

Problem Solving as Search

CS161

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What is search?

- Basic AI problem
- Long history, active topic
- Basis for games, SAT, advanced reasoning
- Used in many other fields
- UCLA plays key role in history of search 😊
- Graduate CS class offered by Prof. Korf

What is search?

- Structure: Search 'engine'



- Sensitive to
 - problem formulation (today)
 - choice of strategy (next lectures)

Examples

- Puzzles
 - 8-puzzle
 - Missionaries and Cannibals
 - N-Queens
 - Crypto arithmetic
 - Rubik's cube
- Planning
 - Practical industry applications
(e.g., Amazon delivery, Uber route and match, etc.)

How would
you
solve these?

Search Problem Formulation

- Common elements:
 - Initial state
 - Final/goal state or goal test/predicate
 - Actions
 - Transition model/successors
 - (Costs)
- Task: find sequence of actions to move from initial to goal state.
- Optimal solution has lowest cost

Search Problem Formulation

- Notions of state and action are not sharp!
- Design problem: art
- Example: 8-puzzle?



Observations

- States are atomic (no internal structure)
- States are discrete
- No percepts
- Deterministic transitions
- How many unique states? $9! = 362,880$
 $15! = 10^{12}$
- Choice of action space is important
 - Move tile x up, down, left, right?
 - Move blank up, down, left, right?
More elegant, fewer actions!
- Actions may not be applicable to all states

Search Trees

- Example: 8-puzzle?



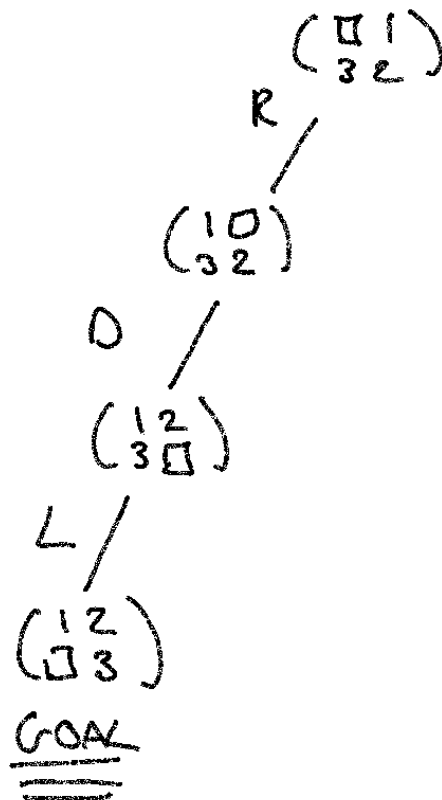
Observations

- Some paths include the goal state
- Solving the search problem is finding such path
- Some paths are infinite (tree infinite)
- Beware: Repeated states
- Different solutions with different qualities
- Search space vs. search tree

Search Trees: Finding Solutions

Initial: $\begin{pmatrix} 1 & 1 \\ 3 & 2 \end{pmatrix}$

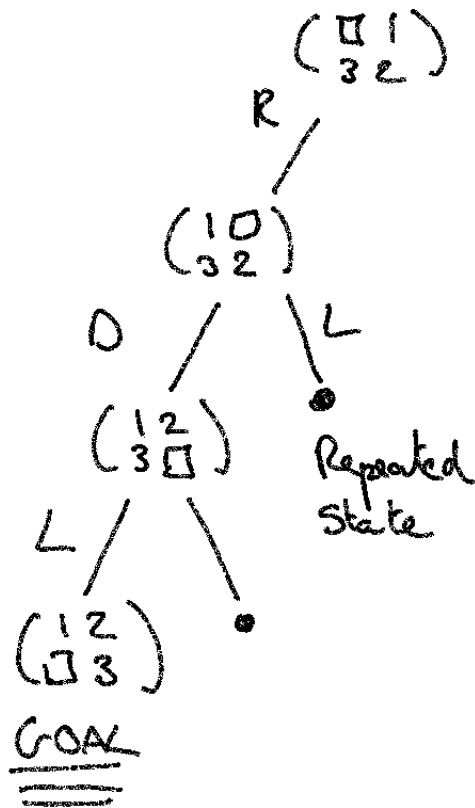
Final $\begin{pmatrix} 1 & 2 \\ 1 & 3 \end{pmatrix}$



