

Multi-objective least squares problem.

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2$$

$$\left. \begin{array}{l} A \in \mathbb{R}^{m \times n} \\ b \in \mathbb{R}^m \end{array} \right\} \text{ given}$$



$$J = \lambda_1 J_1 + \lambda_2 J_2 + \dots + \lambda_k J_k$$

$$\lambda_1, \dots, \lambda_k > 0$$

$$J_i = \|A_i x - b_i\|_2^2$$

$$\text{for } i=1, 2, \dots, k$$

$$\left[\begin{array}{l} A_i \in \mathbb{R}^{m_i \times n} \\ b_i \in \mathbb{R}^{m_i} \end{array} \text{ for } i=1, 2, \dots, k \right] \leftarrow \text{given}$$
$$\lambda_1, \dots, \lambda_k > 0$$

We want to compute \hat{x} such that

$$\hat{x} = \operatorname{argmin}_{x \in \mathbb{R}^n} \lambda_1 J_1 + \lambda_2 J_2 + \dots + \lambda_k J_k = \operatorname{argmin}_{x \in \mathbb{R}^n} \left(\lambda_1 \|A_1 x - b_1\|_2^2 + \lambda_2 \|A_2 x - b_2\|_2^2 + \dots + \lambda_k \|A_k x - b_k\|_2^2 \right)$$

Ex: $A_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$, $b_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

$A_2 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$, $b_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$J = \lambda_1 J_1 + \lambda_2 J_2 = \underbrace{\|A_1 x - b_1\|_2^2}_{J_1} + \underbrace{\|A_2 x - b_2\|_2^2}_{J_2}$ for $\lambda_1 = \lambda_2 = 1$

$\hat{x}_{J_1} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$,

$\hat{x}_{J_2} = \begin{pmatrix} 2/3 \\ 2/3 \end{pmatrix}$

$\underbrace{(A_2^T A_2)^+ A_2^T b_2}_{\text{least squares solution}} = \hat{x}_{J_2}$

$$x \in \mathbb{R}^{m_1}$$

$$y \in \mathbb{R}^{m_2}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^{m_1+m_2}$$

$$\left\| \begin{pmatrix} x \\ y \end{pmatrix} \right\|_2^2 = \|x\|_2^2 + \|y\|_2^2$$

$$J_1 = \|A_1 x - b_1\|_2^2, \quad J_2 = \|A_2 x - b_2\|_2^2, \quad \dots, \quad J_k = \|A_k x - b_k\|_2^2$$

$$J_1 + J_2 + \dots + J_k = \left\| \begin{bmatrix} A_1 x - b_1 \\ A_2 x - b_2 \\ \vdots \\ A_k x - b_k \end{bmatrix} \right\|_2^2$$

$$= \left\| \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_k \end{bmatrix} x - \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_k \end{bmatrix} \right\|_2^2$$

$$= \| \tilde{A} x - \tilde{b} \|_2^2 \quad \text{where}$$

$$\tilde{A} = \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_k \end{bmatrix} \in \mathbb{R}^{(m_1+\dots+m_k) \times n}$$

$$\tilde{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_k \end{bmatrix} \in \mathbb{R}^{m_1+\dots+m_k}$$

If columns of \tilde{A} are linearly independent, then there is a unique minimizer to the problem

$$\| \tilde{A}x - \tilde{b} \|_2^2 \quad \text{which is} \quad \hat{x} = (\tilde{A}^T \tilde{A})^{-1} \tilde{A}^T \tilde{b}.$$

$$J = \lambda_1 J_1 + \lambda_2 J_2 + \dots + \lambda_k J_k$$

$$= \lambda_1 \|A_1 x - b_1\|_2^2 + \lambda_2 \|A_2 x - b_2\|_2^2 + \dots + \lambda_k \|A_k x - b_k\|_2^2$$

$$= \| \sqrt{\lambda_1} A_1 x - \sqrt{\lambda_1} b_1 \|_2^2 + \| \sqrt{\lambda_2} A_2 x - \sqrt{\lambda_2} b_2 \|_2^2 + \dots + \| \sqrt{\lambda_k} A_k x - \sqrt{\lambda_k} b_k \|_2^2$$

$$= \left\| \begin{bmatrix} \sqrt{\lambda_1} A_1 \\ \sqrt{\lambda_2} A_2 \\ \vdots \\ \sqrt{\lambda_k} A_k \end{bmatrix} x - \begin{bmatrix} \sqrt{\lambda_1} b_1 \\ \sqrt{\lambda_2} b_2 \\ \vdots \\ \sqrt{\lambda_k} b_k \end{bmatrix} \right\|_2^2$$

