partykit: A Toolkit for Recursive Partytioning

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Abstract

This vignette is intended to be a short technical introduction to the **partykit** package. It is still unfinished but hopefully already helpful to some interested users.

The purpose of the package is to provide a toolkit with infrastructure for representing, summarizing, and visualizing tree-structured regression and classification models. Thus, the focus is not on *inferring* such a tree structure from data but to *represent* a given tree so that print/plotting and computing predictions can be performed in a standardized way. In particular, this unified infrastructure can be used for reading/coercing tree models from different sources (**rpart**, **RWeka**, PMML) yielding objects that share functionality for print()/plot()/predict() methods.

Keywords: recursive partitioning, regression trees, classification trees, decision trees.

1. Motivating example and overview

To illustrate how **partykit** can be used to represent trees, a simple artificial data set from Witten & Frank's book *Data Mining: Practical Machine Learning Tools and Techniques* is used. It concerns the conditions suitable for playing some unspecified game.

- > data("WeatherPlay", package = "partykit")
- > WeatherPlay

	outlook	temperature	humidity	windy	play
1	sunny	85	85	${\tt false}$	no
2	sunny	80	90	true	no
3	overcast	83	86	${\tt false}$	yes
4	rainy	70	96	${\tt false}$	yes
5	rainy	68	80	${\tt false}$	yes
6	rainy	65	70	true	no
7	${\tt overcast}$	64	65	true	yes
8	sunny	72	95	${\tt false}$	no
9	sunny	69	70	${\tt false}$	yes
10	rainy	75	80	${\tt false}$	yes
11	sunny	75	70	true	yes
12	${\tt overcast}$	72	90	true	yes
13	${\tt overcast}$	81	75	${\tt false}$	yes
14	rainy	71	91	true	no

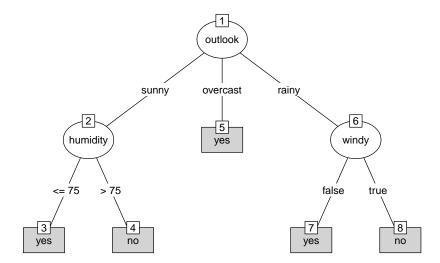


Figure 1: Decision tree for play decision based on weather conditions in WeatherPlay data.

To represent the play decision based on the corresponding weather condition variables one could use the tree displayed in Figure 1. For now, it is ignored how this tree was *inferred* and it is simply assumed to be given.

To represent this tree (also known as recursive partition) in **partykit**, two basic building blocks are used: splits of class "partysplit" and nodes of class "partynode". The resulting recursive partition can then be associated with a data set in an object of class "party".

Splits

First, we employ the partysplit() function to creat the three splits in the "weather tree" from Figure 1. The function takes the following arguments

```
partysplit(varid, breaks = NULL, index = NULL, ..., info = NULL)
```

where varid is an integer id of the variable used for splitting e.g., 1L for outlook, 3L for humidity, 4L for windy etc. Then, breaks and index determine which observations are sent to which of the branches, e.g., breaks = 75 for the humidity split. Apart from further arguments not shown above (and just comprised under '...'), some arbitrary information can be associated with a "partysplit" object by passing it to the info argument. The three splits from Figure 1 can then be created via

```
> sp_o <- partysplit(1L, index = 1:3)
> sp_h <- partysplit(3L, breaks = 75)
> sp_w <- partysplit(4L, index = 1:2)</pre>
```

For the numeric humidity variable the breaks are set while for the factor variables outlook and windy the information is supplied which of the levels should be associated with which of the branches of the tree.

Nodes

Second, we use these splits in the creation of the whole decision tree. In **partykit** a tree is represented by a "partynode" object which is recursive in that it may have "kids" that are again "partynode" objects. These can be created with the function

```
partynode(id, split = NULL, kids = NULL, ..., info = NULL)
```

where id is an integer identifier of the node number, split is a "partysplit" object, and kids is a list of "partynode" objects. Again, there are further arguments not shown (...) and arbitrary information can be supplied in info. The whole tree from Figure 1 can then be created via

```
> pn <- partynode(1L, split = sp_o, kids = list(
+ partynode(2L, split = sp_h, kids = list(
+ partynode(3L, info = "yes"),
+ partynode(4L, info = "no"))),
+ partynode(5L, info = "yes"),
+ partynode(6L, split = sp_w, kids = list(
+ partynode(7L, info = "yes"),
+ partynode(8L, info = "no")))))</pre>
```

where the previously created "partysplit" objects are used as splits and the nodes are simply numbered from 1 to 8. For the terminal nodes of the tree there are no kids and the corresponding play decision is stored in the info argument. Printing the "partynode" object reflects the recursive structure stored.

