Neural Collaborative Filtering

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Abstract

In this paper, we are looking at how neural networks can be used in collaborative filtering to improve recommendation systems. The current standard for models used in recommendation systems with collaborative filtering uses the inner product to associate users and items but these models are linear. Using a neural network would make the model non-linear. To show that it would improve the recommendation system, we compare the inner product model with the neural network model and by the end of this paper, we will show that using a neural network is better then the inner dot product.

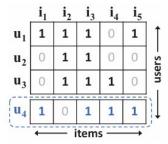
Background

Collaborative filtering is a method used in recommendation systems to suggest items to users based on the preferences and behaviors of other users. Basically assuming that if User A liked something and User B has similar taste to User A then User B will also like something User A liked.

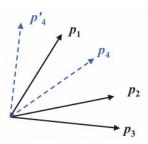
Matrix factorization models are used to discover latent features that explain the patterns in user-item interactions. We basically have a matrix R where rows (m) represent the users and the columns (n) represent the items. We then want to factorize R into two smaller matrices (P) an m*k where each row represents a user and the column represents a latent feature. For the item matrix Qn*k where each row represents an item and each column represents a latent feature of the item. Then the factorization attempts to approximate the matrix R from $P*Q^T$. The latent factors or hidden features are the things which get learned that explain the observed interaction between users and items.

Once the latent features are learned the dot product is used to predict (rank) the rating of between the users and items. Where the interaction between a user and an item can be estimated by measuring how well the latent feature vectors for that user and that item match or align with each other (the dot product). When there is a high dot product it means that the latent features for a user and an item align well, while a low dot product means that the vectors do not align.

However using the dot product does have some drawbacks. The dot product assumes that the user-item interactions are linearly dependent on the latent features. If two items are similar, the dot product assumes that the user's preference for both items is simply the sum of their preferences for the individual latent features. The dot product assumes that user preferences can be captured by a single, linear combination of item attributes (represented by the item's latent feature vector).



(a) user-item matrix



(b) user latent space

Above shows MFs limitation with dot product. From data matrix (a), u_4 is most similar to u_1 , followed by u_3 , and lastly u_2 . Which is the structure within the data meaning. However when we put this into the latent space, by using the dot product it will incorrect model the true ranking. As in the latent space (the arrows), placing p_4 closest to p_1 makes p_4 closer to p_2 than p_3 , which is incorrect.

Model Architecture General model framework of neral collaborative filtering

The GMFModel is an implementation of Generalized Matrix Factorization (GMF) within the Neural Collaborative Filtering (NCF) framework. Matrix Factorization (MF) is a classical technique in recommendation systems where user and item interactions are modeled by the dot product of their respective latent vectors. In GMF, the core operation is the element-wise product of the user and item embeddings, which generalizes the dot product used in MF. This interaction term is then combined with additional features such as episodes, type, and genre, and passed through a neural network for prediction.

The model defines **user** and **item embeddings** using PyTorch's **nn.Embedding**, where each user and item has a learned vector representation. These embeddings are multiplied element-wise to model the interaction between users and items. The resulting interaction vector is concatenated with other input features (episodes, type, genre) and fed through a fully connected layer followed by a **sigmoid activation** to predict a probability (e.g., whether a user will like an anime or not).

By using the **sigmoid function** in the output layer, GMF can be interpreted as a probabilistic model, suitable for tasks such as rating prediction or binary classification. If we were to use a **linear activation** and restrict the interaction term to a simple dot product, the model would recover the standard MF approach. GMF generalizes MF by allowing for **non-linear interactions** and by incorporating additional features, making it more expressive and flexible than traditional matrix factorization.

