## TEAM: WE LOVE DEADLINES

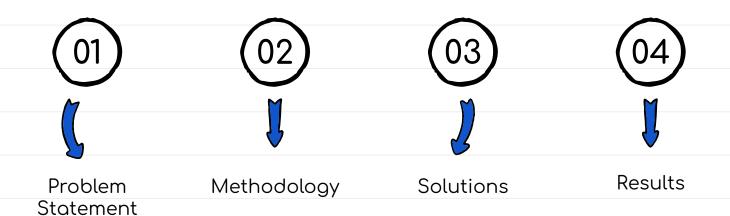
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# Deblurring Image Using SVD

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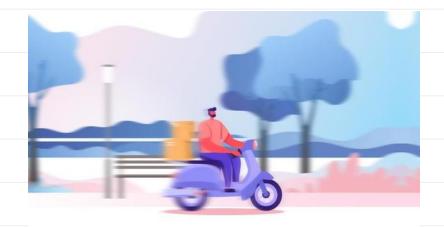
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# PROBLEM STATEMENT

#### **Problem Statement**



Blurred images can occur when taking a picture with an out-of-focus lens or when snapping pictures a moving object with an excessively long exposure time. Blur occurs mathematically when pixel values from the original uncontaminated image are replaced by weighted averages of values from nearby pixels.

# METHODOLOGY

## Blurring Images by Toeplitz matrices

In digital image processing, an image is presented by a 2-D array. We blur the image matrix by multiplication by Toeplitz Matrix, since it represents convolution with blurring kernel

At this stage the image is fully restorable since the transformation is non-degenerate.

## Blurring Images by Toeplitz matrices

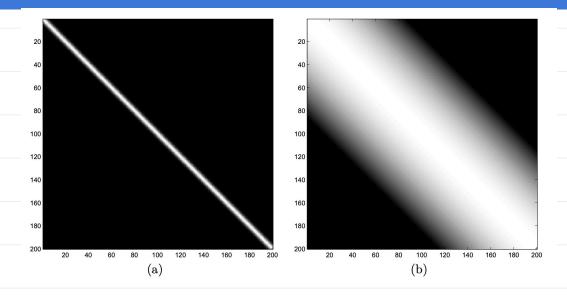


Figure 1: (a) Image of a blurring matrix with the gray-level proportional to the size of the entries, (b) image of the same blurring matrix the gray-level proportional to the logarithm of the size of the size of the entries.

## Two-dimensional signals:

We consider **deblurring of gray-scale images**. Let X represent an image. Then the blurred image can be represented by

$$Y = T_1 X T_2$$
.

Where the symmetric matrix  $T \in \mathbb{R}^{256 \times 256}$  is the blurring operator in the corresponding dimension

Let the available image also contaminated by noise. We represent the noise by the matrix  $E \in \mathbb{R}^{256 \times 256}$  with normally distributed random entries with zero mean. The available blur and noise contaminated image is given by

$$Z = TXT + E$$
.

Our goal is to find such an algorithm that restores the image if the error is non-zero. Simple inverting of matrices won't work since error can become large.

## Two-dimensional signals:

Let  $T_k$  be the rank-k approximation of T obtained by setting all but first k singular values to zero. Consider the approximations

$$X_k = T_k^{\dagger} Z T_k^{\dagger}, \qquad k = 1, 2, \dots$$

They can be computed fairly easily by computing the SVD of T.

We remark that color images can be deblurred in the same manner as gray-scale images. For each pixel three "channels" are provided to represent the colors red, green and blue.

## Structure Similarity Index:

The structural similarity index(SSIM) metric extract 3 key features from an image:

- Luminance
- Contrast
- Structure

The comparison between the two images is performed on the basis of these 3

features.

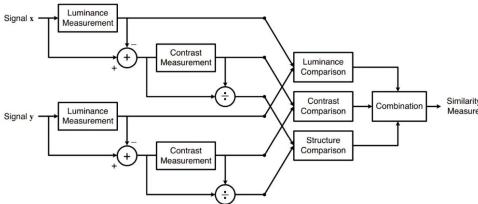


Figure 2 : Shows the arrangement and flow of the structural similarity from an image: Signal Y refer to the reference and sample images.

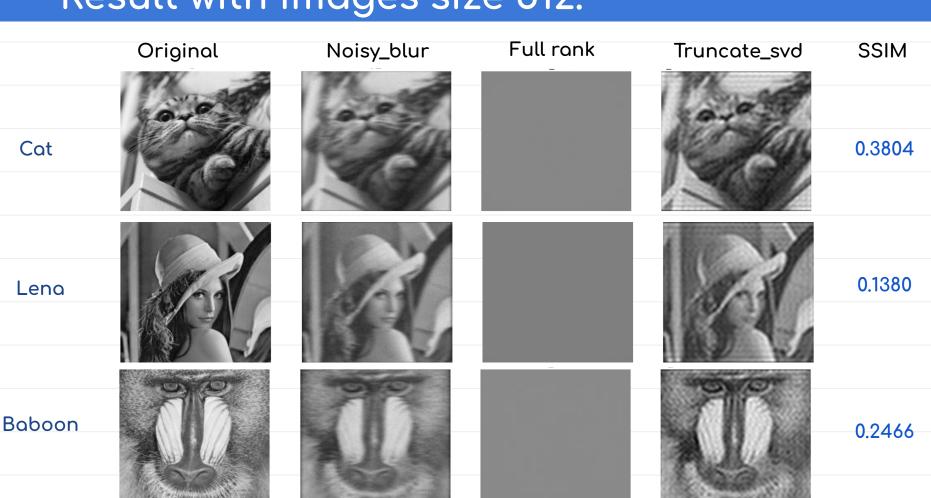
Source: https://www.cns.nyu.edu/pub/eero/wang03-reprint.pdf

