

TRAFFIC LANE PROBLEM

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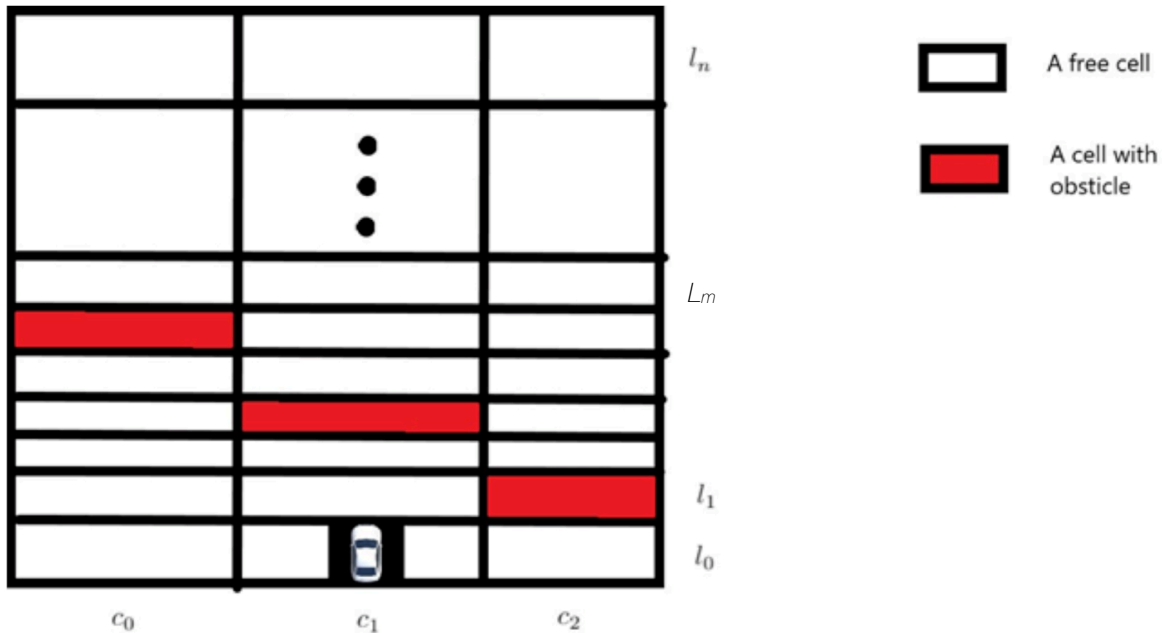


Figure A

a) Recursive formulation of the traffic lane problem:

- i) **Identify the Subproblems** : To minimize the number of traffic lane changes to reach L_n which is the row at the top. We should consider minimum of the lane change values of c_0, c_1 and c_2 at n^{th} row. To calculate values of c 's at n^{th} row, we should find the minimum lane change value of row below which is $(n-1)^{\text{th}}$ row. So our subproblem is the minimum value of the row below.
- ii) **Optimal Substructure Property** : We always calculate the minimum lane change value while considering current row. Thus, every value at any cell is the optimal value after we fill the memorization table.
- iii) **Overlapping Computations** : To find optimal value at m^{th} row, we should consider \Rightarrow
 $\min((L_m, c_0), (L_m, c_1), (L_m, c_2))$.

$$(L_m, c_0) \text{ is } \min((L_{m-1}, c_0), (L_{m-1}, c_1))$$

$$(L_m, c_1) \text{ is } \min((L_{m-1}, c_0), (L_{m-1}, c_1), (L_{m-1}, c_2))$$

$$(L_m, c_2) \text{ is } \min((L_{m-1}, c_1), (L_{m-1}, c_2))$$

As clearly seen above, we are calculated (L_{m-1}, c_0) for 2 times, (L_{m-1}, c_1) for 3 times and (L_{m-1}, c_2) for 2 times. Each step we should do these unnecessary calculations.

- iv) **Define the Problem Recursively** : To find minimum value at the top we should call the recursive function as $R(L_n, c)$. It will call numWays with L_{n-1} and this step will repeat until L_0 .

$$R(L, c) = \min[(R(L-1, c), (R(L-1, c-1) + 1), (R(L-1, c+1) + 1)]$$

b) Naive recursive algorithm:

```

naiveCall(l, c)
{
    IF l == 0
        IF c == 1
            return 0
        ELSE
            return n+1
        END IF
    END IF

    IF places[l][c] is Blocked
        return n+1
    END IF

    IF c == 0
        return min(naiveCall(l-1, c), (naiveCall(l-1, c+1) + 1))
    ELSE IF c == 2
        return min(naiveCall(l-1, c), (naiveCall(l-1, c-1) + 1))
    ELSE
        return min(naiveCall(l-1, c), (naiveCall(l-1, c-1) + 1), (naiveCall(l-1, c+1) + 1))
    END IF
}

```

—> **Asymptotic Time Analysis** : We start at L_n and call recursive function with L_{n-1} and repeat this step until L_0 and in each step we do at most 3 recursive calls which costs $O(3^n)$. Other comparisons done in $O(1)$. So, totally asymptotic time is $O(3^n)$.

