Robert Barlow

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Robotic Engineer **BarlowR.com**

Education

Class of 2021
Olin College of Engineering
BS in Engineering:Robotics
3.5 GPA

Projects

+One

Babson Foundry | May 2019

- Received a fellowship to develop an autonomous drone for avalanche victim search.
- Worked on a team of two to build custom multirotor hardware, design RF circuitry and write C++ embedded software in an attempt to advance the state of the art in safety gear. portfolio.barlowr.com/one

GeoDecibel

Personal Project | March 2019

- Developed custom wooden speakers based on acoustically optimized rhombic dodecahedron configuration.
- Designed and assembled crossovers with selfwound inductors.
- Leveraged 3-axis CNC router & woodshop for fabrication and COMSOL for simulation portfolio.barlowr.com/geodecimal

Birdhub

Principles of Engineering | December 2017

- Designed and constructed a solar powered bird monitoring station with an integrated feeder and cellular IoT connection.
- Worked on a team of 5 students. Lead mechanical design and software. poe.olin.edu/2017/TheBirdhouseProject/

FLOW

Mechanical Prototyping | April 2017

- Designed and constructed single motor driven kinetic sculpture inspired by oceanic wave motion.
- Lead system design and CAD on team of 5 students

portfolio.barlowr.com/flow

Experience

Mechanical Engineering Intern

Zipline International, Half Moon Bay, CA July 2019 to July 2020

- Worked on a multi-disciplinary team to take Zipline's perception system from prototype to volume production.
- Designed hardware from one-off 3D prints through injection molding.
- Worked closely with EE team to design a compute module PCBA and enclosure solution within highly constrained size, weight, weather and thermal requirements.
- Supported mechanical lifecycle testing work and developed a custom wirelessly transmitting in-line tension gauge to characterize real-time aircraft recovery forces
- Setup an electrical prototyping space and helped to maintain Zipline's machine shop.
- Purchased $\stackrel{.}{\&}$ personally refurbished a South Bend 14" lathe to expand machine shop capabilities.

Lead Instructor

Olin Shopbot & Woodworking Space September 2017 to June 2019

- In charge of Olin's Shopbot, a large scale 3 axis CNC router, and associated spaces.
- Duties included preventative and on- demand maintenance work, continuous improvement projects, and instruction of fellow students and faculty in CAM & machine operation.
- Also worked with faculty to create a new advanced woodshop where I worked as an instructor.

Electro-Mechanical Eng. Intern

UC San Diego Engineers for Exploration June 2018 to Sept 2018

- Worked closely with faculty at Scripps Institute of Oceanography to create a sensor system to improve diver workfow in underwater 3D mapping of coral reefs.
- Worked on a team of two to design, manufacture, and test this system, which leverages an IMU, pressure sensor, magnetometer and microprocessor to aggregate and display crucial environmental information. to divers.

Robotic Research Intern

Olin Intelligent Vehicle Lab, Needham, MA May 2017 to September 2017

- Designed, built and flew fixed wing sUAS (small unmanned aerial systems) for Scientific Systems Company, Inc. contract. Developed a novel system for dropping fire suppressant while in-flight.
- sUAS leveraged first-person view systems, long range control and was designed for very high payload capabilities.

Python 3 | ROS | C++ | MATLAB NX | Solidworks | Fusion 360 Photoshop | Illustrator | Indesign CAM | CNC | Mill | Lathe Woodworking | Composites Electrical Prototyping | Eagle