Search Trees: Finding Solutions

Initial: $\begin{pmatrix} \square & 1 \\ 3 & 2 \end{pmatrix}$

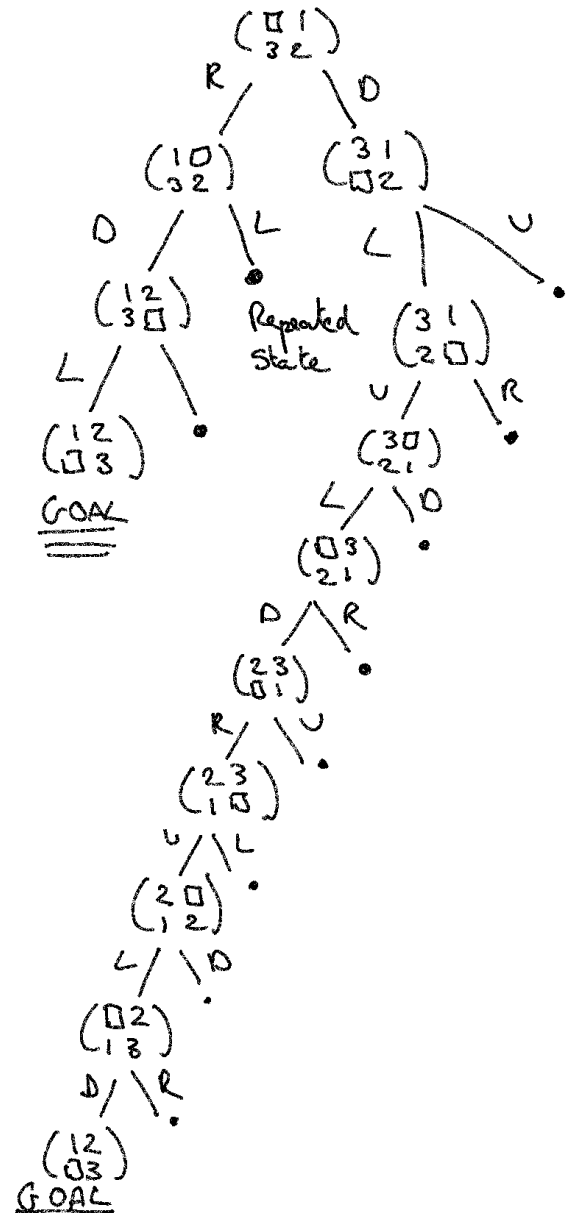
Final $\begin{pmatrix} 1 & 2 \\ \square & 3 \end{pmatrix}$