> pn

```
[1] root
| [2] V1 in (-Inf,1]
| | [3] V3 <= 75 *
| | [4] V3 > 75 *
| [5] V1 in (1,2] *
| [6] V1 in (2, Inf]
| | [7] V4 <= 1 *
| [8] V4 > 1 *
```

However, the displayed information is still rather raw as it has not yet been associated with the WeatherPlay data set.

Trees (or recursive partitions)

Hence, in a third step the recursive tree structure stored in **pn** is coupled with the corresponding data in a "party" object.

```
> py <- party(pn, WeatherPlay)
> py
```

```
[1] root
| [2] outlook in sunny
| | [3] humidity <= 75: yes
| [4] humidity > 75: no
| [5] outlook in overcast: yes
| [6] outlook in rainy
| | [7] windy in false: yes
| [8] windy in true: no
```

And Figure 1 can easily be created by

```
> plot(py)
```

In addition to print() and plot(), the predict() method can now be applied, yielding the predicted terminal node IDs.

```
> predict(py, newdata = WeatherPlay)
```

In addition to the "partynode" and the "data.frame", the function party() takes several further arguments

```
party(node, data, fitted = NULL, terms = NULL, ..., info = NULL)
```

i.e., fitted values, a terms object, arbitrary additional info, and again some further arguments comprised in

Further information

More detailed technical information is provided in the subsequent sections. Section 2, 3, and 4 discuss the partysplit(), partynode(), and party() functions, respectively. Section 5 illustrates how this infrastructure can be employed in a function that recursively *infers* a tree.

Design principles

To facilitate reading of the subsequent sections, two design principles employed in the creation of **partykit** are briefly explained.

- (1) Many helper utilities are encapsulated in functions that follow a simple naming convention. To extract/compute some information foo from splits, nodes, or trees, partykit provides foo_split, foo_node, foo_party functions (that are applicable to "partysplit", "partynode", and "party" objects, repectively). An example for the information foo might be kidids. Such functions are typically not to be called by the end-user but potentially by package designers that want to build functionality on top of partykit.
- (2) Printing and plotting relies on *panel functions* that visualize and/or format certain aspects of the resulting display, e.g., that of inner nodes, terminal nodes, headers, footers, etc. A simple example would be printing with a custom panel function for formatting the terminal node:

```
> print(py,
+ terminal_panel = function(node) paste(": play=", node$info, sep = ""))
```

```
[1] root
| [2] outlook in sunny
| | [3] humidity <= 75: play=yes
| [4] humidity > 75: play=no
| [5] outlook in overcast: play=yes
| [6] outlook in rainy
| | [7] windy in false: play=yes
| [8] windy in true: play=no
```

Furthermore, arguments like terminal_panel can also take *panel-generating functions*, i.e., functions that produce a panel function when applied to the "party" object.

2. Splits

A split is basically a function that maps data, more specifically a partitioning variable, to daugther nodes. Objects of class "partysplit" are designed to represent such functions and are set-up by the partysplit() constructor:

```
> ## binary split in numeric variable `Sepal.Length'
> s15 <- partysplit(which(names(iris) == "Sepal.Length"), breaks = 5)
> class(s15)
[1] "partysplit"
```

The internal structure of class "partysplit" contains information about the partitioning variable, the split-points, the handling of split-points, the treatment of observations with missing values and the daughter nodes to send observations to:

```
> unclass(s15)
$varid
[1] 1
$breaks
[1] 5
$index
NULL
$right
[1] TRUE
$prob
NULL
$info
```

