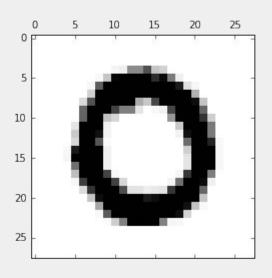
Robot Vision

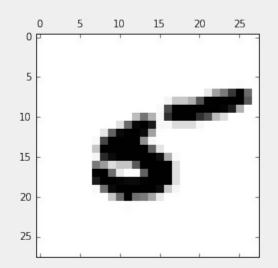
• • •

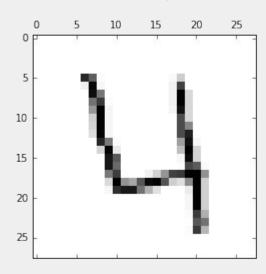
Michael Lai

Goal

Predict Numbers ~ Consider Speed and Accuracy

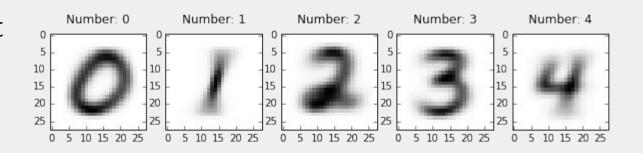


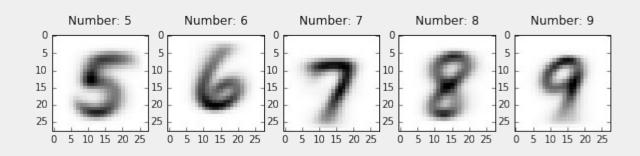




Data Details

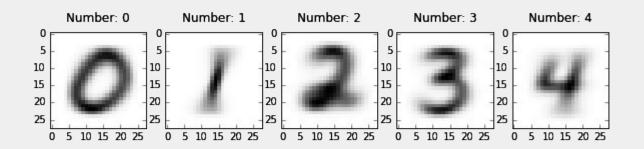
- ☐ MNIST Data Set
- ☐ 42,000 Images
- Handwritten
- ☐ Labeled 0-9

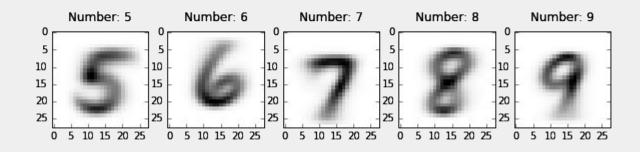




Methods: K Nearest Neighbors

- Pros
 - ☐ Fast Training
 - ☐ Interpretability
- **☐** Cons
 - ☐ Pre-Processing
 - □ Rotation
 - ☐ Bounding Box
 - Accuracy (97%)
 - □ Slow Predictions

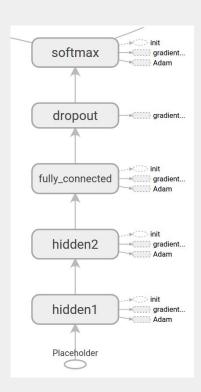




Methods: Convolutional NN with TensorFlow

- Pros
 - Accuracy (99+%)
 - Quick Predictions

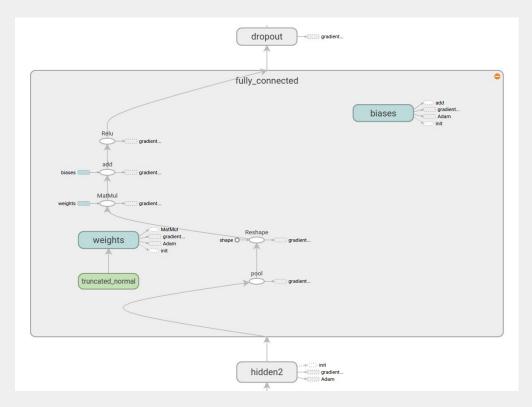
- Cons
 - ☐ Interpretability
 - Slow Training



