

VARIATIONAL BAYESIAN INFERENCE MODEL FOR SHIP DETECTION USING POLARIMETRIC SAR IMAGES

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Objective

- To express the polarimetric SAR image as a tensor, and decompose the SAR image as the sum of a sparse component associated with ships and a sea clutter component. These components are denoted by some latent variables.
- Then, introduce hierarchical priors of the latent variables to establish the probabilistic model of ship detection.
- By using variational Bayesian inference, estimate the posterior distributions of the latent variables.
- Finally, the ship detection result is obtained in the iterative Bayesian inference process



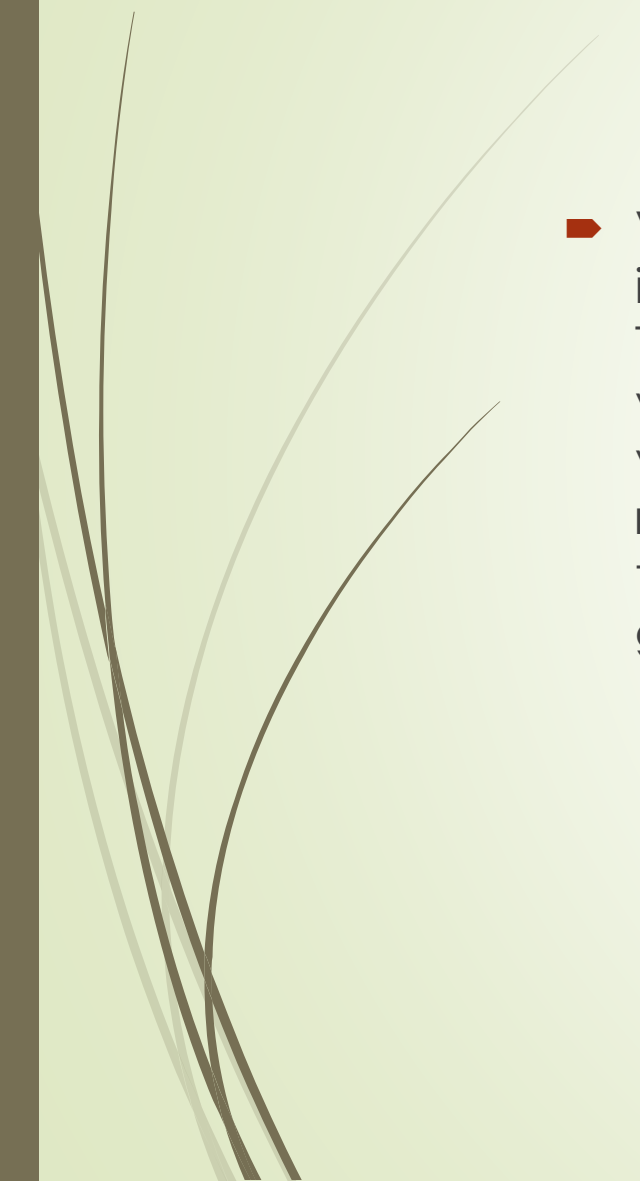
SAR Imaging



- ▶ **Synthetic-aperture radar (SAR)** is a form of radar that is used to create two-dimensional images or three-dimensional reconstructions of objects, such as landscapes. SAR uses the motion of the radar antenna over a target region to provide finer spatial resolution than conventional beam-scanning radars. SAR is typically mounted on a moving platform, such as an aircraft or spacecraft.
- ▶ The Sentinel-1 mission comprises a constellation of two polar-orbiting satellites, operating day and night performing C-band synthetic aperture radar imaging, enabling them to acquire imagery regardless of the weather.
- ▶ Sentinel-1 will work in a pre-programmed operation mode to avoid conflicts and to produce a consistent long-term data archive built for applications based on long time series.



