

Week 3

Nonlinear Equations II

1. Review bisection method
2. Newton method
3. Secant method
4. Solve a system of two nonlinear equations

Week 3 part I

Review bisection method

Steps to solve problems

numerical schemes



algorithm



programs



results

Bisection Method (Bracketing method)

Given x_1 and x_2 such that

$$f(x_1) \cdot f(x_2) < 0,$$

Repeat

$$\text{Set } x_3 = \frac{1}{2}(x_1 + x_2)$$

$$\text{If } f(x_1) \cdot f(x_3) < 0$$

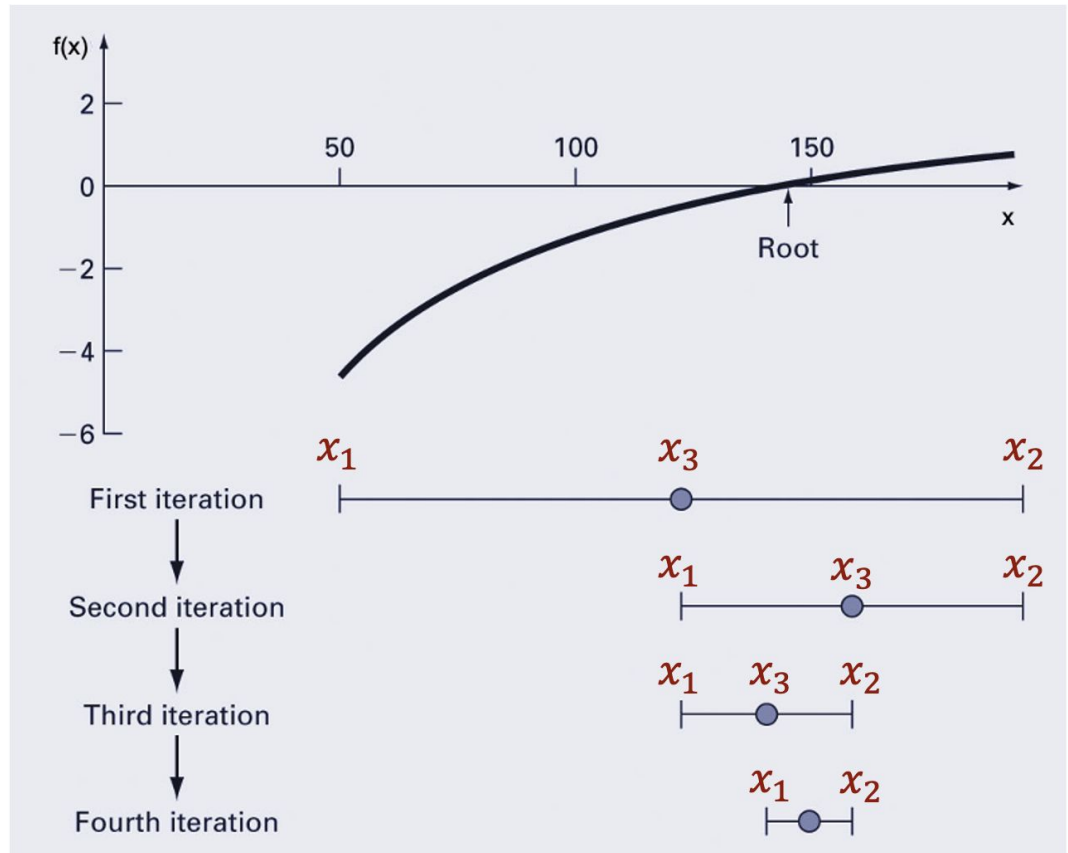
$$\text{Set } x_2 = x_3$$

Else

$$\text{Set } x_1 = x_3$$

End if

Until $(x_2 - x_1) < TOL$



Programming Bisection (Python)

```
Import numpy as np

def F(x):
    y = 8-4.5*(x-np.sin(x))
    return y

x1, x2, imax, TOL = 1, 3, 30, 0.001

if F(x1)*F(x2)>0:
    print('Error: The function has the same sign at points x1 and x2.')
else:
    for i in range(imax):
        x3 = (x1+x2)/2
        toli = (x2-x1)/2
        if F(x3) == 0:
            print('An exact solution x = %.6f was found'%x3)
            break
        if toli<TOL:
            break
        if i==imax:
            print('Solution was not obtained in %i iterations'%imax)
            break
        if F(x1)*F(x3)<0:
            x2 = x3
        else:
            x1 = x3
```

