# **XEst main**

### **Table of Contents**

init	1
run	1
results	1

# init

## run

```
cntr = 0;
for frame_idx = cfg.dat.keyFrames % --->> iter keyframes
  cntr = cntr+1;
  TQVW_sols = quest.get_pose(frame_idx, cfg.dat); % get pose
  TQVW_sols = vest.get_vel(cfg.dat.matches, TQVW_sols); % get velocity
  st_sols = qekf.run_filter(TQVW_sols); % run filter

  dlog.log_state(cntr, frame_idx, TQVW_sols, st_sols);
end % for frame_idx = cfg.dats.keyFrames
```

# results

Tran err mean	0.22021	0.30581	0.15831	0.15692
Tran err std	0.075288	0.11595	0.059177	0.076958
Tran err median	0.20802	0.33699	0.14571	0.15662
Tran err Q_1	0.14782	0.21827	0.1171	0.087069
Tran err Q_3	0.29261	0.39336	0.19953	0.22677
Rot err mean	0.065759	0.033586	0.031964	0.016095
Rot err std	0.082624	0.026133	0.024479	0.014543
Rot err median	0.027054	0.034868	0.034785	0.012323
<i>Rot err Q_1</i>	0.0077886	0.0079305	0.0078698	0.004591
Rot err Q_3	0.12373	0.059242	0.056059	0.027599

#### VEst module:

Here, we compare  $Q\_VEst$  (exp $\_map(W)$ ) for each frame with the  $Q\_est$  of each method for the same frame. TUM

	EightPt	Nister	Kukelova	QuEst
exp(W) err mean	0.053578	0.025994	0.02517	0.016695
exp(W) err std	0.086789	0.032073	0.030718	0.014244
exp(W) err median	0.0040209	0.010582	0.010559	0.014136
exp(W) err Q_1	0.003122	0.003602	0.0035781	0.0039657
exp(W) err Q_3	0.10403	0.048385	0.046761	0.029424

1305031526.739478.png 1305031526.807455.png 1305031526.871446.png 1305031526.939618.png QEKF module: TUM

	EightPt	Nister	Kukelova	QuEst
GT-X T err mean	0.51358	0.53623	0.51647	0.50538
GT-X T err std	0.16785	0.20275	0.17416	0.17257
GT-X T err median	0.55638	0.54854	0.55513	0.49653
GT-X T err Q_1	0.38978	0.37444	0.37619	0.37522
GT-X T err Q_3	0.63738	0.69803	0.65675	0.63554
	EightPt	Nister	Kukelov	ra QuEst
GT-X Q err mean	0.34385	0.3438	5 0.343	885 0.34385
GT-X Q err std	0.0016645	0.001664	5 0.00166	45 0.0016645
GT-X Q err median	0.34341	0.3434	1 0.343	341 0.34341
GT-X Q err Q_1	0.34267	0.3426	7 0.342	0.34267
GT-X Q err Q_3	0.34502	0.3450	2 0.345	0.34502
	EightPt	Nister	Kukelova	QuEst
			<del></del>	<del></del>
GT-X V err mean	0.45678	0.42325	0.41455	0.4581
GT-X V err std	0.18598	0.18689	0.19863	0.18571
GT-X V err median	0.43258	0.36773	0.3618	0.41114

GT-X V err Q_1 GT-X V err Q_3	0.28409 0.62946	0.26409 0.58241		1006 3904		
	EightPt 	Nis	ter	Kuk	elova	QuEst
Z-XH T L1 mean Z-XH T L1 std Z-XH T L1 median Z-XH T L1 Q_1 Z-XH T L1 Q_3	3.8147	3.723 2° 5	3e+05 7.806 .9978	3.03	46e+05 89e+05 22.595 4.0642 93e+05	1.5851e+05 2.7452e+05 20.946 3.0158 3.1702e+05
	EightPt	Nister	Kukelo	ova	QuEst	
Z-XH Q L1 mean Z-XH Q L1 std Z-XH Q L1 median Z-XH Q L1 Q_1 Z-XH Q L1 Q_3		1.5565 0.0441 1.577 1.5255 1.5875	1.55 0.0459 1.57 1.52	903 768 254	1.6483 0.03413 1.6449 1.6177 1.679	
	EightPt 	Nister	Kukel	lova	QuEst	
Z-XH V L1 mean Z-XH V L1 std Z-XH V L1 median Z-XH V L1 Q_1 Z-XH V L1 Q_3	32413 56134 6.8739 0.37614 64827	22897 39650 7.2456 0.27335 45794		390 386 568	19280 33388 4.2012 0.23057 38559	
	EightPt 	Nis	ter	Kuk	elova	QuEst
Z-XH T L2 mean Z-XH T L2 std Z-XH T L2 median Z-XH T L2 Q_1 Z-XH T L2 Q_3	1.5903e+11 2.7546e+11 1448.7 8.5747 3.1807e+11	1.371 8 1 1.584	33.82 3.779 1e+11	9.13 1.05	67e+10 95e+10 542.17 8.478 53e+11	5.1624e+10 8.9415e+10 386.4 4.3143 1.0325e+11
	EightPt ————	Nis	ter ——	Kuk ———	elova ———	QuEst
Z-XH Q L2 mean Z-XH Q L2 std Z-XH Q L2 median Z-XH Q L2 Q_1 Z-XH Q L2 Q_3	1 9.6148e-17 1 1	3.188	1 9e-16 1 1	1.57	1 01e-16 1 1 1	1 2.7195e-16 1 1
	EightPt 	Nis	ter	Kuk	elova	QuEst
Z-XH V L2 mean Z-XH V L2 std Z-XH V L2 median	1.815e+09 3.1437e+09 31.478	1.57	5e+08 4e+09 2.759	1.05	45e+08 04e+09 23.124	5.8897e+08 1.0201e+09 12.279

#### XEst main

Z-XH V L2 Q_1	0.11667	0.058828	0.090598	0.042773
Z-XH V L2 Q_3	3.6301e+09	1.8175e+09	1.2129e+09	1.1779e+09

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