# Contextualizing large scale signalling networks from expression footprints with CARNIVAL

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# April 18, 2020

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# 1 Introduction

While gene expression profiling is commonly used to gain an overview of cellular processes, the identification of upstream processes that drive expression changes remains a challenge. To address this issue, we introduce CARNIVAL [1], a causal network contextualization tool which derives network architectures from gene expression footprints. CARNIVAL (CAusal Reasoning pipeline for Network identification using Integer VALue programming)(see <a href="https://saezlab.github.io/CARNIVAL">https://saezlab.github.io/CARNIVAL</a>) integrates different sources of prior knowledge including signed and directed protein–protein interactions, transcription factor targets, and pathway signatures.

#### 1.1 CARNIVAL pipeline

CARNIVAL refines a quantitative objective function for ILP problem by incorporating TF and pathway activities on a continuous scale. In addition, the CARNIVAL framework allows us to contextualize the network with or without known targets of perturbations. The implementation is separated into two pipelines

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which will be referred henceforth as Standard CARNIVAL StdCARNIVAL (with known perturbation targets as an input) and Inverse CARNIVAL InvCARNIVAL (without information on targets of perturbation), see Figure 1. The differential gene expression is used to infer transcription factor (TF) activities with DoRothEA, which are subsequently discretized in order to formulate ILPconstraints. As a result, CARNIVAL derives a family of highest scoring networks which best explain theinferred TF activities. Continuous pathway and TF activities can be additionally considered in the objective function.

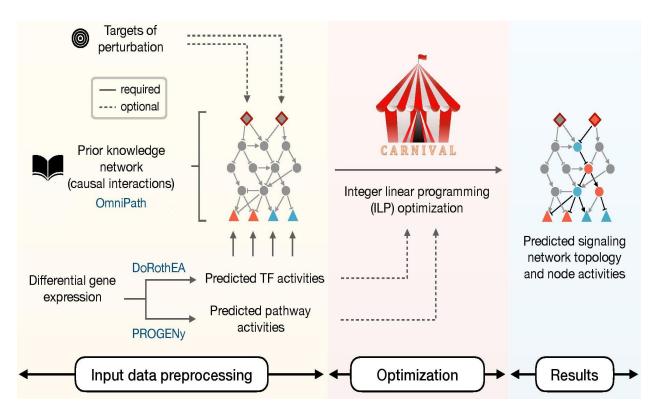


Figure 1: CARNIVAL pipeline

#### 1.2 ILP solvers

CARNIVAL is an extension of the previously implemented Causal Reasoning method from Melas et al. [2]. The network inference process is swiftly performed with an Integer Linear Programming (ILP) formulation of causal reasoning using three solvers: the R-CRAN lpSolve free software used for solving linear problems; the open-source mixed integer programming solver Cbc (Coin-or branch and cut)(see https://projects.coin-or.org/Cbc); or the CPLEX optimizer from IBM (see https://www.ibm.com/analytics/cplex-optimizer) which can be obtained for free through the Academic Initiative. To perform the analysis with cplex or cbc, the users will then need to store the binary cbc or cplex executables on any directory they wish. The binary files of cbc can be found by first downloading one of the optimization suites provided here: https://www.coin-or.org/download/binary/OptimizationSuite/, unzip the download and from there save the cbc executable (which can be found on the bin directory) file on any of the directories they wish of their machines. As for the cplex, the executable file can be obtained after registration on the ILOG CPLEX Optimization Studio here: https://my15.digitalexperience.ibm.com/b73a5759-c6a6-4033-ab6b-d9d4f9a6d65b/dxsites/151914d1-03d2-48fe-97d9-d21166848e65/technology/data-science. Similar like before, users will have

to find the cplex executable binary file and save on a directory of their own wish or keep them on their default installation paths. The path to interactive version of CPLEX is differed based on the operating system. The default installation path for each OS is as follows:

For Mac OS:

# ~/Applications/IBM/ILOG/CPLEX\_Studio129/cplex/bin/x86-64\_osx/cplex

For Linux:

# /opt/ibm/ILOG/CPLEX\_Studio129/cplex/bin/x86-64\_linux/cplex

For Windows:

# C:/Program Files/IBM/ILOG/CPLEX\_Studio129/cplex/bin/x64\_win64/cplex.exe

Note that the version of *CPLEX* has to be changed accordingly (the latest current version is CPLEX-Studio129).

The *lpSolve* solver can be used after downloading and installing the *lpSolve* R-package (see https://cran.r-project.org/web/packages/lpSolve/index.html). This solver only works for smaller examples and it can give only one optimal solution. For larger real-case examples, the users can use *cbc* or *cplex* solvers.

