

Chemical Engineering 4H03

Projection of Latent Structures (Derivation)

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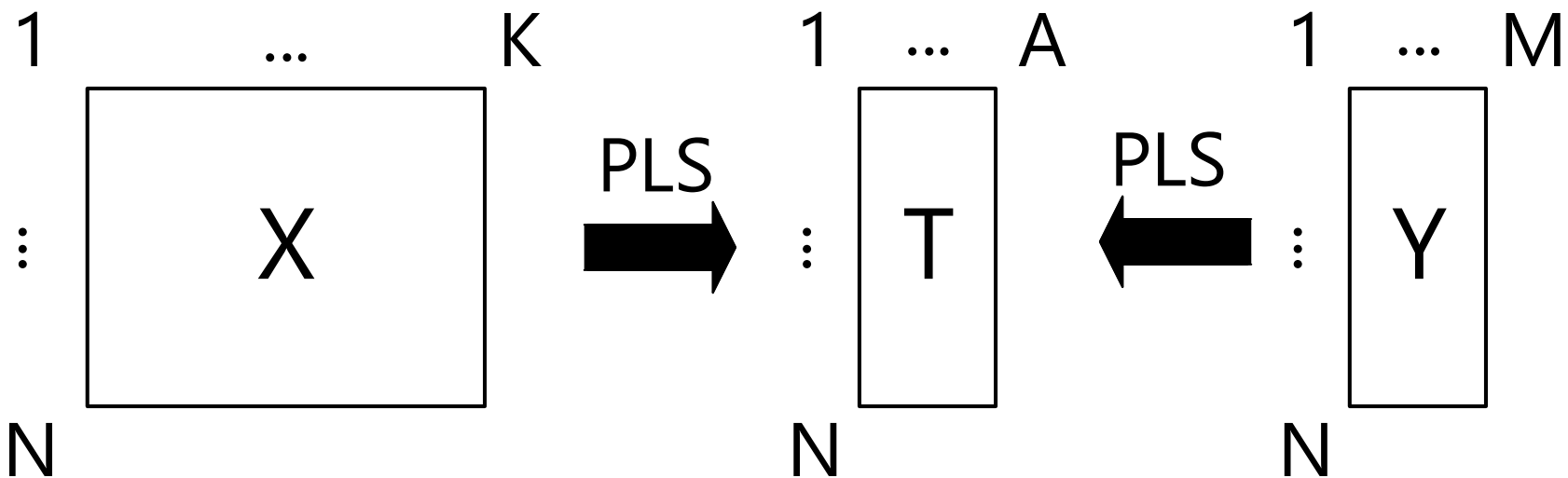
Where are We?

- MLR is good for relating dependent outcomes (\mathbf{y}) to independent inputs (X)
 - NOT appropriate if columns in X are dependent
 - Leads to singularity (ill conditioning) of $X^T X \rightarrow$ inverse issues
 - 'Spinning' of model plane (unstable coefficients)
 - NOT easy to visualize or interpret if K is large
- PCR is a nice tool that dimension-reduces first
 - SOLVES dependent column issue
 - EASIER to visualize with $A < K$
 - Does NOT help that \mathbf{y} is assumed to contain all error
 - Must be done independently for EACH column in Y



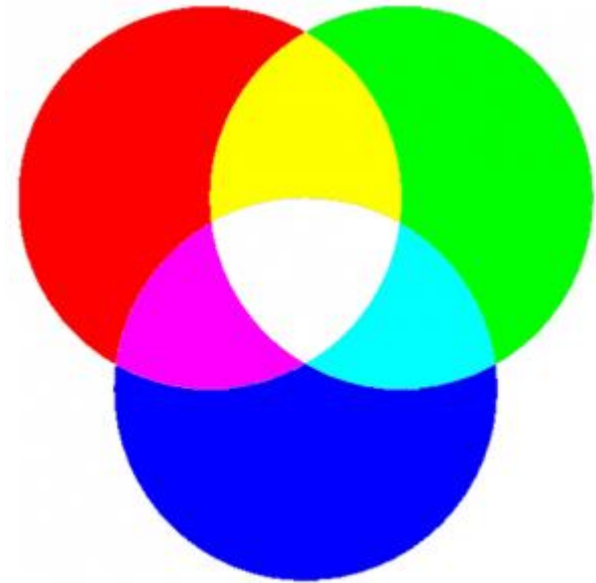
A Better Idea

- Instead, let's fit the latent variable space to have A components, where each component represents data in X **and** data in Y **simultaneously**
 - We will have TWO sets of scores and loadings



