

TEAM: WE LOVE DEADLINES

# Deblurring Image Using SVD

Team Member : Anastasia Gavrish, Artem Chuprov, Bari Khairullin,  
Sudarut Kasemsuk, Waralak Pariwatphan

Skoltech: Numerical Linear Algebra 2022

# TABLE OF CONTENTS

01



Problem  
Statement

02



Methodology

03



Solutions

04

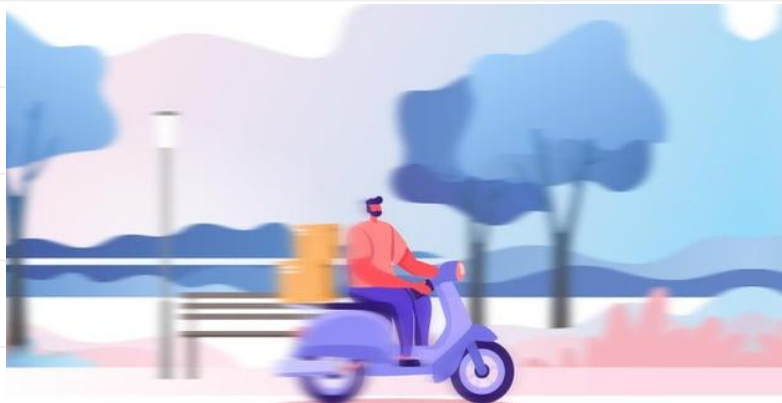


Results

# PROBLEM STATEMENT



# Problem Statement



**Blurred images** can occur when taking a picture with an out-of-focus lens or when snapping pictures a moving object with an **excessively long exposure time**. Blur occurs mathematically when pixel values from the original uncontaminated image are replaced by weighted averages of values from nearby pixels.

# METHODOLOGY



# Blurring Images by Toeplitz matrices

In digital image processing, an image is presented by a 2-D array. We blur the image matrix by **multiplication by Toeplitz Matrix**, since it represents convolution with blurring kernel

$$T = \begin{pmatrix} s_0 & s_1 & \cdots & s_{n-1} \\ s_{-1} & s_0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ s_{-(m-1)} & s_{-(m-2)} & \cdots & s_{-(m-n+1)} \end{pmatrix}$$

At this stage the image is fully restorable since the transformation is non-degenerate.

# Blurring Images by Toeplitz matrices

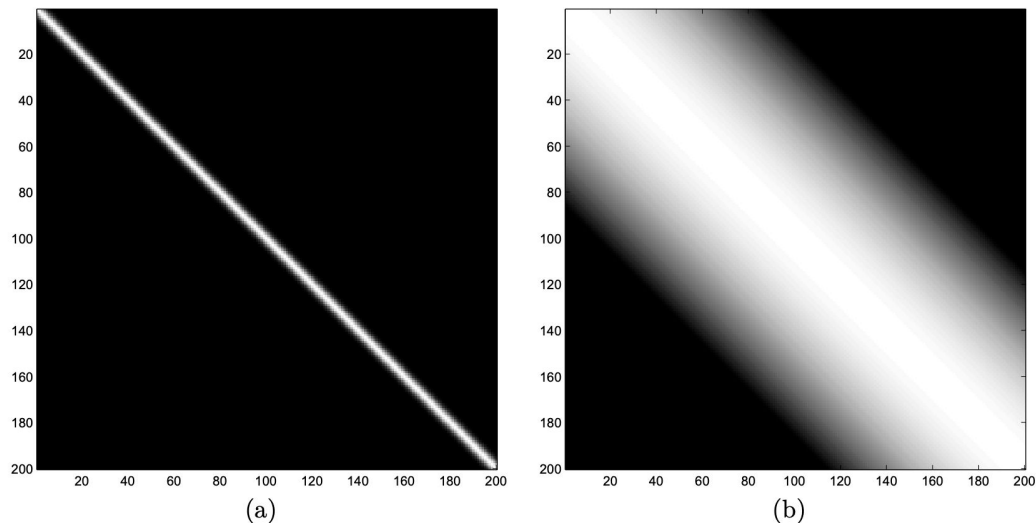


Figure1 : (a) Image of a blurring matrix with the gray-level proportional to the size of the entries, (b) image of the same blurring matrix the gray-level proportional to the logarithm of the size of the entries.