While Cbc is open-source and can be used from any user, the CPLEX solver is more computationally efficient and is able to provide multiple equivalent solutions which are then combined. The mipGAP, limitPop, poolCap, poolIntensity and poolReplace work only if CPLEX solver is used to train the networks.

#### 1.3 Citation

CARNIVAL can be cited as follows:

Liu, A., Trairatphisan, P., Gjerga, E. et al. From expression footprints to causal pathways: contextualizing large signaling networks with CARNIVAL. npj Syst Biol Appl 5, 40 (2019) doi:10.1038/s41540-019-0118-z

#### 1.4 Prerequisites

Besides the above mentioned solvers, users need also to install the following R-package dependencies: readr(see https://cran.r-project.org/web/packages/readr/index.html); igraph (see https://igraph.org/r/); readxl(see https://readxl.tidyverse.org/); dplyr(see https://www.rdocumentation.org/packages/dplyr/versions/0.7.8); lpSolve(see https://cran.r-project.org/web/packages/lpSolve/index.html)

In order to visualize the automatically generated *CARNIVAL* networks, users will also need to download and install the Graph Visualization software *graphviz* (see https://www.graphviz.org/).

# 2 Running CARNIVAL

In the CARNIVAL package, built-in examples are available as the test cases as follows:

- 1. A small toy example where the inputs are known (stdCARNIVAL)
- 2. A small toy example where the inputs are not known (invCARNVAL)

## 2.1 Toy Example - 1

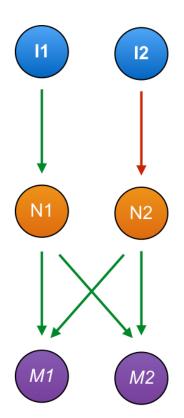
Let us consider the toy example of 2. In this case, the inputs are known (I1=1 and I2=1), while the network has all the interactions as activatory besides the connection connecting I2 with N2. The measurements we have them both M1=1 and M2=1.

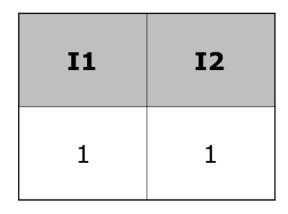
Users can run the CARNIVAL analysis with the free solver as follows:

```
[1] "Writing constraints..."
[1] "Solving LP problem..."
```

```
print(result)
```

```
$weightedSIF
     Node1 Sign Node2 Weight
[1,] "I1" "1"
                "N1"
                      "100"
[2,] "N1" "1" "M1" "100"
[3,] "N1" "1"
                "M2"
                      "100"
$nodesAttributes
    Node ZeroAct UpAct DownAct AvgAct NodeType
[1,] "I1" "0"
                  "100" "0"
                                "100"
                                       "S"
[2,] "N1" "O"
                  "100" "0"
                                "100"
[3,] "I2" "0"
                  "100" "0"
                                "100"
                                       "S"
                  "0" "0"
                                "0"
                                        11 11
[4,] "N2" "100"
                  "100" "0"
[5,] "M1" "O"
                                        "T"
                                "100"
                  "100" "0"
                                       "T"
[6,] "M2" "0"
                                "100"
$sifAll
$sifAll[[1]]
    Node1 Sign Node2
[1,] "I1" "1"
                "N1"
[2,] "N1"
           "1"
                "M1"
[3,] "N1" "1"
                "M2"
```





M1	M2
1	1

Figure 2: Prior Knowledge Network of Toy Example - 1

```
$attributesAll
$attributesAll[[1]]
    Nodes Activity
[1,] "I1" "1"
[2,] "N1" "1"
[3,] "I2" "1"
[4,] "M1" "1"
[5,] "M2" "1"
```

The *result* object will contain the following fields:

- weightedSIF: which contains all the combined solutions generated (lpSolve and cbc will generate only 1 solution, while cplex can generate multiple solutions) with the Weight column indicating how frequently an interaction has appeard on the combined solution.
- nodesAttributes: indicating the weigted mean activities of each of the proteins present in the combined solution and the type of the node (Input (S), Measured (T) or Inferred).
  - sifAll: A list containing all the separate CARNIVAL solutions.

The CARNIVAL results for the Toy Example - 1 are as shown in 3.

