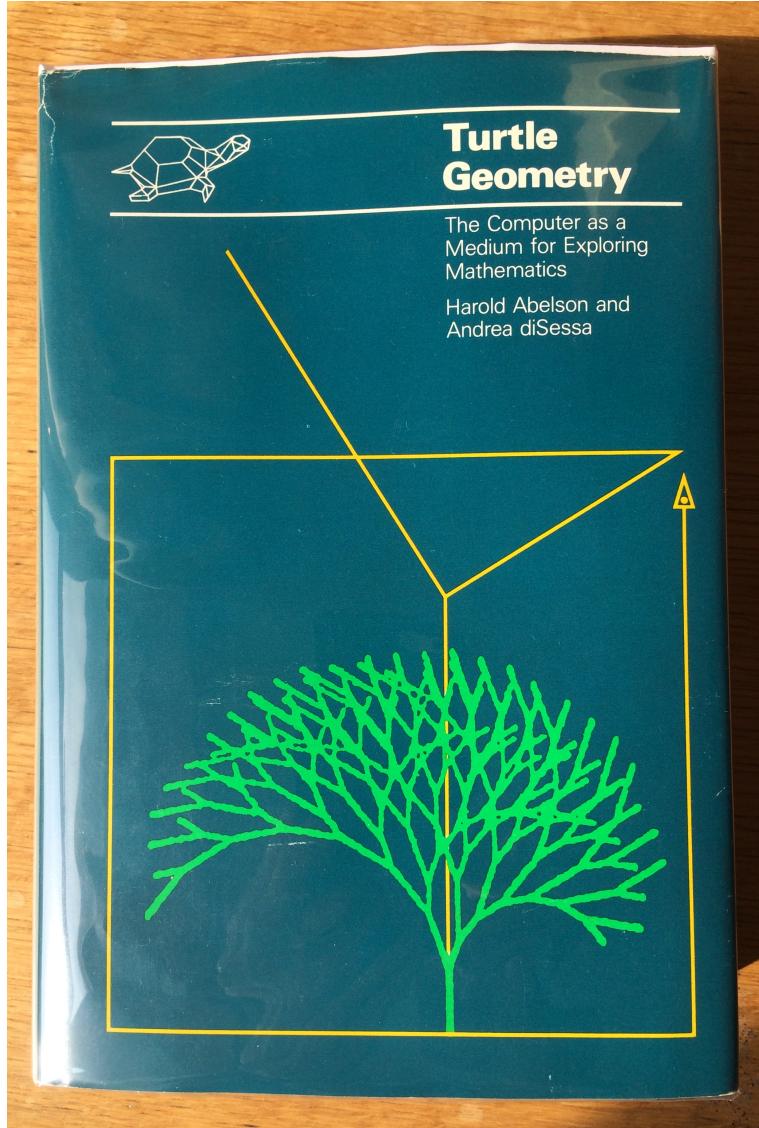


# Turtle Geometry the Python Way

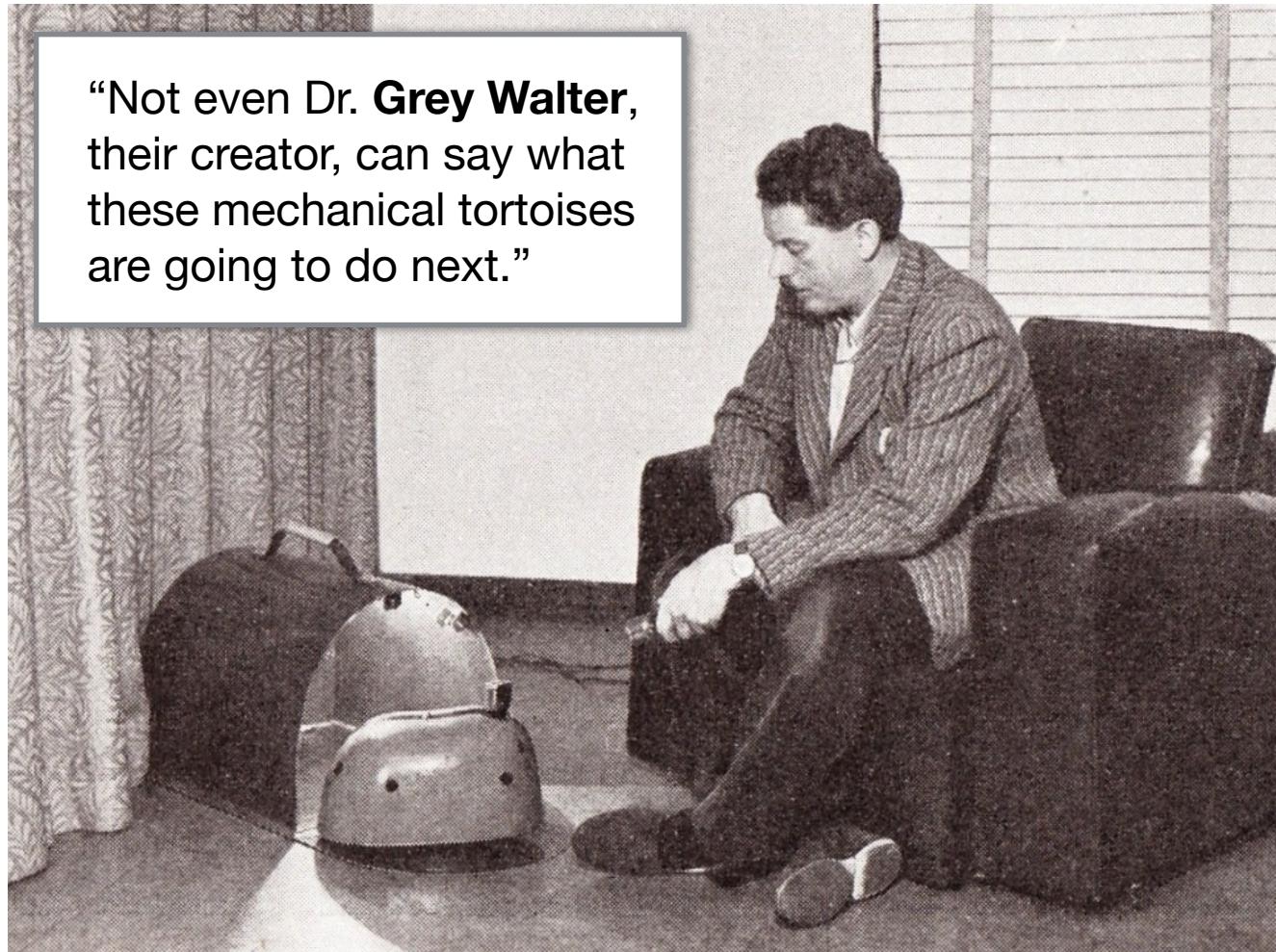
@SteveBattle

# Turtle Geometry



*“The tradition of calling our display creatures ‘turtles’ started with Grey Walter, a neurophysiologist who experimented in Britain... with tiny robot creatures he called ‘tortoises’. These inspired the first turtles designed at MIT.”*  
*(1980)*