NULL

Here, the split is defined in the first variable (corresponds to Sepal.Length in data frame iris) and the splitting rule is Sepal.Length ≤ 5 :

> character_split(s15, data = iris)

\$name

[1] "Sepal.Length"

\$levels

This representation of splits is completely abstract and, most importantly, independent of any data. Now, data comes into play when we actually want to perform splits:

> kidids_split(s15, data = iris)

For each observation in iris the split is performed and the number of the daughter node to send this observation to is returned. Of course, this is a very complicated way of saying

> (!with(iris, Sepal.Length <= 5)) + 1

Formally, a split is a function f mapping an element $x = (x_1, ..., x_p)$ of a p-dimensional sample space \mathcal{X} into a set of k daugther nodes $\mathcal{D} = \{d_1, ..., d_k\}$. This mapping is defined as a composition $f = h \circ g$ of two functions $g : \mathcal{X} \to \mathcal{I}$ and $h : \mathcal{I} \to \mathcal{D}$ with index set $\mathcal{I} = \{1, ..., l\}, l \geq k$.

Let $\mu = (-\infty, \mu_1, \dots, \mu_{l-1}, \infty)$ denote the split points $((\mu_1, \dots, \mu_{l-1}) = \text{breaks})$. We are interested to split according to the information contained in the *i*th element of x (i = varid). For numeric x_i , the split points are also numeric. If x_i is a factor at levels $1, \dots, K$, the default split points are $\mu = (-\infty, 1, \dots, K - 1, \infty)$.

The function g essentially determines, which of the intervals (defined by μ) the value x_i is contained in (I denotes the indicator function here):

$$x \mapsto g(x) = \sum_{j=1}^{l} j I_{\mathcal{A}(j)}(x_i)$$

where $\mathcal{A}(j) = (\mu_{j-1}, \mu_j]$ for right = TRUE except $\mathcal{A}(l) = (\mu_{l-1}, \infty)$. If right = FALSE, then $\mathcal{A}(j) = [\mu_{j-1}, \mu_j)$ except $\mathcal{A}(1) = (-\infty, \mu_1)$. Note that with some categorical variable x_i and default split points, g is the identity.

Now, h maps from the index set \mathcal{I} into the set of daugther nodes:

$$f(x) = h(g(x)) = d_{\sigma_{g(x)}}$$

where $\sigma = (\sigma_1, \dots, \sigma_l) \in \{1, \dots, k\}^l$ (index). By default, $\sigma = (1, \dots, l)$ and k = l.

If x_i is missing, then f(x) is randomly drawn with $\mathbb{P}(f(x) = d_j) = p_j, j = 1, ..., k$ for a discrete probability distribution $p = (p_1, ..., p_k)$ over the k daugther nodes (prob).

In the simplest case of a binary split in a numeric variable x_i , there is only one split point μ_1 and, with $\sigma = (1, 2)$, observations with $x_i \leq \mu_1$ are sent to daugther node d_1 and observations with $x_i > \mu_1$ to d_2 . However, this representation of splits is general enough to deal with more complicated set-ups like surrogate splits, where typically the index needs modification, for example $\sigma = (2, 1)$, categorical splits, i.e., there is one data structure for both ordered and unordered splits, multiway splits, and functional splits. The latter can be implemented by defining a new artificial splitting variable x_{p+1} by means of a potentially very complex function of x later used for splitting.

As an example, consider a split in a categorical variable at three levels where the first two levels go to the left daugther node and the third one to the right daugther node:

```
> ## binary split in factor `Species'
> sp <- partysplit(which(names(iris) == "Species"), index = c(1L, 1L, 2L))
> character_split(sp, data = iris)
```

\$name

[1] "Species"

\$levels

[1] "setosa, versicolor" "virginica"

> table(kidids_split(sp, data = iris), iris\$Species)

 setosa versicolor virginica

 1
 50
 50
 0

 2
 0
 0
 50

The internal structure of this object contains the index slot

> unclass(sp)

