



Machine Learning

Unsupervised Learning



Unsupervised Learning

- In supervised learning the training data provides desired target output for learning
- In unsupervised learning the training data does not contain a target value
 - Training data does not specify what to learn
 - Learning algorithm has to specify what to learn
 - Find potential hidden categories
 - Find patterns in the data (data mining)
 - Learn feature representations for the data
 - Performance function has to be defined entirely in terms of the input data



Clustering

- Clustering is the task of dividing the data into a set of groups (clusters)
- Clustering can be thought of as dividing data into hidden/unknown “classes” (clusters)
 - Akin to clustering but without knowledge of any class labels or any definitions of what “classes” are
 - To allow this, the clustering algorithm has to define internally what makes good clusters
 - “Similarity” of instances is the most common criterion



Clustering

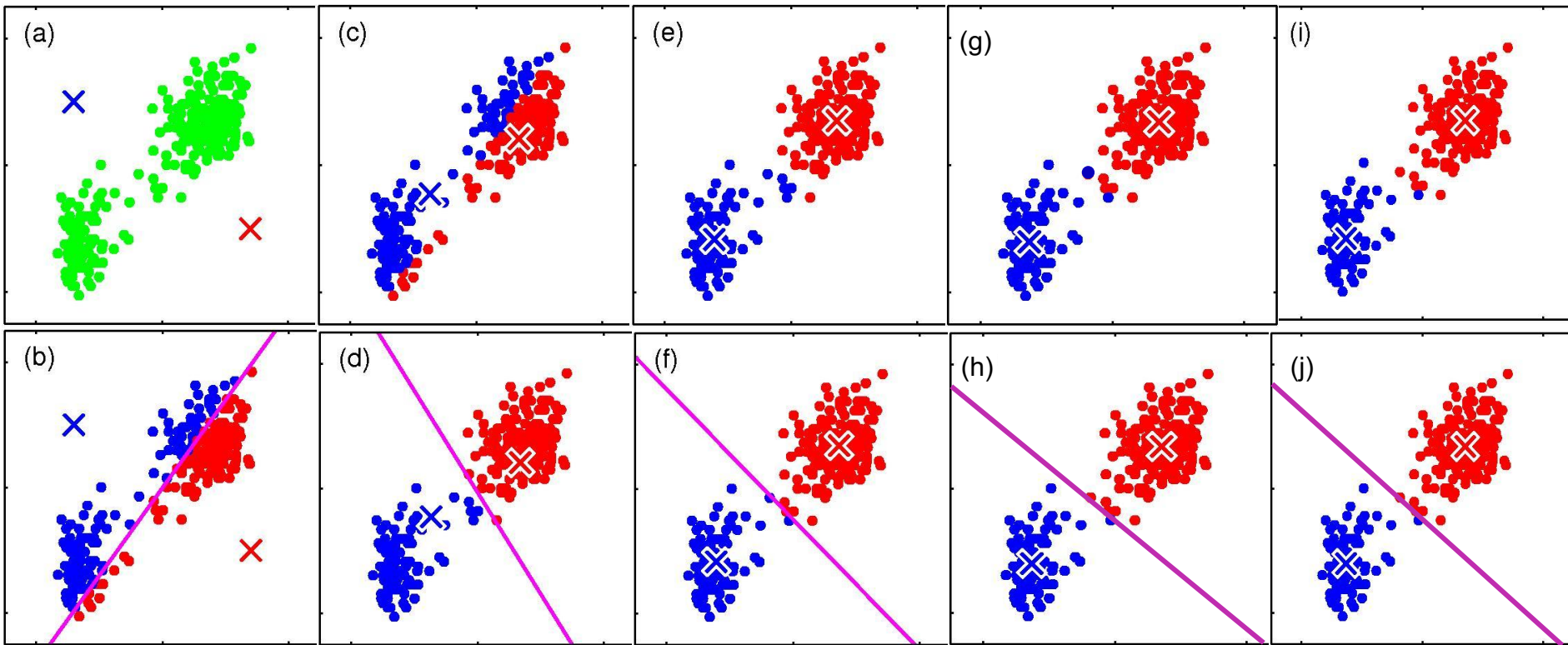
- “Classes” are not given so the number of clusters has to be determined differently
 - Fixed number of clusters set beforehand
 - Maximum “dissimilarity” in a class
 - Ratio of intra-cluster and inter-cluster variance
- Clustering is based on a measure of similarity
 - Euclidian distance of feature vector
 - Graph similarity (traversal stats, modification distance)
 - Dynamic Time Warping (DTW) distance
 - Distribution similarity (KL divergence)