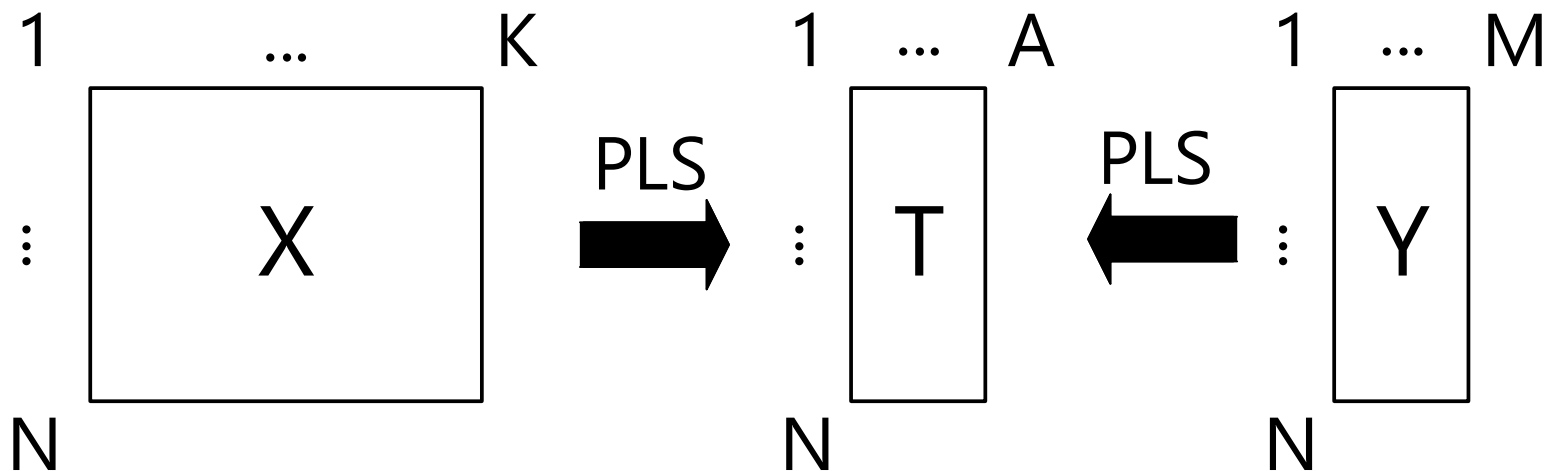
Projection of Latent Structures

The Deluxe Linear Modeling Technique



Overview of PLS

- **P**rojection of **L**atent **S**tructures:
 1. Extracts components from X and Y sequentially
 2. Uses cross-validation to fit an appropriate number of components
 3. Scores for the PLS model are computed from X and Y simultaneously
 4. Makes engineering sense: system is driven by the same underlying latent variables (in X and Y)