# Two-dimensional signals:

We consider **deblurring of gray-scale images**. Let  $X$  represent an image. Then the blurred image can be represented by

$$Y = T_1 X T_2.$$

Where the symmetric matrix  $T \in \mathbb{R}^{256 \times 256}$  is the blurring operator in the corresponding dimension

Let the available image also contaminated by noise. We represent the noise by the matrix  $E \in \mathbb{R}^{256 \times 256}$  **with normally distributed random entries with zero mean**. The available blur and noise contaminated image is given by

$$Z = T X T + E.$$

Our goal is to find such an algorithm that restores the image if the error is non-zero. Simple inverting of matrices won't work since error can become large.



## Two-dimensional signals:

Let  $T_k$  be the rank- $k$  approximation of  $T$  obtained by setting all but first  $k$  singular values to zero. Consider the approximations

$$X_k = T_k^\dagger Z T_k^\dagger, \quad k = 1, 2, \dots$$

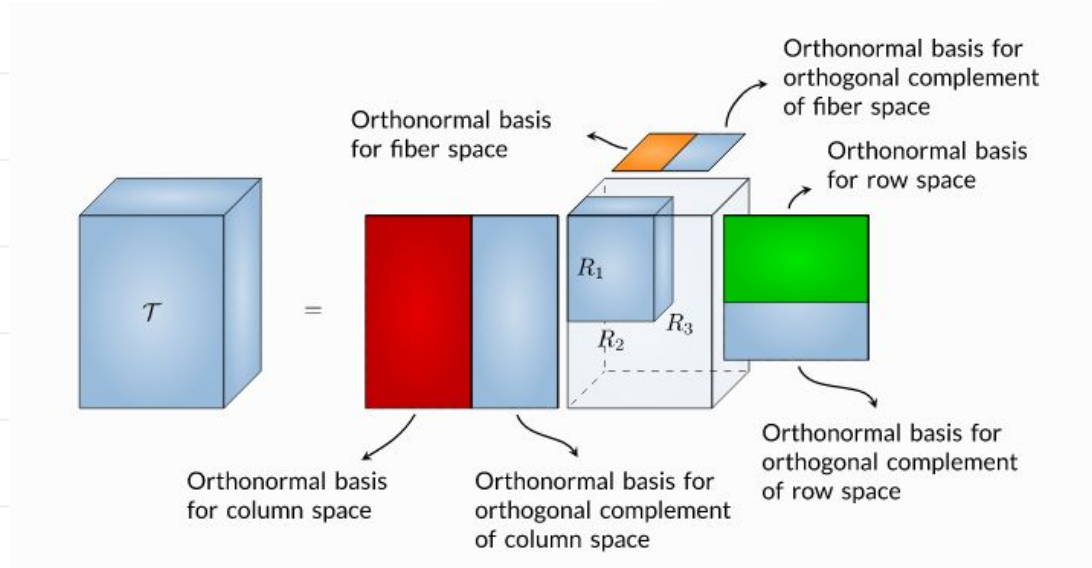
They can be computed fairly easily by computing the SVD of  $T$ .

We remark that color images can be deblurred in the same manner as gray-scale images. For each pixel three “channels” are provided to represent the colors red, green and blue.

# Additional method: MLSVD for color image

## Multilinear singular value decomposition (MLSVD)

The tensor can be represented as the form:  $\mathcal{T} = \mathcal{S} \cdot_1 U^{(1)} \cdot_2 U^{(2)} \cdot_3 U^{(3)}$



# Structure Similarity Index:

The structural similarity index(SSIM) metric extract 3 key features from an image:

- Luminance
- Contrast
- Structure

The **comparison between the two images** is performed on the basis of these 3 features.