K-Means Clustering

- K-Means clustering is one of the simplest clustering algorithms
 - Randomly place k points in the feature space
 - These are the first cluster centers
 - For each cluster center form a set of data points by assigning each data point to the set with the closest center
 - Euclidian distance in feature space
 - Compute new cluster centers as mean of points in each set and repeat until point sets do not change

K-Means Example





K-Means Clustering

- K-Means clustering requires use of particular representation and performance functions
 - Similarity function has to be Cartesian distance
 - Performance function is average squared distance from cluster mean
 - If these assumptions are violated then the mean of the data set for the cluster might no longer be the right pick for the new cluster center
- K-Means performs iterative local optimization on the average squared (Cartesian) distance



K-Means Clustering

- If the similarity metric is not Cartesian distance the algorithm has to be adapted
 - Mean calculation for new cluster center is no longer valid
 - Often it is not even defined (e.g. for certain types of graphs or metrics such as DTW)
 - Use the central element of the set as a cluster prototype (instead of mean)
 - Maintains the property of optimizing the average Cartesian distance in each cluster
 - But: is no longer K-Means clustering !



K-Means Clustering

- K-Means and related techniques are very simple and frequently used clustering techniques
 - Sensitive to the starting point
 - High complexity due to the iterative optimization
 - Prone to local extrema
 - Requires to pre-determine number of clusters
 - Can repeat it with different cluster numbers and see whether the performance increases significantly



Hierarchical Clustering

- Hierarchical clustering forms a hierarchy of clusters (i.e. different number of clusters at each level of the hierarchy).
 - Divisive clustering starts with a single cluster and divides clusters recursively according to a metric
 - Generally exponential complexity to find best cluster split
 - Agglomerative clustering starts with one cluster per data point and recursively merges clusters according to a cluster similarity measure
 - Complexity varies based on similarity metric used



Agglomerative Clustering

- Agglomerative clustering incrementally merges clusters based on cluster similarity
 - Start with one cluster for each data point
 - Find the two most “similar” clusters and merge them and repeat until either only one cluster is left or until the clusters become too dissimilar
- Need to define which two clusters are most similar to each other
 - Similarity of two data sets (not data points)
 - Often called linkage



Linkage Criteria

- Agglomerative clustering can use different linkage (cluster similarity) measures
 - Average (mean) linkage: average similarity between any two items from the two clusters
 - Single (minimum) linkage: similarity of the two most similar items in the two clusters
 - Complete (maximum) linkage: similarity of the two most dissimilar items in the two clusters
- Linkage influences complexity and clusters

