ENGR-421 HW-3 REPORT

Name-Surname: Barış KAPLAN

Initially, I have imported the necessary libraries. These libraries are as follows:

import matplotlib.pyplot as plt import numpy as np import pandas as pd import math

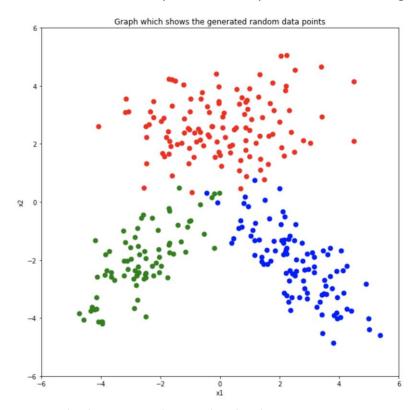
Then, I have generated the mean, covariance matrix, and size parameters.

After that, by using the **np.random.multivariate_normal** function of the numpy library, I have generated the random data points.

By using the **np.vstack** function of numpy library, I have vertically stacked the created random data points.

After that, I have generated the class labels by utilizing the **np.concatenate** function of the numpy library.

Next, by using the **plt.plot** function, I have generated the plot of the created random data points. By utilizing **plt.xlim** and **plt.ylim** functions, I have determined the limits of the x values and the limits of the y values in the plot. You can see the generated plot in Figure 1.



le writing the sigmoid

Figure 1: The plot containing the created random data points

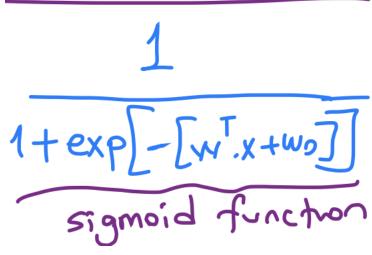


Figure 2: The sigmoid function formula I have used

Subsequently, I have defined the gradient functions for W and w0. While defining the gradient functions, I have utilized the formula in Figure 3 for W and the formula in Figure 4 for w0.

$$\frac{\partial \text{Error}}{\partial \boldsymbol{w}_c} = -\sum_{i=1}^{N} (y_{ic} - \hat{y}_{ic}) \boldsymbol{x}_i \qquad \frac{\partial \text{Error}}{\partial w_{c0}} = -\sum_{i=1}^{N} (y_{ic} - \hat{y}_{ic})$$

Figure 3: The gradient function for W

Figure 4: The gradient function for w0

By using Figure 5 and Figure 6, I have found the gradients in Figure 3 & Figure 4.

$$\begin{aligned}
\hat{y} &= \begin{bmatrix} \omega_1 & \omega_2 & \cdots & \omega_p \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} + \omega_p \\
&= \begin{bmatrix} \omega_0 & \omega_1 & \omega_2 & \cdots & \omega_p \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_1 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times \\
&= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \omega_2 & \times$$

In this step, by using the np.random.uniform() function of numpy library, I have randomly initialized W and w0.

Then, I have applied the gradient descent algorithm to W and w0. In this algorithm, I have generated the predicted values by using the sigmoid function (sigmoid calculation function). Furthermore, to update W and w0 values, I have subtracted the update amount delta W from W and delta w0 from w0 (you can see the update amounts for W and w0 in Figure 7).

$$\Delta w = - 2 \cdot \frac{\partial \mathcal{E}_{ror}}{\partial w} = - 2 \cdot \left[- \frac{\chi}{i} (y_i - \hat{y}_i) \cdot \chi_i \right]$$

$$= 2 \cdot \frac{\chi}{i} (y_i - \hat{y}_i) \cdot \chi_i$$

$$= 2 \cdot \frac{\chi}{i} (y_i - \hat{y}_i) \cdot \chi_i$$

$$= 2 \cdot \frac{\chi}{i} (y_i - \hat{y}_i) \cdot \chi_i$$

Figure 7: The update amount formulas for W and w0

errors

In the gradient descent algorithm, I have updated W and w0 until the condition in Figure 8 is met. When the condition in Figure 8 is met, I have terminated the algorithm.

As the error function, I have utilized the sum squared errors in the gradient descent algorithm. I have utilized the formula in Figure 9 for obtaining the sum squared errors. You can see the learned values of W and w0 (values after applying the gradient descent algorithm) in Figure 10.

```
if np.sqrt(np.sum((w0Val - w0_old_Val))**2 + np.sum((WVal - W_old_Val)**2)) < epsVal:</pre>
   Figure 8: The break condition of the gradient descent algorithm
                        After that, I have plotted the "Iteration vs Error" fig. W:
                                                                                                                                                                                                                                                                                                                                                                                                                              ration
    vs Error" function (see Figure 11) that the gra-[[-0.67723844 -2.42009122 2.42893886] ed in [ 7.17058383 -2.08967379 -2.28079817]]
0.5 \sum_{i=1}^{N} \sum_{c=1}^{K} (y_{ic} - \hat{y}_{ic})^2
b function of the parameter of the pa
           matrix. We can see from the confusion matrix (see Figure 12) that there is 1 misclassified data
Figure 9: The formula for the sum squared
                                                                                                                                                                                                                                                                 Figure 10: The values of W and w0 after the
                                                                                                                                                                                                                                                                gradient descent algorithm finishes
```

point for class 1 (having the red color), there are 4 misclassified data points for class 2 (having the green color), and there are 3 misclassified data points for class 3 (having the blue color). In total, there are 8 (1+4+3) misclassified data points. You can see the decision boundaries between the classes and the misclassified data points from the Figure 13. While drawing the decision boundaries, I have used plt.contour function of the matplotlib.pyplot library.

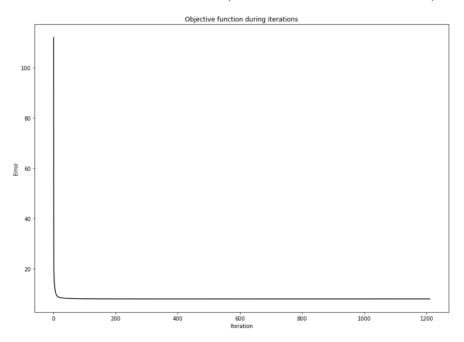


Figure 11: The "Iteration vs Error" graph

The Confusion Matrix:

y_truth	1	2	3
y_pred 1	119	4	2
2	1	76	1
3	0	0	97

Figure 12: The confusion matrix for the data points in my training set

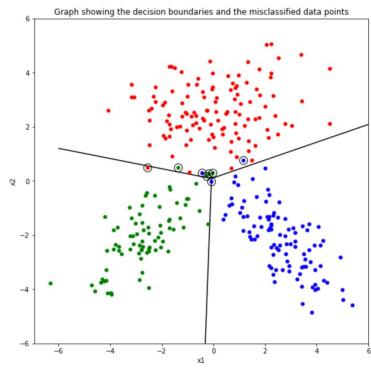


Figure 13: The plot showing the decision boundaries and the misclassified data points