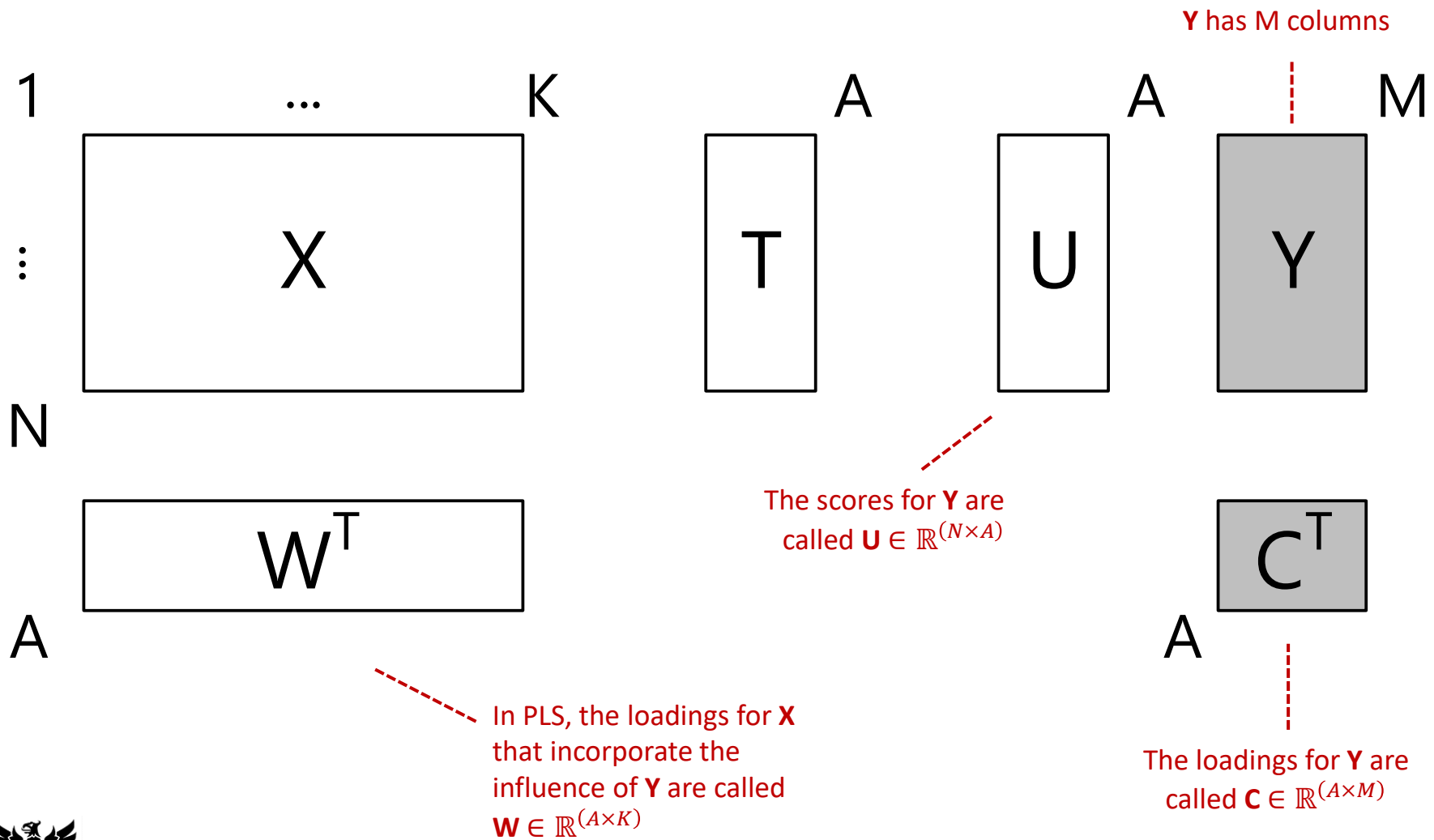


Objective of PLS

- Objective of **PCA** is to explain X
- What do we want from **PLS**?
 - Best explanation of X
 - Best explanation of Y
 - Maximize the relationship between X and Y
- Covariance is going to come up again here