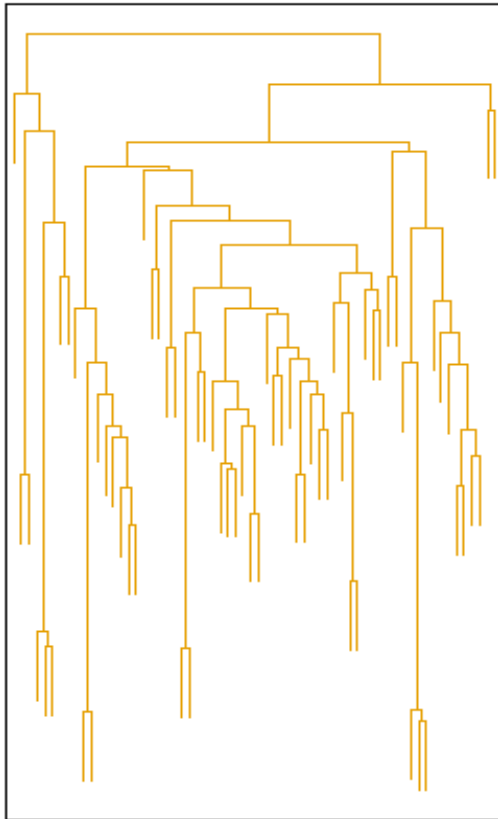


Linkage Criteria

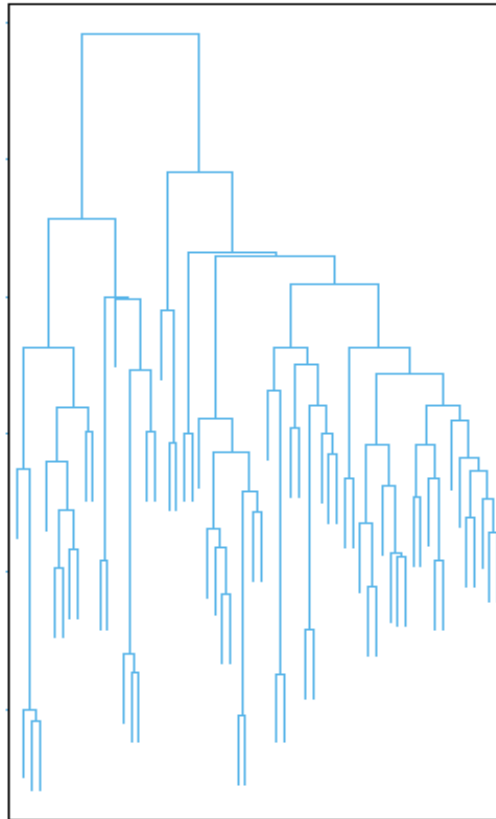
- Average linkage forms most “uniform” clusters
 - Average linkage requires recomputation of the linkage after every merge using $O(n^2)$ time
 - Clustering is $O(n^3)$
- Complete linkage forms most “compact” clusters
 - Complete linkage recomputation uses MAX ($O(n)$)
 - Clustering is $O(n^2)$
- Single linkage forms most “connected” clusters
 - Single linkage recomputation uses MIN ($O(n)$)
 - Clustering is $O(n^2)$

Example

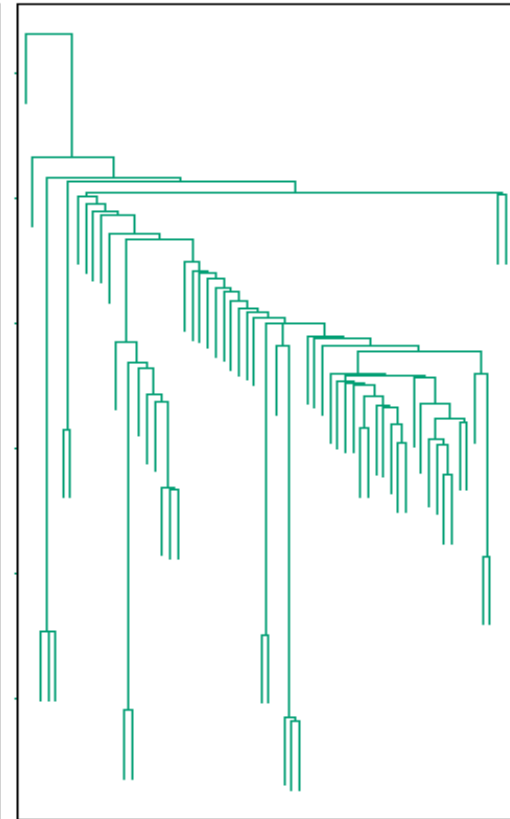
Average



Farthest



Nearest



Hastie



Hierarchical Clustering

- Hierarchical clustering (agglomerative or divisive) form a hierarchy of clusters
 - Need to decide which clusters to use
 - Change to intra-cluster variances
 - Maximum linkage for merging
 - Ratio of inter-cluster and intra-cluster variances
- Hierarchical clustering has a fixed maximum run time that depends on size of data set
 - Agglomerative linkage criteria influence run time
 - Complexity of computing linkage is higher for average
 - Average number of merge operations is different



Probabilistic (Soft) Clustering

- So far a data point had to belong to one cluster
 - For fixed cluster sizes this can result in cluster boundaries that go through dense data
 - Does not look like clusters
 - This makes clusters sensitive in noisy situations
 - Does not allow overlapping clusters
- Probabilistic (Soft) clustering removes this assumption by using the probability that a point belongs to a cluster, $P(z/x^{(i)})$