Programming Bisection (MATLAB)

```
F=@(x) 8-4.5*(x-sin(x));

a = 1; b = 3; imax = 30; tol = 0.001
Fa=F(a); Fb=F(b);
if Fa*Fb > 0
    disp('Error: The function has the same sign at points a and b.')
else
    disp('iteration   a   b (xNS) Solution   f(xNS)   Tolerance')
    for i = 1:imax
        xNS = (a + b)/2;
        toli=(b-a)/2;
        FxNS=F(xNS);
        fprintf('%3i      %11.6f %11.6f %11.6f   %11.6f %11.6f\n',i, a, b, xNS, FxNS, toli)
        if FxNS == 0
            fprintf('An exact solution x =%11.6f was found',xNS)
            break
        end
        if toli < tol
            break
        end
        if i == imax
            fprintf('Solution was not obtained in %i iterations',imax)
            break
        end
        if F(a)*FxNS < 0
            b = xNS;
        else
            a = xNS;
        end
    end
end
end
```

Newton Method (Open method)

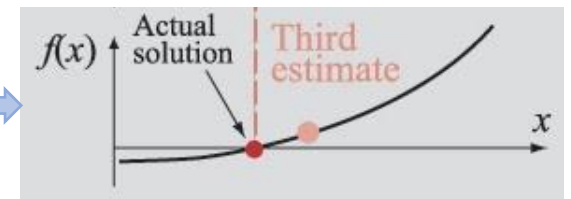
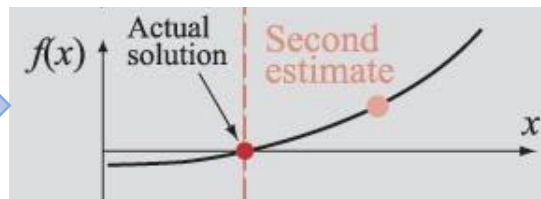
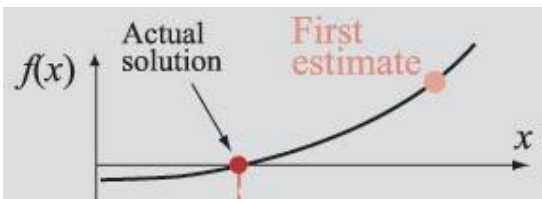
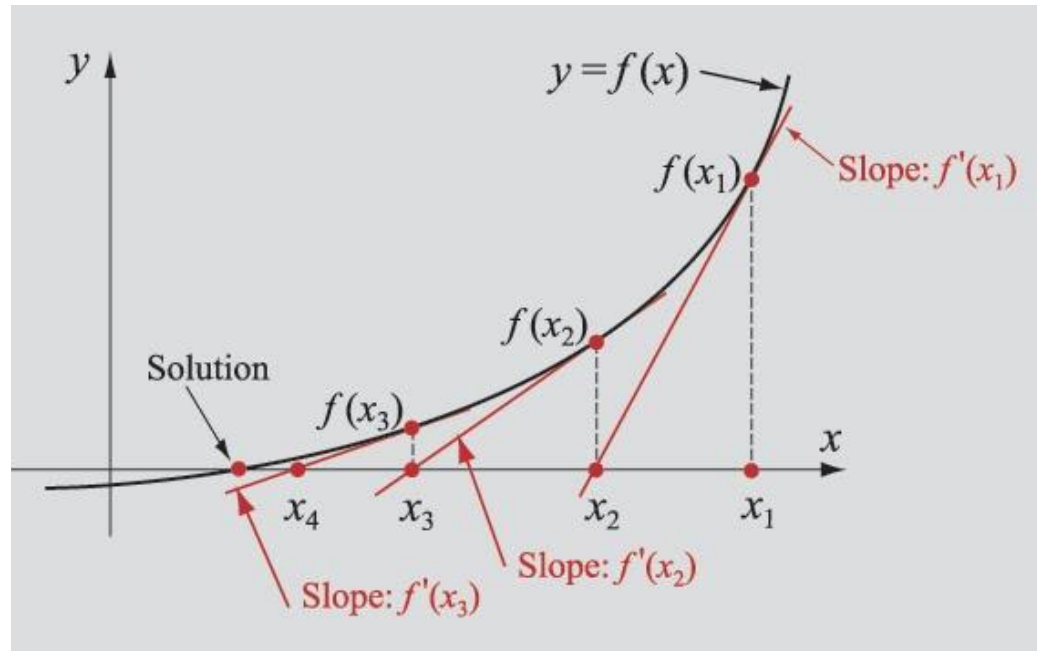
Given x_1 reasonably close to the root,