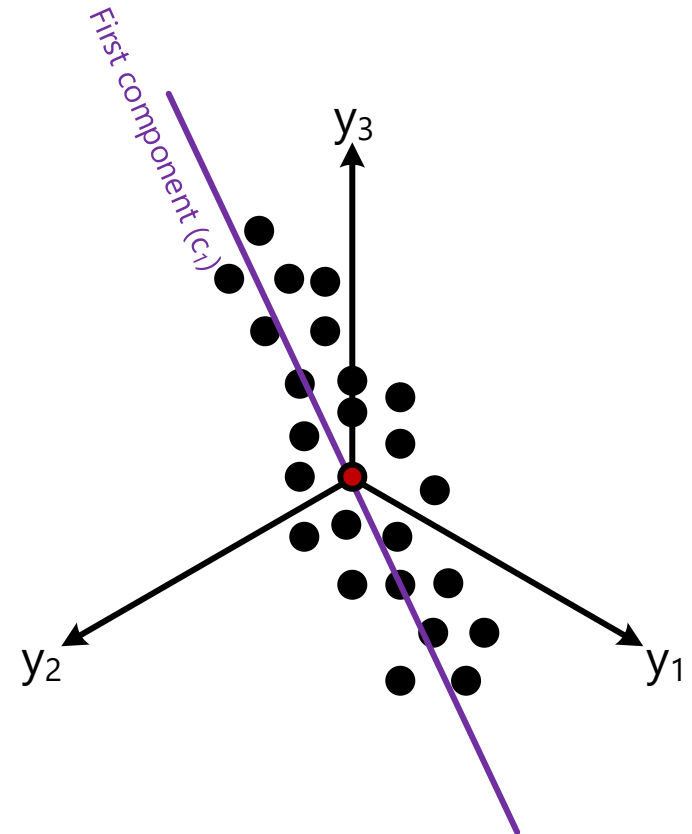
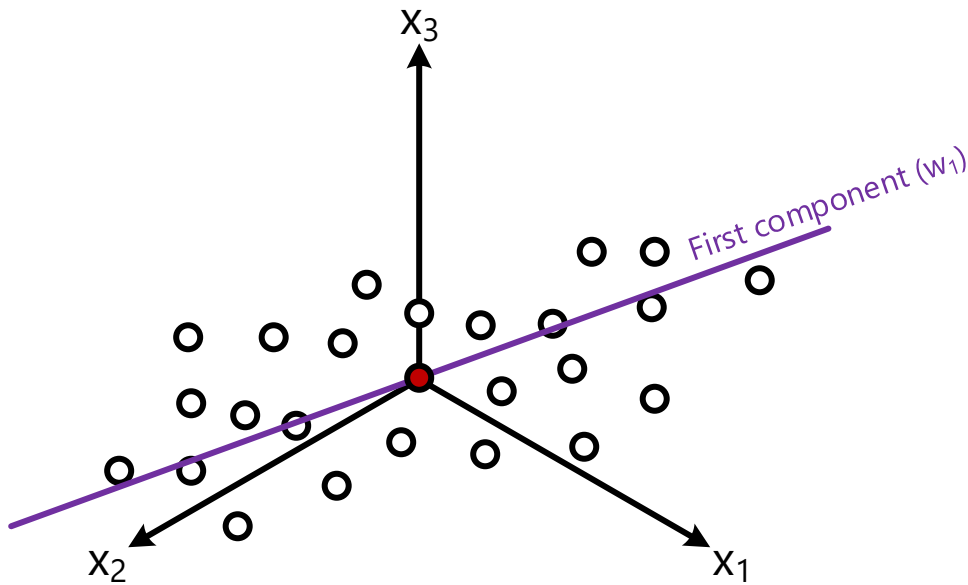


Some New Notation



PLS Geometrically

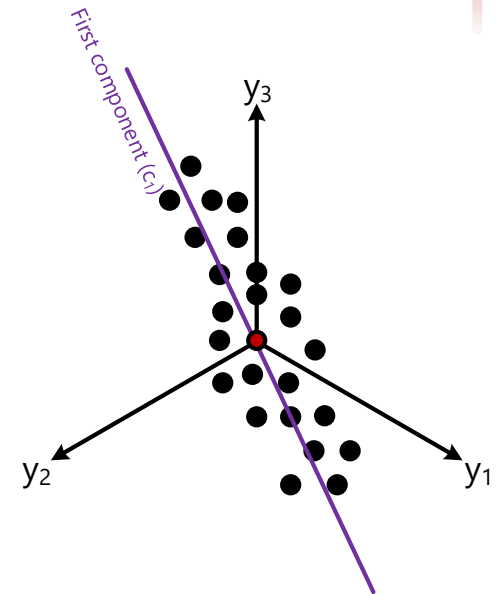
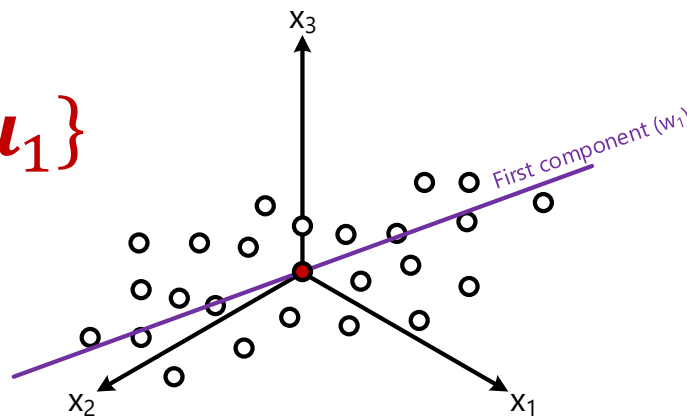
- Consider a data set with $K = M = 3$ (three variables)
 - The first component explains X and Y "well"
 - Why not "best?"