Search Trees: Finding Solutions

Initial: B1
32

Final 1 2
□ 3



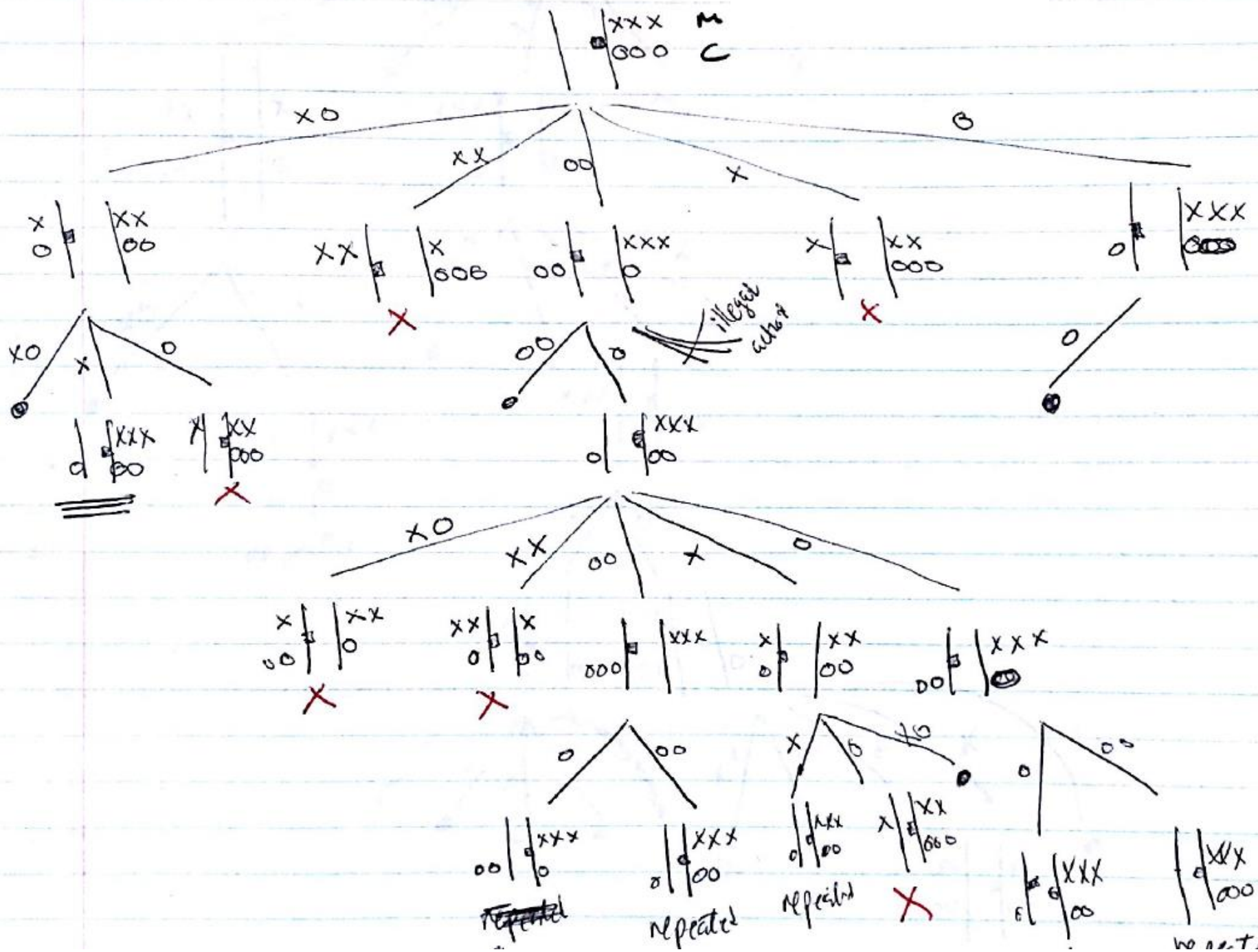
Observations

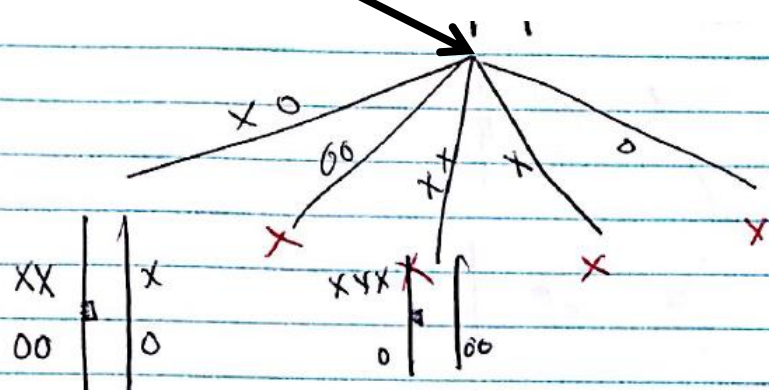
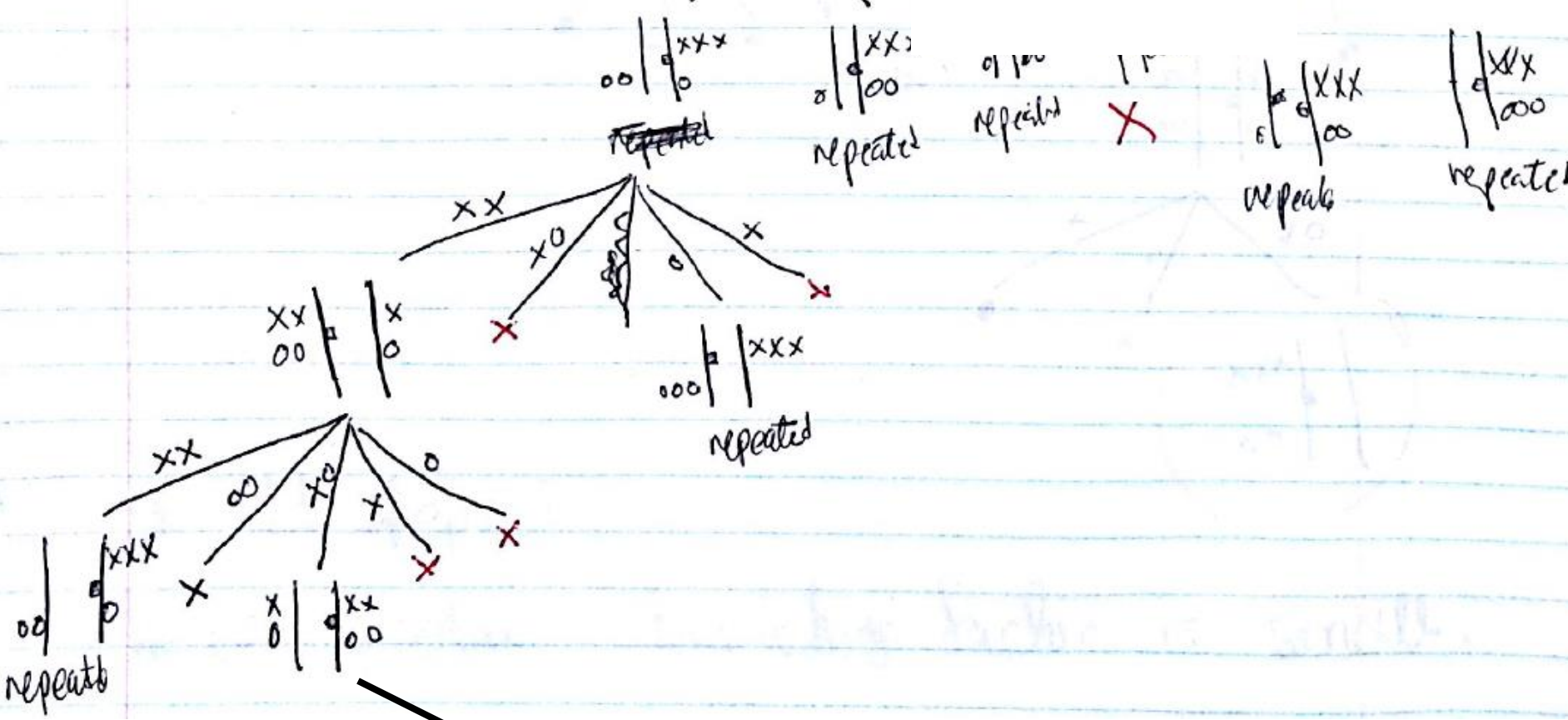
- Avoid repeated states or run into infinite loop
- Two solutions: cost 3 and cost 9
- Difficulty of problem: measured by parameters
 - Number of states
 - Branching factor
 - Solution depth
- 15-puzzle has 1.3 trillion states: few ms to solve
- 24-puzzle has 10^{25} states: one day to solve
- Solving sliding block puzzles is NP-complete!