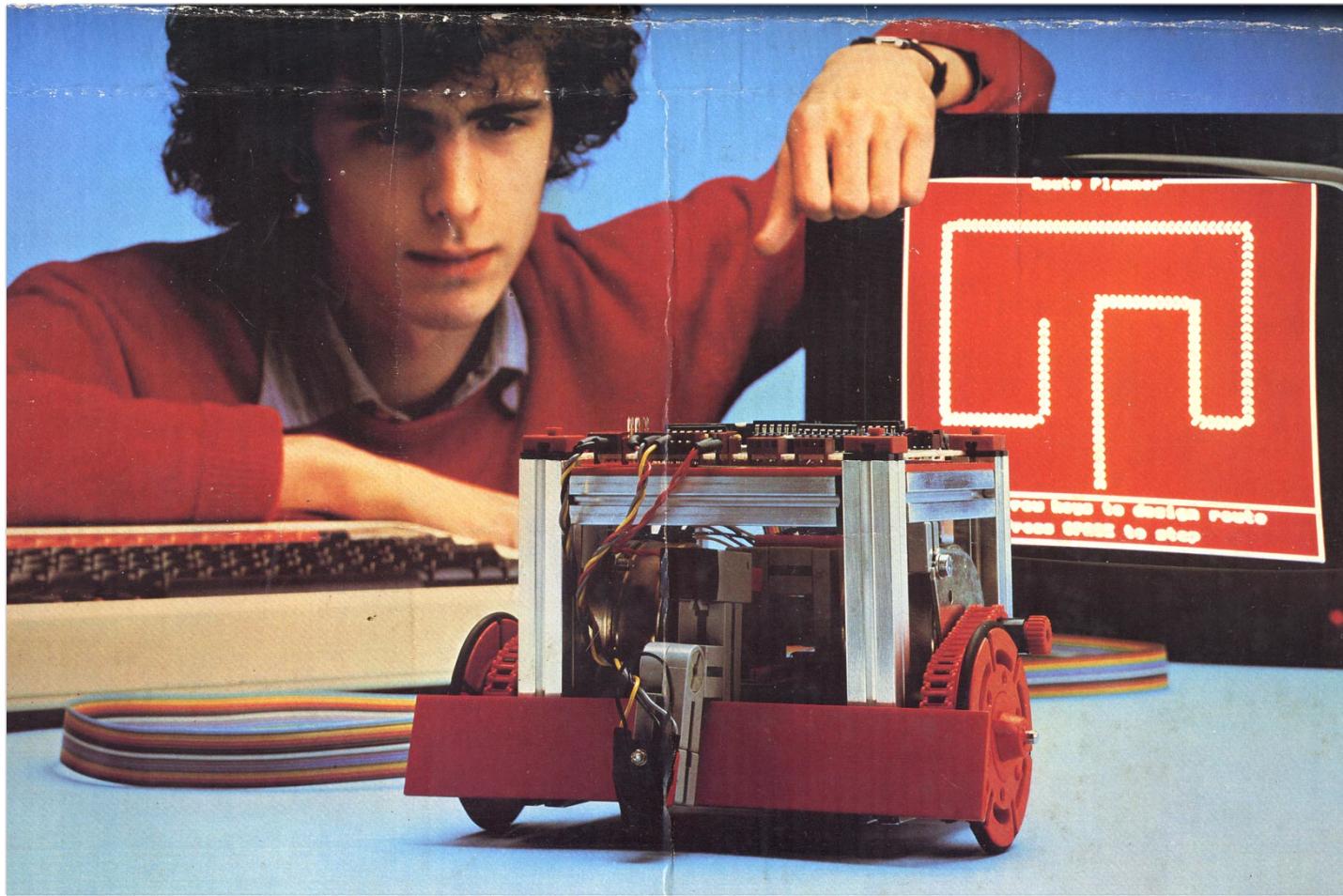
# Turtles and Tortoises



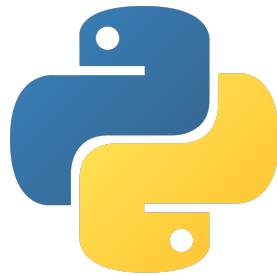
“Not even Dr. **Grey Walter**, their creator, can say what these mechanical tortoises are going to do next.”

Bristol based Inventor of the first autonomous robots in 1948.

# BBC Buggy (1983)



The Buggy was tethered to the BBC Micro and used the 'Logo' language.