Variational Bayesian Inference

- Variational Bayesian methods are a family of techniques for approximating intractable integrals arising in Bayesian inference and machine learning. They are typically used in complex statistical models consisting of observed variables (usually termed "data") as well as unknown parameters and latent variables, with various sorts of relationships among the three types of random variables, as might be described by a graphical model. As is typical in Bayesian inference, the parameters and latent variables are grouped together as "unobserved variables".
- 



Our Approach

- Parameter initialization
- Image initialization
- Modelling the sea clutter component and ship component
- Training
- Running the Bayesian inference model
- Training the final model

```
17 HV_np= np.array(HV)
18 HH_np= np.array(HH)
19 D=c=np.dstack((HH_np, HV_np))
20
21 D.shape
22 m,n,d=D.shape
23 #%%
24 alpha0=0.001      #hyperparameter
25 beta0=1-alpha0    #hyperparameter
26 E=bayespy.nodes.Beta([alpha0,beta0],plates=(m,n),name='E')
```

Parameter initialization

```
31     key=np.sort(np.reshape(D,-1))[int(m*n*0.9)]
32     print(key)
33
34     for i in range(m):
35         for j in range(n):
36             if D[i,j,0]>key and D[i,j,1]>key:
37                 A_mat[i,j]=1
38             else:
39                 C_mat[i,j,:]=D[i,j,:]
40
41     plt.imshow(C_mat[:, :, 0])
42     plt.show()
43     plt.imshow(A_mat)
44     plt.show()
```

Image Initialization


```
51 from bayespy.nodes import Dirichlet, Categorical
52 alpha = Dirichlet(1e-5*np.ones(K),name='alpha')
53 Zi = Categorical(alpha,plates=(N,),name='zi')
54
55 from bayespy.nodes import Gaussian, Wishart
56 mui = Gaussian(np.zeros(D), 1e-5*np.identity(D),plates=(K,),name='mui')
57 Lambdai = Wishart(D, 1e-5*np.identity(D),plates=(K,),name='Lambdai')
58
59 from bayespy.nodes import Mixture
60 Y = Mixture(Zi, Gaussian, mui, Lambdai,name='Y')
61
62 Zi.initialize_from_random()
63
64 from bayespy.inference import VB
65 Q = VB(Y, mui, Lambdai, Zi, alpha)
66
67 Y.observe(np.reshape(C_mat,(-1,2)))
```



Modelling sea clutter (c) and ship (a) component




```
69 Q.update(repeat=10)
```

Training the model

```
72 neta=1e-6*np.ones(K)    #hyperparameter
73 print(neta.shape)
74 print(neta)
75 PI=bayespy.nodes.Dirichlet(neta,name='PI')
76 #%%
77 Z=bayespy.nodes.Categorical(PI,plates=(m,n,K),name='Z')
78
79 mean_vec=np.zeros(d) # to be initialized according to image
80 precission_mat=1e-5*np.identity(d)    # to be initialized according to image
81 mu=bayespy.nodes.Gaussian(mean_vec,precission_mat,plates=(K,),name='U')
82
83 Lambda=bayespy.nodes.Wishart(d,precission_mat,plates=(K,),name='Lambda')
84
85 C=bayespy.nodes.Mixture(Z,bayespy.nodes.Gaussian,mu,Lambda,name='C')
86 #%%
87 A=bayespy.nodes.Bernoulli(E,plates=(m,n),name='A')
88 #%%
89 A.observe(A_mat)
```



Running the Bayesian inference model



```
93     Model=bayespy.inference.VB(A,E,mu,Lambda,C,PI)
94     ###
95     Model.update(repeat=5)
```