# RESULTS

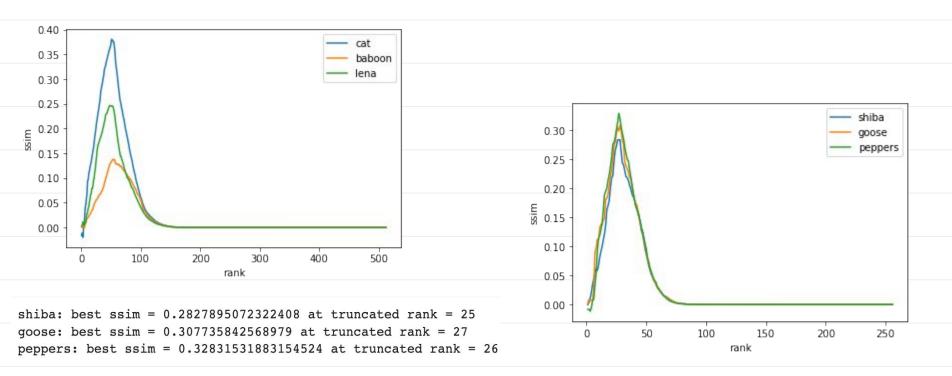
# Result with images size 256:

Result with images size 200.					
	Original	Noisy_blur	Full rank	Truncate_svd	SSIM
Shiba					0.2828
Goose					0.3077
eppers					0.3283

## Result with images size 512:

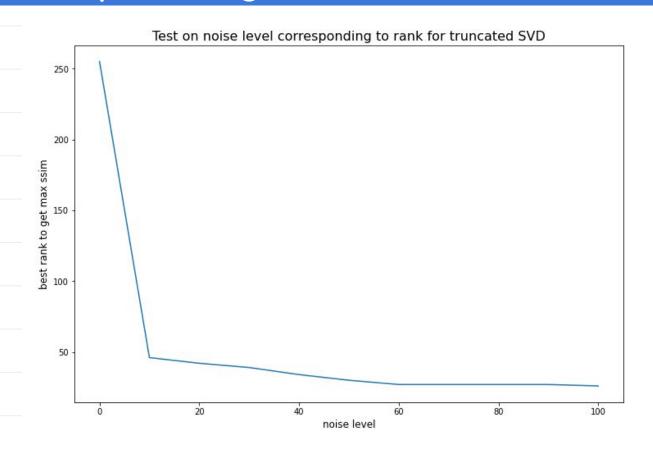


## Comparing with SSIM:

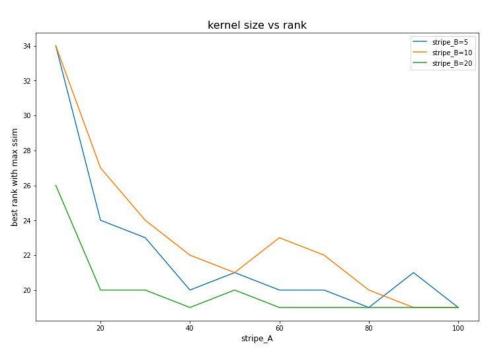


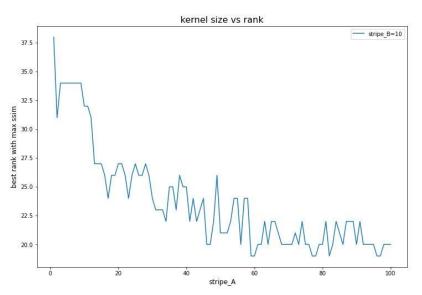
cat: best ssim = 0.38041476769184923 at truncated rank = 50 baboon: best ssim = 0.1380380031258109 at truncated rank = 53 lena: best ssim = 0.24656765862833527 at truncated rank = 47

## Corresponding with rank:



## Toeplitz size and restoration rank:





## Result with RGB image:





Initial blurred image



Noise in blure



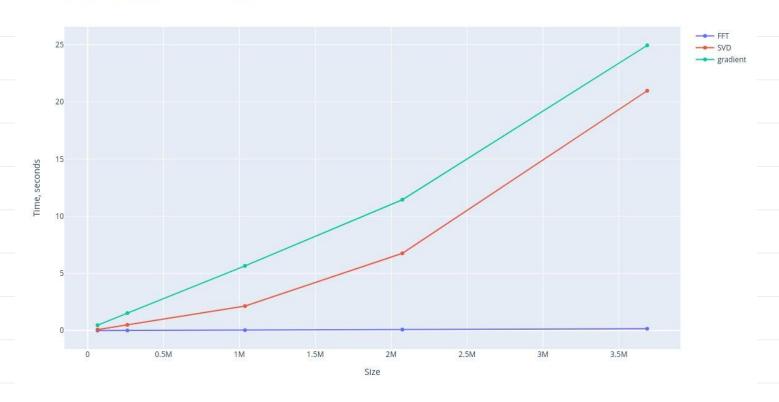


Restoration with rank trancation



## Comparison of algorithms:

Comparison of different deblurring methods



# THANK YOU

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#### **TEAM CONTRIBUTION!**

Anastasia Gavrish



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• RGB generalization

 Efficiency experiments

• coordination

presentation

rank-SSIM experiments