\$varid

[1] 5

\$breaks

NULL

```
$index
[1] 1 1 2
$right
[1] TRUE
$prob
NULL
$info
NULL
```

that maps levels to daughter nodes. This mapping is also useful with splits in ordered variables, for example when representing multiway splits:

```
> ## multiway split in numeric variable `Sepal.Width',
> ## higher values go to the first kid, smallest values
> ## to the last kid
> sw23 <- partysplit(which(names(iris) == "Sepal.Width"),
    breaks = c(3, 3.5), index = 3:1)
> character_split(sw23, data = iris)
$name
[1] "Sepal.Width"
$levels
[1] "(3.5, Inf]" "(3,3.5]" "(-Inf,3]"
> table(kidids_split(sw23, data = iris),
   cut(iris\$Sepal.Width, breaks = c(-Inf, 2, 3, Inf)))
    (-Inf,2] (2,3] (3, Inf]
 1
           0
                 0
 2
                 0
                         48
           0
                82
                          0
```

The mapping of classes of the categorized numeric variable to daugther nodes can be changed by modifying index:

```
> sw23 <- partysplit(which(names(iris) == "Sepal.Width"),
+ breaks = c(3, 3.5), index = c(1L, 3L, 2L))
> character_split(sw23, data = iris)

$name
[1] "Sepal.Width"

$levels
[1] "(-Inf,3]" "(3.5, Inf]" "(3,3.5]"
```

The additional argument prop is used to specify a discrete probability distribution over the daugther nodes that is used to map observations with missing values to daugther nodes. Furthermore, the info argument and slot takes arbitrary objects to be stored with the split (for example split statistics) but is not structured at the moment.

The slots of "partysplit" objects shall be accessed by the corresponding accessor functions.

3. Nodes

Inner and terminal nodes are represented by objects of class "partynode". Each node has a unique identifier id. A node consisting only of such an identifier (and possibly additional information in info) is a terminal node:

```
> n1 <- partynode(id = 1L)
> is.terminal(n1)

[1] TRUE
> print(n1)

[1] root
```

Inner nodes have to have a primary split split and at least two daugther nodes. The daugther nodes are objects of class "partynode" itself and thus represent the recursive nature of this data structure. The daugther nodes are pooled in a list kids. In addition, a list of "partysplit" objects offering surrogate splits can be supplied; a list of "partysplit" objects in slot surrogates defines such additional splits (mostly used for handling missing values). Note that "partynode" objects aren't connected to the actual data.

Based on the binary split \$15 defined in the previous section, we set-up an inner node with two terminal daugther nodes and print this stump (the data is needed because neither split nor nodes contain information about variable names or levels):

Now that we have defined our first simple tree, we want to assign observations to terminal nodes:

Here, the ids of the terminal node each observations falls into are returned. Alternatively, we could compute the position of these daugther nodes in the list kids:

```
> kidids_node(n1, data = iris)
```

Furthermore, the info argument and slot takes arbitrary objects to be stored with the node (predictions, for example, but we will handle this issue later). The slots can be extracted by means of the corresponding accessor functions.

A number of methods are defined for "partynode" objects. is.partynode() checks if the argument is a valid "partynode" object. is.terminal() is TRUE for terminal nodes and FALSE for inner nodes. The subset methods return the "partynode" object corresponding to the ith kid:

```
> n1[2]
```

[NA] root

The as.partynode() and as.list() methods can be used to convert flat list structures into recursive "partynode" objects and vice versa. as.partynode() applied to "partynode" objects renumbers the recursive nodes starting with root node identifier from.

length() gives the number of kid nodes of the root node, depth() the depth of the tree and width() the number of terminal nodes.

4. Trees

Although tree structures can be represented by "partynode" objects, a tree is more than a number of nodes and splits. More information about (parts of the) corresponding data is necessary for high-level computations on trees.

