

EE 5323 - HW04

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HW04 – Vector Fields, Flows, First Integrals

EE 5323 – Nonlinear Systems

Dr. Lewis

Exercise 1

First Integral of Motion for Undamped Oscillator

$$\ddot{x} + x = 0$$

- (a) Write position-velocity state space form $\dot{X} = f(X)$.
- (b) Plot the trajectories $x(t), \dot{x}(t)$ vs. time. Use initial conditions of $x(0) = 0.1, \dot{x}(t) = 0$.
- (c) Plot the vector field $f(X)$ in the phase plane $(x_1, x_2) = (x, \dot{x})$. Plot for points spaced in a uniform mesh in the box $x_1 = [-10, 10], x_2 = [-10, 10]$.
- (d) Plot the system trajectories (flows or orbits) in the phase plane. Take ICs spaced in a uniform mesh in the box $x_1 = [-10, 10], x_2 = [-10, 10]$.
- (e) Derive the First Integral of Motion $F(x_1, x_2)$ as done in class. Plot the FIM as a 3-D surface over the phase plane on the $x_1 = [-10, 10], x_2 = [-10, 10]$.

Answer

- a) Write position-velocity state space form $\dot{X} = f(X)$.

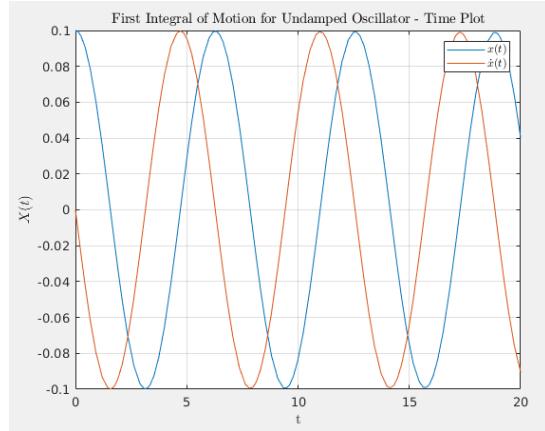
$$\ddot{x} + x = 0 \Rightarrow \ddot{x} = -x \Rightarrow$$

$$X = \begin{bmatrix} x \\ \dot{x} \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}; \quad \dot{X} = \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix} = f(x)$$

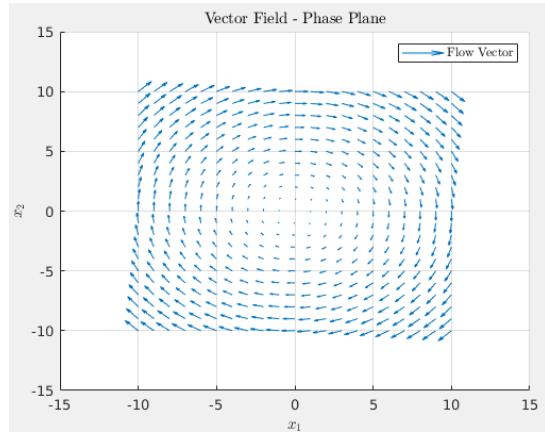
State space form:

$$\dot{X} = AX \Rightarrow \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

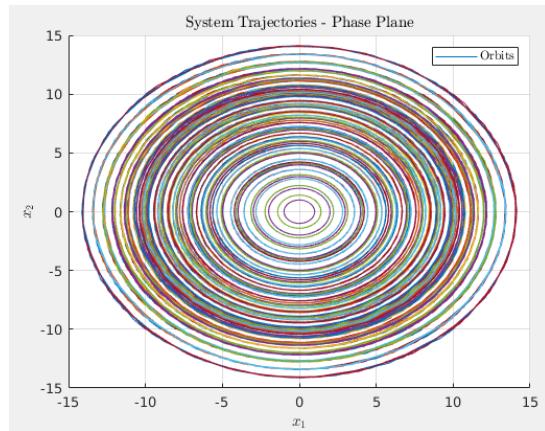
b) Plot the trajectories $x(t)$, $\dot{x}(t)$ vs. time. Use initial conditions of $x(0) = 0.1$, $\dot{x}(t) = 0$.



c) Plot the vector field $f(X)$ in the phase plane $(x_1, x_2) = (x, \dot{x})$. Plot for points spaced in a uniform mesh in the box $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.



d) Plot the system trajectories (flows or orbits) in the phase plane. Take ICs spaced in a uniform mesh in the box $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.



e) Derive the First Integral of Motion $F(x_1, x_2)$ as done in class. Plot the FIM as a 3-D surface over the phase plane on the $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.