Repeat

Compute $f(x_1)$, $f'(x_1)$

$$\text{Set } x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

Until $|x_2 - x_1| < TOL$



Secant Method (Open method)

Given x_0 and x_1 that are near to the root,

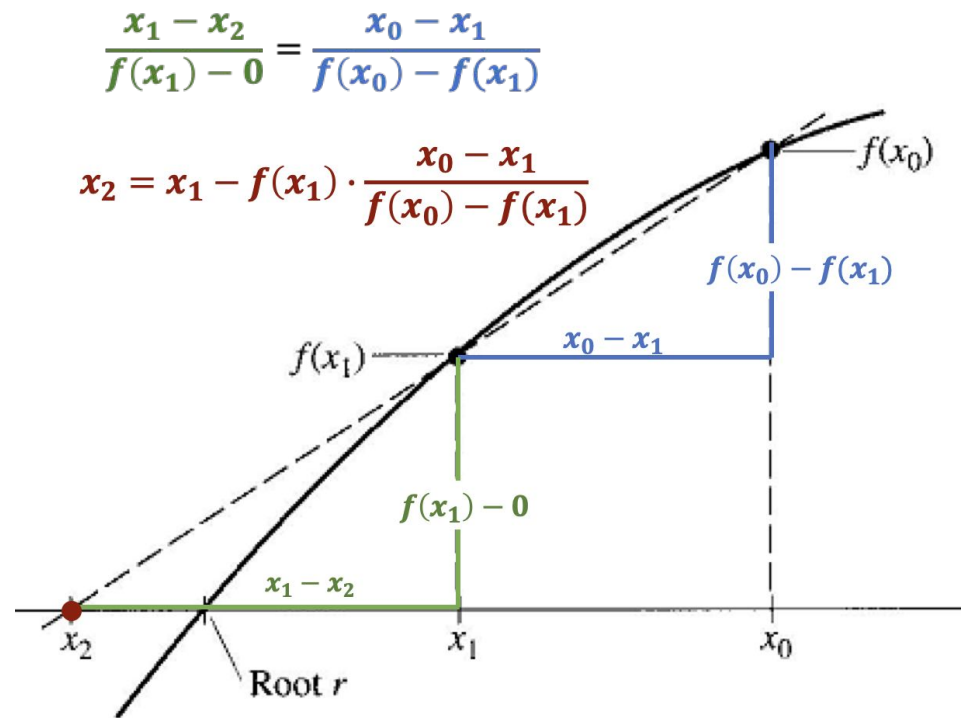
Repeat

$$\text{Set } x_2 = x_1 - f(x_1) \cdot \frac{x_0 - x_1}{f(x_0) - f(x_1)}$$

$$\text{Set } x_0 = x_1$$

$$\text{Set } x_1 = x_2$$

Until $|x_0 - x_1| < TOL$





- When do we use Secant method instead of Newton method?
- Any exceptions for Bisection and Newton method?