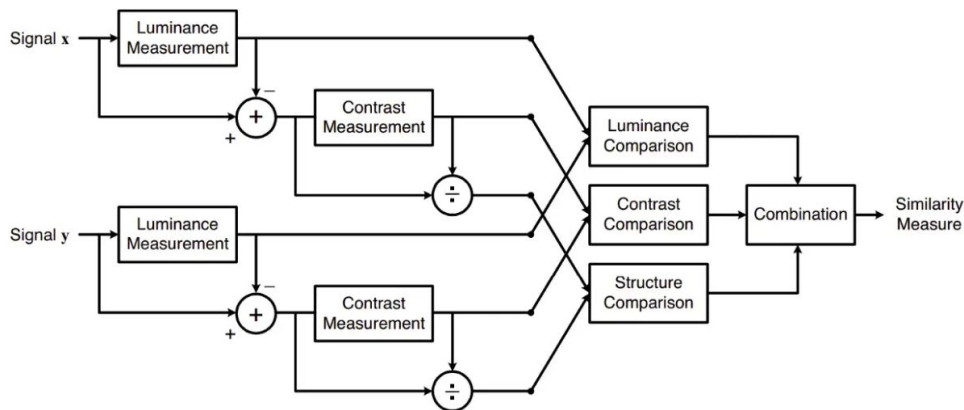


Figure 2 : Shows the arrangement and flow of the structural similarity from an image: Signal Y refer to the reference and sample images.

# RESULTS



# Result with images size 256:

Original

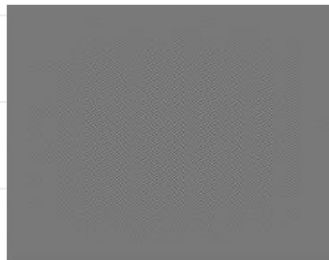
Noisy\_blur

Full rank

Truncate\_svd

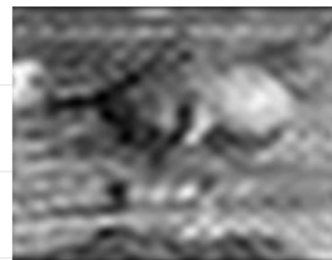
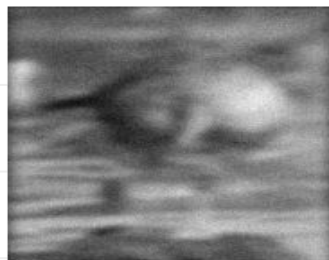
SSIM

Shiba



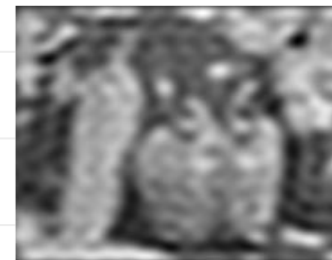
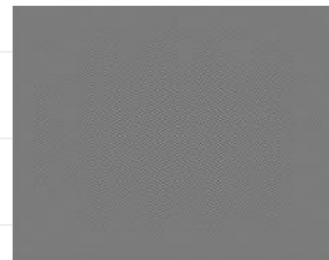
0.2828