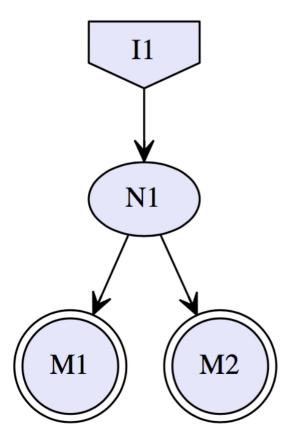


Figure 3: Solution network of Toy Example - 1

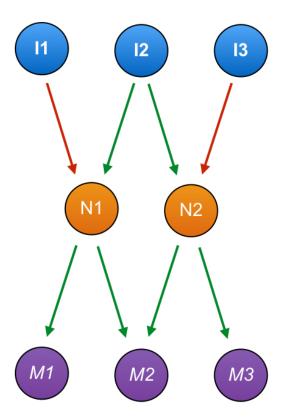
# 2.2 Toy Example - 2

Now let us consider the toy example of 4. In this case, the inputs are not known and thus a dummy *Perturbation* node will be automatically generated and which connects all the nodes in the network which do not have any incoming interaction via activatory and inhibitory interactions. In this way, CARNIVAL will infere the possible activities of the upper nodes in a way which best fits the downstram measurements Users on this case can run the invCARNIVAL analysis with the free solver as follows:

```
[1] "inputObj set to NULL -- running InvCARNIVAL"
[1] "Writing constraints..."
[1] "Solving LP problem..."
```

```
print(result)
```

```
$weightedSIF
     Node1
                      Sign Node2 Weight
[1,] "I2"
                      "1" "N1"
                                 "100"
[2,] "I2"
                      "1"
                           "N2"
                                  "100"
                      "1"
[3,] "N1"
                           "M1"
                                  "100"
[4,] "N1"
                      "1"
                           "M2"
                                  "100"
[5,] "N2"
                      "1"
                           "M2"
                                  "100"
[6,] "N2"
                      "1"
                           "M3"
                                 "100"
[7,] "Perturbation" "1"
                           "I2"
                                 "100"
$nodesAttributes
      Node
                       ZeroAct UpAct DownAct AvgAct NodeType
 [1,] "I1"
                       "100"
                               "0"
                                      "0"
                                               "0"
                                                       11 11
                       "0"
 [2,] "I2"
                                "100" "0"
                                               "100"
                                                       11 11
 [3,] "I3"
                       "100"
                                "0"
                                      "0"
                                               "0"
                                                       11 11
                       "0"
                                "100" "0"
                                                      11 11
 [4,] "N1"
                                               "100"
 [5,] "N2"
                       "0"
                                "100" "0"
                                               "100"
                                                      11 11
                                "100" "0"
 [6,] "Perturbation" "0"
                                                      "S"
                                               "100"
 [7,] "M1"
                       "0"
                               "100" "0"
                                               "100"
                                                       "T"
                                                      "T"
                       "0"
                               "100" "0"
 [8,] "M2"
                                               "100"
 [9,] "M3"
                       "0"
                               "100" "0"
                                               "100"
                                                      "T"
$sifAll
$sifAll[[1]]
     Node1
                      Sign Node2
[1,] "I2"
                      "1" "N1"
[2,] "I2"
                      "1"
                           "N2"
[3,] "N1"
                      "1"
                           "M1"
[4,] "N1"
                      11111
                          "M2"
```



M1	M2	МЗ
1	1	1

Figure 4: Prior Knowledge Network of Toy Example - 2

```
[5,] "N2"
                           "M2"
[6,] "N2"
                           "M3"
[7,] "Perturbation" "1"
                           "I2"
$attributesAll
$attributesAll[[1]]
     Nodes
                     Activity
[1,] "I2"
                     "1"
[2,] "N1"
                     "1"
[3,] "N2"
                     "1"
                     "1"
[4,] "Perturbation"
[5,] "M1"
                     "1"
[6,] "M2"
                     "1"
                     "1"
[7,] "M3"
```

The CARNIVAL results for the Toy Example - 2 are as shown in 5.

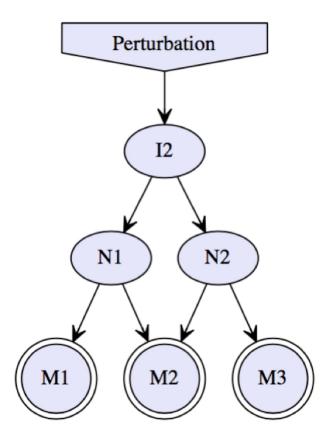


Figure 5: Solution network of Toy Example -  $2\,$ 

#### 2.3 Real Case Example

Real case applications of CARNIVAL using the progeny and DoRothEA packages are provided in <a href="https://github.com/saezlab/CARNIVAL">https://github.com/saezlab/CARNIVAL</a>

# References

- [1] A. Liu, P. Trairatphisan, E. Gjerga, A. Didangelos, J. Barratt and J. Saez-Rodriguez. From expression footprints to causal pathways: contextualizing large signaling networks with CARNIVAL. npj Syst Biol Appl 5, 40 (2019) doi:10.1038/s41540-019-0118-z.
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