph in the form of a regularization term
- Uses the data graph structure to define and propagate similarity
 - Similarity in terms of label can be established / propagated using a sequence of similar nodes



 Graph regularization represents label smoothness over the graph in the form of a regularization term

$$\hat{\theta} = argmin_{\theta} \left(\sum_{(x^{(i)}, y^{(i)}) \in D_{S}} (y^{(i)} - h_{\theta}(x^{(i)}))^{2} + \lambda \sum_{x^{(i)}, x^{(j)} \in D} w_{i,j} (h_{\theta}(x^{(i)}) - h_{\theta}(x^{(j)}))^{2} \right)$$

- Squared error over labeled data with regularization using label smoothness
- Various algorithms can be used to solve this



Semi-Supervised SVMs

 Semi-supervised SVM (S3VM) or Transductive SVM (TSVM) use intrusion of unlabeled data into the margins as regularization

$$\min_{\gamma,w,b} \frac{1}{2} \|w\|^2 + C \left(\sum_{i=1}^{n_s} \xi^{(i)} + \lambda \sum_{i=n_s+1}^{n} \zeta^{(i)} \right)$$
s.t. $y^{(i)} (w^T x^{(i)} + b) \ge 1 - \xi^{(i)}, i = 1, ..., n_s$

$$\left| (w^T x^{(i)} + b) \right| \ge 1 - \zeta^{(i)}, i = n_s + 1, ..., n$$

$$\xi^{(i)}, \zeta^{(i)} \ge 0$$

- Keep unlabeled data outside the margins
 - Avoids discriminant through dense regions
- Optimization harder to solve due to total amount

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- Semi-supervised is aimed at improving learning tasks through the use of a mix of labeled and unlabeled data
 - Takes advantage of unlabeled data often being easier to obtain and much more numerous
- Many techniques exist
 - Learning/training regimens that can be used with existing algorithms
 - E.g. self-learning, EM, multiview-learning
 - Modifications of learning through regularization

E.g. graph regularization, S3SVM

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