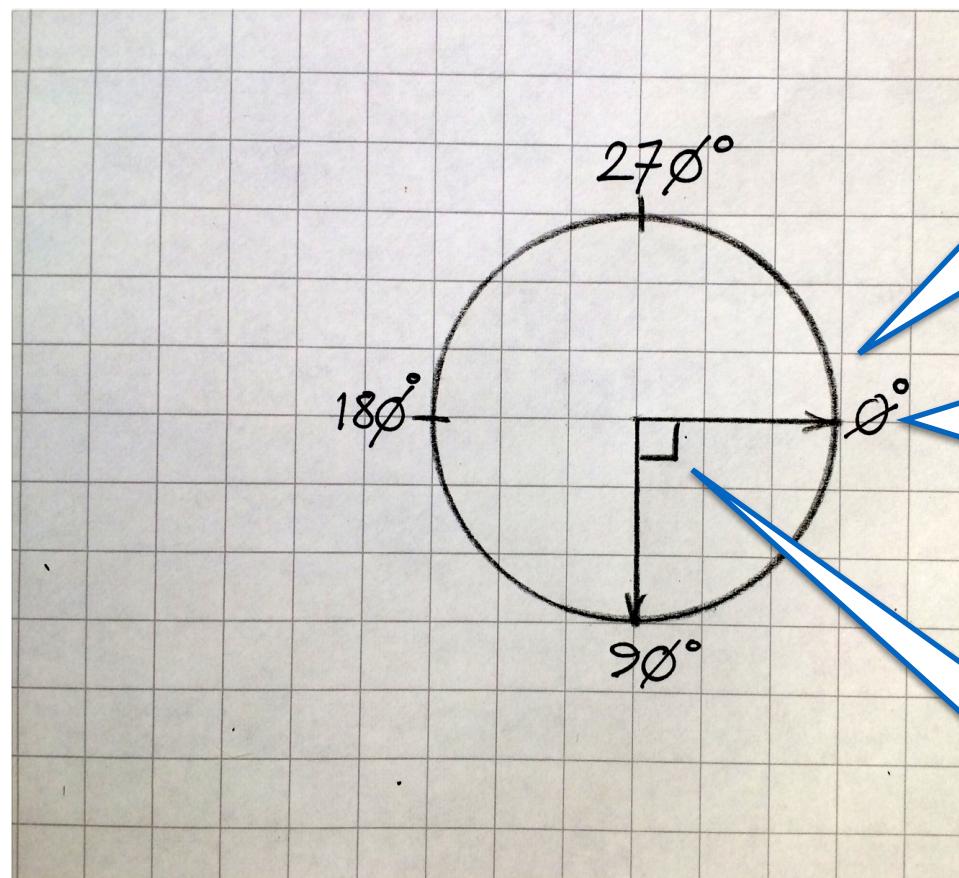
# The Python Way

The diagram illustrates the Python development environment. On the left, a large blue callout box contains the text "Start IDLE and start typing". A line connects this box to the Python 3.4.1 Shell window. The Shell window shows the Python interpreter's prompt (">>>>") followed by a series of commands: "from turtle import \*", "forward(100)", "right(90)", and "forward(100)". A single blue line is drawn on the screen as a result of these commands. To the right of the Shell window is the Python Turtle Graphics window, which displays a square shape drawn with the "forward" and "right" commands. The title bar of the Graphics window reads "Python Turtle Graphics". In the bottom right corner of the Graphics window, there is a small text box containing the number "4".

```
Python 3.4.1 (v3.4.1:c0e311e010fc, May 18 2014, 00:54:21)
[GCC 4.2.1 (Apple Inc. build 5666) (dot 3)] on darwin
Type "copyright", "credits" or "license()" for more information.

>>> from turtle import *
>>> forward(100)
>>> right(90)
>>> forward(100)
>>>
```

# angles



A  $360^\circ$  turn  
returns the  
turtle to  $0^\circ$

The turtle  
starts off  
facing this way

A right angle  
going clockwise

# sequence

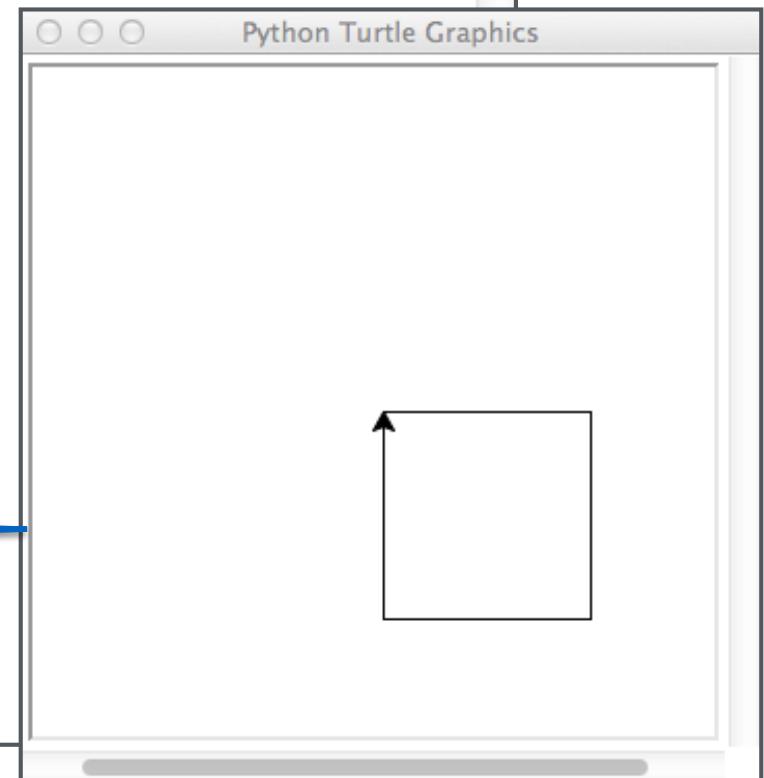
Create a new file  
(Python module)

Save the file  
(but not as 'turtle')

Run

```
Python 3.4.1: sequence.py - /Users/Steve/Do...
from turtle import *
pendown()
forward(100)
right(90)
forward(100)
right(90)
forward(100)
right(90)
forward(100)

done()
```



# turtle functions

forward(**length**)

backward(**length**)

left(**angle**)

right(**angle**)

penup()

pendown()

done()

speed(**s**)

*e.g. 'slow', 'fast', 'fastest'*

shape(**name**)

*e.g. 'turtle', 'classic'*

goto(**x,y**)