Goose












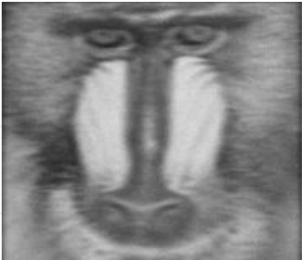


0.3077

Peppers

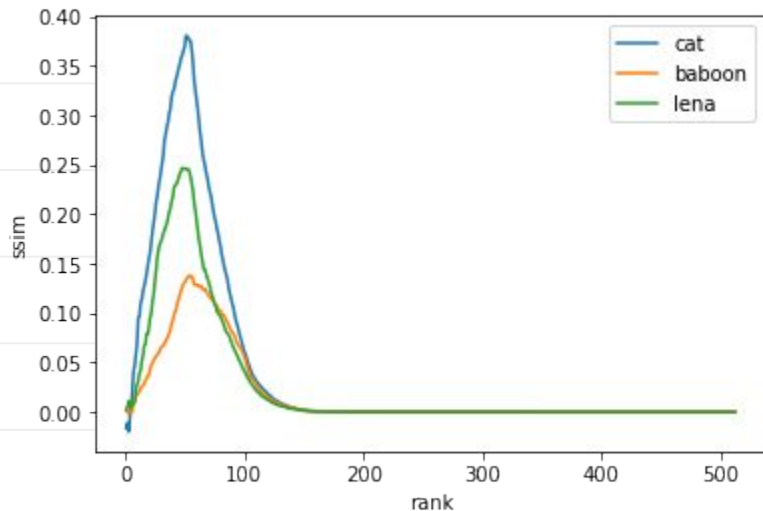


0.3283

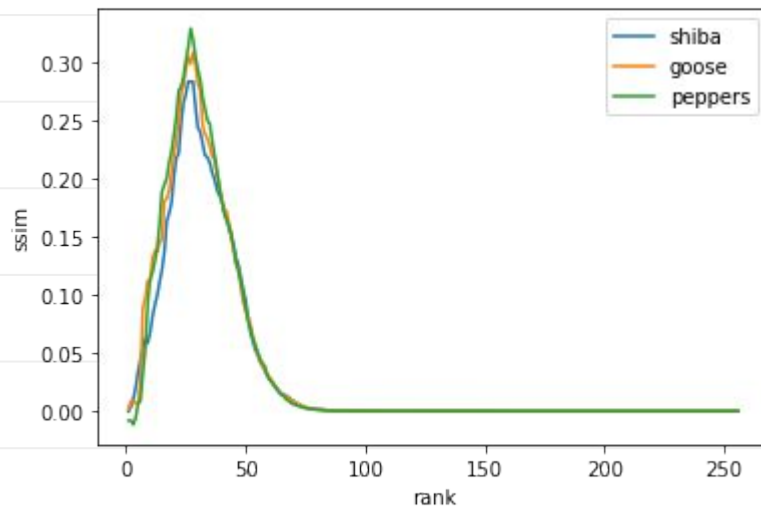
# Result with images size 512:

	Original	Noisy_blur	Full rank	Truncate_svd	SSIM
Cat					0.3804
Lena					0.1380
Baboon					0.2466