Objects of class "party" basically consist of a "partynode" object representing the tree structure in a recursive way and data. The data argument takes a "data.frame" which, however, might have zero columns. Optionally, a "data.frame" with at least one variable (fitted) containing the terminal node numbers of data used for fitting the tree may be specified along with a terms object or any additional (currently unstructured) information as info. Argument names defines names for all nodes in node.

```
> t1 <- party(n1,
+ data = iris,
+ fitted = data.frame(
+ "(fitted)" = fitted_node(n1, data = iris),</pre>
```

```
+ "(response)" = iris$Species,
+ check.names = FALSE)
+ )
> t1

[1] root
| [2] Sepal.Length <= 5: *
| [3] Sepal.Length > 5: *
```

5. My first tree

Package partykit does not offer unified infrastructure for growing trees. However, once you know how to estimate splits from data, it is fairly straightforward to implement trees. Consider a very simple tree algorithm. We assume that both response and features are numeric. We search for the binary best split by means of t-test p-values, i.e., we cycle through all variables and potential split points and assess the quality of the split by comparing the distributions of the response in the so-defined two groups. We select the feature/split point combination with lowest two-sided p-value, however only if this result is significant at level $\alpha = 0.05$.

This strategy can be implemented based on the data (response and features) and some case weights as follows (response is just the name of the response and data is a data frame with all variables):

```
> findsplit <- function(response, data, weights) {</pre>
    ### extract response values from data
    y <- data[[response]]</pre>
    logpmin <- 0
    xselect <- NULL
    ### cycle through all features
    for (i in which(names(data) != response)) {
      ### expand data
      x <- data[[i]]</pre>
      xt <- rep(x, weights)
      yt <- rep(y, weights)
      ### potential split points (not too many)
      qx <- unique(quantile(xt,</pre>
                    prob = seq(from = 0.1, to = 0.9, by = 0.05)))
      ### assess all potential splits by their t-test
      ### log-p-value
      logp <- sapply(qx, function(q) {</pre>
```

```
tt \leftarrow t.test(yt[xt \leftarrow q], yt[xt > q])
        pt(-abs(tt$statistic), tt$parameter, log = TRUE) + log(2)
      7)
      ### if the best split in variable i significant AND
      ### better than what we already had store this information
      if (min(logp) < logpmin & min(logp) < log(0.05)) {
        logpmin <- min(logp)</pre>
        xselect <- i
        splitpoint <- qx[which.min(logp)]</pre>
    }
+
    ### no significant split found, give up
    if (is.null(xselect)) return(NULL)
   ### return split as partysplit object
   return(partysplit(
        varid = as.integer(xselect),
                                               ### which variable?
        breaks = as.numeric(splitpoint), ### which split point?
        info = list(pvalue = exp(logpmin) ### save p-value in addition
    )))
+ }
```

In order to actually grow a tree on data, we have to set-up the recursion for growing a recursive "partynode" structure:

```
> growtree <- function(id = 1L, response, data, weights) {</pre>
    ### for less than 30 obs. stop here
    if (sum(weights) < 30) return(partynode(id = id))</pre>
    ### find best split
    sp <- findsplit(response, data, weights)</pre>
    ### no split found, stop here
    if (is.null(sp)) return(partynode(id = id))
    ### actually split the data
   kidids <- kidids_split(sp, data = data)</pre>
   ### set-up all daugther nodes
  kids <- vector(mode = "list", length = max(kidids))</pre>
   for (kidid in 1:max(kidids)) {
  ### select obs for current node
   w <- weights
  w[kidids != kidid] <- 0
  ### get next node id
```

```
+
    if (kidid > 1) {
+
      myid <- max(nodeids(kids[[kidid - 1]]))</pre>
    } else {
      myid <- id
    }
    ### start recursion on this daugther node
    kids[[kidid]] <- growtree(id = as.integer(myid + 1), response, data, w)</pre>
    ### return nodes
    return(partynode(id = as.integer(id), split = sp, kids = kids))
A very rough sketch of formula-based user-interface needs to set-up the data and call growtree():
> mytree <- function(formula, data, weights = NULL) {</pre>
    ### name of the response variable
    response <- all.vars(formula)[1]</pre>
    \#\#\# data without missing values, response comes last
    data <- data[complete.cases(data), c(all.vars(formula)[-1], response)]</pre>
    ### data is numeric
    stopifnot(all(sapply(data, is.numeric)))
    if (is.null(weights)) weights <- rep(1, nrow(data))</pre>
    ### weights are case weights, i.e., integers
    stopifnot(length(weights) == nrow(data) &
      max(abs(weights - floor(weights))) < .Machine$double.eps)</pre>
    ### grow tree
    nodes <- growtree(id = 1L, response, data, weights)</pre>
    ### compute terminal node number for each obs.
    fitted <- fitted_node(nodes, data = data)</pre>
    ### return rich object
    ret <- party(nodes,</pre>
      data = data,
      fitted = data.frame(
        "(fitted)" = fitted,
        "(response)" = data[[response]],
        "(weights)" = weights,
        check.names = FALSE),
      terms = terms(formula))
    as.constparty(ret)
+ }
```