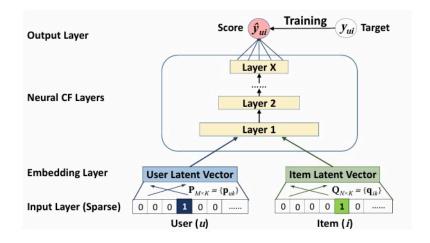


Figure 2: General overview of a model in this framework

```
import torch
from torch import nn

class GMFModel(torch.nn.Module):
    def __init__(self, uid_count, animeid_count, genre_count, latent_dim_len):
        super(GMFModel, self).__init__()
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
        self.uid_count = uid_count
        self.animeid_count = animeid_count
        self.genre_count = genre_count
        self.latent dim len = latent dim len
```

```
self.uid_embedding = nn.Embedding(num_embeddings=self.uid_count,
     embedding dim=self.latent dim len)
    self.animeid embedding = nn.Embedding(num embeddings=self.animeid count,
     embedding_dim=self.latent_dim_len)
    self.uid embedding.to(device)
    self.animeid embedding.to(device)
    self.dropout = nn.Dropout(0.3)
    input_dim = self.latent_dim_len + 2 + self.genre_count
   # Output Layer
    self.output_layer = nn.Sequential(
        nn.Linear(in features=input dim, out features=1),
        nn.Sigmoid())
   # Initialize weights
    self.apply(self.init weights)
def forward(self, uid_index, animeid_index, episodes, type, genre):
    # Get user and item embeddings
   uid_e = self.uid_embedding(uid_index)
    animeid e = self.animeid embedding(animeid index)
    product = uid e * animeid e
    product = self.dropout(product)
    episodes = episodes.unsqueeze(1)
    type = type.unsqueeze(1)
    genre = genre.squeeze(1)
   # Concatenate all features into one vector
   model input = torch.cat([product, episodes, type, genre], dim=-1)
   # Pass input through the output layer
    score = self.output layer(model input)
    return score.squeeze()
def init_weights(self, m):
    if isinstance(m, nn.Linear):
        nn.init.xavier_normal_(m.weight)
        if m.bias is not None:
            nn.init.zeros (m.bias)
    if isinstance(m, nn.Embedding):
        nn.init.normal_(m.weight, mean=0.0, std=0.01)
```

This code implements a **Multi-Layer Perceptron (MLP)** model for a recommendation system, drawing inspiration from the **Neural Collaborative Filtering (NCF)** framework. In this setup, user and item features are represented by embeddings, which are concatenated with additional features (e.g., episodes, type, and genre) to form a combined input vector. This vector is passed through a series of hidden layers with **ReLU** activations, which learn the interactions between the user and item latent features. This approach contrasts with simpler methods like **GMF**, which only use element-wise products of latent vectors.

The MLP model in the NCF framework emphasizes capturing **non-linear interactions** between user and item features, which is done by using a multi-layer architecture. The model employs a **tower structure**, where the layer size progressively decreases. Dropout layers are used for regularization to prevent overfitting.

One key difference is the **ReLU activation** in the output layer, which constrains the model's predictions to be non-negative. If your task involves predicting ratings (e.g., on a 1–5 scale), you may want to adjust this to a **linear activation** or a **sigmoid/tanh** function, depending on the range of values needed.

```
import torch
from torch import nn
class MLPModel(torch.nn.Module):
    def __init__(self, uid_count, animeid_count, genre_count, latent_dim_len, hidden):
        super(MLPModel, self).__init__()
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
        self.uid_count = uid_count
        self.animeid count = animeid count
        self.genre count = genre count # Number of one-hot encoded genres
        self.latent dim len = latent dim len
        self.hidden layer = hidden
        # Embedding Layers for user and anime
        self.uid embedding = nn.Embedding(num embeddings=self.uid count,
         embedding dim=self.latent dim len)
        self.animeid_embedding = nn.Embedding(num_embeddings=self.animeid_count,
         embedding_dim=self.latent_dim_len)
        self.uid_embedding.to(device)
        self.animeid_embedding.to(device)
        self.layers = nn.ModuleList()
        # Combine user, item, and non-embedding features
        input dim = self.latent dim len * 2 + 2 + self.genre count
        # Hidden layers with ReLU activation, from paper
        for dim in self.hidden layer:
            self.layers.append(nn.Linear(in_features=input_dim, out_features=dim))
            self.layers.append(nn.ReLU())
            self.layers.append(nn.Dropout(0.3))
            input dim = dim
        # Output layer with ReLU activation
        self.output layer = nn.Sequential(
            nn.Linear(in_features=self.hidden_layer[-1], out_features=1),
            nn.ReLU())
        self.apply(self.init_weights)
    def forward(self, uid_index, animeid_index, episodes, type, genre):
        uid e = self.uid embedding(uid index)
        animeid e = self.animeid embedding(animeid index)
        episodes = episodes.unsqueeze(1)
        type = type.unsqueeze(1)
        model_input = torch.cat([uid_e, animeid_e, episodes, type, genre], dim=-1)
        # Pass input through hidden layers
        for hidden layer in self.layers:
           model_input = hidden_layer(model_input)
        # Compute final output score
        score = self.output_layer(model_input)
        return score.squeeze()
    def init_weights(self, m):
        if isinstance(m, nn.Linear):
            nn.init.xavier normal (m.weight)
            if m.bias is not None:
                nn.init.zeros_(m.bias)
```

```
if isinstance(m, nn.Embedding):
    nn.init.normal_(m.weight, mean=0.0, std=0.01)
```

In this implementation of the **Neural Matrix Factorization (NeuMF)** model, the goal is to combine two types of models—**Generalized Matrix Factorization (GMF)** and **Multi-Layer Perceptron (MLP)**—to capture both linear and non-linear interactions between users and items, providing a more powerful recommendation system.

The **GMF** component of the model applies a linear kernel to model the latent feature interactions between users and items. Specifically, it computes the dot product of user and item embeddings to capture linear relationships. In this part of the model, each user and item is represented by a latent vector, and their interaction is modeled as the element-wise multiplication of these vectors. This approach is simple but effective for modeling linear patterns in the data.