# Comparing with SSIM:

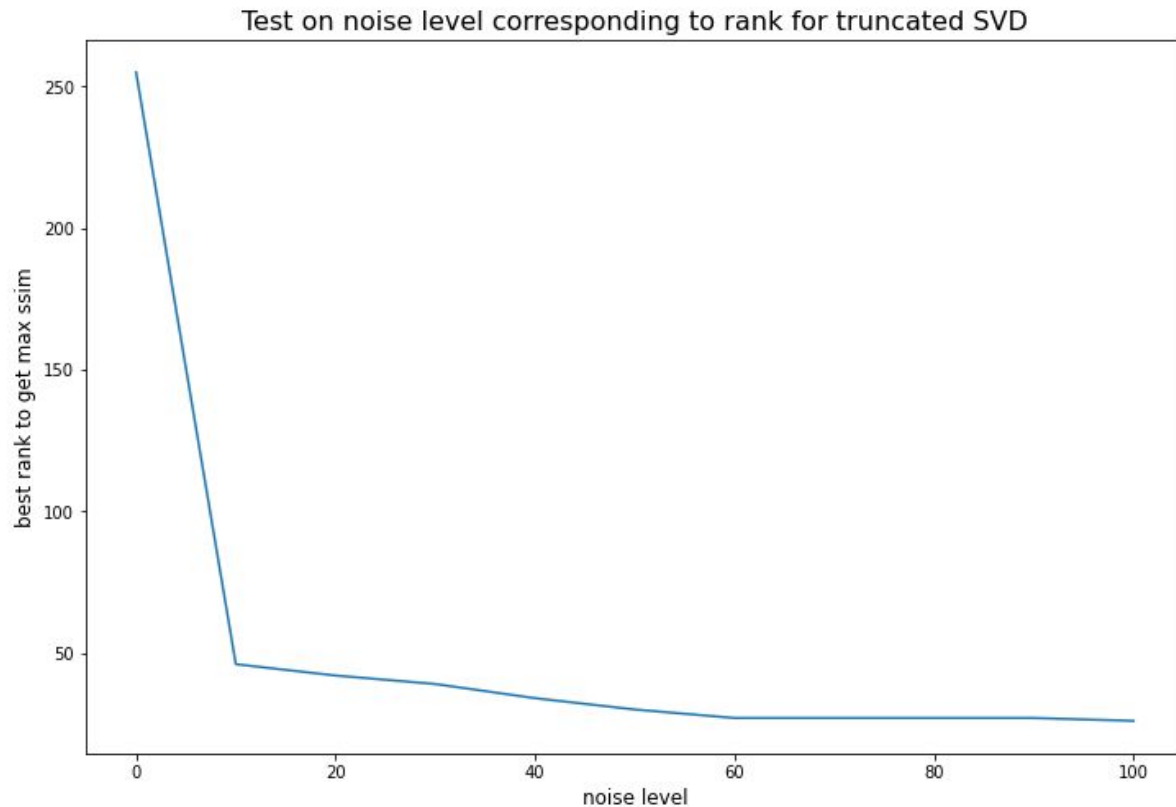


shiba: best ssim = 0.2827895072322408 at truncated rank = 25  
goose: best ssim = 0.307735842568979 at truncated rank = 27  
peppers: best ssim = 0.32831531883154524 at truncated rank = 26



