

Kernel Machines

different models \Rightarrow different assumptions
inductive bias \Rightarrow different objective functions

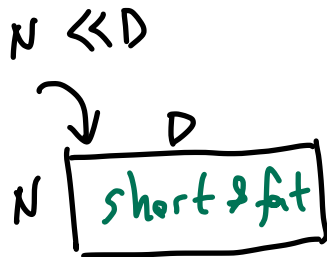
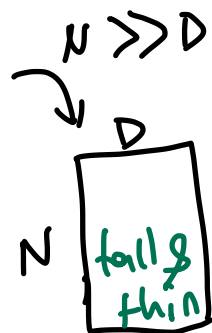
SUPPORT VECTOR MACHINES (SVM)

\hookrightarrow they do not care about probabilities or densities.
 \hookrightarrow weights can be written in terms of training data points.

$$g(x) = \underbrace{w}_{1 \times D}^T \cdot \underbrace{x}_{D \times 1} + \underbrace{w_0}_{1 \times 1}$$

$$\theta = \{w, w_0\}$$

of parameters = $D+1$



$$\begin{aligned} g(x) &= w^T \cdot x + w_0 \\ &= \left[\sum_{i=1}^N \alpha_i \cdot x_i \right]^T \cdot x + w_0 = \sum_{i=1}^N \alpha_i [x_i^T \cdot x] + w_0 \end{aligned}$$

$$\theta = \{\alpha_1, \alpha_2, \dots, \alpha_N, w_0\}$$

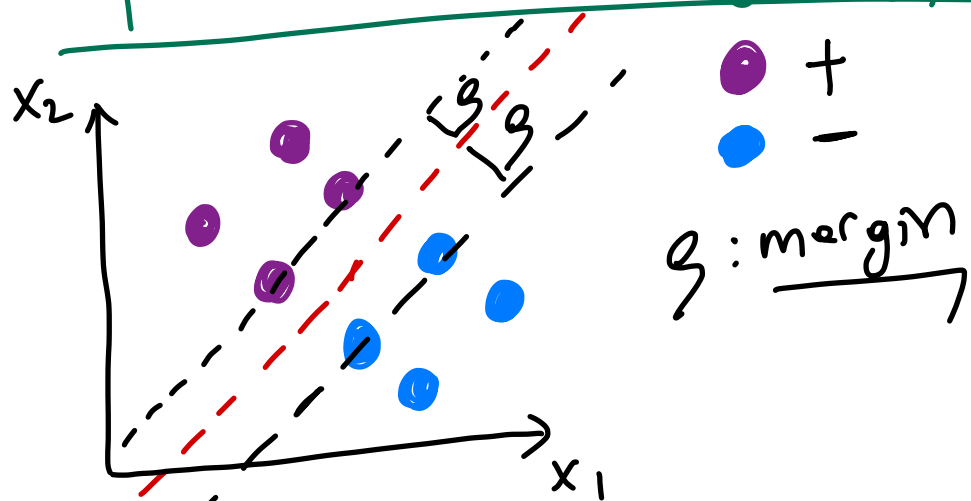
of parameters = $N+1$

representer theorem

$$\Downarrow \quad \underbrace{N}_{1 \times 1} \quad \underbrace{D \times 1}_{D \times 1}$$
$$\underbrace{w}_{D \times 1} = \sum_{i=1}^N \underbrace{\alpha_i}_{1 \times 1} \cdot \underbrace{x_i}_{D \times 1}$$

\hookrightarrow is mostly zero

Optimal Separating Hyperplane



$$\left. \begin{aligned} 3x + 4y - 5 &= 0 \\ -3x - 4y + 5 &= 0 \\ 6x + 8y - 10 &= 0 \end{aligned} \right\} \text{equivalent}$$

$$\boxed{\begin{aligned} -1(x+y) &\geq (-5) - 1 \\ -x - y &\leq +5 \end{aligned}}$$

$$\theta = \{w, w_0\}$$

$$\mathcal{X} = \{(x_i, y_i)\}_{i=1}^N$$

$$x_i \in \mathbb{R}^D$$

$$y_i \in \{-1, +1\}$$

$$w^T \cdot x + w_0 = 0$$

$$\begin{aligned} (y_i) w^T \cdot x_i + w_0 &\geq 1 \quad \text{if } y_i = +1 \\ (y_i) w^T \cdot x_i + w_0 &\leq -1 \quad \text{if } y_i = -1 \end{aligned}$$

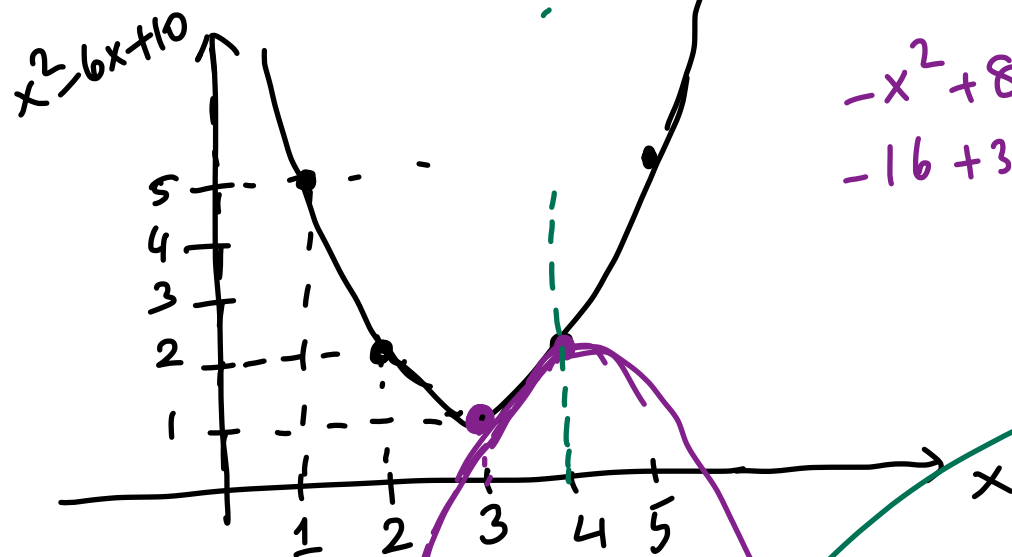
$$\frac{|3(5) + 4(6) + 5|}{\sqrt{(3)^2 + (4)^2}}$$