On the other hand, the MLP component of the NeuMF model uses a deep neural network to learn non-linear interactions between the user and item embeddings. This part of the model is more flexible and capable of learning complex patterns that the GMF component might miss. The MLP uses multiple layers of fully connected neurons with activation functions (typically ReLU) and regularization (like dropout) to model non-linear relationships in the user-item interaction.

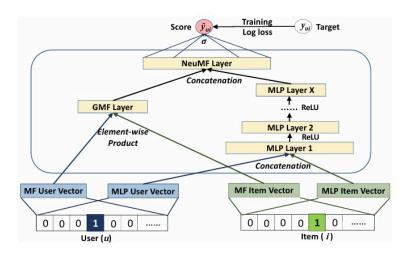
Rather than forcing the GMF and MLP to share the same embeddings, which could limit the model's ability to learn the best representations, the NeuMF model allows the GMF and MLP components to have separate embeddings. This flexibility helps the model learn more effective representations, especially in cases where the optimal latent dimension for the GMF and MLP components might differ. The outputs of these two models are then combined by concatenating their respective outputs and passing them through a final layer to produce the predicted interaction score. This fusion of the two models effectively leverages both the linear nature of GMF and the non-linear nature of MLP, giving the NeuMF model a powerful ability to capture complex user-item interactions.

To improve the training of the NeuMF model and overcome the challenge of local optima in non-convex optimization problems, the model is pre-trained using separate GMF and MLP models. These models are trained independently on the dataset first, using random initialization and an optimization method such as Adam. After these models converge, their learned parameters (embeddings and weights) are transferred into the NeuMF model. This pre-training strategy provides a better starting point for the NeuMF model, allowing it to converge more quickly and perform better during fine-tuning. In particular, the embeddings for the GMF and MLP components are initialized with the pre-trained values, and the final fusion layer's weights are adjusted to control the trade-off between the GMF and MLP outputs.

Once the pre-training is complete, the NeuMF model is trained using **stochastic gradient descent (SGD)**, as opposed to Adam, because the latter relies on momentum, which is not suitable when we are using pre-trained weights. SGD is more appropriate for fine-tuning the model after the initial embeddings have been loaded, as it allows for more stable updates without relying on momentum.

This approach of combining GMF and MLP in the NeuMF framework, along with the pre-training strategy, allows the model to benefit from both the simplicity and interpretability of GMF's linear interactions and the flexibility of MLP's non-linear learning. By fusing the strengths of both models and leveraging pre-trained embeddings, the NeuMF model can better capture complex relationships between users and items, leading to more accurate predictions in recommendation systems.

Model Training



```
import torch
from torch import nn
class NeuMFModel(torch.nn.Module):
    def __init__(self, uid_count, animeid_count, genre_count, latent_dim_len, hidden):
        super(NeuMFModel, self). init ()
        device = torch.device("cuda" if torch.cuda.is available() else "cpu")
        self.uid_count = uid_count
        self.animeid_count = animeid_count
        self.genre_count = genre_count # Number of one-hot encoded genres
        self.latent_dim_len = latent_dim_len
        self.hidden_layer = hidden
        # Embedding layers for user and anime
        self.uid_embedding_gmf = nn.Embedding(num_embeddings=self.uid_count,
         embedding_dim=self.latent_dim_len)
        self.animeid_embedding_gmf = nn.Embedding(num_embeddings=self.animeid_count,