Search Trees: Finding Solutions

- Example: Missionaries and Cannibals?

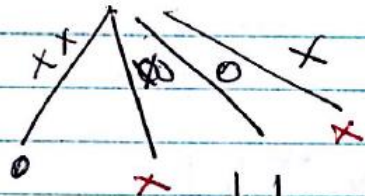
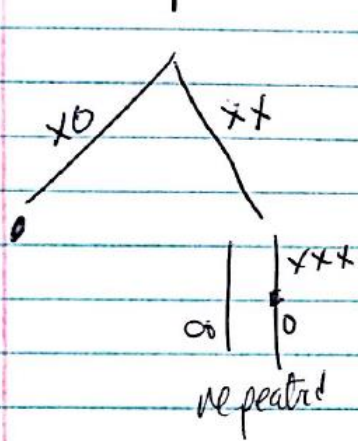




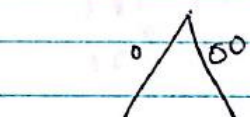


XX	X
00	0

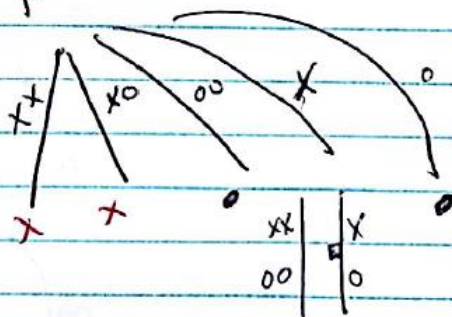
XYX	X
0	00



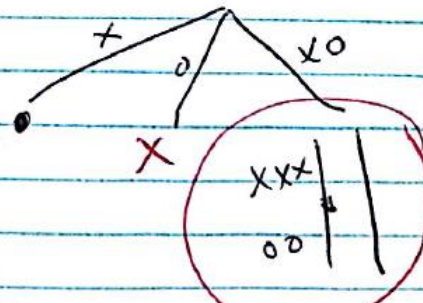
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000	