$$\Rightarrow \min_x J = \min_{x \in \mathbb{R}^n} \| \tilde{A}x - \tilde{b} \|_2^2 \quad \text{where}$$

$$\tilde{A} = \begin{bmatrix} \sqrt{\lambda_1} A_1 \\ \vdots \\ \sqrt{\lambda_k} A_k \end{bmatrix} \in \mathbb{R}^{(m_1 + \dots + m_k) \times n}$$

$$\tilde{b} = \begin{bmatrix} \sqrt{\lambda_1} b_1 \\ \vdots \\ \sqrt{\lambda_k} b_k \end{bmatrix} \in \mathbb{R}^{m_1 + \dots + m_k}$$

If columns of \tilde{A} are linearly independent, we get unique solution \hat{x} as:

$$\hat{x} = (\tilde{A}^T \tilde{A})^{-1} \tilde{A}^T b$$

$$= \begin{pmatrix} [\sqrt{\lambda_1} \vec{A}_1 & \sqrt{\lambda_2} \vec{A}_2 & \dots & \sqrt{\lambda_k} \vec{A}_k] \begin{bmatrix} \sqrt{\lambda_1} A_1 \\ \sqrt{\lambda_2} A_2 \\ \vdots \\ \sqrt{\lambda_k} A_k \end{bmatrix} \end{pmatrix}^{-1} (\sqrt{\lambda_1} A_1^T \sqrt{\lambda_2} A_2^T \dots \sqrt{\lambda_k} A_k^T) \begin{pmatrix} \sqrt{\lambda_1} b_1 \\ \sqrt{\lambda_2} b_2 \\ \vdots \\ \sqrt{\lambda_k} b_k \end{pmatrix}$$

$$\hat{x} = (\lambda_1 A_1^T A_1 + \lambda_2 A_2^T A_2 + \dots + \lambda_k A_k^T A_k)^{-1} (\lambda_1 A_1^T b_1 + \lambda_2 A_2^T b_2 + \dots + \lambda_k A_k^T b_k)$$

Case $k=2$:

$$J = \lambda_1 J_1 + \lambda_2 J_2$$

$$\lambda_1, \lambda_2 > 0$$

$$J = J_1 + \underbrace{\left(\frac{\lambda_2}{\lambda_1}\right)}_{\hat{\lambda}} J_2$$

$$J = J_1 + \lambda J_2 \quad \text{for } \lambda > 0$$

$$\min_{x \in \mathbb{R}^n} J = \min_{x \in \mathbb{R}^n} (J_1 + \lambda J_2)$$

$$\lambda > 0$$

$$J(x, \lambda) = \arg \min_{x \in \mathbb{R}^n} (J_1 + \lambda J_2)$$

$$\text{for } \lambda > 0$$

Ex: $A_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, b_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

$A_2 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}, b_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$J = J_1 + \lambda J_2 = \|A_1 x - b_1\|_2^2 + \lambda \|A_2 x - b_2\|_2^2$

$\hat{x}(\lambda) = (A_1^T A_1 + \lambda A_2^T A_2)^{-1} (A_1^T b_1 + \lambda A_2^T b_2)$

$$\hat{x}(\lambda) = \frac{1}{3\lambda^2 + 4\lambda + 1} \begin{bmatrix} 2\lambda^2 + 4\lambda + 1 \\ 2\lambda^2 + \lambda \end{bmatrix}$$

Inversion Problem / Reconstruction / control design $x \in \mathbb{R}^n$

$$y = Ax + \eta$$

$$J_1 + \lambda J_2$$

$$J_1: \|y - Ax\|_2^2$$

Additionally (prior knowledge)

$$\text{i) } J_2 = \|x\|_2^2$$

$$\text{ii) } J_2 = \|x - x^{\text{prior}}\|_2^2$$

$$\text{iii) } J_2 = \|Dx\|_2^2 \quad \text{where}$$

$$D = \begin{bmatrix} 1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & 0 & \dots & 0 \\ & & \ddots & \ddots & \ddots & \\ & & & -1 & 1 \end{bmatrix}_{(n-1) \times n}$$

Consider

$$J = J_1 + \lambda J_2$$

$$\operatorname{argmin}_{x \in \mathbb{R}^n} J = \operatorname{argmin}_{x \in \mathbb{R}^n} (\|Ax - b\|_2^2 + \lambda \|x\|_2^2)$$

$$\hat{x} = (A^T A + \lambda I)^{-1} (A^T b)$$