$$\ddot{x} + x = 0 \implies \ddot{x}\dot{x} + x\dot{x} = 0 ;$$

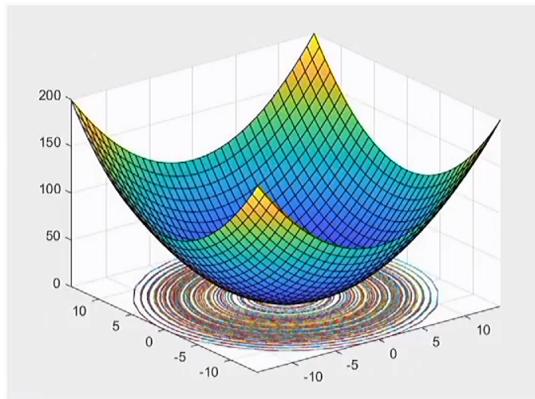
Where

$$\frac{d}{dt} \left(\frac{1}{2} \dot{x}^2 + \frac{1}{2} x^2 \right) = 0 \implies F(x) = \frac{1}{2} x_2^2 + \frac{1}{2} x_1^2 ;$$

$$\dot{F}(x) = \frac{\partial F}{\partial x} \dot{x} ; \quad \frac{\partial F}{\partial x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix} ; \quad \dot{x} = \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix}$$

Hence, we have FIM as

$$\dot{F}(x) = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix} = 0$$



Matlab Code

```
1 %% HW04 - Q01 - Vector Fields , Flows , First Integrals
2 % @author: Bardia Mojra
3 % @date: 10/14/2021
4 % @title HW03 - Q01 - First Integral of Motion for Undamped
5 % Oscillator
6 % @class ee5323 - Nonlinear Systems
7 % @professor - Dr. Frank Lewis
8
9 clc
10 clear
11 close all
12 warning('off','all')
13 warning
14
15 % part b
16 t_intv= [0 20];
17 x_0= [0.1, 0]'; % initial conditions for x(t)
18 figure
19 [t,x]= ode23('q01_sys', t_intv, x_0);
20 plot(t,x)
21 hold on;
22 grid on;
23 title('First Integral of Motion for Undamped Oscillator - Time
24 Plot','Interpreter','latex');
25 ylabel('$X(t)$','Interpreter','latex');
26 xlabel('t','Interpreter','latex');
27 legend('$x(t)$', '$\dot{x}(t)$','Interpreter','latex');
28
29 % part c
30 figure
31 hold on;
32 grid on;
33 [x1,x2] = meshgrid(-10:1:10, -10:1:10);
34 dx1=[];
35 dx2=[];
36 N=length(x1);
37 for i=1:N
38     for j=1:N
39         dx = q01_sys(0, [x1(i,j);x2(i,j)]);
40         dx1(i,j) = dx(1);
41         dx2(i,j) = dx(2);
42     end
43 end
44 quiver(x1,x2,dx1,dx2);
45 ylabel('$x_2$','Interpreter','latex');
46 xlabel('$x_1$','Interpreter','latex');
```

```

45 legend('Flow Vector','Interpreter','latex');
46 title('Vector Field - Phase Plane','Interpreter','latex');
47
48 % part d
49 figure
50 hold on
51 for i = -10:1:10
52     for j = -10:1:10
53         init =[i j];
54         [t, x] = ode23('q01_sys', [0 10], init);
55         figure(3)
56         plot(x(:,1),x(:,2))
57         hold on;
58     end
59 end
60 ylabel('$x_2$', 'Interpreter', 'latex');
61 xlabel('$x_1$', 'Interpreter', 'latex');
62 legend('Orbits', 'Interpreter', 'latex');
63 title('System Trajectories - Phase Plane', 'Interpreter', 'latex');
64 grid on;
65
66 % part e
67 figure
68 hold on
69 for i = -10:1:10
70     for j = -10:1:10
71         init =[i j];
72         [t, x] = ode23('q01_sys', [0 10], init);
73         N=length(x);
74         figure(4)
75         hold on;
76         plot3(x(:,1), x(:,2), zeros(N,1))
77         hold on;
78         syms x1 x2
79         fsurf(0.5*x1^2 + 0.5*x2^2)
80         hold on;
81     end
82 end
83 ylabel('$x_2$', 'Interpreter', 'latex');
84 xlabel('$x_1$', 'Interpreter', 'latex');
85 xlabel('$V$', 'Interpreter', 'latex');
86 legend('Potential', 'Interpreter', 'latex');
87 title('First Integral of Motion - Phase Plane', 'Interpreter', 'latex');
88 grid on;
89
90 %%%