XXX	XYX	0
0	00	00



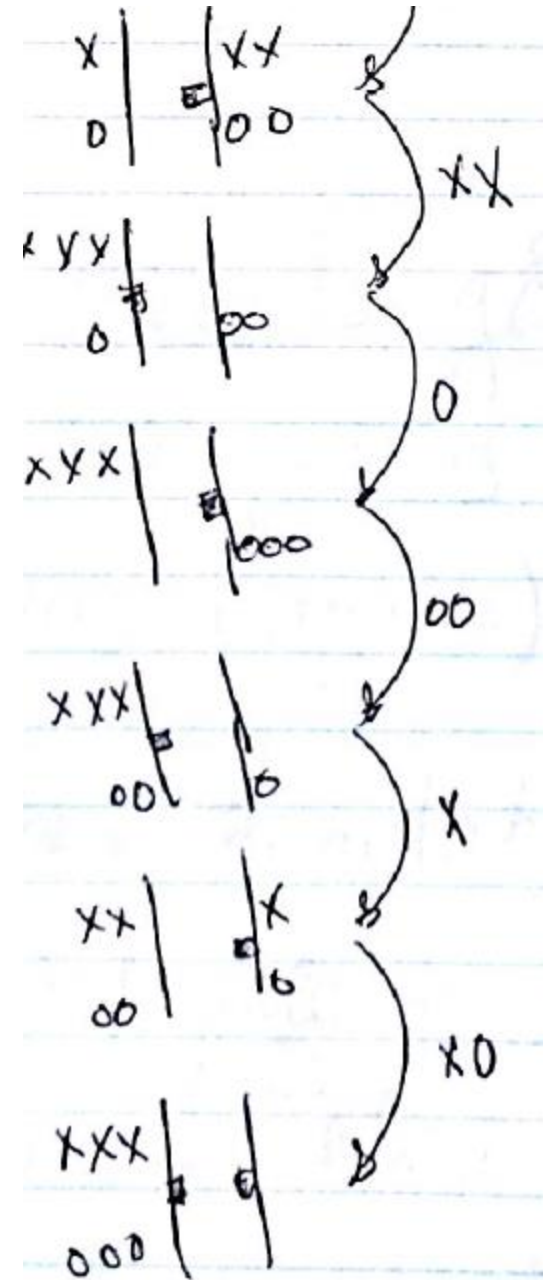
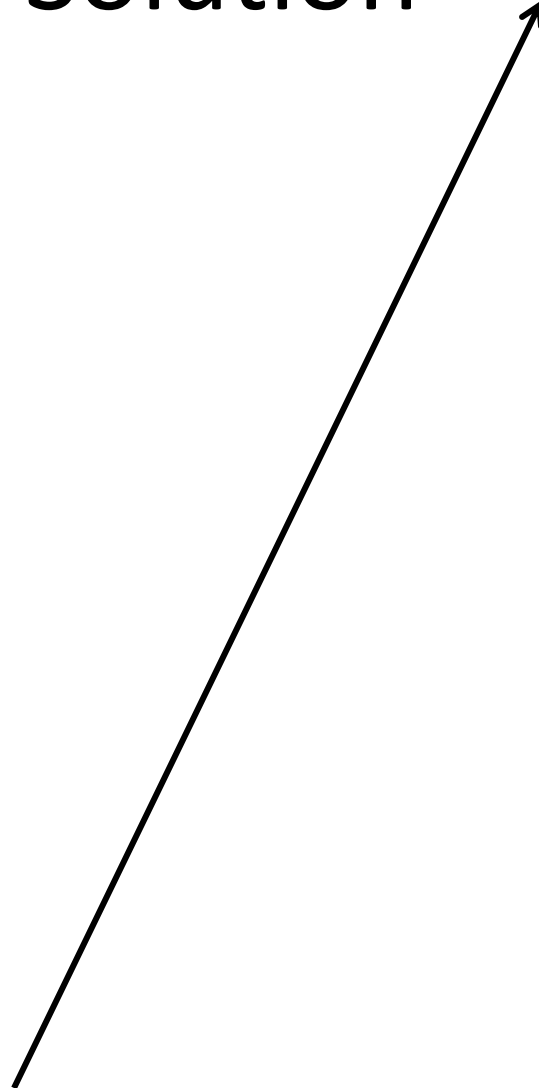
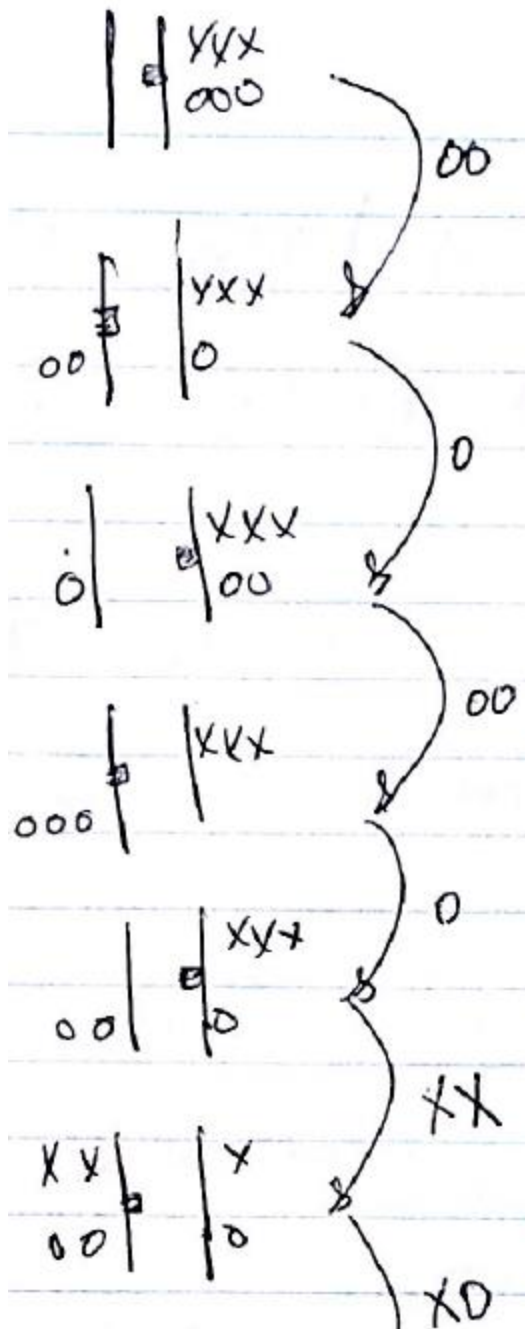
XX	X
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Observations

- Many choices for
 - State description
 - Actions
- Many correct, some better than others
- Find correct level of abstraction

Solution



Search Trees: Finding Solutions

- Example: 8-Queens?



Observations

- State formulation:
 - Incremental state
 - Complete state
- May or may not allow bad intermediate states
- No goal state \Rightarrow goal predicate
- Solution cost:
 - Incremental state: 8
 - Complete state: 0-8 (Can be solved in 0 moves!)

Search Trees: Finding Solutions

- Example: Crypt-arithmetic?

FORTY	→	29786
TEN		850
TEN		850
+-----		+-----
SIXTY		31486



Observations

- Assign numbers to letters in fixed order
(better: smallest number of remaining values)
- Incremental or complete state

Search Trees: Finding Solutions

- Example: Knut's Problem?
- Start: 4
- Actions
 - Factorial: $x!$
 - Sqrt: \sqrt{x}
 - Floor: $\lfloor x \rfloor$
- Transitions: math
- Goal: 5 \Rightarrow HOW?



Observations

- Conjecture:
Any positive integer can be reached
- No bound on intermediate representation
- Infinite state space
- Example of class of problems: recursively defined objects
Circuits, proofs, programs, etc.

