

Progress Report

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1 Research Plan

This section outlines my current research plan where the main ideas, target conference/journal, and expected date of completion for each paper are provided. Target conferences: ICRA, IROS (March), CASE (Late Feb.), NIPS. Target Journals: RAL, CVPR, CORAL.

- Koopman-01 (**IROS - Dec. 1st - active**): Koopman-based MPC control of VTOL-DIP and VTOL-TIP in simulation, DLO pose estimation in simulation, experiments on choice of basis function and lifting dimensions, and performance comparison with optimal, robust, and/or adaptive control schemes.
- Koopman-02 (**ACC - Sep 30th - active**): A review on Koopman-based control schemes. **Not enough, make it part of another paper.** Read papers and write literature reviews.
- Koopman-03 (RAL - Mar. 1st - status): Extension to Koopman-01, Koopman-based dynamic estimation of DLO, collect dynamic DLO dataset, prediction of DLO configuration.
- Quest-01 (**IROS - Mar. 1st - next**): Optimal transform solution for QuEst based on dominant mode decomposition (DMD).
- Quest-02 (IROS/RAL - date - status): QuEst-based EKF, structure from motion, and VSLAM, compare performance with existing methods.
- Koopman-04 (IROS/RAL - date - status): Physics Informed (PI) Koopman-based control of a DLO, show obtained is persistent, compare to other non-PI methods, offline-online learning.
- Koopman-05 (IROS/RAL - date - status): PI Koopman operator (PIKO) based persistent model for DLOs, low dimensional, compare performance, offline-online learning/adapting, fast transfer learning.
- Koopman-06 (IROS/RAL - date - status): PIKO-based unit segment model for DLOs, more generalized, should yield better performance if number segments are selected online in order to obtain optimal representation in real-time given available hardware, compare results.
- Koopman-07 (IROS/RAL - date - status): DLO dataset, PIKO-based reinforcement learning of real DLO dynamics in a digital twin (DT)

setting, experiments of model persistence, compare learning rate with neural network based methods, compare performance with available methods, and experiments on learning limitations.

- Koopman-08 (IROS/RAL - date - status): Koopman-based real-time control of DLO on GPU.
- Koopman-09 (IROS/RAL - date - status): PIKO-based real-time control of DLO on GPU.
- Koopman-10 (IROS/RAL - date - status): PIKO-based real-time control of deformable planar objects (DPO).
- Koopman-11 (IROS/RAL - date - status): PIKO-based real-time control of deformable volume objects (DVO).
- Koopman-12 (IROS/RAL - date - status): PIKO-based unit segment for DPOs, on GPU.
- Koopman-13 (IROS/RAL - date - status): PIKO-based unit segment for DVOs, on GPU.

2 To Do

- QEKF Paper (**On pause**):
 - Noise issue: noise cannot be modeled - DMD is a robust noise on high dimensional orthonormal time series and should be able to denoise QuEst solutions.
 - SfM: RQuEst cannot find solution - A potential solution is described briefly above.
- DLO Manipulation: (**ICRA - section out of date**)
 - Setup digital twin reinforcement learning setup:
 - * Unity Robotics extension setup – done.
 - * Design dynamic DLO data collection system.
 - * Build work cell. – done
 - * Collect data and create a dataset.
 - * Define evaluation metrics.

- * Create a high frequency RGBD dataset with UV-frames and open-loop input control actions as the ground truth.
- Real-Time Preception – on hold
- Learning DLO Dynamics and System Identification - PIKO - Ongoing

3 Progress

The following items are listed in the order of priority:

- DLO Manipulation (**IROS**): This week, I planned on working SimScape multi-body simulation tutorials but I did not work on it. I am very much angry and frankly hurt over Dr. Beksi choosing to humiliate me in front of the lab. It bothers that he provided no valid reason, nor apologized for his conduct. It bothers me because I trusted him and listened to him. It bothers me because I have been working as hard as anybody else in this lab spite everything I am going through. It bothers me because I am doing good research but it is dismissed and humiliated because of a conference deadline. I feel alone, pushed out and depressed. I was wrong to listen to Dr. Beksi and not going on vacations, or going out. Listening to him is making me lose all motivation.
- Maicol (REU): No update, he is busy with classes.
- DoD SMART (**Dec 1st.**): I started the application.
- XEst (**RAL —**): No update.