```

```
91 %  
92 % function xdot = q01_sys(t,x)  
93 %     xdot = [x(2); -x(1)];  
94 % end  
95 %
```

Exercise 2

First Integral of Motion for Undamped Oscillator

$$\ddot{x} + x = 0$$

- (a) Write position-velocity state space form $\dot{X} = f(X)$.
- (b) Plot the trajectories $x(t), \dot{x}(t)$ vs. time. Use initial conditions of $x(0) = 0.1, \dot{x}(t) = 0$.
- (c) Plot the vector field $f(X)$ in the phase plane $(x_1, x_2) = (x, \dot{x})$. Plot for points spaced in a uniform mesh in the box $x_1 = [-10, 10], x_2 = [-10, 10]$.
- (d) Plot the system trajectories (flows or orbits) in the phase plane. Take ICs spaced in a uniform mesh in the box $x_1 = [-10, 10], x_2 = [-10, 10]$.
- (e) Derive the First Integral of Motion $F(x_1, x_2)$ as done in class. Plot the FIM as a 3-D surface over the phase plane on the $x_1 = [-10, 10], x_2 = [-10, 10]$.

Answer

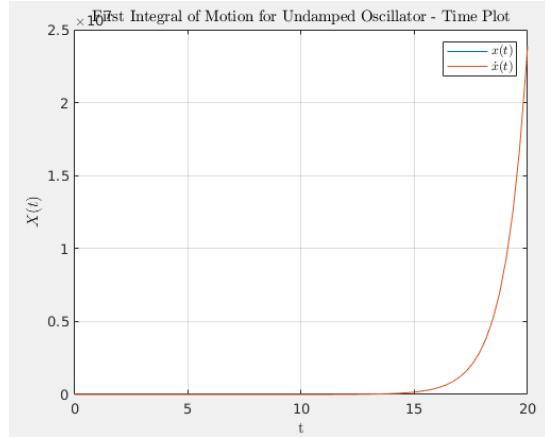
- a) Write position-velocity state space form $\dot{X} = f(X)$.

$$\ddot{x} - x = 0 \Rightarrow \ddot{x} = +x \Rightarrow$$
$$X = \begin{bmatrix} x \\ \dot{x} \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}; \quad \dot{X} = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} = f(x)$$

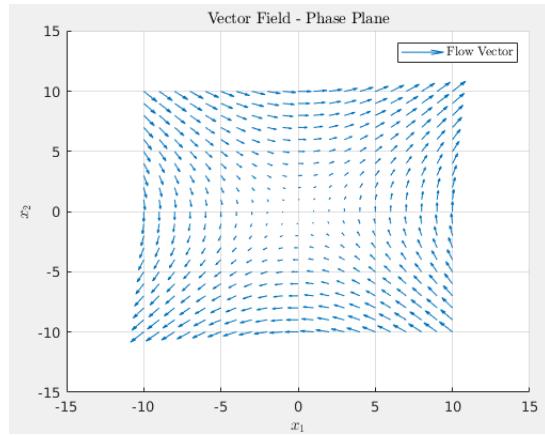
State space form:

$$\dot{X} = AX \Rightarrow \begin{bmatrix} \dot{x} \\ \ddot{x} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix}$$

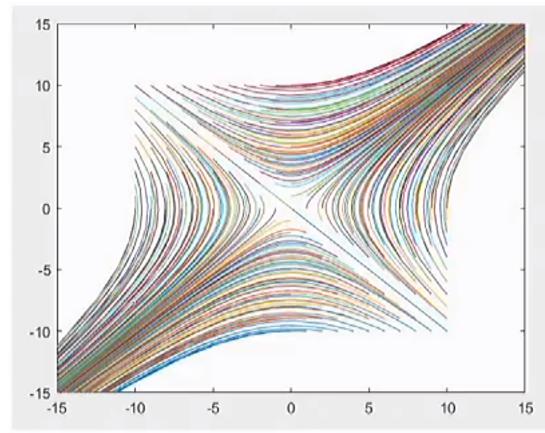
b) Plot the trajectories $x(t)$, $\dot{x}(t)$ vs. time. Use initial conditions of $x(0) = 0.1$, $\dot{x}(t) = 0$.



c) Plot the vector field $f(X)$ in the phase plane $(x_1, x_2) = (x, \dot{x})$. Plot for points spaced in a uniform mesh in the box $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.



d) Plot the system trajectories (flows or orbits) in the phase plane. Take ICs spaced in a uniform mesh in the box $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.