—> **Space Complexity Analysis** : To determine the space complexity, we can consider a recursion tree. We store recursive calls in run-time stack memory, the total number of recursive calls that will be stored in a stack at max is the height of our recursive tree which is $O(n)$. Therefore, our total space complexity is $O(n)$

c) Recursive algorithm, top down with memoization:

Pseudo

```

checkMemo(l, c)
{
    IF myMemo[l][c] is Calculated Before
        return myMemo[l][c]
    ELSE
        myMemo[l][c] = topBottom(l, c)
        return myMemo[l][c]
    END IF
}

topBottom(l, c)
{
    IF l == 0: // if reached bottom
        IF c == 1
            return 0
        ELSE
            return n+1
        END IF
    END IF

    IF places[l][c] is BLOCKED
        return n+1
    END IF

    IF c == 0
        return min(checkMemo(l-1, c), (checkMemo(l-1, c+1) + 1))
    ELSE c == 2
        return min(checkMemo(l-1, c), (checkMemo(l-1, c-1) + 1))
    ELSE
        return min(checkMemo(l-1, c), (checkMemo(l-1, c-1) + 1), (checkMemo(l-1, c+1) + 1))
    END IF
}

```

—> **Asymtotic Time Analysis** : We start at L_n and call recursive function with L_{n-1} and repeat this step until L_0 and in each step we write down optimal solution to additional array. So we calculate each cell in matrix for once which cost at most $3 * n$ and it is $O(n)$. Other comparisons costs $O(1)$. So, totally asymtotic time is $O(n)$.

—> **Space Complexity Analysis** : We used one additional memory matrix which costs $3 * n$. Therefore, our space complexity is $O(n)$.

d) Iterative algorithm, bottom up with memoization:**Pseudo**

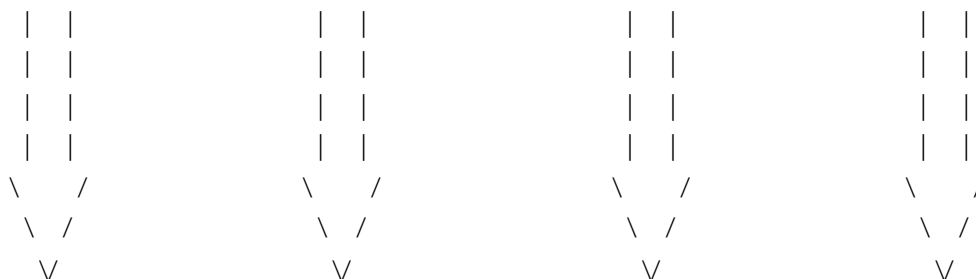
```

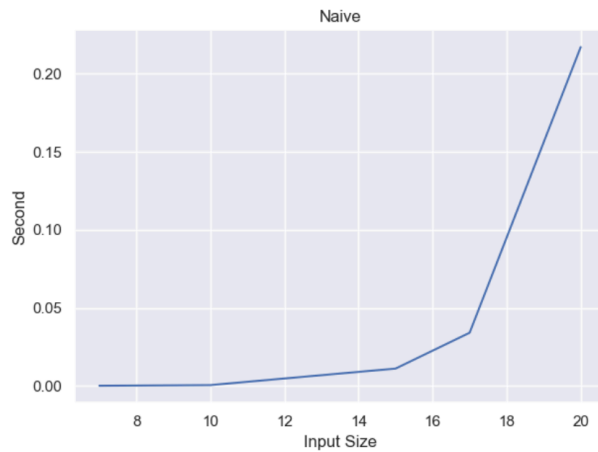
FOR i = 1 to length of myMemo
  FOR j = 0 to 2
    IF myMemo[i][j] is not Blocked
      IF j==0
        myMemo[i][j] = min(myMemo[i-1][0], myMemo[i-1][1] + 1)
      ELSE IF j == 2:
        myMemo[i][j] = min(myMemo[i-1][2], myMemo[i-1][1] + 1)
      ELSE
        myMemo[i][j] = min(myMemo[i-1][1], myMemo[i-1][2] + 1, myMemo[i-1][0] + 1)
      END IF
    END IF
  END FOR
END FOR