Probabilistic Clustering

- Like in Bayesian (probabilistic) classification, probabilistic clustering takes a generative view

$$P(z | x) = \frac{p(x | z)P(z)}{p(x)}$$

- But, cluster labels are not given so they need to be predicted based on a cluster “purity” criterion
 - Clusters should have a particular shape and as cleanly as possible reflect the data
 - Maximize marginal likelihood given a particular type of cluster distribution

$$\hat{\theta} = \arg \max_{\theta} \prod_i p(x^{(i)}) = \arg \max_{\theta} \prod_i \sum_{c_j} p(x^{(i)}, z = c_j)$$



Gaussian Mixture Models

- In Gaussian Mixture Models each cluster is represented by a multivariate Gaussian distribution

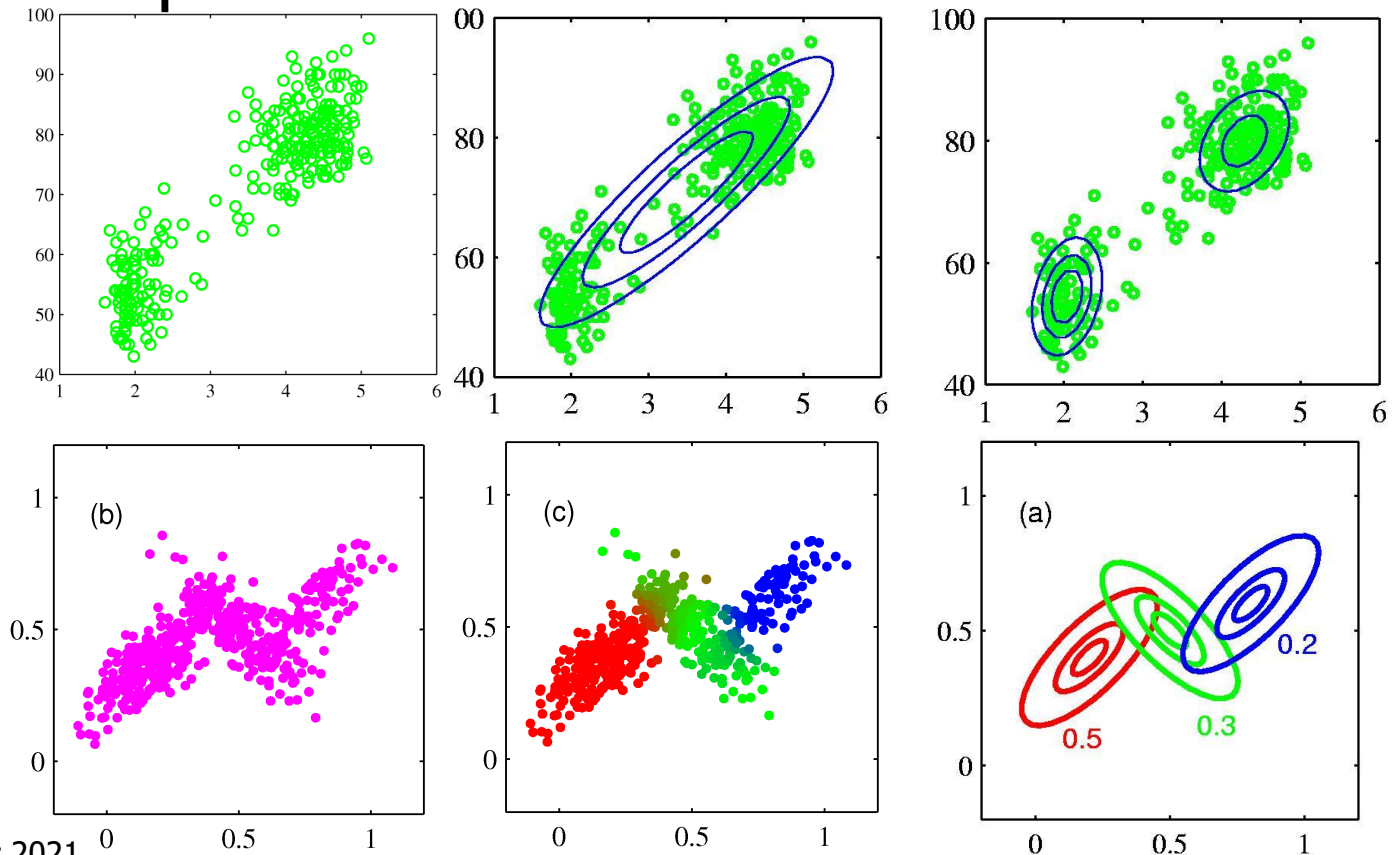
$$p(x | z_i) = \frac{1}{(2\pi)^{\frac{m}{2}} \|\Sigma_i\|^{\frac{1}{2}}} e^{-\frac{1}{2}(x-\mu_i)^T \Sigma_i^{-1} (x-\mu_i)}$$

