

14. A wheel with a radius of 22.0 cm rolls without slipping along a horizontal floor (Fig. 3-21). At time t_1 , the dot P painted on the rim of the wheel is at the point of contact between the wheel and the floor. At a later time t_2 , the wheel has rolled through one-half of a revolution. What are (a) the magnitude and (b) the angle (relative to the floor) of the displacement of P ?

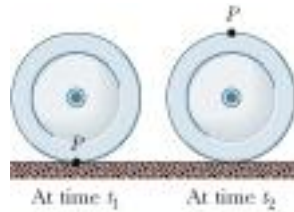


Figure 3-21 Problem 14.

17. Rock *faults* are ruptures along which opposite faces of rock have slid past each other. In Fig. 3-22, points A and B coincided before the rock in the foreground slid down to the right. The net displacement \overrightarrow{AB} is along the plane of the fault. The horizontal component of \overrightarrow{AB} is the *strike-slip* AC . The component of \overrightarrow{AB} that is directed down the plane of the fault is the *dip-slip* AD . (a) What is the magnitude of the net displacement \overrightarrow{AB} if the strike-slip is 18.0 m and the dip-slip is 13.0 m? (b) If the plane of the fault is inclined at angle $\phi = 48.0^\circ$ to the horizontal, what is the vertical component of \overrightarrow{AB} ?

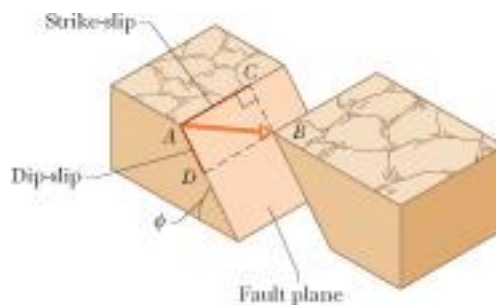


Figure 3-22 Problem 17.

18. Vectors \vec{A} and \vec{B} lie in an xy plane. \vec{A} has magnitude 11.0 and angle 100° ; \vec{B} has components $B_x = -6.50$ and $B_y = -8.40$. (a) What is $5\vec{A} \cdot \vec{B}$? What is $4\vec{A} \times 3\vec{B}$ in (b) unit-vector notation and (c) magnitude-angle notation with spherical coordinates (see Fig. 3-23)? (d) What is the angle between the directions of \vec{A} and $4\vec{A} \times 3\vec{B}$? (*Hint*: Think a bit before you resort to a calculation.) What is $\vec{A} + 3.00\hat{k}$ in (e) unit-vector notation and (f) magnitude-angle notation with spherical coordinates?

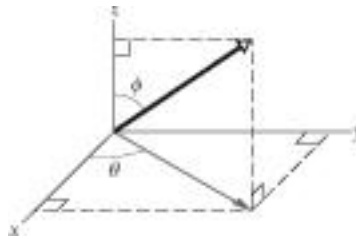


Figure 3-23 Problem 18.