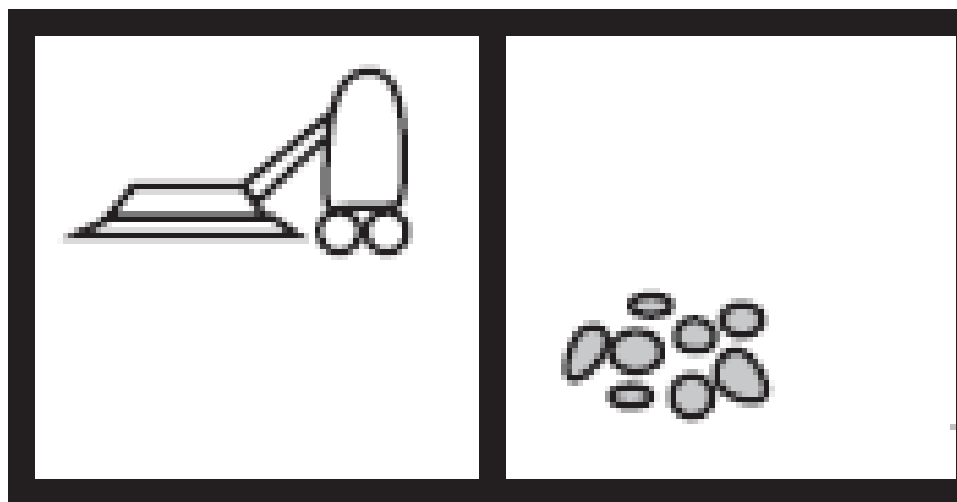
More Real-World Search Problems

- Route finding
 - Amazon, computer networks, travel planning, airline planning, navigation systems
- Traveling salesperson problems
 - Planning circuit board drill movements, mail delivery, street cleaning, etc.
 - What is a state?
- Hardware layout
- Continuous robot navigation
- Scheduling
- Theorem proving

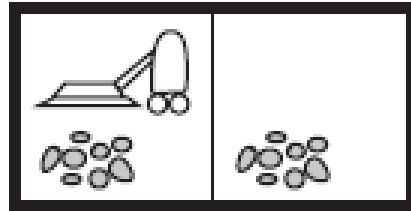
Extensions/Complications

- Minimizing solution cost ('optimal solution')
 - Cost of solution is sum of action costs
- Not sure about effect of actions
 - Non-determinism (see probability later)
- Not sure about initial state
- Contingent planning: action based on sensing
- Conformant planning: plan without sensors
 - Example: Not knowing initial state (see next)

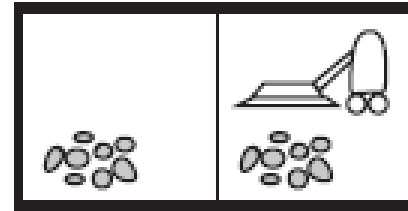
Vacuum Cleaner World



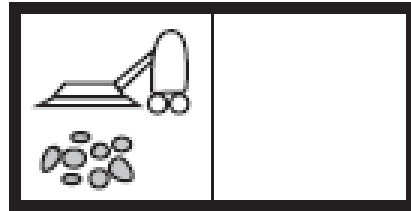
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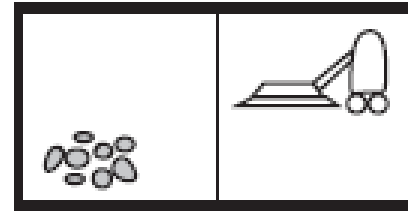
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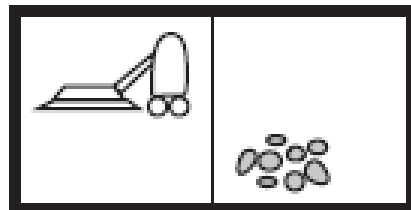
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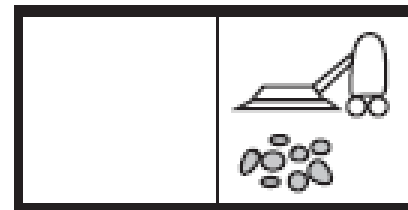
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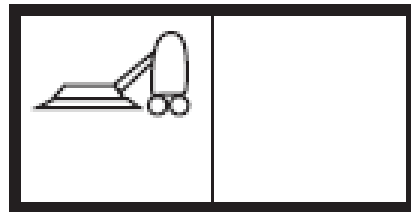
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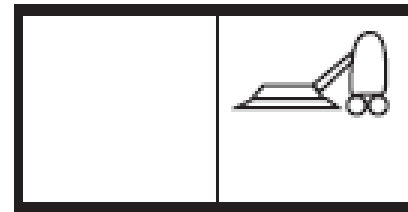
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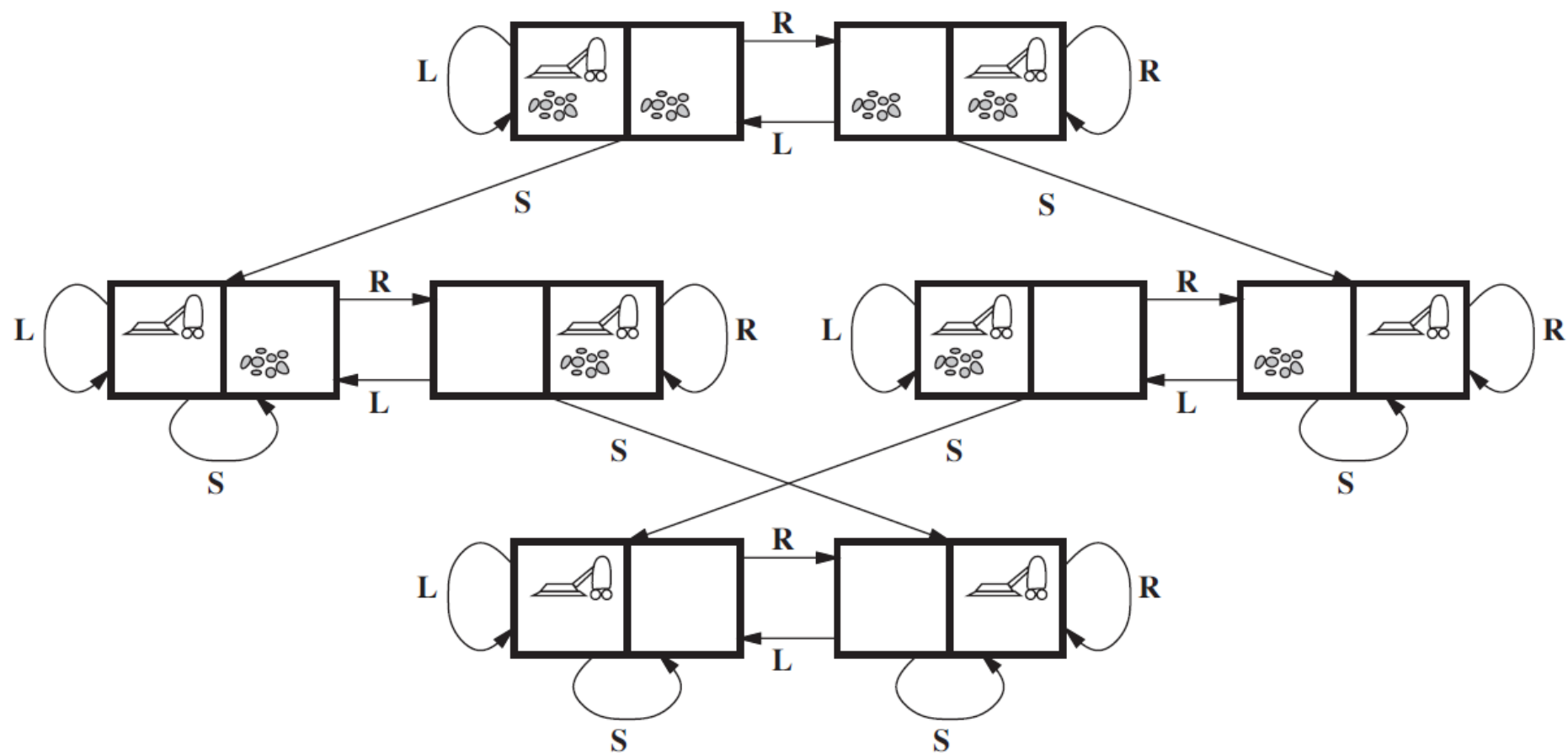