- Cluster assignments are then done probabilistically

$$P(z | x) = \frac{p(x | z)P(z)}{p(x)}$$

Gaussian Mixture Models

■ Examples





Gaussian Mixture Model

- Learning is performed by maximizing the marginal likelihood

$$\begin{aligned}\hat{\theta} &= \operatorname{argmax}_{\theta} \prod_i p(x^{(i)}) = \operatorname{argmax}_{\theta} \prod_i \sum_{c_j} p(x^{(i)}, z = c_j) \\ &= \operatorname{argmax}_{\theta} \prod_i \sum_{c_j} p(x^{(i)} | z = c_j) P(z = c_j) \\ &= \operatorname{argmax}_{\theta} \prod_i \sum_{c_j} \frac{1}{(2\pi)^{\frac{m}{2}} \|\Sigma_j\|^{\frac{1}{2}}} e^{-\frac{1}{2}(x^{(i)} - \mu_j)^T \Sigma_j^{-1} (x^{(i)} - \mu_j)} P(z = c_j)\end{aligned}$$

- Requires learning Gaussian parameters for $p(x/z)$ as well as prior cluster probabilities $P(z)$
 - Difficult to solve and with many local extrema



Expectation Maximization

- Expectation Maximization (EM) is a general algorithm to maximize marginal likelihood

$$\hat{\theta} = \operatorname{argmax}_{\theta} \prod_i \sum_{c_j} p(x^{(i)}, z = c_j | \theta) = \operatorname{argmax}_{\theta} \sum_i \log \left(\sum_{c_j} p(x^{(i)}, z = c_j | \theta) \right)$$

- Performs optimization by iterating two steps
 - Expectation step: computes the expectations for the hidden/missing variables given the current parameters
 - Maximization step: optimizes the parameters with a weighted estimate (optimizing lower bound)
- Similar to coordinate ascent
 - In the GMM case it is similar to the way K-Means does its optimization



Expectation Maximization

- Expectation step:
 - Computer expected distribution for hidden variables

$$P(z_j | x^{(i)}, \theta_t) = \alpha p(x^{(i)} | z_j, \theta_t) P(z_j | \theta_t)$$

- Maximization step:
 - Recompute the optimal parameters for the expected log likelihood (a lower bound on the likelihood)

$$\begin{aligned}\theta_{t+1} &= \operatorname{argmax}_{\theta} \sum_i \sum_j P(z_j | x^{(i)}, \theta_t) \log p(z_j, x^{(i)} | \theta) \\ &= \operatorname{argmax}_{\theta} \sum_i E_z [\log p(z_j, x^{(i)} | \theta)]\end{aligned}$$

Optimise lower bound (bo



Expectation Maximization

- Expectation maximization effectively conducts coordinate ascent on the lower bound of the log likelihood
 - Still maximizes the original likelihood
 - Expectation step tightens the bound
 - Ensures that bound eventually has same extremum as function
 - Significantly simpler than original optimization
 - Often both steps are analytically solvable
 - Guaranteed convergence
 - But: Only to local optimum, making start point important



EM for GMM

- Applying EM to GMM:
 - Expectation step computes the expected cluster values for the data points
 - Maximization step re-computes the means and variances of the Gaussian distributions for each cluster as well as the cluster priors