e) Derive the First Integral of Motion $F(x_1, x_2)$ as done in class. Plot the FIM as a 3-D surface over the phase plane on the $x_1 = [-10, 10]$, $x_2 = [-10, 10]$.

$$\ddot{x} + x = 0 \implies \ddot{x}\dot{x} - x\dot{x}^2 = 0 ;$$

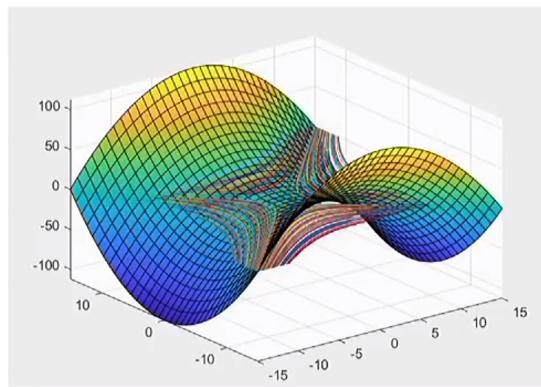
Where

$$\frac{d}{dt} \left(-\frac{1}{2}\dot{x}^2 - \frac{1}{2}x^2 \right) = 0 \implies F(x) = -\frac{1}{2}x_2^2 - \frac{1}{2}x_1^2 ;$$

$$\dot{F}(x) = \frac{\partial F}{\partial x} \dot{x} ; \quad \frac{\partial F}{\partial x} = \begin{bmatrix} -x_1 & x_2 \end{bmatrix} ; \quad \dot{x} = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix}$$

Hence, we have FIM as

$$\dot{F}(x) = \begin{bmatrix} -x_1 & x_2 \end{bmatrix} \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} = 0$$



Matlab Code

```
1 %% HW04 - Q02 - Vector Fields , Flows , First Integrals
2 % @author: Bardia Mojra
3 % @date: 10/14/2021
4 % @title HW03 - Q01 - First Integral of Motion for Undamped
5 % Oscillator
6 % @class ee5323 - Nonlinear Systems
7 % @professor - Dr. Frank Lewis
8
9 clc
10 clear
11 close all
12 warning('off','all')
13 warning
14
15 % part b
16 t_intv= [0 20];
17 x_0= [0.1, 0]'; % initial conditions for x(t)
18 figure
19 [t,x]= ode23('q02_sys', t_intv, x_0);
20 plot(t,x)
21 hold on;
22 grid on;
23 title('First Integral of Motion for Undamped Oscillator - Time
24 Plot','Interpreter','latex');
25 ylabel('$X(t)$','Interpreter','latex');
26 xlabel('t','Interpreter','latex');
27 legend('$x(t)$', '$\dot{x}(t)$','Interpreter','latex');
28
29 % part c
30 figure
31 hold on;
32 grid on;
33 [x1,x2] = meshgrid(-10:1:10, -10:1:10);
34 dx1=[];
35 dx2=[];
36 N=length(x1);
37 for i=1:N
38     for j=1:N
39         dx = q02_sys(0, [x1(i,j);x2(i,j)]);
40         dx1(i,j) = dx(1);
41         dx2(i,j) = dx(2);
42     end
43 end
44 quiver(x1,x2,dx1,dx2);
45 ylabel('$x_2$','Interpreter','latex');
46 xlabel('$x_1$','Interpreter','latex');
```

```

45 legend('Flow Vector','Interpreter','latex');
46 title('Vector Field - Phase Plane','Interpreter','latex');
47
48 % part d
49 figure
50 hold on
51 for i = -10:1:10
52     for j = -10:1:10
53         init =[i j];
54         [t, x] = ode23('q02_sys', [0 10], init);
55         figure(3)
56         plot(x(:,1),x(:,2))
57         hold on;
58     end
59 end
60 ylabel('$x_2$', 'Interpreter', 'latex');
61 xlabel('$x_1$', 'Interpreter', 'latex');
62 legend('Orbits', 'Interpreter', 'latex');
63 title('System Trajectories - Phase Plane', 'Interpreter', 'latex');
64 grid on;
65
66 % part e
67 figure
68 hold on
69 for i = -10:1:10
70     for j = -10:1:10
71         init =[i j];
72         [t, x] = ode23('q02_sys', [0 10], init);
73         N=length(x);
74         figure(4)
75         hold on;
76         plot3(x(:,1), x(:,2), zeros(N,1))
77         hold on;
78         syms x1 x2
79         fsurf(-0.5*x1^2 -0.5*x2^2)
80         hold on;
81     end
82 end
83
84 %%
85 %
86 %
87 % function xdot = q02_sys(t,x)
88 %     xdot = [x(2); x(1)];
89 % end

```