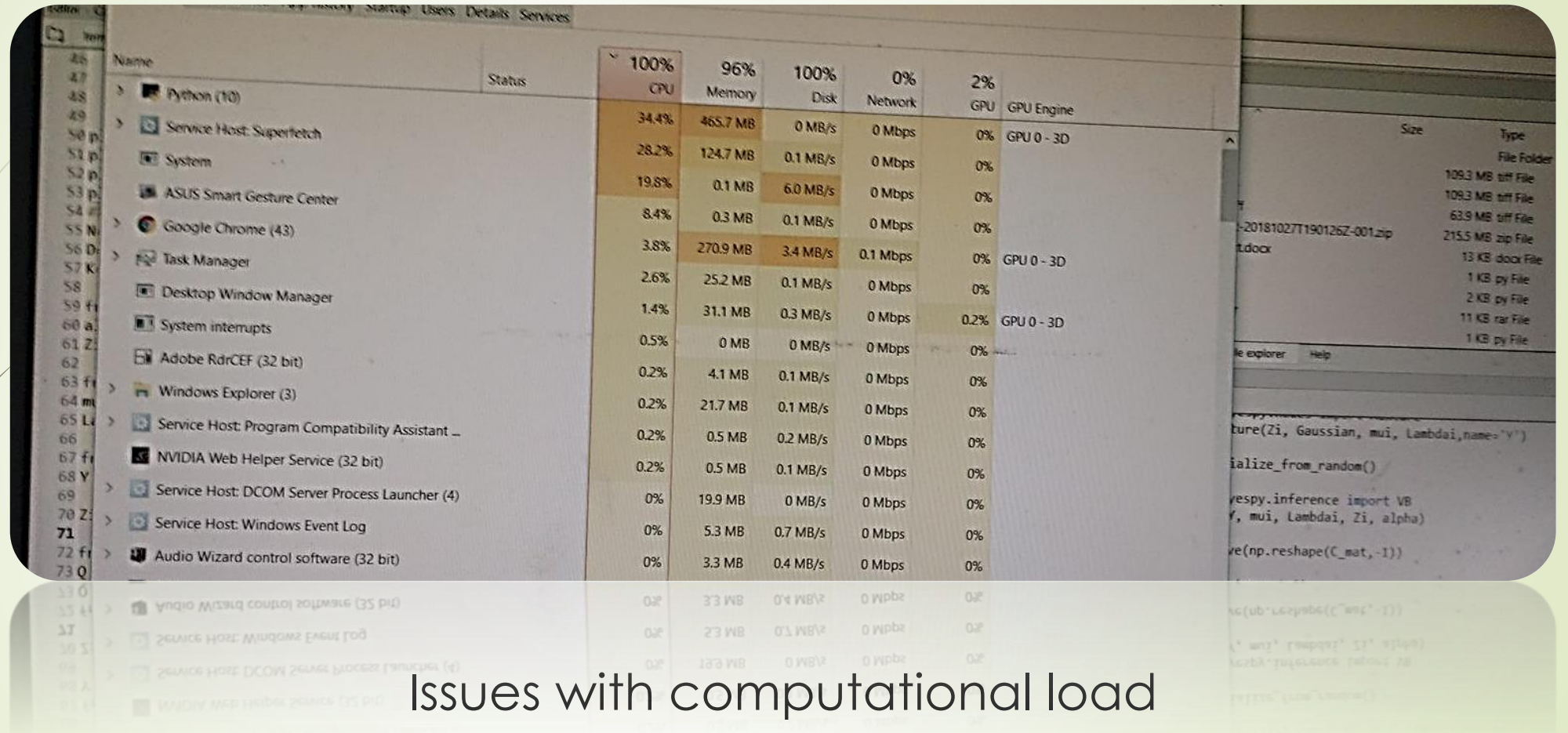


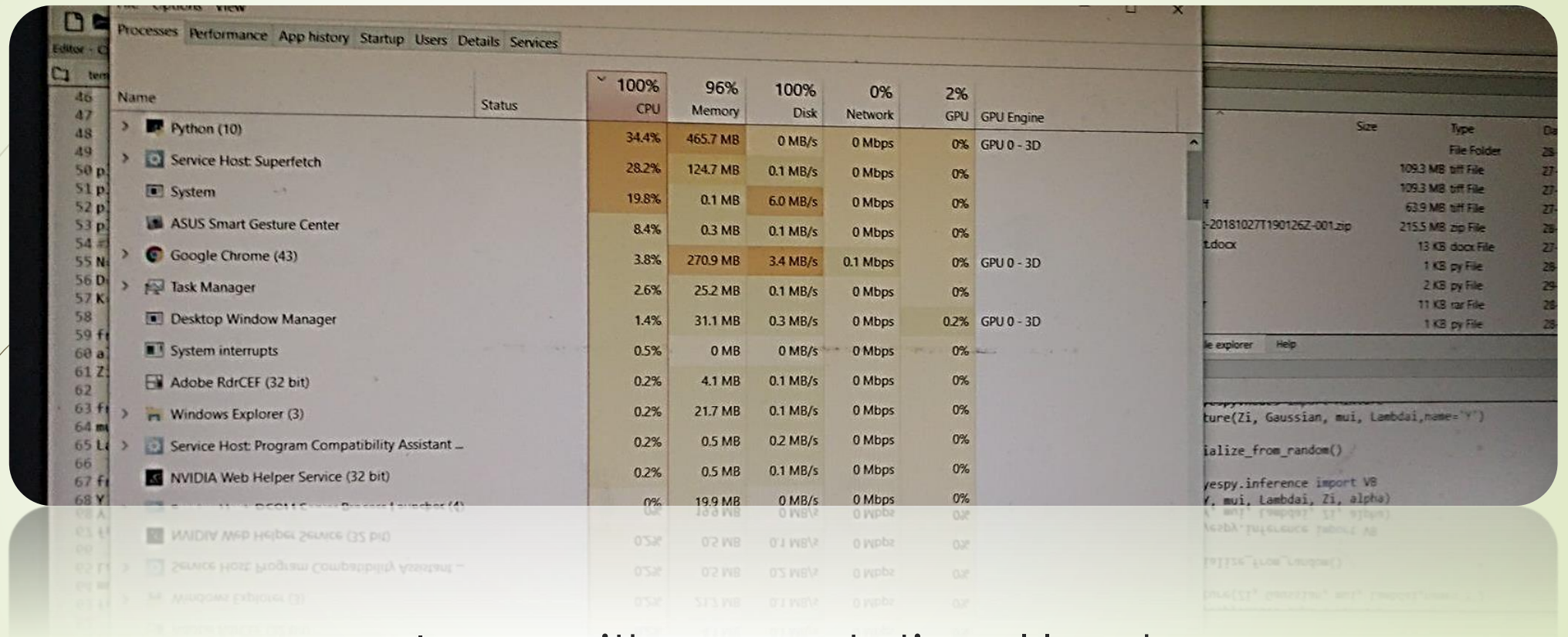
Training for the final model



Problems faced

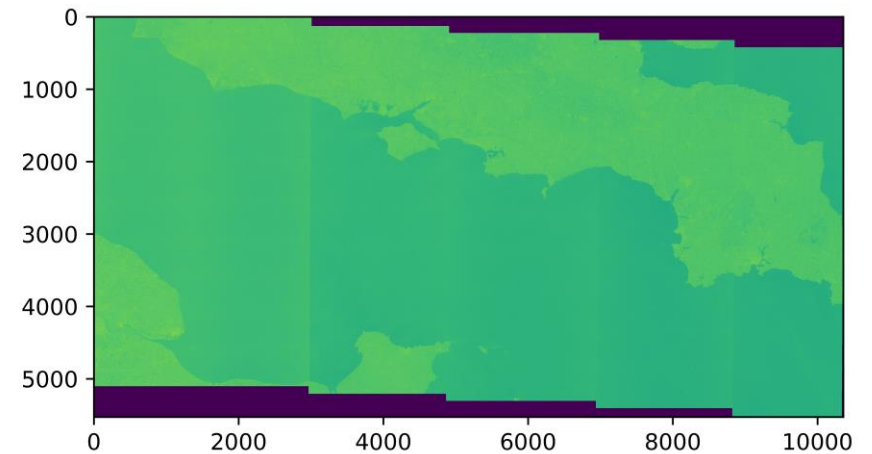
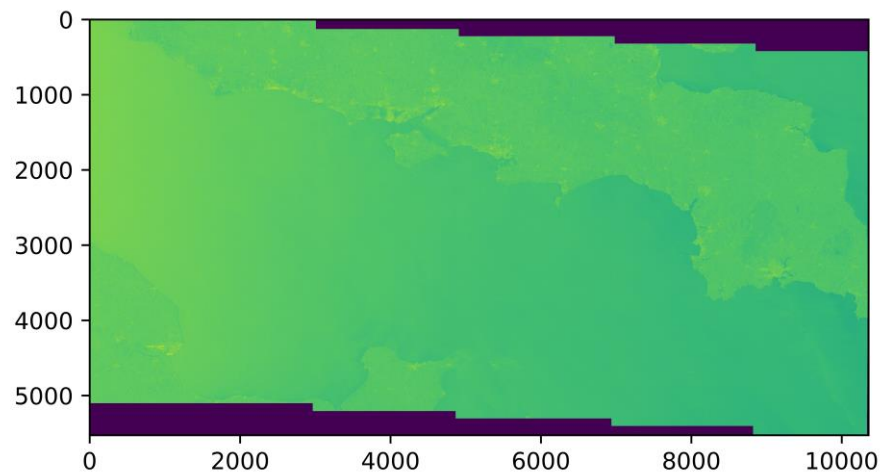
- The model ran for a small part of the image
- The actual image was too big and posed computational problems
- Our machines were unable to run computations for such a large set of pixels.
- We repeatedly ran out of computation power