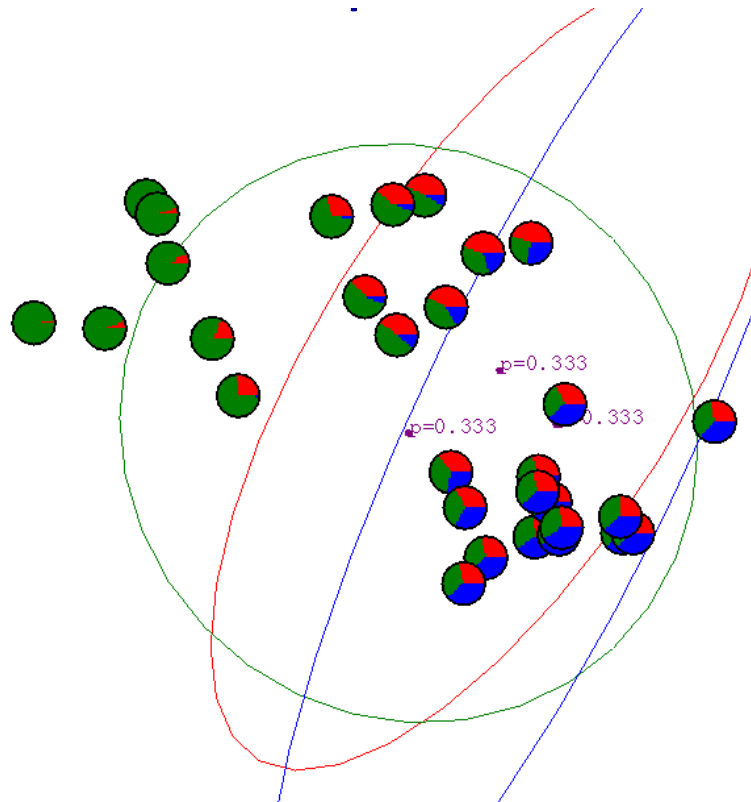
$$P(z_j | x^{(i)}, \theta_t) = \alpha p(x^{(i)} | z_j, \theta_t) \tilde{P}(z_j | \theta_t)$$

$$\tilde{P}(z_j | \theta_{t+1}) = \frac{\sum_i P(z_j | x^{(i)}, \theta_t)}{n}, \quad \mu_j(t+1) = \frac{\sum_i P(z_j | x^{(i)}, \theta_t) x^{(i)}}{\sum_i P(z_j | x^{(i)}, \theta_t)}$$

$$\Sigma_j(t+1) = \frac{\sum_i P(z_j | x^{(i)}, \theta_t) (x^{(i)} - \mu_j(t+1)) (x^{(i)} - \mu_j(t+1))^T}{\sum_i P(z_j | x^{(i)}, \theta_t)}$$