Introduction to functions in Python and MATLAB

Python

fsolve from scipy

Roots of nonlinear equations
defined by $f(x)=0$

`Sol = fsolve(function,x0)`

`x0`: The starting estimate
for the roots

<https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.fsolve.html>

MATLAB

fzero

Root of nonlinear function

`Sol =
fzero(function,x0)`

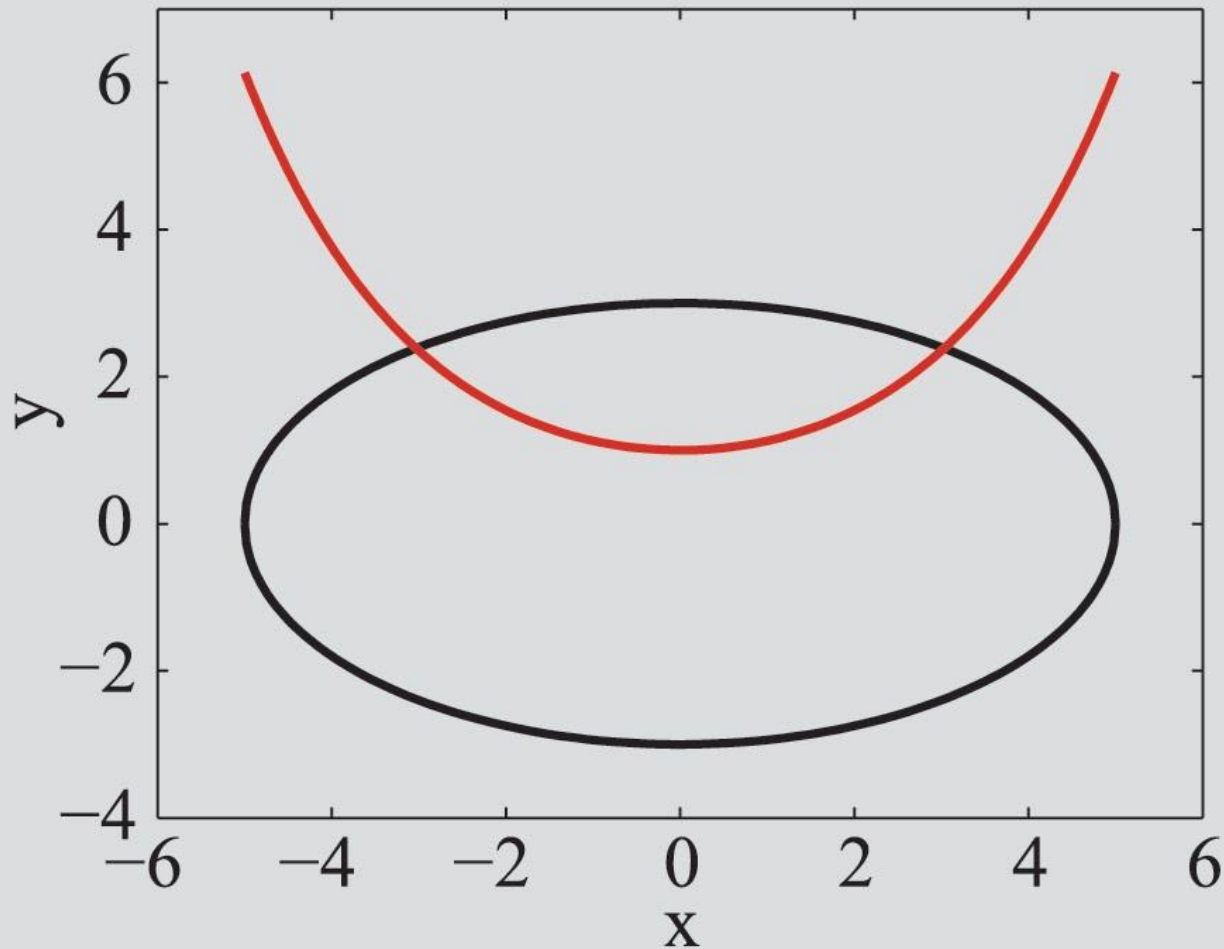
`x0`: value of `x` near to
where the function
crosses the axis