         embedding_dim=self.latent_dim_len)
        self.uid_embedding_mlp = nn.Embedding(num_embeddings=self.uid_count,
         embedding_dim=self.latent_dim_len)
        self.animeid_embedding_mlp = nn.Embedding(num_embeddings=self.animeid_count,
         embedding_dim=self.latent_dim_len)
        # Define the layers of the MLP
        self.layers = nn.ModuleList()
        # Combine user, item, and non-embedding features
        input_dim = self.latent_dim_len * 2 + 2 + self.genre_count
        for dim in self.hidden layer:
            self.layers.append(nn.Linear(in_features=input_dim, out_features=dim))
            self.layers.append(nn.ReLU())
            self.layers.append(nn.Dropout(0.3))
            input dim = dim
        # Output Layer
        self.output layer = nn.Sequential(
            nn.Linear(in_features=self.hidden_layer[-1] + self.latent_dim_len, out_features=1),
            nn.Sigmoid())
        # Initialize weights
        self.apply(self.init weights)
    def forward(self, uid_index, animeid_index, episodes, type, genre):
        # Get user and item embeddings
        uid_mlp = self.uid_embedding_mlp(uid_index)
        animeid mlp = self.animeid embedding mlp(animeid index)
        uid_gmf = self.uid_embedding_gmf(uid_index)
        animeid_gmf = self.animeid_embedding_gmf(animeid_index)
        episodes = episodes.unsqueeze(1) # (batch size, 1)
        type = type.unsqueeze(1)
        # Concatenate all features into one vector
        model_input = torch.cat([uid_mlp, animeid_mlp, episodes, type, genre], dim=-1)
        product = torch.mul(uid_gmf, animeid_gmf)
        # Pass input through hidden layers
        for hidden layer in self.layers:
```

```
model input = hidden layer(model input)
        product = torch.nn.ReLU()(product)
   # Compute final output score (prediction)
   vector = torch.cat([model_input, product], dim=-1)
    score = self.output layer(vector)
   return score.squeeze()
def init weights(self, m):
   if isinstance(m, nn.Linear):
        nn.init.xavier normal (m.weight)
        if m.bias is not None:
            nn.init.zeros (m.bias)
    if isinstance(m, nn.Embedding):
        nn.init.normal_(m.weight, mean=0.0, std=0.01)
def pretrain_loader(self):
   mlp model = MLPModel(uid count=uid count,
                     animeid count=animeid count,
                     genre_count=genre_count,
                     latent dim len=latent dim len,
                     hidden=hidden layers)
    gmf_model = GMFModel(uid_count=uid_count,
                     animeid_count=animeid_count,
                     genre count=genre count,
                     latent dim len=latent dim len)
   # Move models to GPU
   mlp model.cuda()
    gmf_model.cuda()
   # Load the weights from pre-trained models
   mlp_model.load_state_dict(torch.load('models/mlp_model.pth'))
    gmf_model.load_state_dict(torch.load('models/gmf_model.pth'))
   # Load the embedding layers from the MLP and GMF models into NeuMF
   self.uid_embedding_mlp.weight.data = mlp_model.uid_embedding.weight.data
    self.animeid_embedding_mlp.weight.data = mlp_model.animeid_embedding.weight.data
    self.uid_embedding_gmf.weight.data = gmf_model.uid_embedding.weight.data
    self.animeid_embedding_gmf.weight.data = gmf_model.animeid_embedding.weight.data
   # Load the MLP hidden layers' weights into the NeuMF model
    for i in range(len(self.layers)):
        if isinstance(self.layers[i], nn.Linear):
            # Only load weights for Linear layers
            self.layers[i].weight.data = mlp model.layers[i].weight.data
            self.layers[i].bias.data = mlp_model.layers[i].bias.data
```