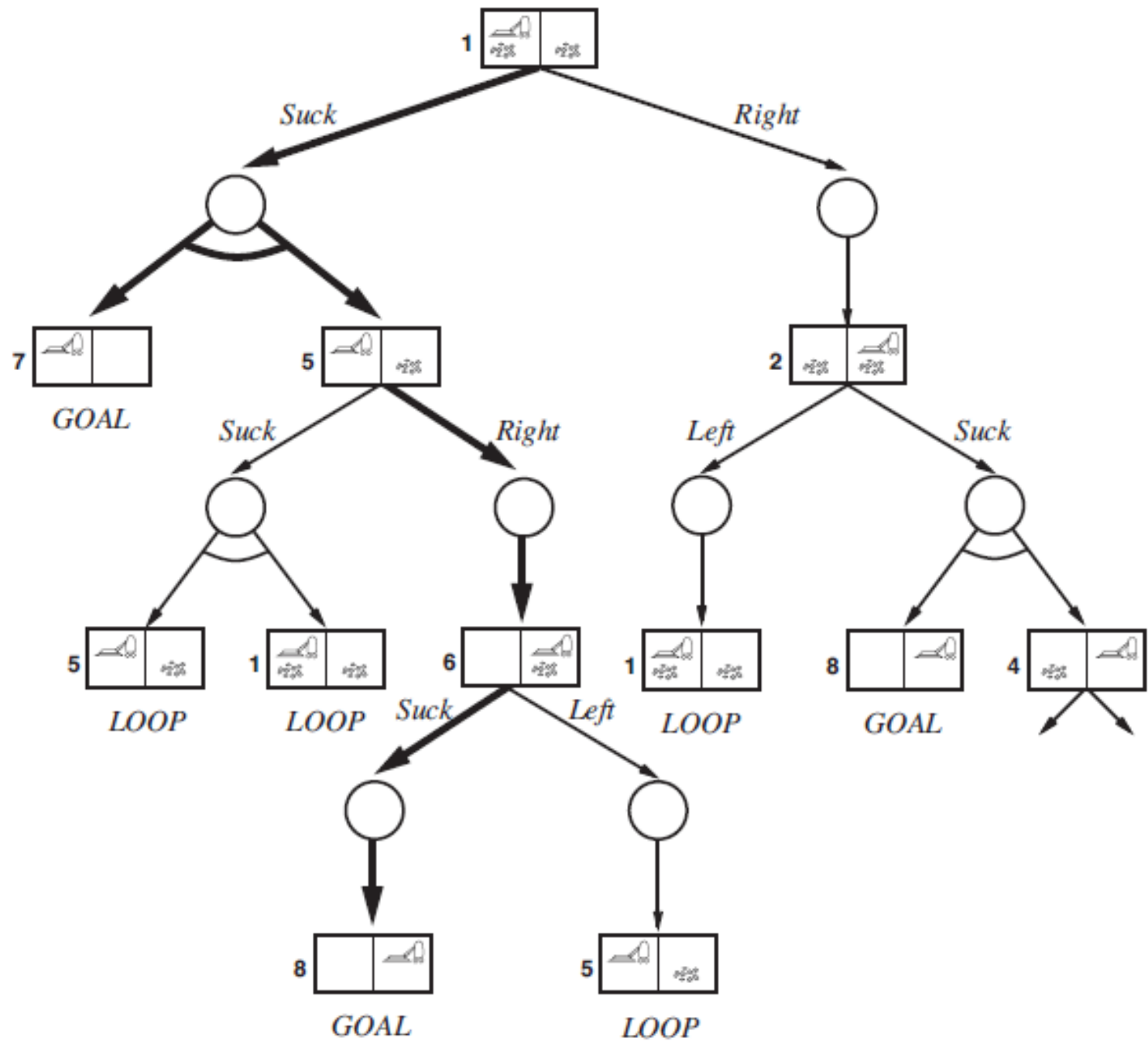
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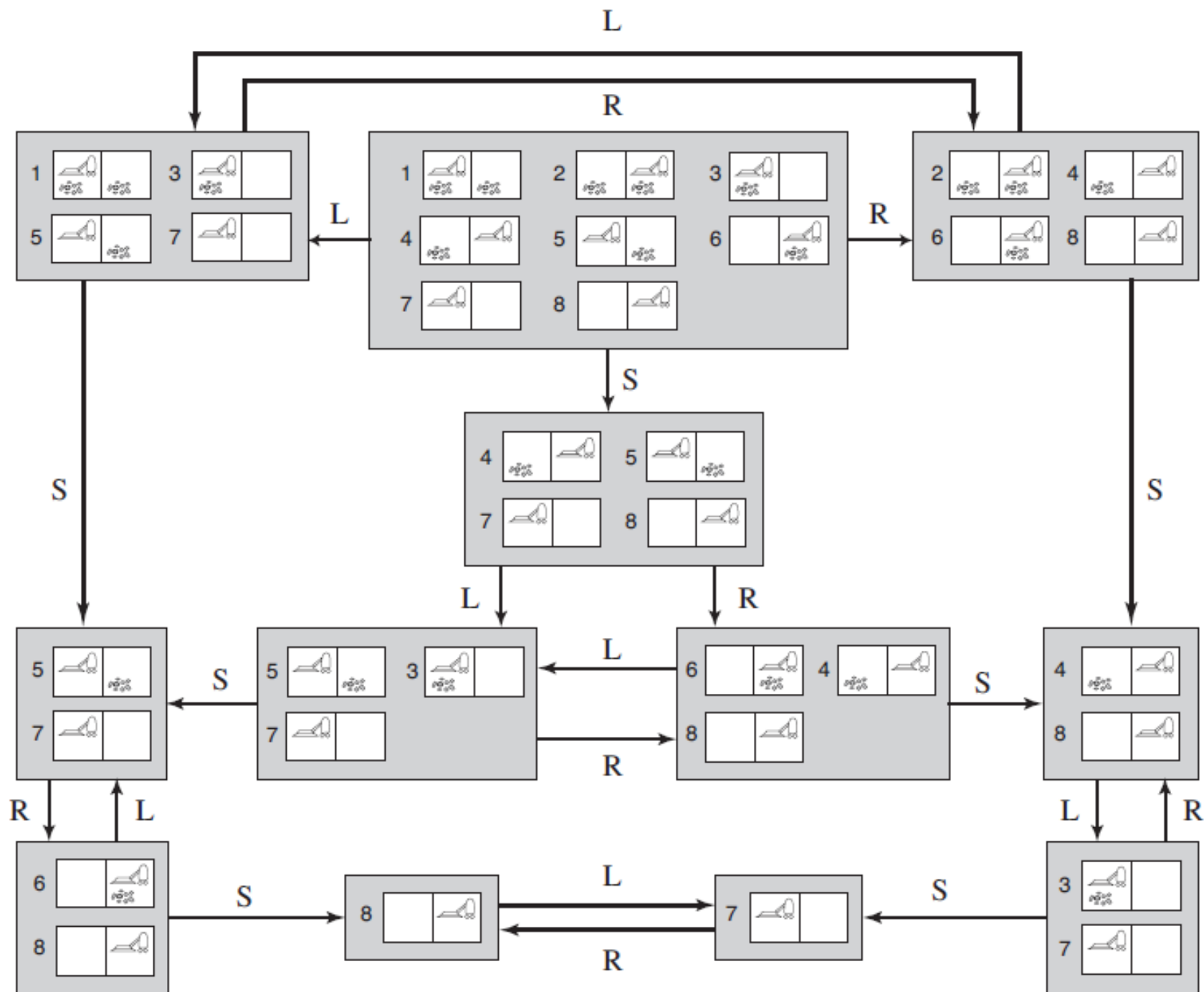


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Observations

- When uncertain about initial state, use belief states.
- Belief state is a set of deterministic states