We now can fit this tree, for example to the airquality data; the print() method provides us with a first overview on the resulting model

```
> aqt <- mytree(Ozone ~ Solar.R + Wind + Temp, data = airquality)</pre>
> aqt
Model formula:
Ozone ~ Solar.R + Wind + Temp
Fitted party:
[1] root
    [2] Temp \leq 87.5
        [3] Solar.R \leq 48.95: 11.929 (n = 14, err = 580.9)
        [4] Solar.R > 48.95
             [5] Temp <= 77
                 [6] Wind \leq 8.84: 29.500 (n = 8, err = 450.0)
                 [7] Wind > 8.84
                     [8] Temp \leftarrow 76.1: 17.852 (n = 27, err = 1677.4)
                     [9] Temp > 76.1: 21.333 (n = 3, err = 0.7)
            1
            [10] Temp > 77
                 [11] Wind \leq 9.7: 61.154 (n = 26, err = 33555.4)
                 [12] Wind > 9.7: 37.688 (n = 16, err = 1849.4)
    [13] Temp > 87.5: 90.059 (n = 17, err = 3652.9)
Number of inner nodes:
Number of terminal nodes: 7
We depict the model graphically using plot() (see Figure 2) and compute predictions using
> predict(aqt, newdata = airquality[1:10,])
                           3
                                              5
29.50000 29.50000 17.85185 17.85185 11.92857 17.85185 29.50000
17.85185 11.92857 29.50000
An interesting feature is the ability to extract subsets of trees:
> aqt4 <- aqt[4]
> aqt4
Model formula:
Ozone ~ Solar.R + Wind + Temp
Fitted party:
[4] root
    [5] Temp <= 77
    [6] Wind \leq 8.84: 29.500 (n = 8, err = 450.0)
        [7] Wind > 8.84
            [8] Temp \leftarrow 76.1: 17.852 (n = 27, err = 1677.4)
```

> plot(aqt)

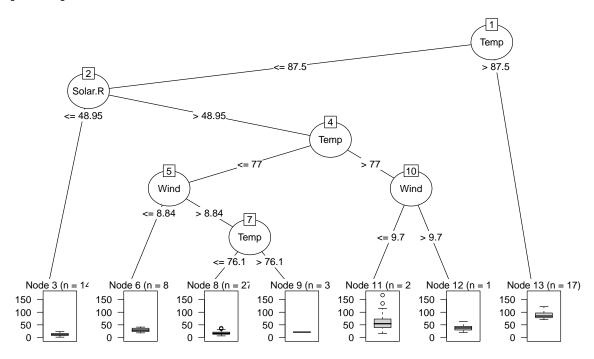


Figure 2: Tree.

Number of inner nodes: 4
Number of terminal nodes: 5

which again are objects inheriting from "party" and thus can be plotted easily (see Figure 3). We also might be interested in extracting the p-values in the inner nodes in a nicely formatted way:

> plot(aqt4)

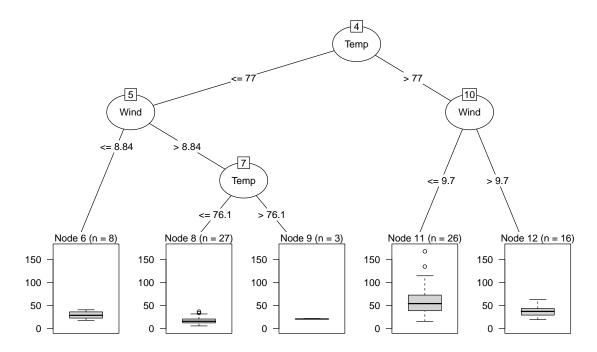


Figure 3: Subtree.

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