*x,y coordinates*

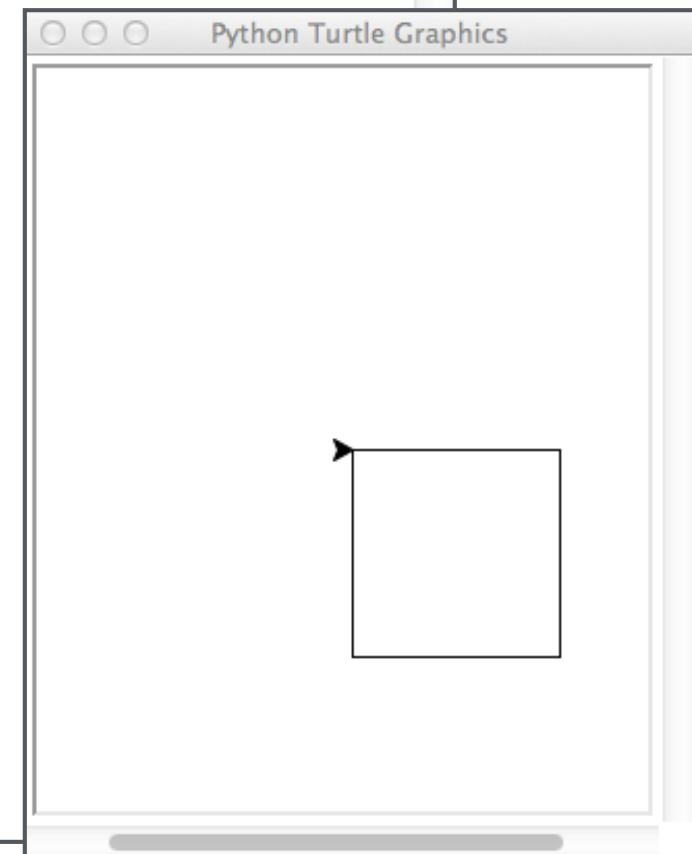
# for loops

The loop repeats a fixed number of times (4).

Everything inside the loop is indented.  
use TAB not SPACE

```
Python 3.4.1: square.py - /Users/Steve/Doc...
from turtle import *
speed('slow')
pendown()
for i in range(4):
    forward(100)
    right(90)
done()
```

slow down the output



# defining functions

Function definition

Note the double  
indentation

call the  
function

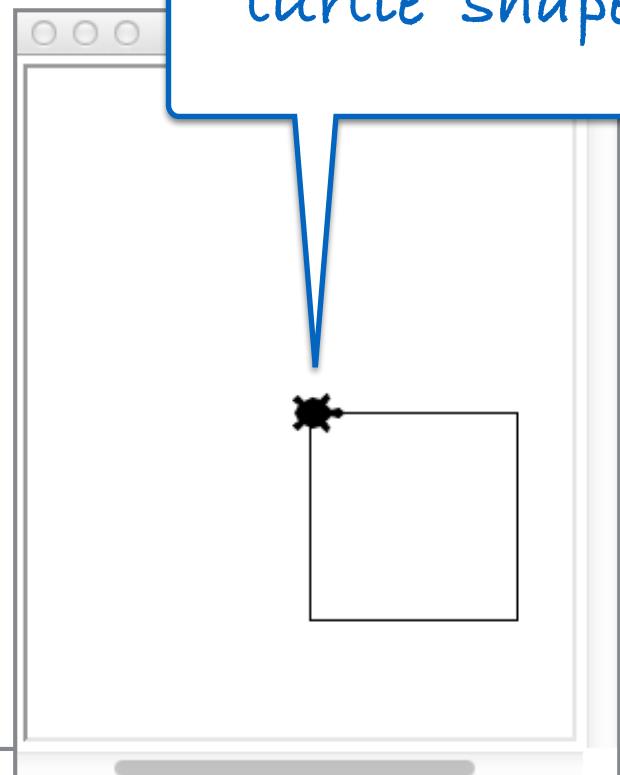
```
Python 3.4.1: square_fun.py - /Users/Steve/...
from turtle import *

def square():
    for i in range(4):
        forward(100)
        right(90)

speed('slow')
shape('turtle')
pendown()

square()
done()
```