$$y_i(w^T \cdot x_i + w_0) \geq +1 \quad \forall i$$

$$\frac{|w^T \cdot x_i + w_0|}{\|w\|_2} = \frac{y_i(w^T \cdot x_i + w_0)}{\|w\|_2} \geq g \Rightarrow y_i(w^T \cdot x_i + w_0) \geq \underbrace{\|w\|_2}_{1} \cdot g$$

to obtain a unique solution $\Rightarrow \|w\|_2 \cdot g = 1$

minimize $x^2 - 6x + 10$



$$-x^2 + 8x - 14$$

$$-16 + 32 - 14$$

$$\frac{\partial(x^2 - 6x + 10)}{\partial x} = 2x - 6$$

$$\frac{\partial^2(x^2 - 6x + 10)}{\partial x^2} = 2$$

$$x^* = 3$$

maximize $-x^2 + 8x - 14$

minimize $x^2 - 6x + 10$
subject to: $x \geq 4$

\Rightarrow minimize
subject to

$$x^2 - 6x + 10$$

$$\underline{x - 4} \geq 0$$

$] \nearrow$

Lagrangian $(x, \lambda) = [x^2 - 6x + 10] - \lambda \cdot [\underline{x - 4}] \leftarrow \begin{matrix} \text{minimize} \\ \text{this function} \end{matrix}$

$$\frac{\partial [x^2 - 6x + 10 - \lambda x + 4\lambda]}{\partial x} = 2x - 6 - \lambda = 0$$

$$\lambda = \underline{2x - 6}$$

$$x^2 - 6x + 10 - (2x - 6)(x - 4) = x^2 - 6x + 10 - 2x^2 + 14x - 24$$

$$= -x^2 + 8x - 14 \leftarrow \begin{matrix} \text{maximize} \\ x^* = 4 \end{matrix}$$

$$[\|w\|_2 \cdot \gamma = 1] \quad \text{maximize } \gamma \Leftrightarrow \text{minimize } \|w\|_2$$

$$\text{minimize } \|w\|_2 \Leftrightarrow \text{minimize } \frac{1}{2} \|w\|_2^2$$

$$\sqrt{w_1^2 + w_2^2 + \dots + w_D^2}$$

$$\text{minimize } \frac{1}{2} \|w\|_2^2$$

$$\text{subject to: } y_i (\underline{w}^T x_i + \underline{w}_0) \geq 1 \quad \forall i$$

D+1 decision variables

N constraints

$$\|w\|_2^2 = \underline{w}^T \underline{w}$$

$$L_P = \frac{1}{2} \|w\|_2^2 - \sum_{i=1}^N \alpha_i [y_i (\underline{w}^T x_i + \underline{w}_0) - 1]$$

$$\frac{\partial L_P}{\partial w} = \frac{\partial}{\partial w} \left[\frac{1}{2} \cdot \underline{w}^T \underline{w} - \sum_{i=1}^N \alpha_i [y_i (\underline{w}^T x_i + \underline{w}_0) - 1] \right] = \underline{w} - \sum_{i=1}^N \alpha_i y_i x_i$$

$$\Rightarrow \underline{w} = \sum_{i=1}^N \alpha_i y_i x_i$$

$$\frac{\partial L_P}{\partial w_0} = - \sum_{i=1}^N \alpha_i y_i = 0 \Rightarrow \sum_{i=1}^N \alpha_i y_i = 0$$

$$\sum_{i=1}^N \alpha_i y_i = 0$$

~~$$\sum_{i=1}^N \alpha_i^2 y_i^T x_i \cdot x_i$$~~

$$(a_1 + a_2)(a_1 + a_2) \neq (a_1 + a_2)^2$$

$$\left(\sum_{i=1}^2 a_i \right) \left(\sum_{i=1}^2 a_i \right) \neq \sum_{i=1}^2 a_i^2$$

$$\underline{w}^T \underline{w} = \left[\sum_{i=1}^N \alpha_i y_i x_i \right]^T \cdot \left[\sum_{i=1}^N \alpha_i y_i x_i \right]$$

$$\|w\|_2^2 = w^T \cdot w = \left[\sum_{i=1}^N \alpha_i y_i x_i \right]^T \cdot \left[\sum_{j=1}^N \alpha_j y_j x_j \right] = \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j$$

$$L_p = \underbrace{\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j}_{\frac{1}{2} \|w\|_2^2} - \sum_{i=1}^N \alpha_i \left[y_i \left[\sum_{j=1}^N \alpha_j y_j x_j \right]^T \cdot x_i + w_0 \right] - 1$$

$$= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j - \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j - \left[\sum_{i=1}^N \alpha_i y_i w_0 + \sum_{i=1}^N \alpha_i \right]$$

$$= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j$$

maximize $\sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T \cdot x_j$

subject to: $\sum_{i=1}^N \alpha_i y_i = 0$

$\alpha_i \geq 0$

$$x_i^T \cdot x_j = x_j^T \cdot x_i$$

of decision variables = N
of constraints = 1