This Python code defines the AnimeData class for preparing and processing anime and user rating data using the scikit-learn, pandas, and torch libraries. The init method initializes the class with the input datasets, encodes categorical data using LabelEncoder and MultiLabelBinarizer, and merges user ratings with anime information. The processed data includes one-hot encoded genres and numerical mappings for IDs, names, and types. The process method encodes the input features, while __len__ and __getitem__ provide data access and indexing. The get_loaders method splits the dataset into training and test sets, converts them into PyTorch tensors, and organizes them into DataLoader objects for batch processing during model training and evaluation.

Minimal CPU-Ready Working Example

```
from sklearn.preprocessing import LabelEncoder, MultiLabelBinarizer
import pandas as pd
import torch
from torch.utils.data import DataLoader, TensorDataset
class AnimeData(object):
    def __init__(self, ratings, anime):
        self.ratings = ratings
        self.anime = anime
        encoder = LabelEncoder()
        # Remove data where user did not rate anime
        self.ratings = self.ratings.loc[self.ratings.iloc[:, 2] != -1]
        # Remove overall members and rating -> not needed
        self.anime.drop(['members', 'rating'], axis=1, inplace=True)
        # anime_id,name,genre,type,episodes,rating,members
        # user_id, anime_id, rating
        # Encode the IDs to an integer mapping for embedding
        self.ratings['user_id'] = self.ratings['user_id'].astype("category").cat.codes
        self.ratings['anime_id'] = self.ratings['anime_id'].astype("category").cat.codes
        self.anime['anime_id'] = self.anime['anime_id'].astype("category").cat.codes
        self.anime = self.anime[self.anime['episodes'] != 'Unknown']
        # Encode the name and type
        self.anime['name'] = encoder.fit transform(self.anime['name'])
        self.name_map = dict(zip(encoder.classes_, encoder.transform(encoder.classes_)))
        self.anime['type'] = encoder.fit_transform(self.anime['type'])
        self.type_map = dict(zip(encoder.classes_, encoder.transform(encoder.classes_)))
        # One hot encode the genres
        self.anime['genre'] = self.anime['genre'].str.split(', ')
        bin = MultiLabelBinarizer()
        onehot = bin.fit transform(self.anime['genre'])
        dfs = pd.DataFrame(onehot, columns=bin.classes_)
        self.anime.drop('genre', axis=1, inplace=True)
        self.anime.reset index(drop=True, inplace=True)
        dfs.reset_index(drop=True, inplace=True)
        self.genre = dfs
        self.anime = pd.concat([self.anime, dfs], axis=1)
        # Merge user and anime data into single dataset
        self.data = self.ratings.merge(self.anime, on='anime_id', how='left')
        self.data['rating'] = self.data['rating'] / 10
        self.data['episodes'] = self.data['episodes'].astype('int64')
        self.features = self.data[['user_id', 'anime_id', 'type', 'episodes']+
        list(self.genre.columns)]
        self.target = self.data['rating']
        self.genre_cols = self.features.columns[5:]
    def process(self, item):
        # Encode the type and name
        tid = self.type map[item[2]] # "TV" -> Encoded type using `type map`
        #name = self.name_map[item[3]] # Anime name -> Encoded name using `name_map`, unused
        # One-hot encode the genres
        genre_encoded = [1 if genre in item[5].split(", ") else 0 for genre in self.genre_cols]
```

```
# Combine all the features into a single list
    dfn = [item[0], # anime_id
          item[1], # user_id
                   # Encoded type
          item[4]] # episodes
    dfn += genre_encoded # Append the genre encoding
   # Return as a Pandas Series (1D array)
    cols = ['user id', 'anime id', 'type', 'episodes'] + list(self.genre.columns)
   return pd.Series(dfn, index=cols)
def __len__(self):
   return len(self.features)
def __getitem__(self, item):
   x = self.features[item]
   y = self.target[item]
   if self.transform:
       x = self.transform(x)
   return x, y
def get loaders(self):
   train, test = train_test_split(self.data, test_size=0.2)
    train_user_item = torch.tensor(train[self.features.columns].values, dtype=torch.long)
   train labels = torch.tensor(train['rating'].values, dtype=torch.float32)
    test user item = torch.tensor(test[self.features.columns].values, dtype=torch.long)
    test labels = torch.tensor(test['rating'].values, dtype=torch.float32)
    train_set = TensorDataset(train_user_item[:, 0], # user_id
                              train_user_item[:, 1], # anime_id
                              train_user_item[:, 2], # type
                              train user item[:, 3], # episodes
                              train_user_item[:, 4:], # genres
                              train labels)
    test_set = TensorDataset(test_user_item[:, 0], # user_id
                             test_user_item[:, 1], # anime_id
                              test_user_item[:, 2], # type
                              test_user_item[:, 3], # episodes
                              test_user_item[:, 4:], # genres
                              test labels)
    train = DataLoader(train set, batch size=128, shuffle=True)
    test = DataLoader(test set, batch size=128, shuffle=True)
    return train, test
```

The code implements a recommendation system for anime using collaborative filtering and neural network models in PyTorch, featuring three model architectures: MLP (Multilayer Perceptron), GMF (Generalized Matrix Factorization), and NeuMF (Neural Matrix Factorization). The system begins by loading and cleaning data from two CSV files (anime.csv for anime metadata and rating.csv for user ratings), removing missing values and irrelevant entries. This processed data is then used to train the models. The MLP model is a neural network that learns latent factors through hidden layers, the GMF model uses matrix factorization to focus on collaborative filtering, and the NeuMF model combines both MLP and GMF to leverage the strengths of both approaches. Each model is initialized with key parameters such as user and item counts and latent dimensions. The training process uses the Adam optimizer with MSE loss, running for multiple epochs. During training, evaluation metrics like MAE, RMSE, and R^2 are calculated to track performance on both training and test sets. Device handling ensures that if a GPU is available, it is used to speed up computations.

The output shows that the MLP model demonstrates gradual improvement, but its test loss fluctuates slightly, indicating room for better generalization. Its evaluation metrics ($MAE = 0.1104, RMSE = 0.1386, R^2 = 0.2205$) suggest the model is still underperforming. The GMF model improves on the MLP, with better evaluation metrics