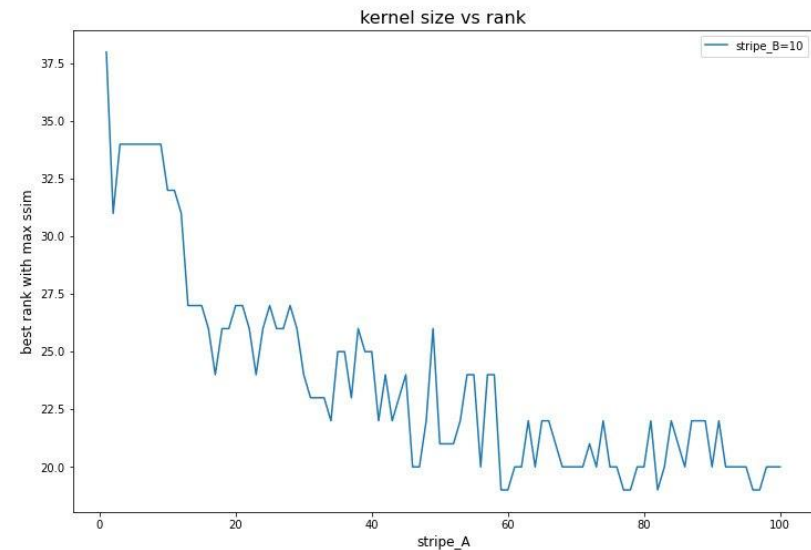
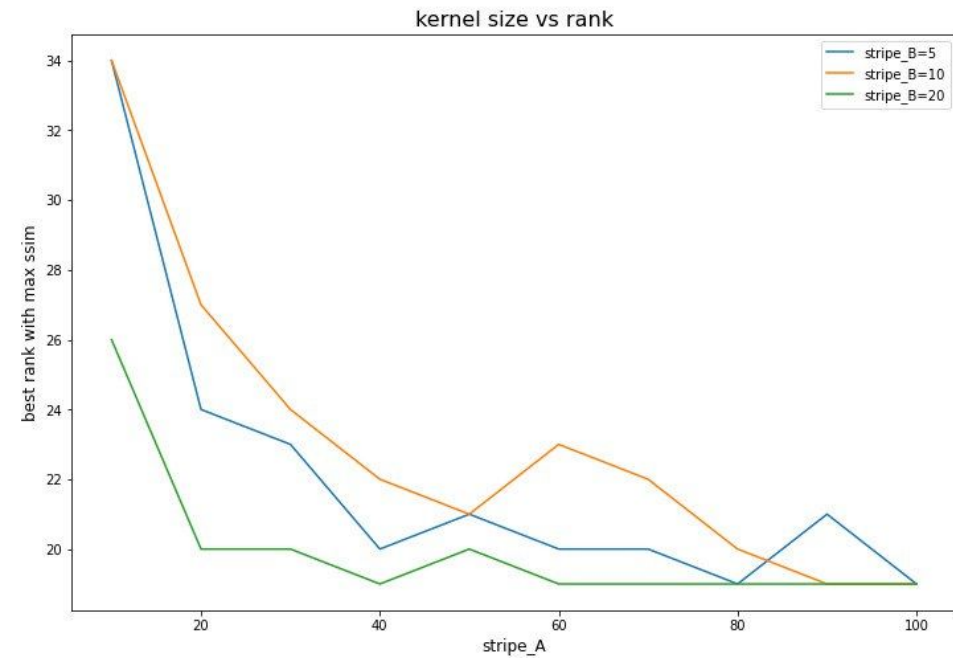
cat: best ssim = 0.38041476769184923 at truncated rank = 50  
baboon: best ssim = 0.1380380031258109 at truncated rank = 53  
lena: best ssim = 0.24656765862833527 at truncated rank = 47