Methods: Convolutional NN with TensorFlow

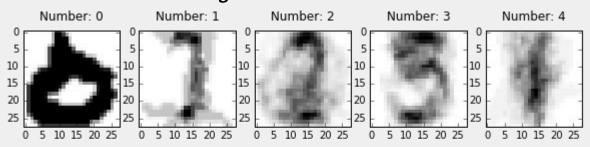
- Pros
 - ☐ Accuracy (99+%)
 - Quick Predictions

- **☐** Cons
 - Interpretability
 - ☐ Slow Training

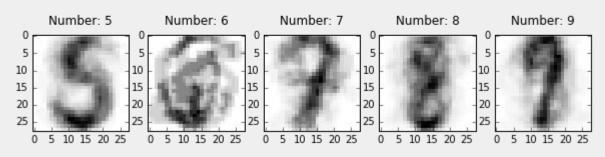


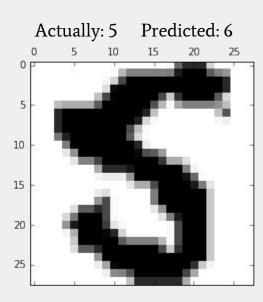
Results: K Nearest Neighbors

Averages of Incorrect Classification



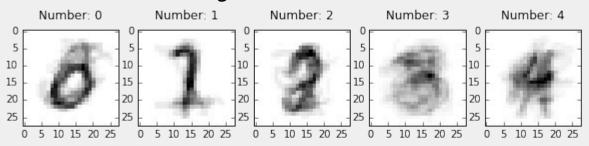
Overall Accuracy 97%



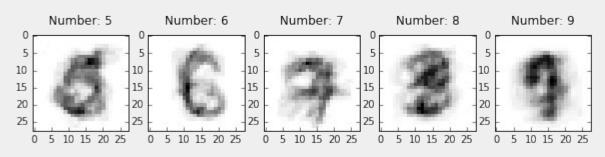


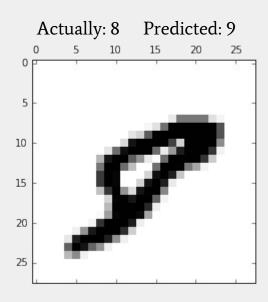
Results: Convolutional Neural Network

Averages of Incorrect Classification

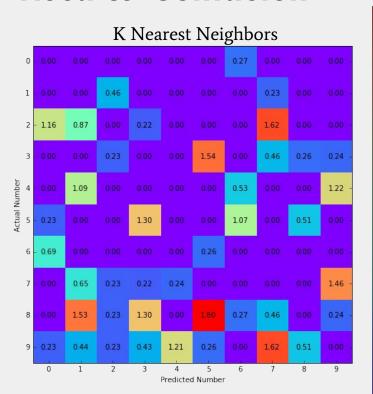


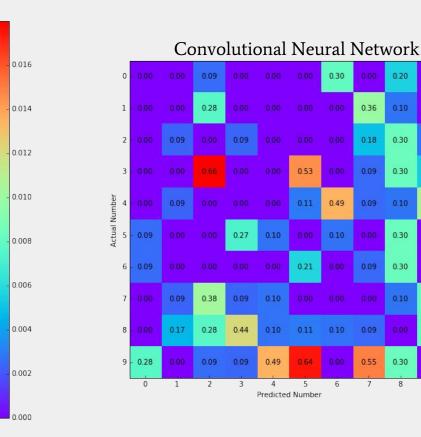
Overall Accuracy 99%





Results: Confusion





0.0064

0.0056

0.0048

0.0040

0.0032

0.0024

0.0016

0.0008

0.0000

0.10

0.20

0.39

0.29

0.29

Decision

Use Neural Networks

99% Accuracy

66% Fewer Errors Compared to KNN

Quick Prediction Speed