PLS Geometrically

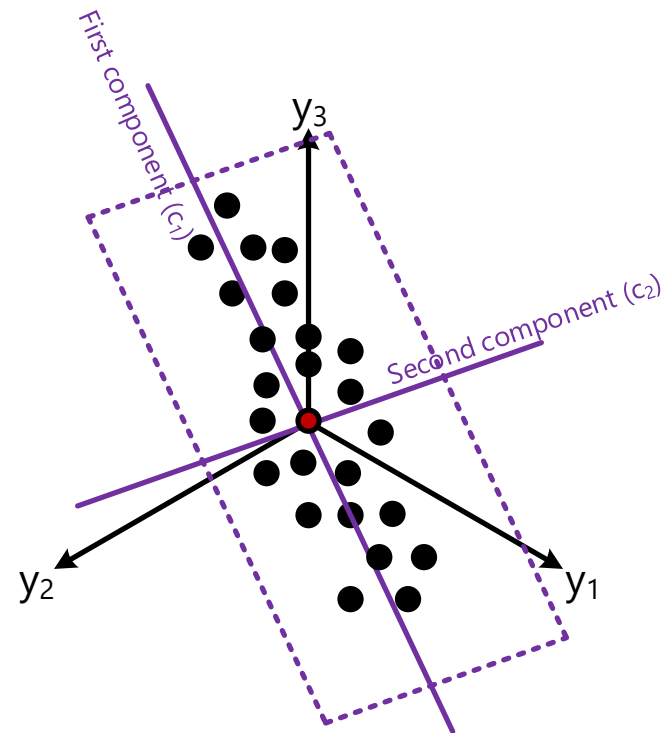
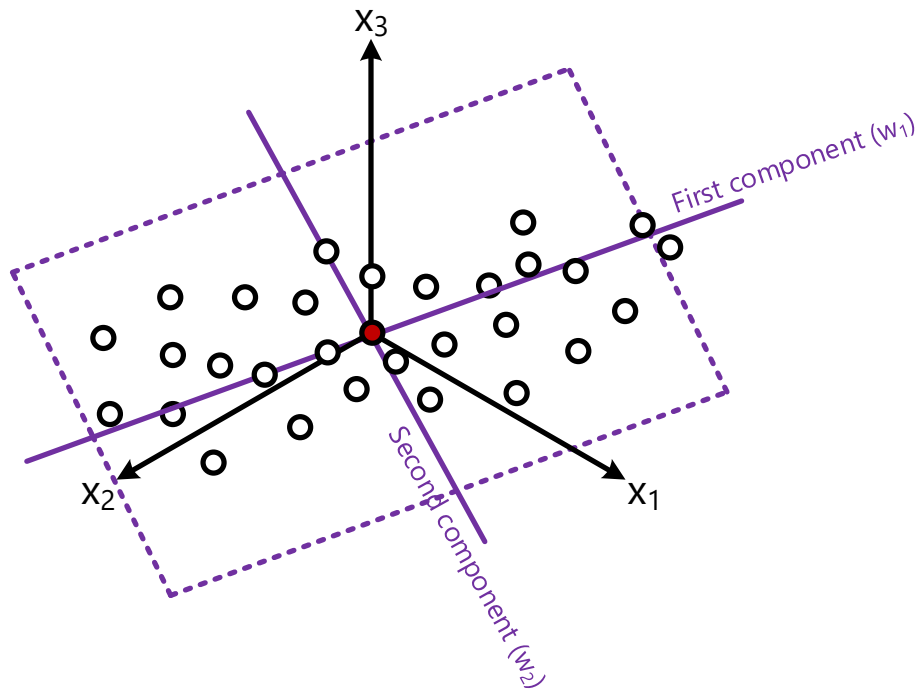
- Compute the SCORES t_1 and u_1 for both model spaces
 - IN PCA, we would want to maximize the variance of t_1
 - If we were magically fitting one component to Y , we would want to maximize the variance of u_1
- Surprising absolutely no one, our objective in PLS is to maximize the **COVARIANCE** of t_1 and u_1

$$\max_{w_1, c_1} \phi = \mathcal{C}\{t_1, u_1\}$$



PLS Geometrically

- Now add the second component
 - w_2 is orthogonal to w_1
 - c_2 is orthogonal to c_1



PLS Analytically (Basic Version)

- PLS scores explain variance in X (recall \mathbf{w} are loadings)
 - $\mathbf{t}_a = X_a \mathbf{w}_a$ Variance in X for in a^{th} component
 - $\max \phi = \mathbf{t}_a^T \mathbf{t}_a$ Subject to $\mathbf{w}_a^T \mathbf{w}_a = 1.0$
- PLS scores ALSO explain variance in Y
 - $\mathbf{u}_a = Y_a \mathbf{c}_a$ Variance in Y for in a^{th} component
 - $\max v = \mathbf{u}_a^T \mathbf{u}_a$ Subject to $\mathbf{c}_a^T \mathbf{c}_a = 1.0$
- It does this by maximizing the **relationship** between **explained variance** in X and Y
 - $\max \psi = f(\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\})$