<https://www.mathworks.com/help/matlab/ref/fzero.html>

Week 3 part IV

Solve A System of Two Nonlinear Equation

Equation sets



A system of two nonlinear equations

$$\begin{aligned}f_1(x,y) &= 0 \\ f_2(x,y) &= 0\end{aligned}$$

If x_2 and y_2 are the true solutions (but unknown) of the system and are sufficiently close to x_1 and y_1 , then the values of f_1 and f_2 at x_2 and y_2 can be expressed using ***Taylor series expansion*** of the functions $f_1(x_1, y_1)$, $f_2(x_1, y_1)$:

$$\begin{aligned}f_1(x_2, y_2) &= f_1(x_1, y_1) + (x_2 - x_1) \frac{\partial f_1}{\partial x} + (y_2 - y_1) \frac{\partial f_1}{\partial y} + \dots \\ f_2(x_2, y_2) &= f_2(x_1, y_1) + (x_2 - x_1) \frac{\partial f_2}{\partial x} + (y_2 - y_1) \frac{\partial f_2}{\partial y} + \dots\end{aligned}\tag{1}$$

$$f_1(x_2, y_2) = f_1(x_1, y_1) + (x_2 - x_1) \frac{\partial f_1}{\partial x} + (y_2 - y_1) \frac{\partial f_1}{\partial y} + \dots = 0 \quad (2)$$

$$f_2(x_2, y_2) = f_2(x_1, y_1) + (x_2 - x_1) \frac{\partial f_2}{\partial x} + (y_2 - y_1) \frac{\partial f_2}{\partial y} + \dots = 0$$

$$-f_1(x_1, y_1) = (x_2 - x_1) \frac{\partial f_1}{\partial x} + (y_2 - y_1) \frac{\partial f_1}{\partial y} \quad (3)$$

$$-f_2(x_1, y_1) = (x_2 - x_1) \frac{\partial f_2}{\partial x} + (y_2 - y_1) \frac{\partial f_2}{\partial y}$$

$$-f_1(x_1, y_1) = \Delta x \frac{\partial f_1}{\partial x} + \Delta y \frac{\partial f_1}{\partial y} \quad (4)$$

$$-f_2(x_1, y_1) = \Delta x \frac{\partial f_2}{\partial x} + \Delta y \frac{\partial f_2}{\partial y}$$

$$-f_1(x_1, y_1) = \Delta x \frac{\partial f_1}{\partial x} + \Delta y \frac{\partial f_1}{\partial y} \quad (5)$$

$$-f_2(x_1, y_1) = \Delta x \frac{\partial f_2}{\partial x} + \Delta y \frac{\partial f_2}{\partial y}$$

$$\Delta x = \frac{-f_1(x_1, y_1) \frac{\partial f_2}{\partial y} + f_2(x_1, y_1) \frac{\partial f_1}{\partial y}}{\boxed{\frac{\partial f_1}{\partial x} \frac{\partial f_2}{\partial y} - \frac{\partial f_1}{\partial y} \frac{\partial f_2}{\partial x}}} \quad (6)$$

Jacobian matrix:

$$J_F(x, y) = \begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} \end{bmatrix}$$

$$\Delta y = \frac{-f_2(x_1, y_1) \frac{\partial f_1}{\partial x} + f_1(x_1, y_1) \frac{\partial f_2}{\partial x}}{\frac{\partial f_1}{\partial x} \frac{\partial f_2}{\partial y} - \frac{\partial f_1}{\partial y} \frac{\partial f_2}{\partial x}}$$

$$x_2 = x_1 + \Delta x$$

$$y_2 = y_1 + \Delta y \quad (7)$$

Algorithm for solving a set of equations

1. Estimate an initial solutions, x_1, y_1
2. Calculate Jacobian and $f_{1x}, f_{1y}, f_{2x}, f_{2y}$
3. Solve for $\Delta x, \Delta y$
4. Estimate the new solutions, $x_2, y_2, x_3, y_3, \dots$
5. Compute the tolerance, then repeat or break