 $(MAE=0.0909,RMSE=0.1201,R^2=0.4143)$, indicating it captures user-item interactions more effectively. The NeuMF model, a hybrid of MLP and GMF, outperforms both, with the best evaluation results $(MAE=0.0870,RMSE=0.1151,R^2=0.4624)$, demonstrating the power of combining neural networks with matrix factorization. Insights from the results show that while the training loss decreases steadily, the fluctuating test loss suggests potential overfitting, pointing to the need for further regularization and tuning. The improvement in R^2 across models, especially with NeuMF, underscores the value of hybrid approaches in capturing complex user-item relationships. To optimize performance, hyperparameter tuning, regularization techniques like dropout, and using more advanced methods like cross-validation or embedding layers could further enhance the system. In conclusion, the code successfully trains and evaluates three recommendation models, with the NeuMF model performing the best, offering a promising foundation for further optimization and refinement.

```
import pandas as pd
#from mlp import MLPModel
#from gmf import GMFModel
from torch import nn
import torch
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
df1 = pd.read csv('data/anime.csv')
df2 = pd.read_csv('data/rating.csv')
df2 = df2[:1000000]
df1.dropna(inplace=True)
df2.dropna(inplace=True)
df2 = df2.loc[df2.iloc[:, 2] != -1]
df1 = df1[df1['episodes'] != 'Unknown']
handler = AnimeData(df2, df1)
uid_count = len(handler.ratings['user_id'].unique()) # Number of unique users
animeid count = len(handler.anime['anime id'].unique()) # Number of unique anime
genre_count = 43 # Number of one-hot encoded genre categories
latent_dim_len = 50 # Latent dimension Length for embeddings
hidden_layers = [128, 64, 32, 16] # Example hidden layers for MLP
# Initialize the MLP model
mlp model = MLPModel(uid count=uid count,
                 animeid count=animeid count,
                 genre_count=genre_count,
                 latent dim len=latent dim len,
                 hidden=hidden_layers)
gmf model = GMFModel(uid count=uid count,
                 animeid count=animeid count,
                 genre count=genre count,
                 latent_dim_len=latent_dim_len)
neumf_model = NeuMFModel(uid_count=uid_count,
                 animeid_count=animeid_count,
                 genre count=genre count,
                 latent_dim_len=latent_dim_len,
                 hidden=hidden layers)
gmf_model.to(device)
mlp model.to(device)
neumf_model.to(device)
a, b = handler.get_loaders()
loss_function = nn.MSELoss()
gmfo = torch.optim.Adam(gmf model.parameters(), lr=0.0001)
```

```
mlpo = torch.optim.Adam(mlp model.parameters(), lr=0.0001)
nfmo = torch.optim.SGD(neumf model.parameters(), lr=0.0001, momentum=0.9)
def run_and_eval(a, b, model, opt, lr=0.001, epochs=10):
    optimizer = opt
    loss_function = nn .MSELoss()
    model.train()
    for i in range(epochs):
       model.train()
        total loss = 0
        for user, anime, type, episodes, genre, labels in a:
            user, anime = user.to(device), anime.to(device)
            episodes, type, genre = episodes.to(device), type.to(device), genre.to(device)
           labels = labels.to(device)
           optimizer.zero grad()
            pred = model(user, anime, episodes, type, genre)
           loss = loss function(pred, labels)
           loss.backward()
           optimizer.step()
            total_loss += loss.item()
        print(f"Epoch [{i + 1}/{10}], Loss: {total_loss / len(a)}")
        model.eval() # Set the model to evaluation mode
        total loss = 0
        total samples = 0
        all_predictions = []
        all labels = []
        with torch.no_grad(): # Disable gradient calculation
            for user, anime, type, episodes, genre, labels in b:
                user, anime = user.to(device), anime.to(device)
                episodes, type, genre = episodes.to(device), type.to(device), genre.to(device)
                labels = labels.to(device)
                # Get model predictions
                pred = model(user, anime, episodes, type, genre)
                # Calculate the loss (e.g., MSE loss)
                loss = loss_function(pred, labels)
                total_loss += loss.item() * len(labels) # Accumulate loss
                total_samples += len(labels) # Accumulate the number of samples
                # Store predictions and actual values
                all predictions.extend(pred.cpu().numpy())
                all_labels.extend(labels.cpu().numpy())
        # Calculate average loss
        avg_loss = total_loss / total_samples
        print(f"Test Loss [{i+1}/10]: {avg_loss}")
    # Additional Metrics
    from sklearn.metrics import mean_absolute_error, mean_squared_error, r2_score
   mae = mean_absolute_error(all_labels, all_predictions)
   mse = mean_squared_error(all_labels, all_predictions)
    rmse = mse ** 0.5
   r2 = r2_score(all_labels, all_predictions)
    print(f"Test MAE: {mae:.4f}")
    print(f"Test RMSE: {rmse:.4f}")
    print(f"$R^2$ Score: {r2:.4f}")
```

```
run_and_eval(a, b, mlp_model, mlpo, lr=0.0001, epochs=10)
#torch.save(mlp_model.state_dict(), 'mlp_model.pth')
print()
run_and_eval(a, b, gmf_model, gmfo, lr=0.0001, epochs=10)
#torch.save(gmf_model.state_dict(), 'gmf_model.pth')

neumf_model.pretrain_loader()
run_and_eval(a, b, neumf_model, nfmo, lr=0.0001, epochs=10)
torch.save(neumf_model.state_dict(), 'neumf_model.pth')

Results:

Using device: cuda
Epoch [1/10], Loss: 3.6950174334295
Test Loss [1/10]: 0.157952371776796
Epoch [2/10], Loss: 0.11668900996973773
Test Loss [2/10]: 0.03814665263147855
Epoch [3/10], Loss: 0.040147326586463444
Test Loss [3/10]: 0.02276981720777128
```