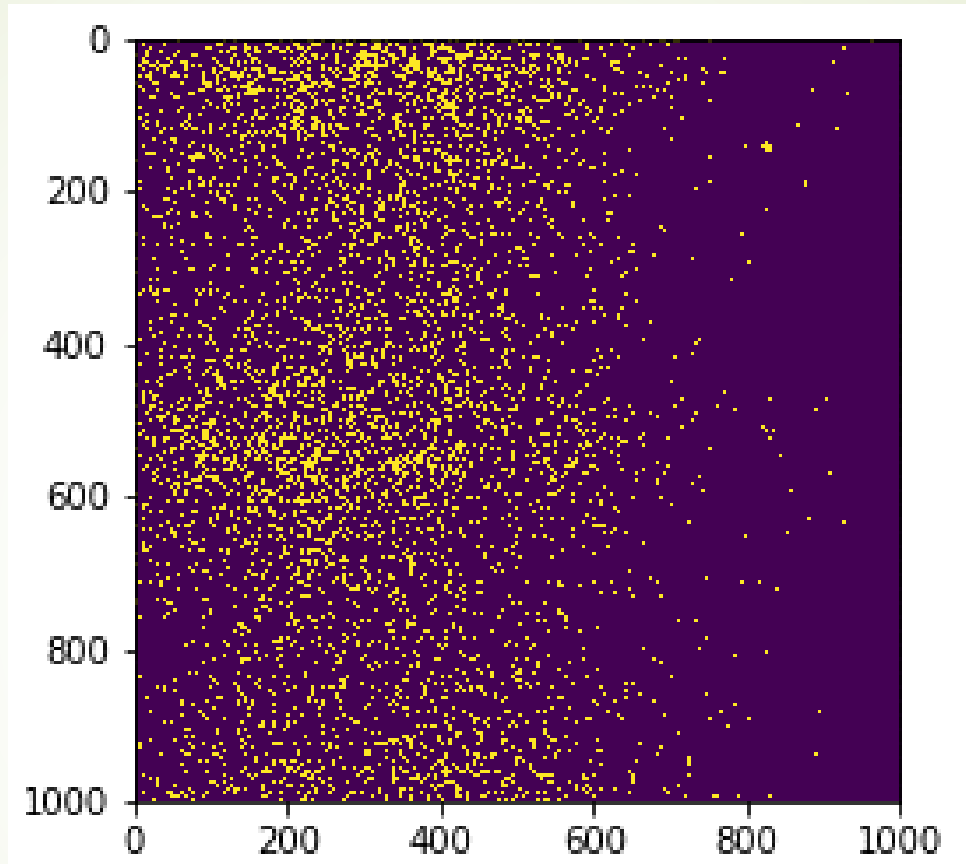




Issues with computational load

Input Images (.png for illustration)





Result (.png for illustration)