Detailed Design (DD) Timer0_CTC mode

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APIs

- 1. Initialization API
- 2. Set Callback API
- 3. Set compare match



1 Initializing API

Name	Initialization Function
Prototype	STD MCAL_Timer0_init(void);
Parameter in	
Parameter	-
out	
Parameter	-
in-out	
Return Type	STD E_OK \ STD E_NOT_OK
Description	This Function is responsible of initializing the Timer0:
	* 1. Setup the timer0 in CTC mode (clear timer on compare match).
	* 2. Set the appropriate prescaler.
	* 3. Enable the timer.
Covered	[SRS_TIMER0_2.1], [SRS_TIMER0_2.2], [SRS_TIMER0_3.1],
Requirement	[SRS_TIMERO_3.2], [SRS_TIMERO_3.3].

2 Set callback API

Name	Set callback function
Prototype	void TIMER0_SetCallBack_CTC (void (*Local_PointerToFunction_OVF)
	(void))
Parameter in	void (*Local_PointerToFunction_CTC) (void)
Parameter	-
out	
Parameter	-
in-out	
Return Type	STD E_OK \ STD E_NOT_OK
Description	This Function sets the callback function to execute when the
	compared value is met.
Covered	[SRS_TIMER0_2.3], [SRS_TIMER0_2.4], [SRS_TIMER0_2.5],
Requirement	[SRS_TIMER0_3.1], [SRS_TIMER0_3.2], [SRS_TIMER0_3.3]

3 Set preload API

Name	Set compare match
Prototype	void TIMER0_voidSetCompareMatchValue
	(u8 Copy_u8CompareMatchValue);
Parameter in	u8 Copy_u8CompareMatchValue
Parameter	-
out	
Parameter	-
in-out	
Return Type	STD E_OK \ STD E_NOT_OK
Description	Set Compare Match Value in OCRO Register To make Timer Over Flow
	at This Value
Covered	[[SRS_TIMER0_2.4], [SRS_TIMER0_3.1]. [SRS_TIMER0_3.2].
Requirement	[SRS_TIMERO_3.3].