```

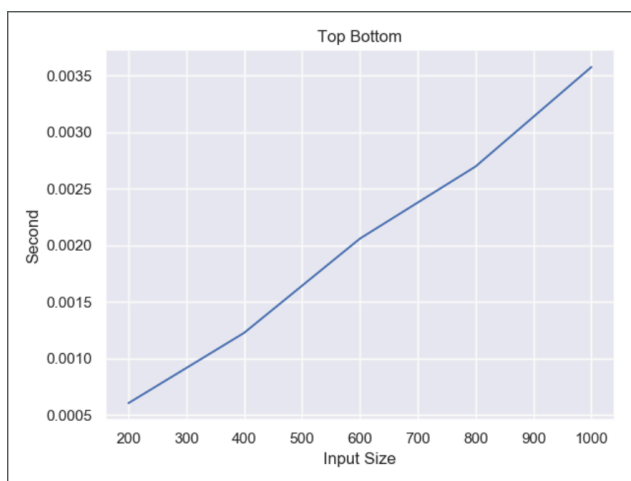
—> **Asymtotic Time Analysis** : We start at L_1 and compare values at L_{n+1} and choose minimum of them then repeat this step until L_n and in each step we write down optimal solution to additional array. So we calculate each cell in matrix for once which cost at most $3 * n$ and it is $O(n)$. Other comparisons costs $O(1)$.
So, totally asymtotic time is $O(n)$.

—> **Space Complexity Analysis** : We used one additional memory matrix which costs $3 * n$. Therefore, our space complexity is $O(n)$.

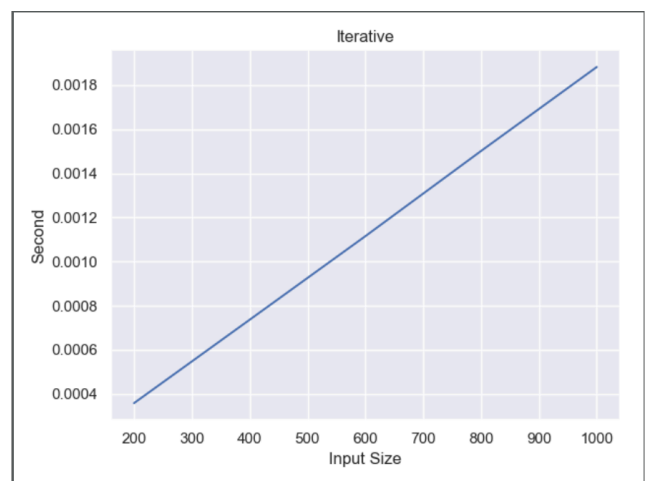
PART E FOLLOWS

e) **Experimental evaluations:**

Result of **naive algorithm** proves the asymptotic complexity analysis. It is exponential function.



Result of **top bottom algorithm** proves the asymptotic complexity analysis. It is linear function.



Result of **iterative algorithm** proves the asymptotic complexity analysis. It is linear function.

TEST CASES FOLLOWS

Test Cases: In following screenshots, 'Naive' wrongly typed as 'Native'

1) EMPTY LANE

```
[1, 0, 1]
[0, 0, 0]
[1, 0, 0]
[0, 0, 0]
[0, 0, 0]
[0, 0, 0]
[1, 0, 0]
[0, 0, 1]
[0, 0, 1]
[1, 0, 0]
Native time = 0.0011082079999999994 Optimal= 0

TopBottom time= 3.391099999999758e-05 Optimal= 0

Iterative time= 2.058799999998806e-05 Optimal= 0
```

2) ZigZag

```
[1, 0, 1]
[1, 0, 0]
[0, 1, 0]
[0, 0, 1]
[0, 1, 0]
[1, 0, 0]
[0, 1, 0]
[0, 0, 1]
[0, 1, 0]
[1, 0, 0]
Native time = 0.0001602740000000158 Optimal= 4

TopBottom time= 2.771899999998162e-05 Optimal= 4

Iterative time= 1.8860999999981143e-05 Optimal= 4
```

3) Straight Obstacles

```
[1, 0, 1]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]
[0, 1, 0]

Native time = 1.8408000000025293e-05 Optimal= 1
TopBottom time= 2.3482999999990817e-05 Optimal= 1
Iterative time= 1.6119000000036632e-05 Optimal= 1
```

4) Single road

```
[1, 0, 1]

Native time = 2.7039999999645126e-06 Optimal= 0
TopBottom time= 1.5090000000106407e-06 Optimal= 0
Iterative time= 1.4469999999877636e-06 Optimal= 0
```

5) Empty Road

```
Native time = 0 Optimal= 0
TopBottom time= 0 Optimal= 0
Iterative time= 0 Optimal= 0
```

6) Correctness: We can see the correctness of algorithm by doing some trials.