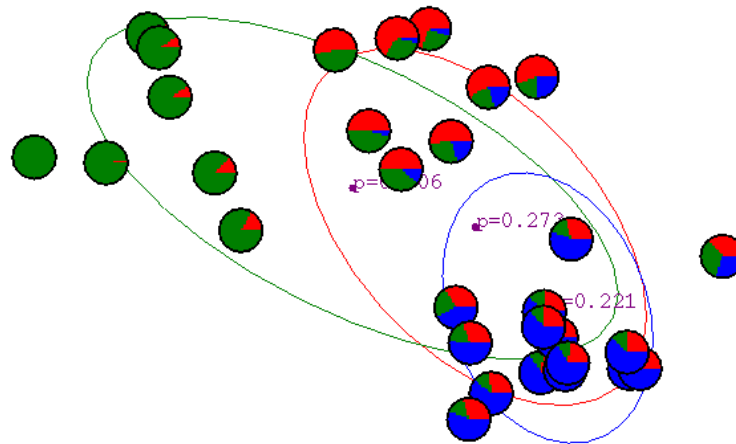
GMM Example

- Start with 3 clusters



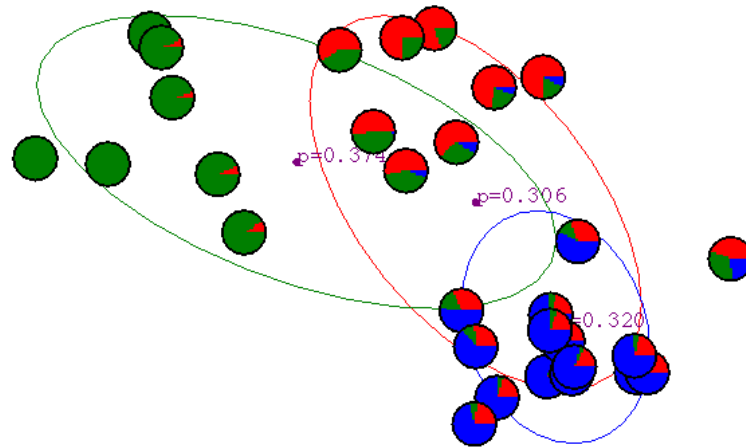
GMM Example

- First Iteration



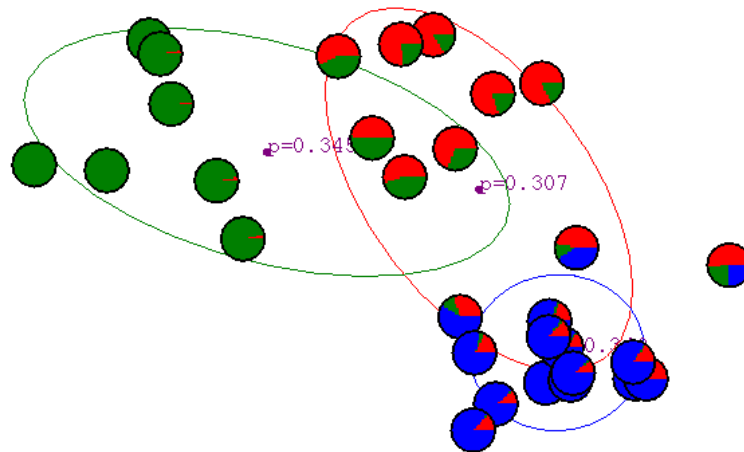
GMM Example

- Second Iteration



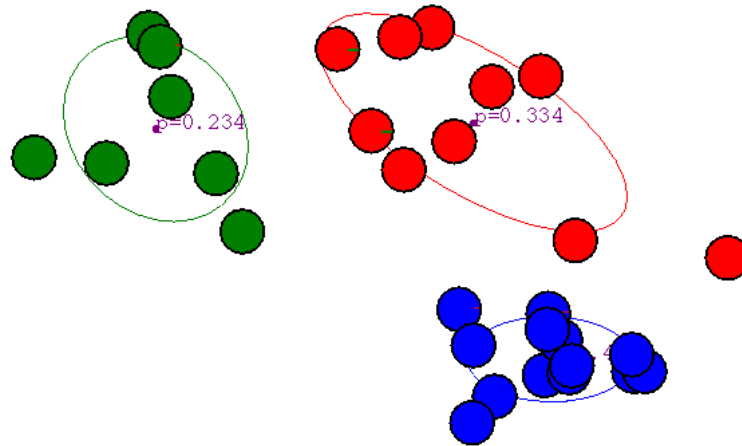
GMM Example

- Third Iteration



GMM Example

- 20th Iteration





Clustering

- There are a wide range of other clustering methods
 - Clustering methods for other similarity metrics
 - E.g.: Spectral clustering – graph similarity measure
 - Clustering using neural networks
 - E.g.: Self-organizing maps for topological clustering
 - Clustering using sampling methods
 - E.g.: Ant colony optimization-based clustering



Clustering

- Clustering is an unsupervised learning problem aimed at dividing data into groups
 - Like classification but without known classes
 - What makes good clusters has to be designed into the algorithm in the form of a similarity measure
- Deterministic clustering assigns each data point to exactly one cluster
 - K-Means clustering uses a fixed number of clusters
 - Hierarchical clustering builds hierarchy of clusters



Clustering

- Clustering can be used for a number of purposes
 - Identify different “types” within the data
 - “Type” can be used as a feature for subsequent tasks
 - In probabilistic clustering the probability vector over “types” can be used as a continuous feature vector
 - Identify different “causes” for the data
 - Can be used to identify whether the data generation process was uniform
 - Approximately compress the data set