Test Loss [3/10]: 0.022276981720272128 Epoch [4/10], Loss: 0.022898902423949267 Test Loss [4/10]: 0.0206319713626718 Epoch [5/10], Loss: 0.019955833869365353 Test Loss [5/10]: 0.020516480288159767 Epoch [6/10], Loss: 0.018866505908579186 Test Loss [6/10]: 0.020635879038299828 Epoch [7/10], Loss: 0.01828422652079384 Test Loss [7/10]: 0.02011084193172132 Epoch [8/10], Loss: 0.017863553787622624 Test Loss [8/10]: 0.019992064000603074 Epoch [9/10], Loss: 0.0176579500614437 Test Loss [9/10]: 0.020253627192886033 Epoch [10/10], Loss: 0.017454158246397105 Test Loss [10/10]: 0.019198449493947483 Test MAE: 0.1104 Test RMSE: 0.1386 \$R^2\$ Score: 0.2205 Epoch [1/10], Loss: 0.04003728575764353 Test Loss [1/10]: 0.028299097051615502 Epoch [2/10], Loss: 0.025533486508182983 Test Loss [2/10]: 0.022891827709723422 Epoch [3/10], Loss: 0.021175410911702965 Test Loss [3/10]: 0.019831051891316644 Epoch [4/10], Loss: 0.018362480420187267 Test Loss [4/10]: 0.017628081791847532 Epoch [5/10], Loss: 0.016429371527416643 Test Loss [5/10]: 0.01631068073150627 Epoch [6/10], Loss: 0.015305056382203475 Test Loss [6/10]: 0.015574246103732257 Epoch [7/10], Loss: 0.01463160192022472 Test Loss [7/10]: 0.015128253192493068 Epoch [8/10], Loss: 0.014160454717286095 Test Loss [8/10]: 0.014841098104719667 Epoch [9/10], Loss: 0.013809964230738773 Test Loss [9/10]: 0.014603769124104361 Epoch [10/10], Loss: 0.013505750678043297 Test Loss [10/10]: 0.014424409991700846 Test MAE: 0.0909 Test RMSE: 0.1201 \$R^2\$ Score: 0.4143 Epoch [1/10], Loss: 0.027678686989260452 Test Loss [1/10]: 0.014772928314505123

Epoch [2/10], Loss: 0.01634571377412012 Test Loss [2/10]: 0.014307665699783177

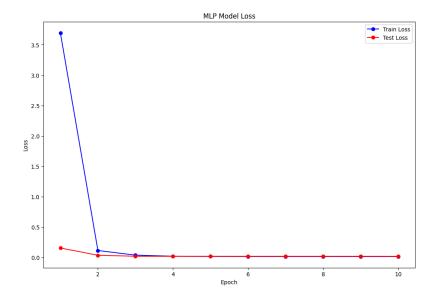
```
Epoch [3/10], Loss: 0.014723368335014456
Test Loss [3/10]: 0.01403033738548863
Epoch [4/10], Loss: 0.01394584908455086
Test Loss [4/10]: 0.013758254560114869
Epoch [5/10], Loss: 0.01346005102425137
Test Loss [5/10]: 0.013632847206995794
Epoch [6/10], Loss: 0.013093187849867632
Test Loss [6/10]: 0.013532563343907766
Epoch [7/10], Loss: 0.012803735120885321
Test Loss [7/10]: 0.013445049989493694
Epoch [8/10], Loss: 0.01252872828114485
Test Loss [8/10]: 0.013395482611195579
Epoch [9/10], Loss: 0.012248591937687769
Test Loss [9/10]: 0.013305518026749452
Epoch [10/10], Loss: 0.011973678431735057
Test Loss [10/10]: 0.013241319170093422
Test MAE: 0.0870
Test RMSE: 0.1151
$R^2$ Score: 0.4624
```