PLS Maximizes Covariance of $\{X, Y\}$

- Recall the calculation for covariance

$$\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} = \mathcal{E}\{(\mathbf{t}_a - \bar{\mathbf{t}}_a)(\mathbf{u}_a - \bar{\mathbf{u}}_a)\}$$

$$\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} \equiv \frac{1}{N} \mathbf{t}_a^T \mathbf{u}_a \quad \text{----- WHY!!!!??}$$

- Although this is our objective, covariance is hard to interpret and is dependent on units
- Instead, let's maximize **correlation**, which is a value between -1 and 1!



PLS Maximizes Covariance of $\{X, Y\}$

- Correlation for x and y is

$$r\{x, y\} = \frac{\mathcal{E}\{(x - \bar{x})(y - \bar{y})\}}{\sqrt{\mathcal{V}(x)\mathcal{V}(y)}} = \frac{\mathcal{C}\{x, y\}}{\sqrt{\mathcal{V}(x)\mathcal{V}(y)}} = \frac{\mathcal{C}\{x, y\}}{\sqrt{\mathcal{V}(x)}\sqrt{\mathcal{V}(y)}}$$

$$\mathcal{C}\{x, y\} ::= r\{x, y\} \cdot \sqrt{\mathcal{V}(x)} \cdot \sqrt{\mathcal{V}(y)}$$

For PLS scores:

$$\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} = r\{\mathbf{t}_a, \mathbf{u}_a\} \cdot \sqrt{\mathcal{V}(\mathbf{t}_a)} \cdot \sqrt{\mathcal{V}(\mathbf{u}_a)}$$

$$\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} = r\{\mathbf{t}_a, \mathbf{u}_a\} \cdot \sqrt{\mathbf{t}_a^T \mathbf{t}_a} \cdot \sqrt{\mathbf{u}_a^T \mathbf{u}_a}$$

$$\max \phi = \mathbf{t}_a^T \mathbf{t}_a$$

$$\max v = \mathbf{u}_a^T \mathbf{u}_a$$



PLS Maximizes Covariance of $\{X, Y\}$

$$\mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} = r\{\mathbf{t}_a, \mathbf{u}_a\} \cdot \sqrt{\mathbf{t}_a^T \mathbf{t}_a} \cdot \sqrt{\mathbf{u}_a^T \mathbf{u}_a}$$
$$\max \phi = \mathbf{t}_a^T \mathbf{t}_a \quad \max \nu = \mathbf{u}_a^T \mathbf{u}_a$$

Maximizing covariance simultaneously maximizes the RELATIONSHIP between t_a and u_a as well as their own variance (which was the point of PCA!)

I consider this important



PLS Summarized

- The OPTIMIZATION objective for PLS is to maximize the covariance between \mathbf{t}_a and \mathbf{u}_a for each component
 - $\max \psi = \mathcal{C}\{\mathbf{t}_a, \mathbf{u}_a\} = r\{\mathbf{t}_a, \mathbf{u}_a\} \cdot \sqrt{\mathbf{t}_a^T \mathbf{t}_a} \cdot \sqrt{\mathbf{u}_a^T \mathbf{u}_a}$
 - Explains X via $\mathbf{t}_a^T \mathbf{t}_a$
 - Explains Y via $\mathbf{u}_a^T \mathbf{u}_a$
 - But we also want a high **CORRELATION** between \mathbf{t}_a and \mathbf{u}_a
 - Unsurprisingly, a high $r\{\mathbf{t}_a, \mathbf{u}_a\}$
 - Decision variables are \mathbf{w}_a and \mathbf{c}_a
- Some notes
 - Requires formal constrained optimization (outside 4H scope)
 - Can also be obtained through NIPALS (described next)



Final Remarks

- PLS elegantly exploits the covariance between t and u scores to simultaneously maximize correlation AND the individual variances of each
 - **Thus we explain all dimensions as well as possible**
- This is **fundamental** to the understanding of PLS
 - DISCUSSION: differences between PCR and PLS?
- Next up: **Computing PLS components using NIPALS**
 - Good news: the algorithm is similar to PCA
 - Bad news: it takes more steps and the interpretation is (a teensy bit)messier

