



REMOTE OPERATION OF ROBOTS

In this article you will find a comprehensive guide for remote operation of robots

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NOTE: All files are available for download at the bottom of this page.

Examples are valid for:

CB3 Software version: from 3.4 forward

e-Series Software versions: All versions

Note that newer software versions may behave differently.

The goal of this guide is to give users the tools to operate the robot without need for manual manipulation on the TeachPendant. Different interfaces will be covered to display the remote capabilities of the robot.

Note: this guide only covers PC-based interfacing. In addition, several snippets of code will be included as reference to some of the sections below. This is **sample code** and not meant to be a full interface. It is the responsibility of the user to develop proper GUIs/CLIs, integration tests, and error-handling based on the needs of their application.

