## Xiao(Barry) Liang

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<u>barryliang521@</u>	gmail.com 📞 +81 07010769166 🕮 2-2-1 Aomi, Koto city, Tokyo 🗞 https://bi	arry-liang.github.io/resume/	
SUMMARY	Seeking for a PhD position related to Robot Learning and 3D Vision		
	<ul> <li>Skilled in C++, Python, MATLAB, ROS and OpenCV. (★★★)</li> </ul>		
	<ul> <li>Familiar with Linux, PyTorch, Shell, Webots and Universe Robot (★</li> </ul>	★★)	
	<ul> <li>Experienced in Blender, Cuda, OpenMP, and V-REP Pro. (★★)</li> </ul>		
	<ul> <li>Fluent in English and beginner level in Japanese.</li> </ul>		
	<ul> <li>Interdisciplinary engineer, fully trained project experience with leader</li> </ul>	ship, nice group worker	
<b>EDUCATION</b>	The University of Tokyo (UT), Tokyo, Japan		
	Member of Yamakawa Lab. (High Speed Flexible Robotics Lab)		
		9 – Aug 2021 (expected)	
	Shanghai Jiao Tong University (SJTU), Shanghai, China		
	University of Michigan – Shanghai Jiao Tong University Joint Institute	(UM-SJTU JI)	
	B.Sc. in Mechanical Engineering (English Program)	Sept 2015 – Aug 2019	
	Overall GPA: 3.77/4.00; Major GPA: 3.93/4.00 (ranking 2/58).		
INTERNSHIP	Computer Vision Engineer, Huawei Tokyo Research Center, Tokyo, Japan		
COURSES	Deep learning, Machine learning, Robot Manipulation, Data Science and M	Machine Leaning,	
HIGHLIGHTS	Linear Algebra, Automatic Control, Intro to Robotics, Data Structure and	Algorithms	
RESEARCH	Marker-Based Pose Estimation for Rotating Objects using High-Speed	Vision	
EXPERIENCE		Dec 2020 –present	
EM EMENCE	• Apply visual feedback to measure the position and orientation of rotating	•	
	• Achieve a general marker-matching algorithm to avoid the marker labeling		
	Tracking and Catching of a Thrown Ring		
	Yamakawa Laboratory (High Speed Flexible Robotics Lab) @UT	June 2020 – Dec 2020	
	• Proposed a marker-based pose tracking algorithm using a high-speed vis		
	• Designed a catching point selection algorithm to make the robot accomplish high-speed catching		
	Design and Analysis of a Wheel-Leg Hybrid Robot with Novel Transformation Mechanism		
	Laboratory of Smart Solids and Structures @SJTU	June 2018 – Sept 2018	
	• Designed a vehicle robot with actively transformed three-leg wheels	1	
	• Conducted automatic control of wheel-transformation to pass through sa	nd road and smooth road	
SELECTED	CCD Camera Imaging (Silver Award)		
<b>PROJECTS</b>	VM450 Capstone Design @SJTU	Sept 2018 – Dec 2018	
	• Designed a software-based optical imaging model to analog CCD camera imaging system		
	• Compared small hole imaging and lens imaging and conducted feasibility analysis		
	Motion Planning of Robot MORO: Roaming Obstacle Avoidance and C	hassis Path Planning	
	VM467 Introduction to Robotics @SJTU	June 2018 – Aug 2018	
	•Utilized the sensor system and SLAM algorithm to plan the path and con		
	•Applied and compared the A star and Dijkstra algorithm in shortest path planning		
	A Spinning Bike-based Air Purification Device		
	VG100 Introduction to Engineering @SJTU	June 2016 – Aug 2016	
	• Designed and manufactured an exercise bike with belt transmission	C1	
THEOD	• Designed and installed an air purification shell to pump out air through the	ne ilitration system	
TUTOR	Undergraduate Education Office, UM-SJTU JI	G (2010 / 2010	
<b>EXPERIENCE</b>	e e	Sept 2018 – Aug 2019	
	Worked as TA for one major course: VM395 Laboratory I  Academic Advising Conton LIM SITE II		
	Academic Advising Center, UM-SJTU JI Student Advisor @SJTU	Sept 2017 – Aug 2019	
	• Provide academic advice to JI students	Sepi 2017 – Aug 2019	
	<ul> <li>Hold workshops aiming to promote academic skills and share profession</li> </ul>	al interests	
SELECTED			
	The Japanese Government's MEXT scholarship	Sept 2019- Aug 2021	
HONORS	Shanghai Distinguished Graduates Award	June 2019	
	National Scholarship (Twice, top 1% in SJTU)	Oct 2017, Oct 2018	
	Honorable Mention in Mathematical Contest in Modeling	Apr 2018	
	Yu Liming Scholarship (Twice, top 5% in UM-SJTU JI)	Nov 2016, Nov 2017	
	Undergraduate Excellent Scholarship (3 times, top 3% in SJTU) Dec 20	16, Dec 2017, Dec 2018	