'turtle' shape

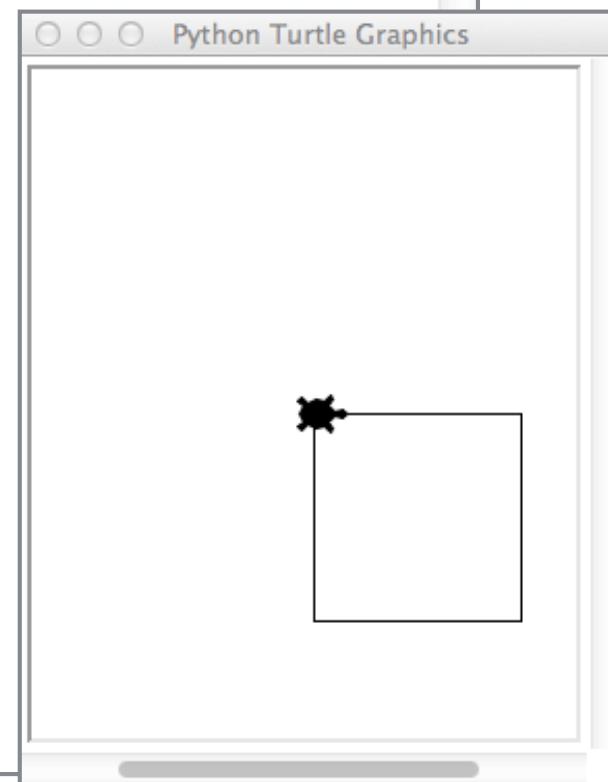


# function parameters

call 'square'  
with argument  
100

```
Python 3.4.1: square_len.py - /Users/...  
from turtle import *  
  
def square(length):  
    for i in range(4):  
        forward(length)  
        right(90)  
  
speed('slow')  
shape('turtle')  
pendown()  
  
square(100)  
  
done()
```

Add parameter  
'length'



# polygons

calculate angle  
and assign to a  
variable

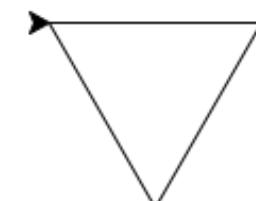
```
Python 3.4.1: polygon.py - /Users/Steve/Do...
from turtle import *
def polygon(length, sides):
    for i in range(sides):
        forward(length)
        angle = 360/sides
        print(angle)
        right(angle)
speed('slow')
pendown()
polygon(100,3)
done()
```

The output from  
'print' appears in  
the IDLE console

```
Python 3.
[GCC 4.2.
Type "cop
>> =====
>>
120.0
120.0
120.0
```

Comma  
separated  
parameters

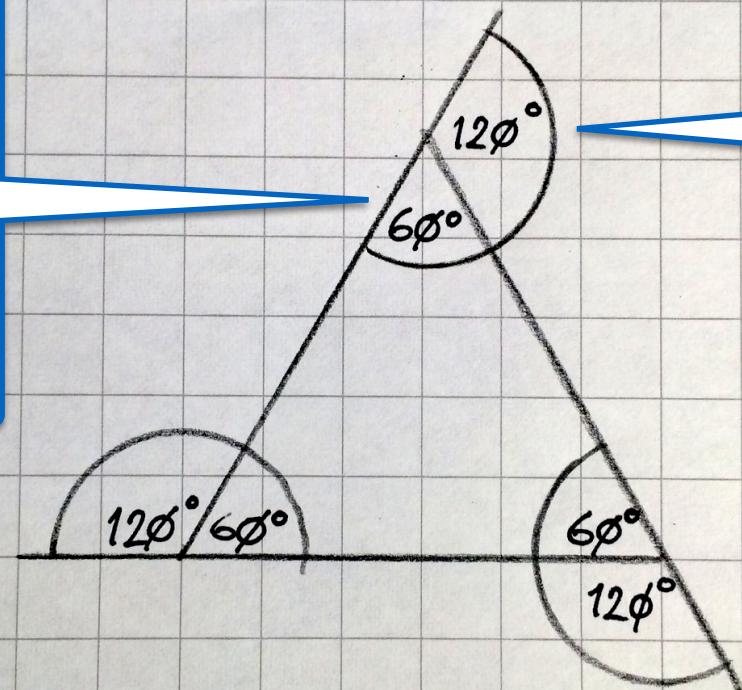
The angles of a  
polygon sum to  
 $360^\circ$



# Interior & Exterior angles

The (interior) angles of a triangle sum to only  $180^\circ$

The turtle turns through the exterior angles, which sum to  $360^\circ$





# stars

Python 3.4.1: star.py - /Users/Steve/Documents/Python/star.py

```
from turtle import *

def star(length, sides, multiple):
    for i in range(sides):
        forward(length)
        angle = multiple * 360/sides
        print(angle)
        right(angle)
```

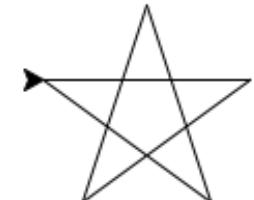
```
speed('slow')
pendown()
star(100,5,2)
done()
```

What happens if we turn turtle through a multiple of  $360^\circ$ ?