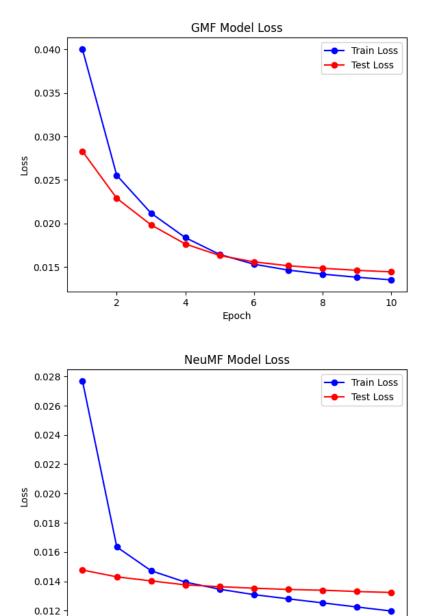
This code uses Matplotlib to plot the training and test losses over 10 epochs for three different models: MLP, GMF, and NeuMF. It initializes lists for the training and test losses of each model, then creates separate plots for each model, showing how losses change across epochs. Blue markers represent training loss while red markers indicate test loss. Each plot is labeled with the respective model name, and axes are labeled for clarity. These plots help visualize and compare the performance and convergence of the models, highlighting how well each one learns and generalizes over time. This detailed analysis aids in understanding the training progress and the effectiveness of each model in reducing loss.

```
import matplotlib.pyplot as plt
# MLP model data
mlp train loss = [3.6950174334295, 0.11668900996973773, 0.040147326586463444, 0.022898902423949267,
         0.019955833869365353,
                  0.018866505908579186, 0.01828422652079384, 0.017863553787622624,
         0.0176579500614437, 0.017454158246397105]
mlp test loss = [0.157952371776796, 0.03814665263147855, 0.022276981720272128, 0.0206319713626718,
         0.020516480288159767,
                 0.020635879038299828, 0.02011084193172132, 0.019992064000603074,
         0.020253627192886033, 0.019198449493947483]
# GMF model data
gmf train loss = [0.04003728575764353, 0.025533486508182983, 0.021175410911702965,
         0.018362480420187267, 0.016429371527416643,
                  0.015305056382203475, 0.01463160192022472, 0.014160454717286095,
         0.013809964230738773, 0.0135057506780432971
gmf test loss = [0.028299097051615502, 0.022891827709723422, 0.019831051891316644,
         0.017628081791847532, 0.01631068073150627,
                 0.015574246103732257, 0.015128253192493068, 0.014841098104719667,
         0.014603769124104361, 0.014424409991700846]
# NeuMF model data
neumf train loss = [0.027678686989260452, 0.01634571377412012, 0.014723368335014456,
         0.01394584908455086, 0.01346005102425137,
                    0.013093187849867632, 0.012803735120885321, 0.01252872828114485,
         0.012248591937687769, 0.011973678431735057]
neumf test loss = [0.014772928314505123, 0.014307665699783177, 0.01403033738548863,
         0.013758254560114869, 0.013632847206995794,
                   0.013532563343907766, 0.013445049989493694, 0.013395482611195579,
         0.013305518026749452, 0.013241319170093422]
# Plotting the losses
plt.figure(figsize=(12, 8))
# MLP model loss
```

```
plt.plot(range(1, 11), mlp_train_loss, label="Train Loss", color='blue', marker='o')
plt.plot(range(1, 11), mlp_test_loss, label="Test Loss", color='red', marker='o')
plt.title("MLP Model Loss")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()
plt.show()
# GMF model loss
plt.plot(range(1, 11), gmf_train_loss, label="Train Loss", color='blue', marker='o')
plt.plot(range(1, 11), gmf_test_loss, label="Test Loss", color='red', marker='o')
plt.title("GMF Model Loss")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()
plt.show()
# NeuMF model loss
plt.plot(range(1, 11), neumf_train_loss, label="Train Loss", color='blue', marker='o')
plt.plot(range(1, 11), neumf_test_loss, label="Test Loss", color='red', marker='o')
plt.title("NeuMF Model Loss")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()
plt.show()
```

Results:





The results for three models —MLP, GMF, and NeuMF— are presented over 10 epochs, showcasing their training, testing, and performance metrics. The MLP Model shows significant learning, with training loss decreasing from 3.6950 in the first epoch to 0.0175 in the tenth epoch. However, its test loss fluctuates slightly, starting at 0.1580 and ending at 0.0192. Its performance metrics are moderate, with a Test Mean Absolute Error (MAE) of 0.1104, Test Root Mean Squared Error (RMSE) of 0.1386, and an R^2 Score of 0.2205. The GMF Model, which uses Generalized Matrix Factorization, demonstrates more effective convergence, with training loss decreasing from 0.0400 to 0.0135 by the tenth epoch. Its test loss improves from 0.0283 to 0.0144. Performance metrics for GMF show a Test MAE of 0.0909, Test RMSE of 0.1201, and an R^2 Score of 0.4143, indicating better performance than the MLP Model. The NeuMF Model, based on Neural Matrix Factorization, outperforms the other two models. Its training loss decreases from 0.0277 to 0.0120, while test loss decreases slightly from 0.0148 to 0.0132. NeuMF's performance metrics include the lowest Test MAE (0.0870), Test RMSE (0.1151), and the highest R^2 Score (0.4624), indicating the best overall performance. In summary, while the MLP Model shows significant learning, it exhibits moderate performance. The GMF Model demonstrates better performance with effective convergence and lower test loss than the MLP. However, the NeuMF Model achieves the best results, with the lowest test loss, MAE, RMSE, and the highest R^2 Score, making it the most effective in capturing user-item interactions among the three models.

4

6

Epoch

8

10

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Discussion

The three models in this paper —MLP, GMF, and NeuMF— compared to the basic matrix factorization (that uses inner dot product) have better accuracy but these models are still simple and limited in scope. These models can be expanded upon by making it able to handle auxillary data such as current trends, personal reviews, and others. It could also improve accuracy further when compined with current matrix factorization models.

References

- [1] He, X., Liao, L., Zhang, H., Nie, L., Hu, X., & Chua, T. S. (2017, April). Neural collaborative filtering. In *Proceedings of the 26th international conference on world wide web* (pp. 173-182).
- [2] Koren, Y., Bell, R., & Volinsky, C. (2009). Matrix factorization techniques for recommender systems. *Computer*, 42(8), 30-37.