# Corresponding with rank:





# Toeplitz size and restoration rank:



# Result with RGB image:

Original image



Initial blurred image



Noise in blur



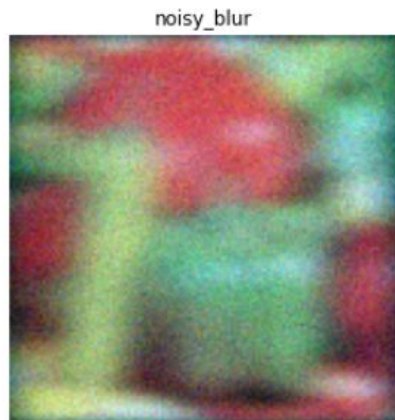
Restoration without rank truncation



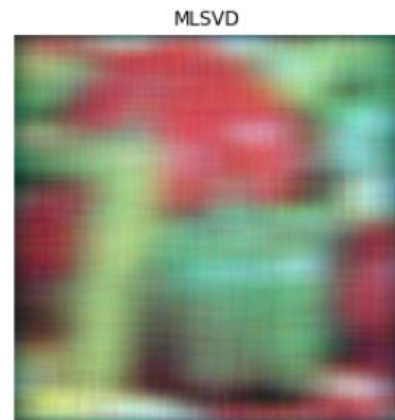
Restoration with rank truncation



# Result with RGB image (additional method):



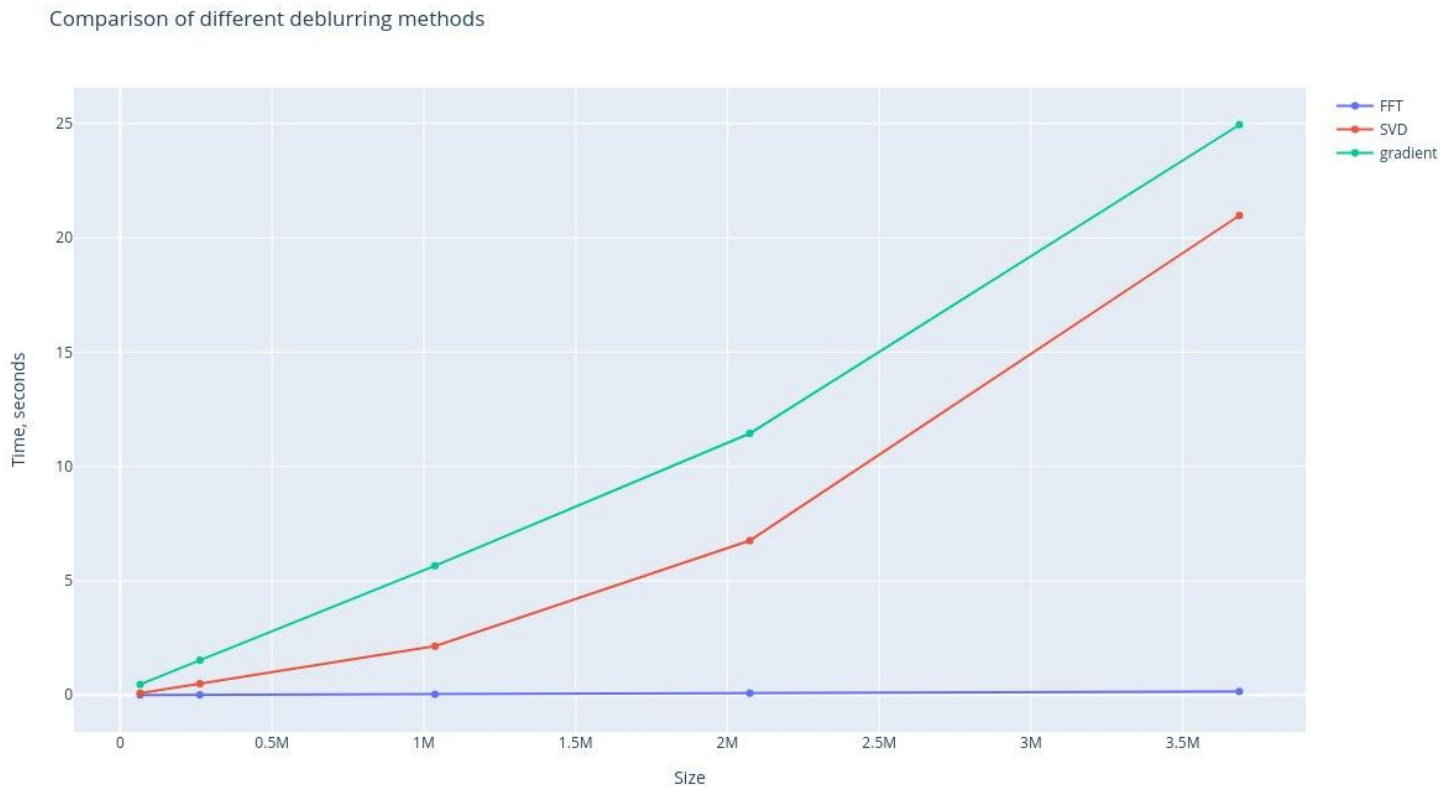
SSIM = 0.2308



SSIM = 0.2241

We apply MLSVD to the blur image and find the best truncated rank and compare the result with our method

# Comparison of algorithms:

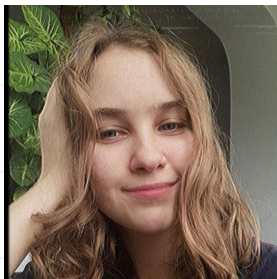


# THANK YOU

Skoltech: Numerical Linear Algebra 2022

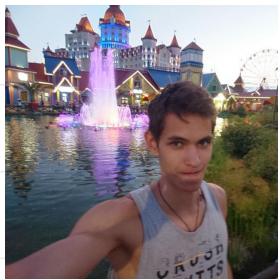
# TEAM CONTRIBUTION!

Anastasia  
Gavrish



- RGB generalization

Artem  
Chuprov



- Efficiency experiments

Bari  
Khairullin



- coordination

Sudarut  
Kasemsuk



- presentation

Waralak  
Pariwatphan



- rank-SSIM experiments