Try also heptagons:  
`star(100,7,2)`  
`star(100,7,4)`

Double the angle of a normal pentagon

```
Python
[GCC 4...
Type "co"
>>> =====
>>>
144.0
144.0
144.0
144.0
144.0
```



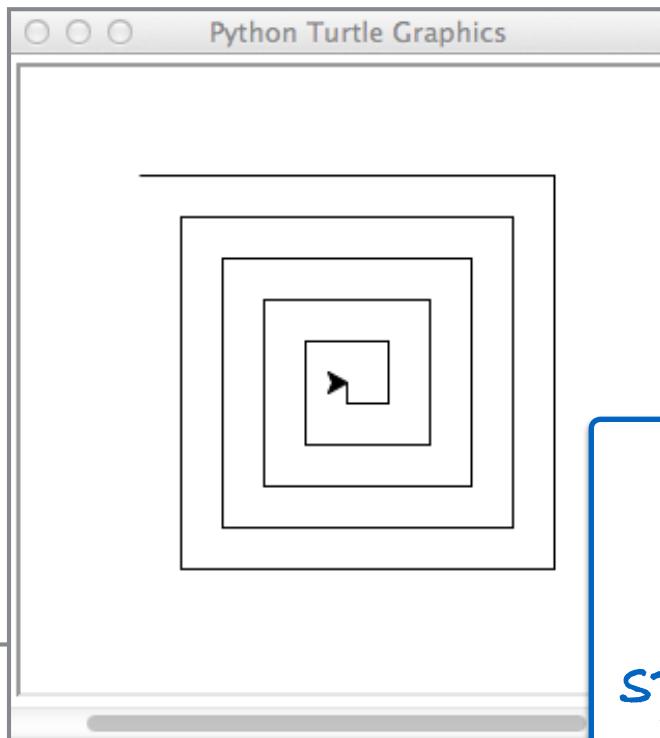
# while loops

```
Python 3.4.1: spiral.py - /Users/Steve/Documents/Python/spiral.py
from turtle import *

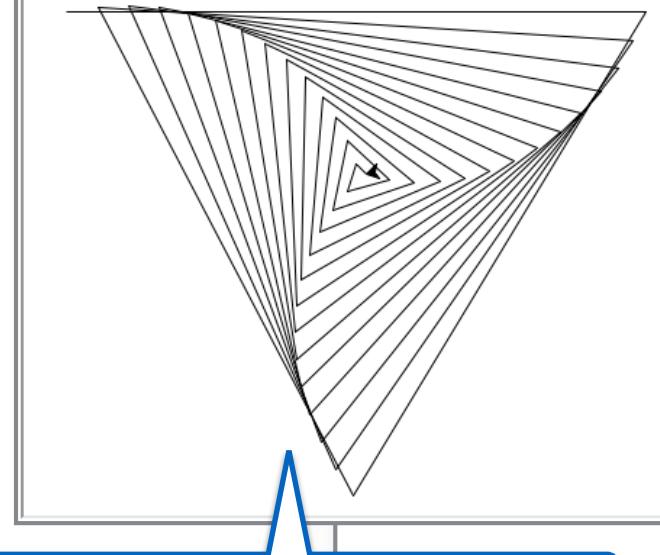
def spiral(length, sides, multiple, decrement):
    while length>0: _____
        forward(length)
        right(multiple * 360/sides)
        length = length - decrement

speed('slow')
penup()
goto(-200,200)
pendown()
spiral(200,4,1,10)
done()
```

'goto' these coordinates.



Exit the 'while' loop when the condition is false.



Try a non-integer multiple:  
`spiral(400, 3, 1.01, 10)`

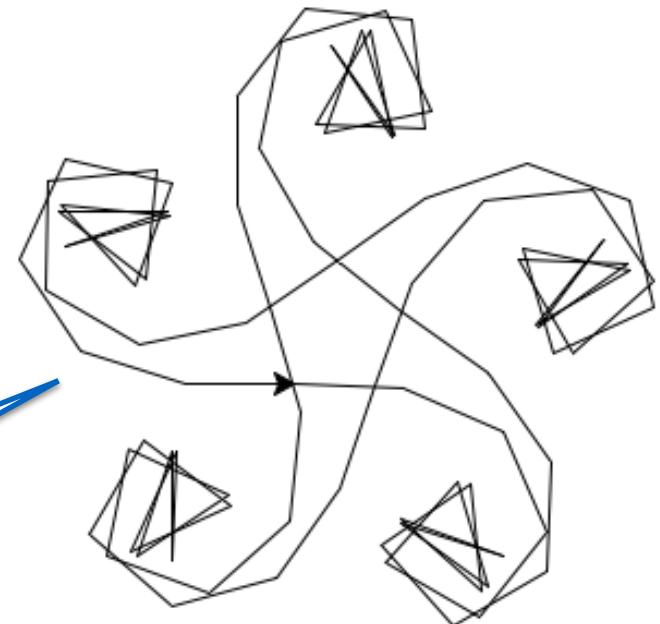
# recursion

```
Python 3.4.1: inspiral.py - /Users/Steve/Document  
from turtle import *  
  
def inspiral(length, angle, increment):  
    forward(length)  
    right(angle)  
    inspiral(length, (angle + increment) % 360, increment)  
  
speed('slow')  
pendown()  
inspiral(50, 2, 20)  
done()
```

Recursive functions  
call themselves.

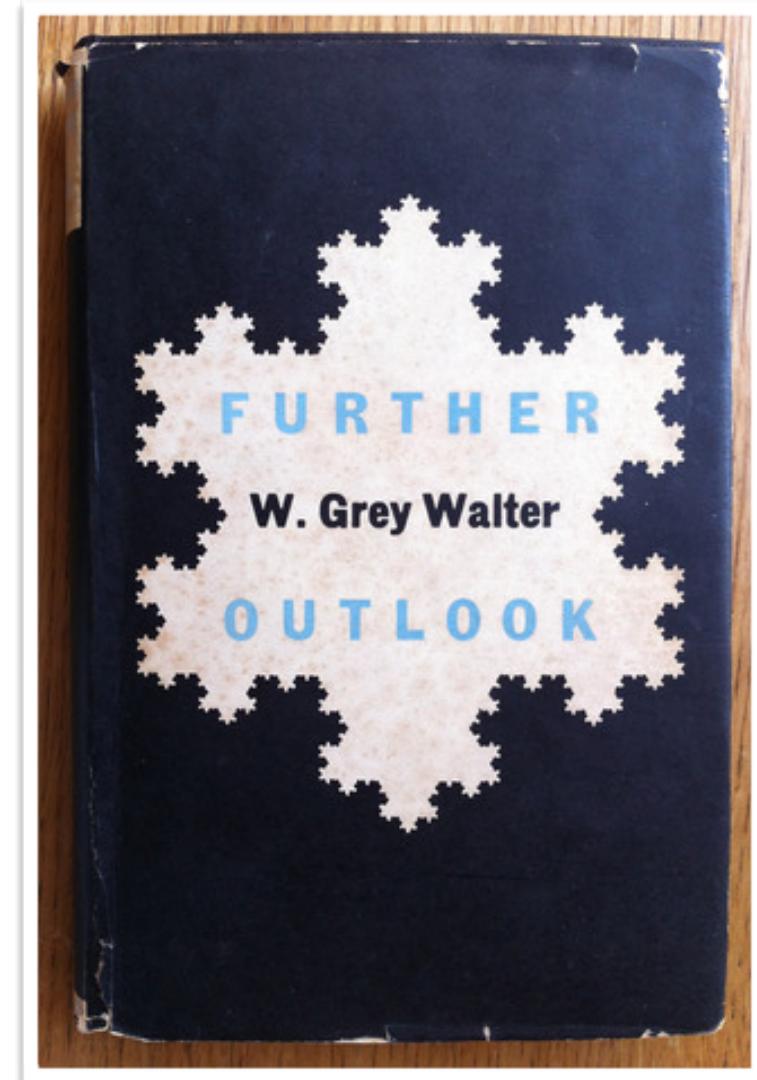
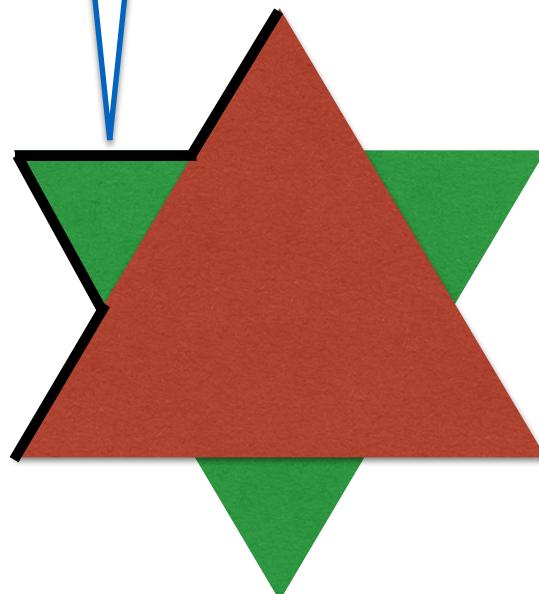
The angle is close to 0  
on the 'straights'

We can also get spiral motion by increasing  
the angle



# The Snowflake Curve

Every side has smaller sides and so on, ad infinitum.



# conditionals

```
Python 3.4.1: snowflake.py – /Users/Steve/Documents/Python/snowflake.py
from turtle import *

def snowflake(length, level):
    for i in range(3):
        side(length, level)
        right(120)

def side(length, level):
    if level==0:
        forward(length)
    else:
        side(length/3, level-1)
        left(60)
        side(length/3, level-1)
        right(120)
        side(length/3, level-1)
        left(60)
        side(length/3, level-1)

speed('fastest')
penup()
goto(-100,100)
pendown()
snowflake(200,4)
done()
```

test if we've bottomed out.

